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Solution: The key is to draw the Free Body Diagram (FBD) in order to keep the signs right. To identify the direction of the spring forces on the left side object, let $x_2 = 0$ and increase x_1 from 0. Then the k_1 spring on the left will be stretched producing its spring force to the left and the k_2 spring

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3. Give the state description matrices in normal-mode form for the transfer functions of Problem 1. Make sure that all entries in the state matrices are real-valued by keeping any pairs of complex conjugate poles together, and realize them as a separate subblock in control canonical form. Solution: (a) $F = -0.25$, $G = 1$, $H = 0.25$, $J = 0$.

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