

6 January - MATH 345

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• need a program called XPPAUT

• can download onto own machine

• available on computers in lab in LSK

• textbook (optional) by Strogatz

• background reading ch.1 & sections 2.0-2.3

A geometric way of thinking

Flows on the line \mathbb{R} (or an interval)

$$\dot{x} = f(x), \quad x \in \mathbb{R} \quad \left(\dot{x} = \frac{dx}{dt} \right) \quad \begin{array}{l} \text{a continuously differentiable} \\ \text{function of } t \text{ defined on} \\ \text{some open interval} \end{array}$$

• 'Analytic' viewpoint: find solution as an explicit function of t

$$\frac{dx}{dt} = f(x) \rightarrow \frac{dx}{f(x)} = dt \rightarrow \int \frac{dx}{f(x)} = \int dt$$

Example 1.1a

$$\dot{x} = x(1-x) \rightarrow \frac{dx}{x(1-x)} = dt \rightarrow \int \frac{dx}{x(1-x)} = \int dt$$

• integrate using partial fractions method

$$\frac{1}{x(1-x)} = \frac{1}{x} + \frac{1}{1-x}$$

$$\int \frac{dx}{x(1-x)} = \int \frac{dx}{x} + \int \frac{dx}{1-x}$$

$$\int \frac{dx}{x(1-x)} = \ln|x| - \ln|1-x| \quad (+\text{arbitrary constant})$$

$$\int dt = t \quad (+\text{arb. const.})$$

$$\ln|x| - \ln|1-x| = t + \alpha \quad \text{combined constants}$$

• solve for x as a function of t

- solve for x as in previous slide

$$\ln \frac{|x|}{|1-x|} = t + \alpha$$

↑ use log law

$$\left| \frac{x}{1-x} \right| = e^{t+\alpha} = e^{\alpha} e^t$$

- want to get rid of abs. val.

$$\frac{x}{1-x} = \pm e^{\alpha} e^t = C e^t$$

$\pm e^{\alpha}$

- typically there is an initial condition $x_0 = x(0)$

$$\text{for } t=0, e^t = 1 \rightarrow \frac{x_0}{1-x_0} = C$$

- C is solved for, giving x in terms of x_0 .

$$x = x(t) = \frac{x_0}{x_0 + (1-x_0)e^{-t}}$$

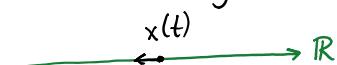
- solution is valid in an open interval of t -values that includes $t=0$

Exercise: what is the open interval?

it depends on initial value x_0 .

- can check solution for $t=0$ (should be x_0)
- 'Geometric' viewpoint: instead of finding $x(t)$ explicitly, get qualitative information about it
- under certain conditions, a unique continuously differentiable solution exists
- the dependent variable (x here) is called the phase variable
- the space that the phase variable belongs to (IR here) is called the phase space
- think of $x(t)$ as the position in phase space of an imaginary particle called a phase point at time t (e.g. a point moving on a line)
- the function $x(t)$ describes the trajectory (or orbit) of the phase point
e.g. if $x(t)$ is a decreasing function of t

theorem on p.27 in
older version of textbook

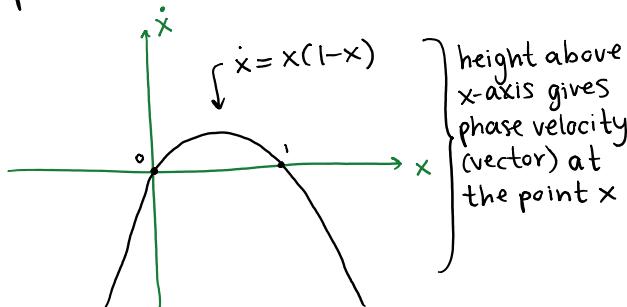


- $\dot{x}(t)$ is the phase velocity of the phase point (it is a vector)
 - f is a vector field: at every point x , it specifies the phase velocity vector
- $$\dot{x}(t) = f(x(t))$$
- the collection of all trajectories $x(t)$ (corresponding to all initial conditions) is called the flow
 - we say f generates a one-dimensional flow in \mathbb{R}
 - the collection of all distinct trajectories is called the phase portrait

Example 1.1b

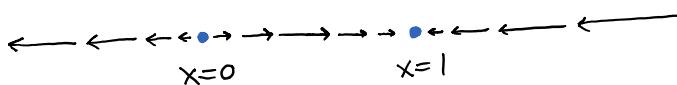
$$\dot{x} = x(1-x), x \in \mathbb{R}$$

- plot \dot{x} vs. x (think of \dot{x} as 'y')



- from the plot,
- | | | |
|------------------|-------------------|---------------------------|
| $\dot{x} < 0$ if | $-\infty < x < 0$ | i.e. $x(t)$ is decreasing |
| $\dot{x} > 0$ if | $0 < x < 1$ | i.e. $x(t)$ is increasing |
| $\dot{x} < 0$ if | $1 < x < \infty$ | i.e. $x(t)$ is decreasing |
| $\dot{x} = 0$ if | $x=0, 1$ | i.e. $x(t)$ is constant |

- sketch of the vector field:



- tells you how fast it's moving & direction
- $\dot{x}=0$ means $x(t)=\text{const}$: an equilibrium solution that stays for all t
- $\dot{x}=0$ if $x=0, 1$ (x-intercept of \dot{x} vs. x plot)

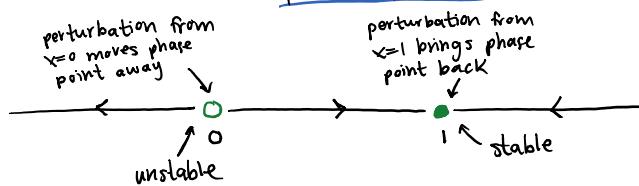
Exercise: $x(t) = \frac{x_0}{x_0 + (1-x_0)e^{-t}}$

substitute $x_0=0, 1$ and check that

$$x(t) = 0, 1$$

- the points $x=0, 1$ are fixed points (in general, solve $f(x)=0$ for x)
- denoted $x^*=0, 1$ using textbook's notation

- sketch of the phase portrait:



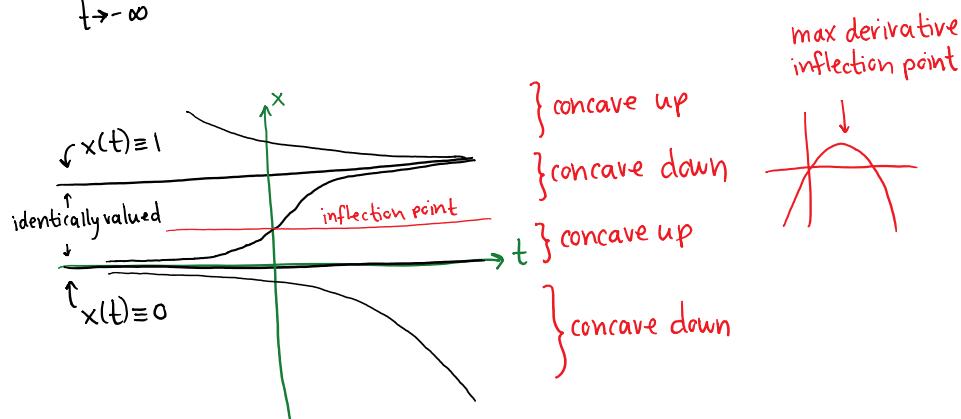
- there are 5 distinct trajectories:

$$(-\infty, 0), \{0\}, (0, 1), \{1\}, (1, \infty)$$

- can deduce shapes of graph $x(t)$ vs. t

$$\lim_{t \rightarrow \infty} x(t) = 1 \text{ if } x_0 > 0$$

$$\lim_{t \rightarrow -\infty} x(t) = 0 \text{ if } x_0 < 1$$

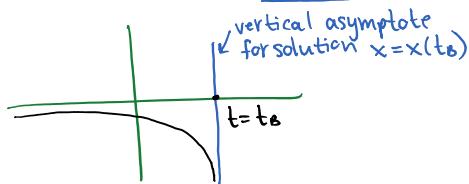


Exercise: confirm asymptotic behaviour as $t \rightarrow \pm \infty$

and graph with explicit solution

$$x(t) = \frac{x_0}{x_0 + (1-x_0)e^{-t}}$$

- one detail the geometric viewpoint misses is that some solutions blow up in finite time

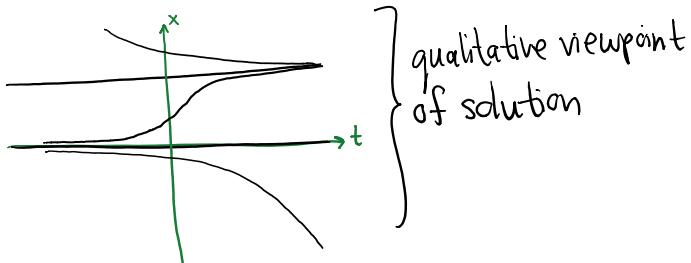
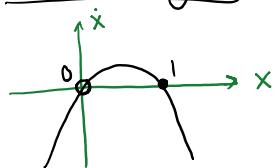


- t_B depends on x_0

Exercise: for what t is solution $x(t)$ defined if

- i) $x_0=0$
- ii) $x_0=1$
- iii) $0 < x_0 < 1$
- iv) $x_0 < 0$
- v) $x_0 > 1$

Summary:



- Sometimes we denote the solution as

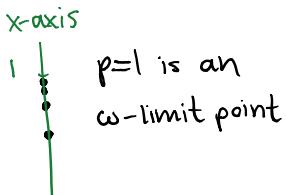
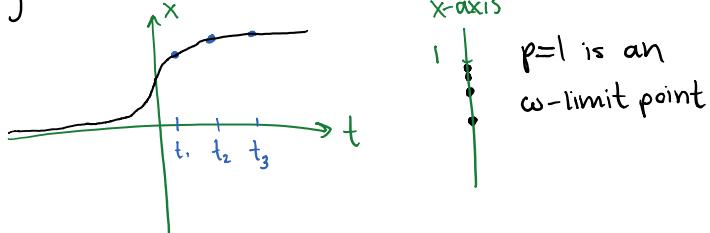
$$x = x(t, x_0) \quad \text{i.e. explicitly include the initial condition as a variable}$$

- if $x(t, x_0)$ is defined and bounded for all $t \in [0, \infty)$

then a point p is an omega limit point (ω -limit point) of x_0 if

$$p = \lim_{k \rightarrow \infty} x(t_k, x_0) \quad \text{for some sequence of times } t_k \rightarrow \infty \text{ as } k \rightarrow \infty$$

e.g. $0 < x_0 < 1$



- α -limit point goes backwards in time