

A detailed wireframe model of a particle accelerator. It features a large, roughly oval-shaped main ring with a complex internal structure. Several smaller, circular and semi-circular sections are connected to the main ring, representing different stages or components of the accelerator. The entire structure is rendered in a light gray wireframe style, showing the underlying geometry and layout.

Wrap-up: Numerical Methods in Accelerator Physics

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Learning objectives for lecture series:

- basic models of accelerator physics
- suitable methods for their implementation

Topics covered:

1. **reduced models:** steering, focusing, acceleration
2. **maps** of linear periodic systems + **stability analysis**
3. beam **transport models:** particles, beam distributions (self-consistent modelling)
4. **control-room** applications and **diagnostics:**
 - tune reconstruction
 - tomographic reconstruction of phase space
 - closed-orbit control

- **30 min** oral exam
 - format = conceptual discussion on models of accelerator physics and numerical implementations
 - exam material = Σ summary slides
- ⚠ you do not need to know how to write python code – focus on the **ideas and concepts** we discussed!

- I. basic concepts: lectures 1-3
- II. longitudinal dynamics: lectures 4-6
- III. transverse dynamics: lectures 7-8
- IV. applications: lectures 9-14

I. basic concepts: lectures 1-3

- ⇒ using the simple pendulum as example
- ⇒ time scales in a synchrotron
(transverse / longitudinal motion period, storage times)
- ⇒ phase space (system state), Hamiltonian (equations of motion)
- ⇒ discrete integrators: Euler, Euler-Cromer, leapfrog
- ⇒ statistical moments, emittance
- ⇒ non-linearities, Liouville theorem vs. filamentation (emittance growth)
- ⇒ discrete frequency analysis, NAFF algorithm (vs. FFT)
- ⇒ control of simulation error sources:
 1. discretisation error (symplecticity!)
 2. modelling error
 3. numerical artefacts
 4. (input error)
- ⇒ deterministic chaos,
early indicators: (max.) Lyapunov exponent, frequency map analysis

I. basic concepts: lectures 1-3

II. longitudinal dynamics: lectures 4-6

- Lorentz force, electric longitudinal field E_z to accelerate
- beam rigidity, paraxial approximation
- momentum compaction, phase slippage, transition energy
- phase focusing and stability (classical vs. relativistic regime)
- longitudinal tracking equations (discrete one-turn map)
- synchrotron Hamiltonian, rf bucket
- Monte-Carlo sampling (random number generation)
- equilibrium distributions (thermal PDF),
small-amplitude approximation vs. nonlinear matching
- emittance growth mechanisms (filamentation ↔ bucket non-linearity)
from dipole and quadrupole moment oscillations

- I. basic concepts: **lectures 1-3**
- II. longitudinal dynamics: **lectures 4-6**
- III. transverse dynamics: **lectures 7-8**
 - magnetic fields for bending (steering) and focusing
 - multipole representation, dipole / quadrupole / sextupole magnets
 - Hill differential equation, quasi-harmonic oscillation
 - betatron transport matrices
 - FODO cell, alternate-gradient focusing
 - optics / Twiss functions, β -function as beam envelope, dispersion function
 - stability of periodic transport maps
 - betatron tune, chromaticity

- I. basic concepts: [lectures 1-3](#)
- II. longitudinal dynamics: [lectures 4-6](#)
- III. transverse dynamics: [lectures 7-8](#)
- IV. applications:
 - longitudinal phase-space tomography ([lecture 9](#))
 - Radon transform, sinogram, Fourier Slice Theorem
 - filtered back projection vs. algebraic reconstruction technique
 - closed orbit distortion ([lecture 10](#))
 - local orbit correction (bumps)
 - global orbit correction (orbit response matrix, SVD)
 - machine learning ([lectures 11-12](#))
 - Bayesian optimisation (Gaussian processes, uncertainty modelling)
 - reinforcement learning (discrete vs. continuous state/action spaces, Q-learning & actor-critic methods)
 - self-consistent modelling / collective effects ([lecture 13](#))
 - categories of beam interactions (space charge, ...)
 - longitudinal space charge, line density derivative λ' model
 - microwave instability

**You have gained solid fundamental
knowledge on numerical modelling of
periodic physics + have seen in action some
dynamical examples from accelerator physics!**

... and perhaps became a happy python user.

Well done! :))