

## PS 4

Thursday, April 23, 2020 3:10 PM

### Problem 1

$$[R] = R_T - [R^*]$$

$$[X] = X_T - [X^*]$$

$$[Y] = Y_T - [Y^*]$$

$$\frac{d[Y]}{dt} = -\frac{d[Y^*]}{dt} = \frac{y_3[X^*](Y_T - [Y^*])}{k_3 + (Y_T - [Y^*])} - \frac{v_4[Y^*]}{k_4 + [Y^*]}$$

$$\frac{y_3[X^*](Y_T - [Y^*])}{k_3 + (Y_T - [Y^*])} = \frac{v_4[Y^*]}{k_4 + [Y^*]} \quad Y^* = \frac{[Y^*]}{Y_T}$$

Solving  $R^*$ :

$$\frac{d[R^*]}{dt} = k_{on}(R_T - [R^*])[L] - k_{off}[R^*]$$

$$\frac{d[R^*]}{dt} = k_{on}R_T[L] - k_{on}[R^*][L] - k_{off}[R^*]$$

$$\text{at } R_T \text{ @ S.S. } \theta_B = [R^*]/R_T \quad K_D = k_{off}/k_{on}[L]$$

$$0 = k_{on}[L] - k_{on}\theta_B[L] - k_{off}\theta_B$$

$$0 = k_{on}[L] - \theta_B(k_{on}[L] + k_{off})$$

$$k_{on}[L] = \theta_B(k_{on}[L] + k_{off})$$

$$\theta_B = \frac{k_{on}[L]}{k_{on}[L] + k_{off}}$$

$$\boxed{\theta_B = \frac{1}{1 + K_D}}$$

$$\Rightarrow \theta_B(1 + K_D) = 1$$

$$\frac{\theta_B(1 + K_D)}{K_D} = \frac{1}{K_D}$$

$$\frac{\theta_B}{K_D} + \theta_B = \frac{1}{K_D}$$

$$\theta_B \left( \frac{1}{K_D} + 1 \right) = \frac{1}{K_D}$$

$$\boxed{\theta_B = \frac{1}{K_D + 1}}$$

Solving  $X^*$ :

$$\frac{d[X^*]}{dt} = -\frac{d[X]}{dt} = \frac{V_1[X]}{K_1 + [X]} - \frac{V_2[X^*]}{K_2 + [X^*]} \quad \text{where } V_1 = y_1[R^*]$$

$$= \frac{V_1(X_T - [X^*])}{K_1 + (X_T - [X^*])} - \frac{V_2[X^*]}{K_2 + [X^*]}$$

$$\frac{V_1}{V_2} = \frac{y_1 \theta_B R_T}{V_2}$$

$$0 = \frac{\frac{V_1}{V_2}(X_T - [X^*])}{K_1 + (X_T - [X^*])} - \frac{[X^*]}{K_2 + [X^*]}$$

$$= \frac{\frac{\gamma_1 \theta_B R_T (x_T - [x^*])}{V_2} - \frac{[x^*]}{K_2 + [x^*]}}{K_1 + (x_T - [x^*])}$$

$$x^* = [x^*]/x_T$$

$$0 = \frac{\frac{\gamma_1 \theta_B R_T x_T - \gamma_1 \theta_B R_T [x^*]}{V_2} - \frac{[x^*]}{K_2 + [x^*]}}{K_1 + (x_T - [x^*])}$$

$\div x_T$

$$0 = \frac{\frac{\gamma_1 \theta_B R_T - \gamma_1 \theta_B R_T x^*}{V_2} - \frac{x^*}{K_2 + x^*}}{K_1 + (1 - x^*)}$$

$$0 = \frac{\left(\frac{V_1}{V_2}\right)(1 - x^*) - \frac{x^*}{K_2 + x^*}}{K_1 + (1 - x^*)}$$

$$\frac{x^*}{K_2 + x^*} = \left(\frac{V_1}{V_2}\right) \frac{(1 - x^*)}{K_1 + (1 - x^*)}$$

$$\frac{x^*}{K_2 + x^*} = \frac{\gamma_1 \theta_B R_T}{V_2} \frac{(1 - x^*)}{K_1 + (1 - x^*)}$$

$$x^* = 5\theta_B \frac{(1 - x^*)(K_2 + x^*)}{K_1 + (1 - x^*)}$$

$$x^* = \frac{5\theta_B [K_2 + x^* - x^* K_2 + x^{*2}]}{K_1 + (1 - x^*)}$$

$$x^*(K_1 + (1 - x^*)) = 5\theta_B [K_2 + x^* - x^* K_2 + x^{*2}]$$

$$x^* K_1 + x^* - x^{*2} = 5\theta_B [K_2 + x^* - K_2 x^* + x^{*2}]$$

↓ Plugged into Wolfram Alpha

$$x^* = \frac{[(K + 5(K-1)\theta_B + 1)^2 + 20K\theta_B(5\theta_B - 1)]^{1/2} - K - 5\theta_B K + 5\theta_B - 1}{(-2 + 10\theta_B)}$$

all Kappas = K

Solving  $y^*$ :

$$(a) \quad \frac{d[y^*]}{dt} = -\frac{d[y]}{dt} = \frac{V_3[y]}{K_3 + [y]} - \frac{V_4[y^*]}{K_4 + [y^*]} \quad V_3 = \gamma_3 [x^*] \quad \frac{V_3 x_T}{V_4} = 10 \quad [y] = Y_T - [Y^*]$$

$$0 = \frac{V_3(Y_T - [Y^*])}{K_3 + (Y_T - [Y^*])} - \frac{V_4[Y^*]}{K_4 + [Y^*]}$$

$\div \text{but } V_3$

$$0 = \frac{V_3(Y_T - V^*)}{K_3 + (Y_T - V^*)} - \frac{V_4(Y^*)}{K_4 + Y^*}$$

÷ by  $V_4$

$$0 = \left(\frac{V_3}{V_4}\right) \frac{(Y_T - V^*)}{K_3 + (Y_T - V^*)} - \frac{Y^*}{K_4 + Y^*}$$

÷ by  $Y_T$

$$0 = \left(\frac{V_3}{V_4}\right) \frac{(1 - Y^*)}{K_3 + (1 - Y^*)} - \frac{Y^*}{K_4 + Y^*}$$

Plug in  $V_3$

$$\frac{Y^*}{K_4 + Y^*} = \frac{V_3 X^* Y_T (1 - Y^*)}{V_4 K_3 + (1 - Y^*)}$$

$$\frac{Y^*}{K_4 + Y^*} = \frac{10 X^* (1 - Y^*)}{K_3 + (1 - Y^*)}$$

$$Y^* = \frac{10 X^* (1 - Y^*) (K_4 + Y^*)}{K_3 + (1 - Y^*)}$$

$$Y^* = \frac{10 X^* [K_4 + Y^* - K_4 Y^* - Y^{*2}]}{K_3 + (1 - Y^*)}$$

$$Y^* [K_3 + 1 - Y^*] = 10 X^* [K_4 + Y^* - K_4 Y^* - Y^{*2}]$$

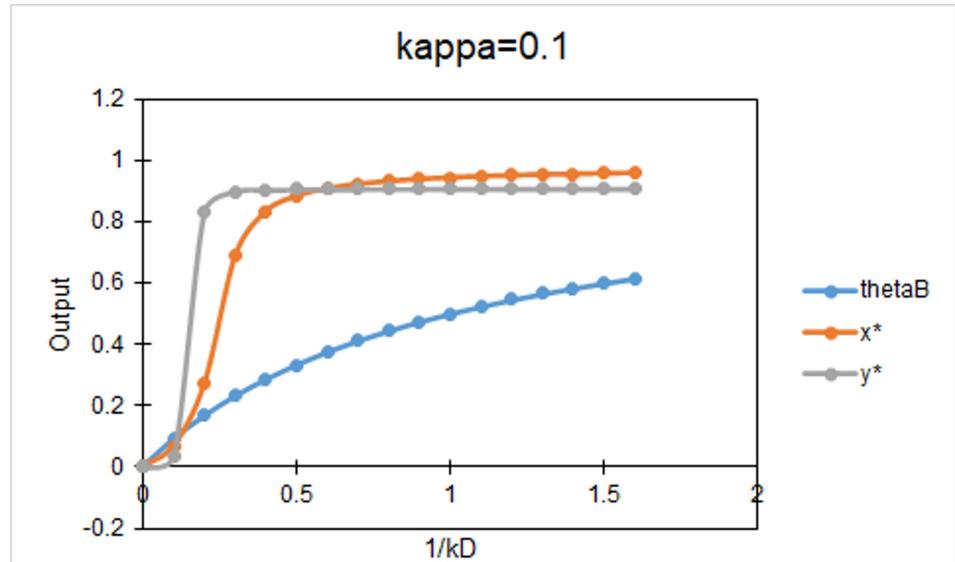
$$\cancel{K_3 Y^* + Y^* - Y^{*2}} = 10 X^* K_4 + 10 X^* Y^* - 10 X^* K_4 Y^* - 10 X^* Y^{*2}$$

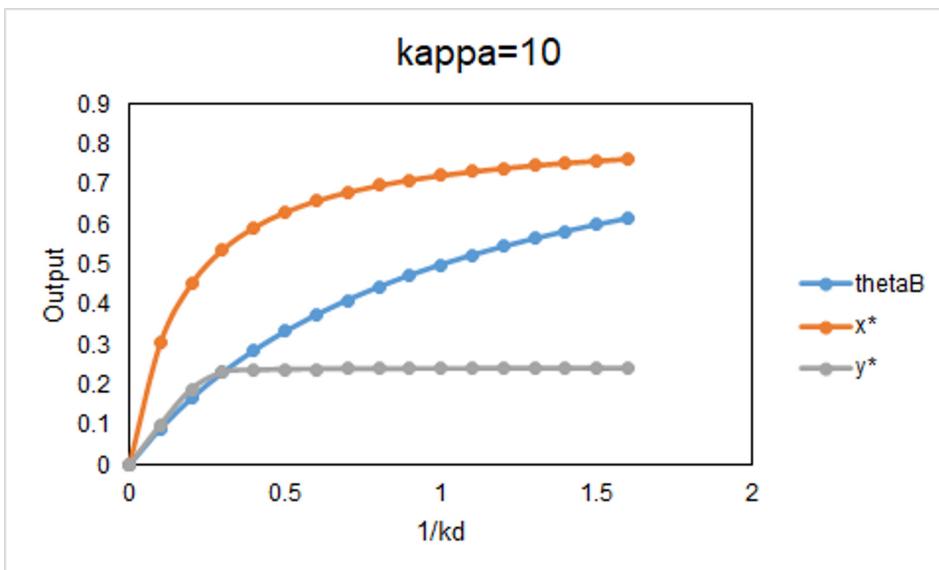
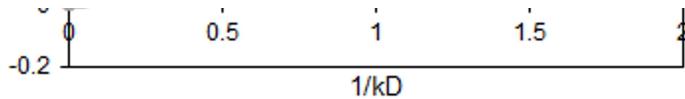
$$(10 X^* - 1) Y^{*2} + [K_3 + 1 - 10 X^* + 10 X^* K_4] Y^* - 10 X^* K_4 = 0$$

↓ Plugged into Wolfram Alpha

$$Y^* = \frac{\sqrt{[K + 10 X^* - 10 X^* + 1]^2 + (10 X^* - 1)(-10 X^* K)} + -K - 10 X^* + 10 X^* - 1}{2(10 X^* - 1)}$$

b)





c)  $\text{output} = \frac{\text{input}^{n_H}}{C_{1/2} + \text{input}^{n_H}}$   $\Rightarrow$  values from plots in part b

For  $\theta_B$ :

	input	output	
$K=1$	0.1	0.090909	$n_H = 1.3$
$K=10$	0.1	0.090909	estimated from graph: $C_{1/2} \approx 0.48$

For  $x^*$ :  $0.1 \quad 0.069616 \quad C_{1/2} \approx 0.25 \quad n_H = 1.7$   
 $0.1 \quad 0.304557 \quad C_{1/2} \approx 0.15 \quad n_H = 1.2$

For  $y^*$ :  $0.1 \quad 0.037617 \quad C_{1/2} \approx 0.12 \quad n_H = 2.3$   
 $0.1 \quad 0.100982 \quad C_{1/2} \approx 0.12 \quad n_H = 1.9$

d)

For  $K=0.1$

$$\theta_B: \% = \frac{0.130435 - 0.090909}{0.090909} = 43\%$$

$$x^*: \% = \frac{0.140502 - 0.069616}{0.069616} = 102\%$$

$$y^*: \% = \frac{0.500836 - 0.037617}{0.037617} = 139\%$$

For  $K=10$

$$\theta_B: 43\%$$

$$x^*: \frac{0.38973 - 0.304557}{0.304557} = 27.97\%$$

$$y^*: \frac{0.148177 - 0.100982}{0.100982} = 44.7\%$$

- e) For  $K=0.1$ , there are large changes in output, and for  $K=10$  the changes are smaller. Your parameters that you choose will be reflective of the system you want.

If  $\dots$  then  $\dots$  will choose a smaller  $K$ . Inversely if  $\dots$  want

- b) For part b), there are large changes in output when  $K$  is in the range or smaller. Your parameters that you choose will be reflective of the system you want. If you want to amplify signal, you'll choose a smaller  $K$ , whereas if you want the latter, you will choose larger  $K$  values.

### Problem 2

a) See attached code

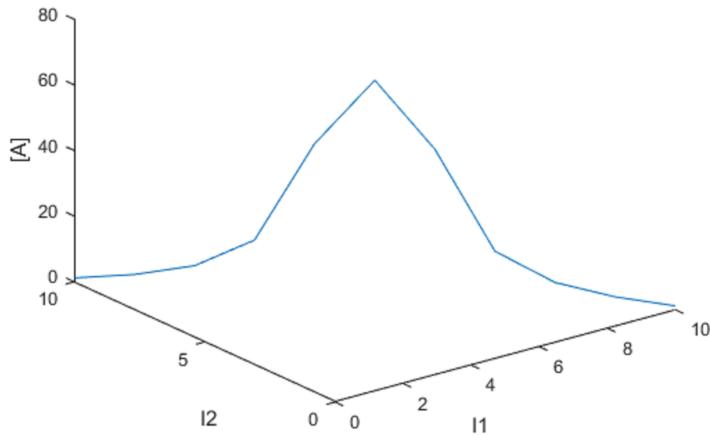
$$[A] = 1.1097$$

$$[B] = 49.4451$$

$$[C] = 49.4451$$

b) See attached code

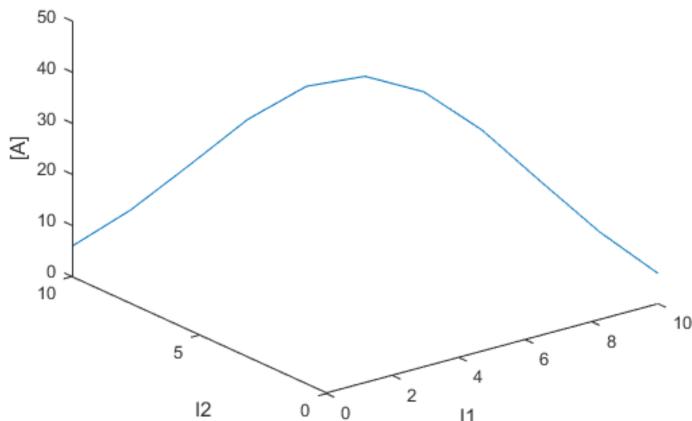
part B 3D plot



c) AND logic gate

d) See attached code

part B 3D plot



This gate is probably called a fuzzy operator because the maximum is reached more gradually rather than abruptly like in part B. It also doesn't reach as high of values, it's more of a hill shape than mountain shape (part B).

- e) In this case, the AND gate allows for quick and large responses when inhibitors are present, so it allows the system to operate at some maximum easily.