# Homework 10

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December 6, 2021

### Problem 1

The KKT conditions are:

$$\begin{aligned} 2x_1 + 2\mu_1(x_1 - 1) + 2\mu_2(x_1 - 1) &= 0 \\ 2x_2 + 2\mu_1(x_2 - 1) + 2\mu_2x_2 &= 0 \\ \mu_i &\geq 0, \ i = 1, 2 \\ \mu_i g_i(\mathbf{x}) &= 0, \ i = 1, 2 \end{aligned}$$

Case I:  $g_2$  is inactive and  $g_1$  is active. Then  $\mu_2 = 0$  and  $g_1(\mathbf{x}) = 0$ .

$$\begin{cases} x_1 = x_2 = 1 - \frac{\sqrt{2}}{2} \\ \mu_1 = \sqrt{2} - 1 \end{cases} \quad \text{or} \quad \begin{cases} x_1 = x_2 = 1 + \frac{\sqrt{2}}{2} \\ \mu_1 = -1 - \sqrt{2} \end{cases} \quad \text{(contradiction to } \mu_1 \ge 0)$$

By the sufficiency of KKT conditions for convex problems,  $\boldsymbol{x}^* = (1 - \frac{\sqrt{2}}{2}, 1 - \frac{\sqrt{2}}{2}), \ \mu_1 = \sqrt{2} - 1, \ \mu_2 = 0.$ 

Note that: this theorem(the sufficiency of KKT conditions for convex problems) will be used for many times. For the sake of convenience we denote it as "Thm 1".

#### Problem 2

- (a) The feasible set is  $\{(x_1, x_2) : x_1 = 1 \land x_2 = 0\}$ . Then  $\mathbf{x}^* = (1, 0), f^* = 1$ .
- (b) The KKT conditions are:

$$2x_1 + 2\mu_1(x_1 - 1) + 2\mu_2(x_1 - 1) = 0$$

$$2x_2 + 2\mu_1(x_2 - 1) + 2\mu_2(x_2 + 1) = 0$$

$$\mu_i \ge 0, \ i = 1, 2$$

$$\mu_1[(x_1 - 1)^2 + (x_2 - 1)^2 - 1] = 0$$

$$\mu_2[(x_1 - 1)^2 + (x_2 + 1)^2 - 1] = 0$$

 $x_1 = 1$  and  $x_2 = 0$  will lead to contradiction. Thus there does not exist Lagrange multipliers satisfying the KKT conditions and both g are active.

$$\nabla \boldsymbol{g}(\boldsymbol{x}^*) = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$$

1

Thus  $x^*$  is not regular.

#### Problem 3

Let

$$egin{aligned} oldsymbol{g}(oldsymbol{x}^*) &= egin{bmatrix} g_1(oldsymbol{x}^*) \ g_2(oldsymbol{x}^*) \ g_3(oldsymbol{x}^*) \ g_4(oldsymbol{x}^*) \end{bmatrix} = egin{bmatrix} x_1^2 - x_2 \ x_1 + x_2 - 6 \ -x_1 \ -x_2 \end{bmatrix} \end{aligned}$$

The KKT conditions are:

$$2(x_1 - \frac{9}{4}) + 2\mu_1 x_1 + \mu_2 - \mu_3 = 0$$

$$2(x_2 - 2) - \mu_1 + \mu_2 - \mu_4 = 0$$

$$\mu_i \ge 0, \ i = 1, 2, 3, 4$$

$$\mu_i g_i(\mathbf{x}) = 0, \ i = 1, 2, 3, 4$$

Case I:  $g_1$  is active and  $g_2, g_3, g_4$  are inactive. Then  $x_1^2 = x_2$  and  $\mu_2 = \mu_3 = \mu_4 = 0$ .

Then we have

$$x_1 = \frac{3}{2}, \ x_2 = \frac{9}{4}, \ \mu_1 = \frac{1}{2}$$

By Thm 1 and the fact that f, g are convex:

$$\boldsymbol{x}^* = \begin{bmatrix} \frac{3}{2} & \frac{9}{4} \end{bmatrix}, \ \mu_1 = \frac{1}{2}, \ \mu_2 = \mu_3 = \mu_4 = 0$$

## Problem 4

(a) The KKT conditions are:

$$x - z + \lambda y - \mu = 0$$
$$y^{T}x = 0$$
$$\mu \ge 0$$
$$Mx = 0$$

where  $\lambda \in \mathbb{R}$ ,  $\mu = (\mu_1, \dots, \mu_n)^T \in \mathbb{R}$ ,  $\mathbf{M} = \operatorname{diag}(\mu_1, \dots, \mu_n)$ . Then we have:

- If  $x_i^* = 0$  and  $\mu_i \ge 0$ , then  $x_i = \mu_i + z_i \lambda y_i = 0$  which means that  $z_i \lambda y_i \le 0$ . Thus  $x_i = (z_i \lambda y_i)^+$ .
- If  $\mu_i = 0$ , then  $x_i = z_i \lambda y_i > 0$ .

Thus  $x_i = (z_i - \lambda y_i)^+$ . And by the fact that  $\mathbf{y}^T \mathbf{x} = 0$ ,  $\sum_{i=1}^n y_i (z_i - \lambda y_i)^+$ .

(b) My code is in the next page (Also in the file "code.py").

The final result is:  $\boldsymbol{x}^* = (\frac{1}{3}, \frac{4}{3}, \frac{5}{3})^T$  and  $\lambda = \frac{2}{3}$ .

```
1 import numpy as np
2
   def solve(z,y):
3
4
        compute lamda for a particular optimization problem:
5
        \min 0.5*\setminus norm\{x-z\}^2
       s.t. y^Tx = 0
7
             x >= 0
8
9
       Inputs:
10
11
        - z: vector in objective function, of shape (N,) or (N,1)
        - y: vector in equality constraint function, of any given shape (N,) or \dots
12
                                                         (N,1)
13
       Returns a tuple of:
14
15
        - x: the optimal point of the problem, of shape (N,) or (N,1). x = \dots
                                                        (z-lamda*y)^+.
        - lamda: the Lagrange multiplier of the equality constraint function in \dots
                                                        KKT conditions.
17
18
       shape = z.shape
19
20
       z = z.reshape(-1)
       y = y.reshape(-1)
21
        # initialize some parameters
22
       p = np.sum(y>0) # number of the elements > 0 in y
23
       m = len(y) - p
24
       u = np.sort(z[y==1]) # u = {z_i: i \setminus in I_+}
25
       w = np.sort(-z[y==-1])
26
       u = np.append([-np.inf],u)
27
28
       u = np.append(u,[np.inf])
       w = np.append([-np.inf],w)
29
30
       w = np.append(w,[np.inf])
31
       U = np.zeros(p+1)
32
       W = np.zeros(m+1)
33
34
        for i in range(p):
            U[p-i-1] = U[p-i] + u[p-i]
35
        for i in range(m):
36
            W[i+1] = W[i] + w[i+1]
37
        # initialization of lamda, l and k
38
39
       lam = -1
       k = 0
40
       1 = 0
41
        # Nlog(N) algortithm
42
        while (k \le p) and (1 \le m):
43
            lam = (U[k] + W[1]) / (p - k + 1)
44
            if (u[k] \le lam \le u[k+1]) and (w[l] \le lam \le w[l+1]):
45
46
             \  \  \, \text{if} \quad \, u\, [\,k\!+\!1\,] \  \, < \  \, w\, [\,l\!+\!1\,] \,: \\
47
                k = k+1
48
49
50
51
        return (((z - lam * y) > 0) * (z - lam * y)).reshape(shape), lam
52
53
z_p4 = np.array([1.0, 2.0, 1.0])
55 y_p4 = np.array([1.0, 1.0, -1.0])
x,lamda = solve(z_p4, y_p4)
57 # print(x,lamda)
```