# SCALABLE PROCESSING OF MOVING FLOCK PATTERNS

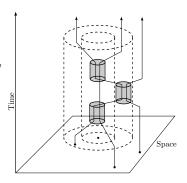
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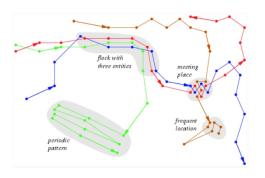
#### LARGE TRAJECTORY DATABASES

- A spatial trajectory is a trace in time generated by a moving entity in a geographical space.
- $\blacksquare$  i.e.  $p_1 \rightarrow p_2 \rightarrow \cdots \rightarrow p_n$
- A trajectory is stored as a set of points,  $p_i = (x, y, t)$  (spatial coordinate + time stamp).



(Shoval, 2017)

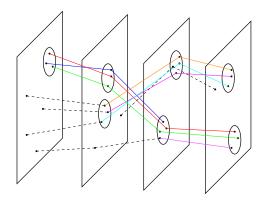
#### MOVEMENT PATTERNS



(Gudmundsson, et al. 2008)

• i.e. convoys, moving clusters, swarms, gatherings, **flocks**, ...

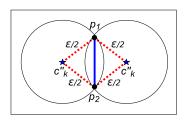
## FLOCKS



- lacksquare arepsilon: Maximum distance between objects.
- $\blacksquare$   $\mu$ : Minimum number of objects.
- $\bullet$   $\delta$ : Minimum time the objects keep 'together'.

#### Basic Flock Evaluation algorithm

- Vieira, et al. 2009.
- The first polynomial-time solution for determining disk locations.
- Under fixed time duration it has polynomial time complexity  $O(\delta|\tau|^{(2\delta)+1})$

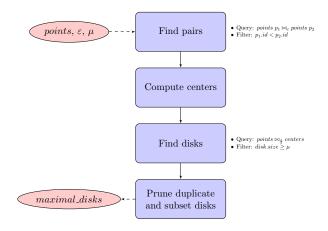


## Basic Flock Evaluation algorithm

- Two main parts:
  - ► In the spatial domain it finds maximal disks at each time stamp.
  - ► In the temporal domain it joins consecutive times to match set of maximal disks.

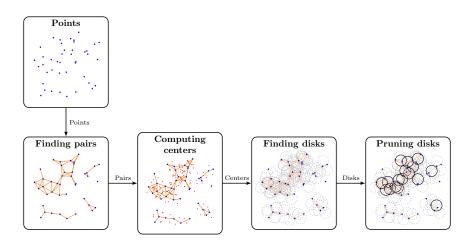
#### ON THE SPATIAL DOMAIN

#### ■ BFE overview...

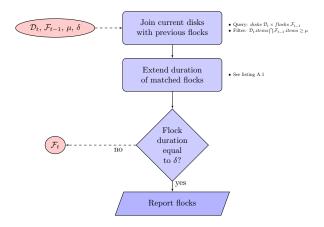


#### ON THE SPATIAL DOMAIN

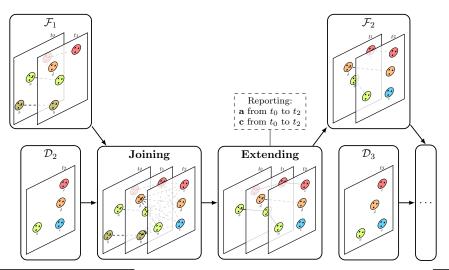
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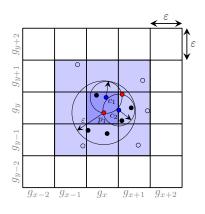
#### ■ BFE overview...

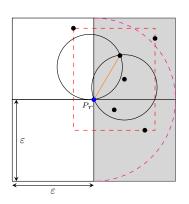


■ BFE overview...



# PSI ALGORITHM





(Vieira, et al. 2009)

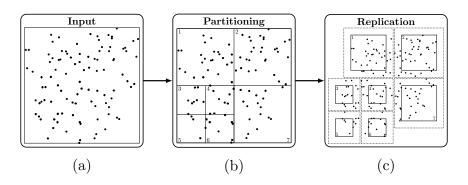
(Tanaka, et al. 2016)

#### CHALLENGES AND CONTRIBUTIONS

- Due to high complexity it does not scale well.
- In databases with a large number of moving entities per time stamp it has a direct impact.
- Just sequential implementation yet.
- We propose a parallel solution in both domains.

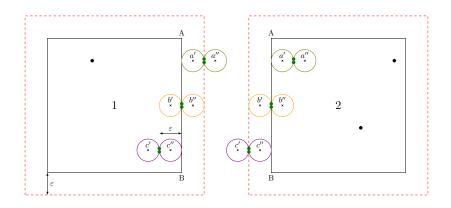
## ON THE SPATIAL DOMAIN

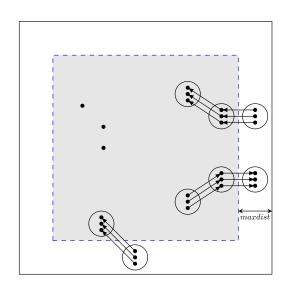
■ Parallel overview...

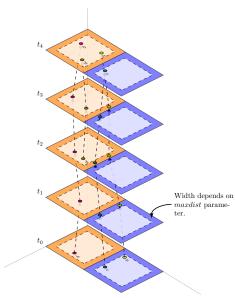


## ON THE SPATIAL DOMAIN

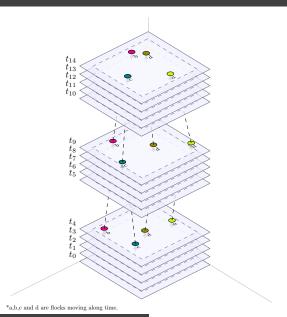
#### ■ Parallel overview...







\*a,b,c and d are flocks moving along time.



# DATASETS

|           | Number of    | Total number | Maximum        |
|-----------|--------------|--------------|----------------|
| Dataset   | Trajectories | of points    | Duration (min) |
| Berlin10K | 10000        | 97526        | 10             |
| LA25K     | 25000        | 1495637      | 30             |
| LA50K     | 50000        | 2993517      | 60             |

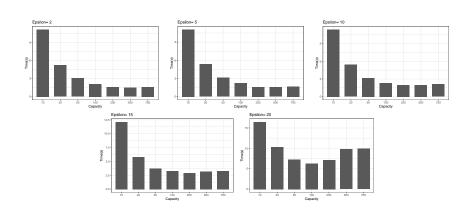
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# DATASETS

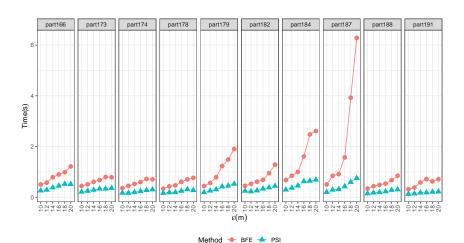
Synthetic dataset [LA: 50K objects]

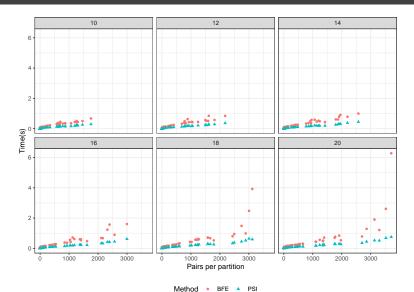


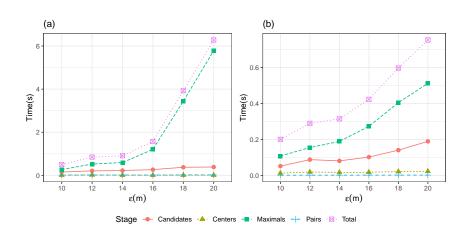
• Optimizing the number of partitions for Phase 1.

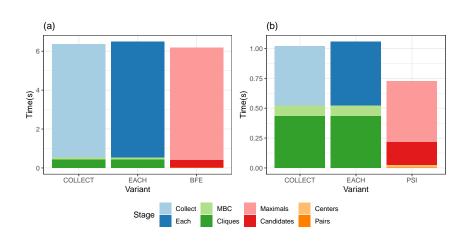


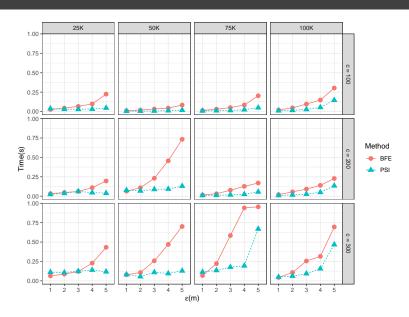
Analyzing most costly partitions.

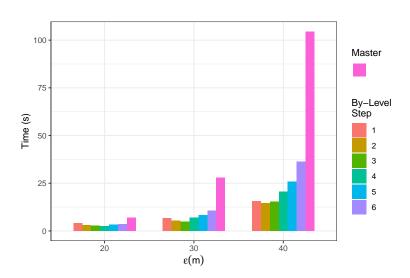


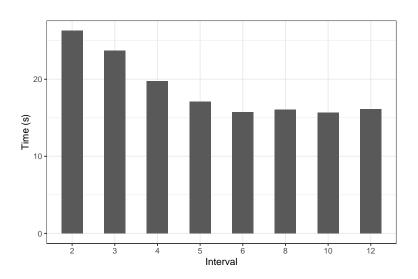


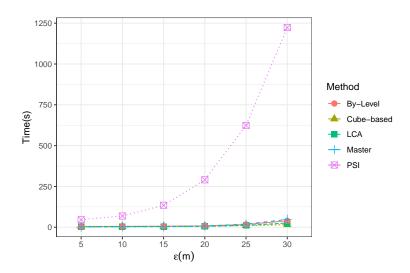


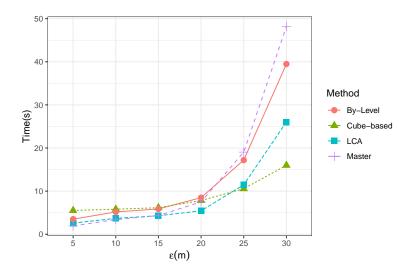


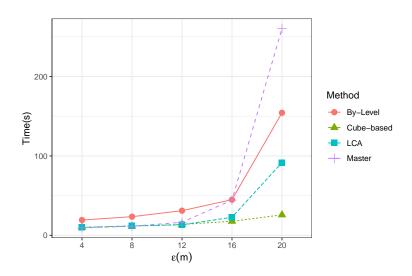












Thank you!