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Kirk problem 3.24. Don't try to solve it analytically - instead solve for the optimal control  $u$  numerically for both parts (a) and (b). Plot  $u$  for parts (a) and (b) and compare the solutions. Plot the states with  $x(0) = [1, 1]^T$  for parts (a) and (b) and compare the solutions. 2.

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