

# Chapter 1

## Introduction

The future upgrade of the Large Hadron Collider (LHC) accelerator, the Super Large Hadron Collider (SLHC), will increase the beam luminosity leading to a corresponding growth of the amount of data to be treated by the data acquisition systems. This will thus require high rate data links and high radiation tolerant Application Specific Integrated Circuits (ASICs).

To address these needs, the Gigabit Transceiver (GBT) architecture and transmission protocol was developed to provide the simultaneous transfer of readout data, timing and trigger signals in addition to slow control and monitoring data.

The GBT system can be described in two parts, where one half of the system consists of radiation hard GBT ASICs that will act as detectors and will thus be located in the radioactive zone. These ASICs will be used to implement bidirectional multipurpose 4.8 Gbit/s optical links for the high-energy physics experiments.

The other half of the system is located in the counting room and consists of a Common Readout Unit (CRU) that will provide an interface between the detector ASICs and an online computerfarm. The CRU consists of Commercial Off-The-Shelf (COTS) components and will through optical links receive data from the radiation detector.

This master thesis will focus on development of control and data flow firmware, development of signal processing firmware and the software interface to a PC.

## 1.1 Field Programmable Gate Array

A Field-Programmable Gate Array (FPGA) is a high density Integrated Circuit (IC) that is designed to be completely programmable by the customer after manufacturing (i.e. when the chip is shipped and "in the field"). The chips are shipped completely "blank", meaning that there are no pre-programmed logic.<sup>1</sup> An FPGA can either be re-programmed using SRAM technology, or one-time programmed by burning antifuses. The latter method makes it less prone to soft errors when exposed to radiation.

FPGAs are composed of arrays of Configurable Logic Blocks (CLBs) surrounded by programmable routing resources and I/O pads. A CLB consists of a LookUp Table (LUT) together with a clock and simple write logic, and uses the address bus of the LUT as the function input pins and the value at the selected address as the function output. LUTs are considered fast logic, since computing a complex function only requires a single memory lookup. The LUT can be made out of an SRAM memory-block [? ].

The FPGA (section 1.1.1) used in this thesis is a re-programmable type. It stores the user hardware setup in an SRAM memory to configure routing and logic functions (for a permanent program storage, the FPGA can be configured to store the hardware setup in the on-board flash memory, which then programs the SRAM when powered on).

### 1.1.1 Cyclone V GT

The Cyclone V GT by Altera is a modern FPGA with many features. It was chosen for this thesis mainly because of the on-board high speed transceivers that is compatible with the GBT-FPGA. Originally, a Terasic Cyclone V GX development board was tested to use with the GBT-Fpga, which in hand offered many more possibilities in terms of communication with the outside world. However, it was discovered that the transceivers were not fast enough for the GBT-FPGA, so it had to be replaced by the more powerful Cyclone V GT fpga development board (see comparison).

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<sup>1</sup>With the exception of FPGA evaluation boards, which comes shipped with a pre-programmed hardware setup for demo purposes.

## 1.2 Hardware Description Language

The most common way to program a FPGA is by Hardware Description Language (HDL), with the major ones being SystemVerilog and VHDL. HDL consists of text-based expressions used to describe digital hardware and use this to further simulate and synthesize the hardware described. A hardware module is simulated by applying information at the inputs and then do a check on the corresponding outputs and verify that they behave as intended. Synthesis of hardware means transforming the HDL code into a netlist of logic and wire connections describing the hardware. HDLs have become more and more useful as system complexity have increased [? ]. The hardware described in this thesis is done using VHDL, a strongly typed HDL that is known for its capability of describing parallel processes.

Below is a small example of logic described using VHDL:

## 1.3 Transceiver Technology

To be able to send serial data in the gigahertz domain, a high-speed transceiver protocol is needed. The Cyclone V GT-series FPGAs supports a number of transceiver protocols that can reach speeds up to 6.144 Gbit/s. This section gives a general description of some of these protocols.

### 1.3.1 Differential Signals

Common for all protocols described under is the fact that the signals are treated differentially.

While a single ended signal involves one conductor between the transmitter and receiver, with the signal swinging from a given voltage to ground, differential signals involves a conductor pair, with two signals that are identical, but with opposite polarity. The pair would ideally have equal path lengths in order to have zero return currents, avoiding problems like *EMI*. In addition, placing the signals as close as possible to one another will give benefits in terms of common noise rejection.

When done correctly, differential signals have advantages over single ended signals such as effective isolation from power systems, minimized crosstalk and noise immunity through common-mode noise rejection. It also improves S/N ratio and effectively doubles the signal level at the output ( $+v - (-v) = 2v$ ), which makes it especially useful in low signal applications. The disadvantage comes in

an increase in pin count and space required, since differential signals consists of two wires instead of one [? ].

### **1.3.2 Low-Voltage Differential Signaling**

Low-Voltage Differential Signaling (LVDS) is said to be the most commonly used differential interface. The interface offers a low power consumption with a voltage swing of 350 mV and good noise immunity. LVDS can deliver data rates up to 3.125 Gbit/s [? ].

### **1.3.3 Current-Mode Logic**

For data rates that exceeds 3.125 Gbit/s, Current-Mode Logic (CML) signaling is preferred. This is due to the fact that certain communication standards such as PCIe, SATA and HDMI, shares consistency with CML in signal amplitude and reference to  $V_{cc}$ . CML can reach a data rate in excess of 10 Gbit/s, but has a higher power consumption than LVDS, with a voltage swing of approximately 800 mV [? ].

### **1.3.4 CPRI**

### **1.3.5 Phase-Locked Loops**

A Phase-Locked Loop (PLL) is a device

# Chapter 2

## The Gigabit Transceiver

History, mgt,  
Short about  
the electronic  
components,  
gbt-sca, gbtx

### 2.1 Encoding modes

The "GBT-Frame" mode, which is Reed-Solomon Based; the "8b10b" mode; and the "Wide-Bus" mode which is without encoding.

### 2.2 GBT-FPGA Core

The following sections describe the different components that makes up the GBT-FPGA Core. The information was obtained by reading the GBT-FPGA User Guide [? ].

#### 2.2.1 GBT Bank

The GBT Bank is defined as the top module of the GBT-FPGA Core. It integrates up to four GBT Links and contains the ports required to operate the GBT Links.

#### 2.2.2 GBT Link

The GBT Link is the actual channel of the link. It is composed of three components: GBT Tx, GBT Rx, and the Multi-Gigabit Transceiver (MGT). The following subsections gives a brief description of these components.

**GBT Tx**

The GBT Tx component is responsible for scrambling and encoding data before transmitting it through the MGT.

**GBT Rx**

The GBT Rx component is responsible for receiving, decoding and de-scrambling the data through the MGT.

**Multi-Gigabit Transceiver**

The MGT is responsible for the transmitting, receiving, serialization and de-serialization of the GBT data. It is divided into a transmitter and a receiver part. The transmitter contains a PISO with two input clocks; one for parallel data and one for serial data. It shifts in 40 bit words from the GBT Tx with a reference clock of 120 MHz, serializes the data and sends it out with the help of a dedicated Tx PLL that generates a serial clock of 2400MHz.

The receiver contains a Clock & Data Recovery (CDR) block, a SIPO, a RXREC-CLK Phase Aligner block and a Barrel-shifter.