

Map-based component separation survey

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Parametric component separation

Broadly speaking, it consists of finding spectral parameters of the foreground components with a pixel-by-pixel optimization procedure.

(ref. [Stompor et. al 2009](#))

We model the data as

$$\mathbf{d}_p = \mathbf{A}_p \mathbf{s}_p + \mathbf{n}_p$$

where $\mathbf{A}_p = \mathbf{A}_p(\beta)$ is the mixing matrix of the form
number of freqs \times number of components.

A log-likelihood can be written as:

$$-2 \log \mathcal{L}_{\text{data}}(\mathbf{s}, \beta) = \text{const} + (\mathbf{d} - \mathbf{A}\mathbf{s})^t \mathbf{N}^{-1} (\mathbf{d} - \mathbf{A}\mathbf{s})$$

The log-likelihood reaches a maximum for the values of (\mathbf{s}, β) fulfilling the relations:

$$-(\partial_{\beta}(\mathbf{A})\mathbf{s})^t \mathbf{N}^{-1}(\mathbf{d} - \mathbf{A}\mathbf{s}) = 0 \quad (1)$$

$$\mathbf{s} = (\mathbf{A}^t \mathbf{N}^{-1} \mathbf{A})^{-1} \mathbf{A}^t \mathbf{N}^{-1} \mathbf{d} \quad (2)$$

We can constrain the spectral parameters by eliminating the sky signals from the full log-likelihood using (1):

$$-2 \log \mathcal{L}_{\text{spec}}(\beta) = \text{const} - (\mathbf{A}^t \mathbf{N}^{-1} \mathbf{d})^t (\mathbf{A}^t \mathbf{N}^{-1} \mathbf{A})^{-1} (\mathbf{A}^t \mathbf{N}^{-1} \mathbf{d}) \quad (3)$$

using it, we can find the maximum value of the likelihood attained for any chosen value of the β .

Finally we uncover the signals \mathbf{s} using (2).

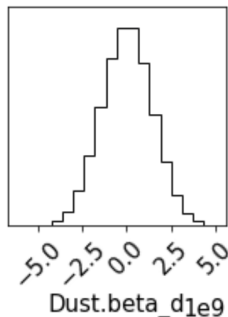
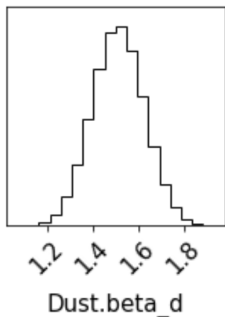
ref: [API](#)

- ▶ Developed by Josquin Errard (from APC) et. al
- ▶ Is a Python module that includes a procedure with the parametric component separation method described above. Also has ILC maybe for future studies.
- ▶ Works fine with partial maps
- ▶ Has a PySM toolbox providing most functionalities

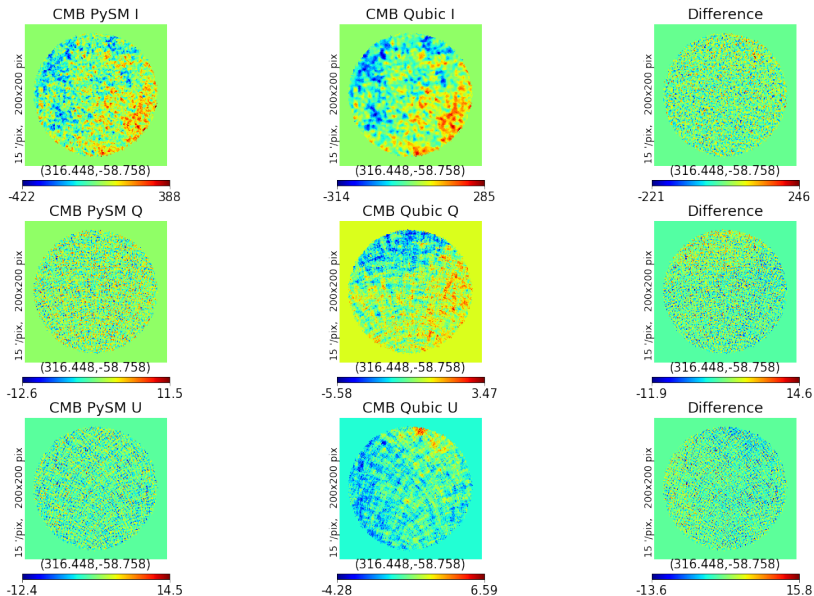
Results

Results for the following

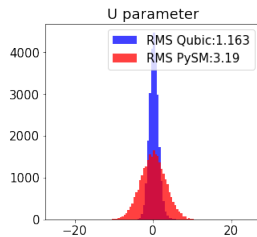
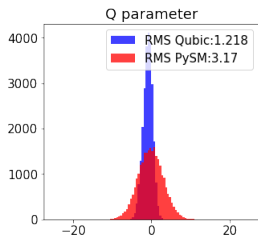
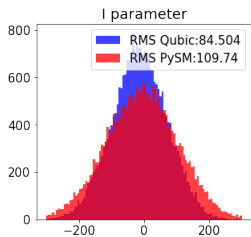
- ▶ 3 bands at 150GHz
- ▶ skyconfig = {'dust': 'd0', 'CMB': 'c1'}
- ▶ qss.get_partial_sky_maps_withnoise(spatial_noise = *False*, nunu_correlation = *False*)



Results



Results

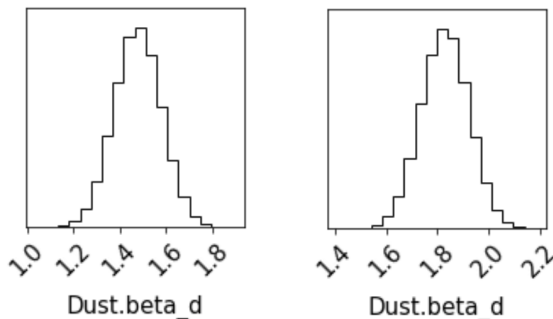


- ▶ $\beta = 1.5$ for PySM maps which is coherent
- ▶ $\beta = 0.437$ for QSS maps, which is problematic, error is huge ($> 1e9$) as well
- ▶ The difference of the CMB maps is non zero

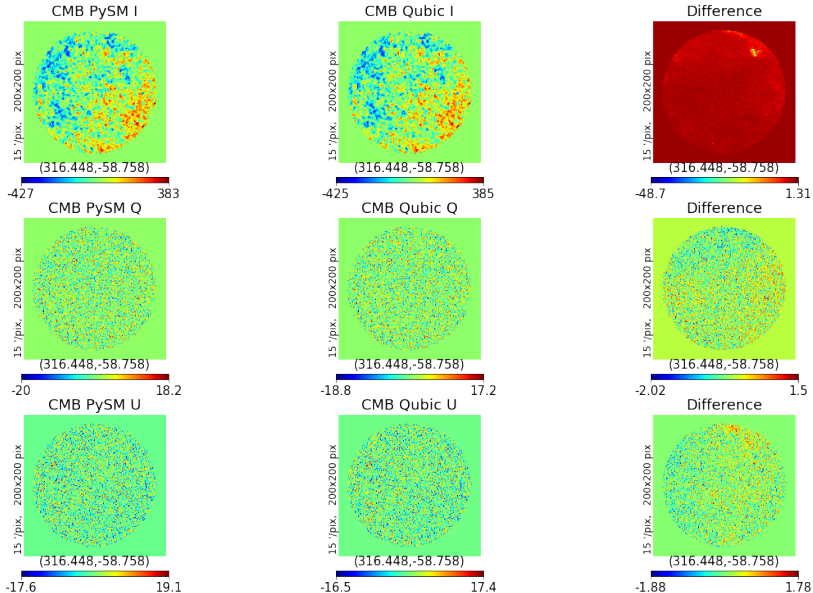
The problem should be related to the noise structure of the Qubic simulated maps...

Results

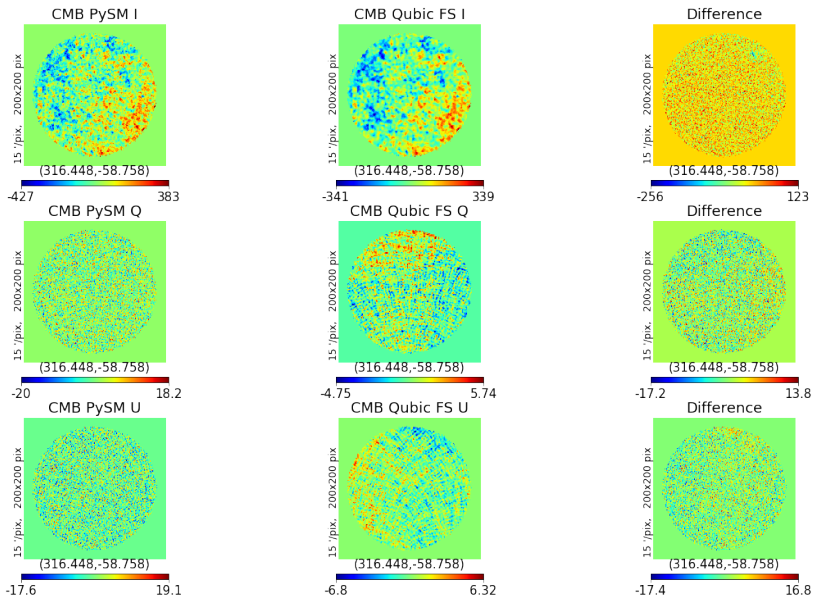
- ▶ 3 bands at 150GHz
- ▶ skyconfig = {'dust':'d0', 'CMB':'c1'}
- ▶ qss.get_partial_sky_maps_withnoise(spatial_noise = *False*, nu_nu_correlation = *False*)
- ▶ White noise and no Qubic noise



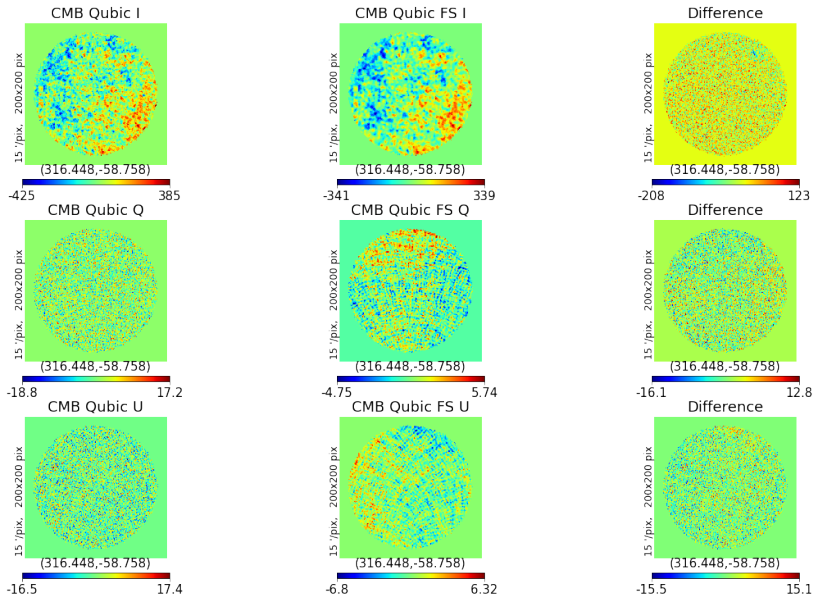
Results



Results



Results



- ▶ $\beta = 1.476$ for PySM maps which is coherent
- ▶ $\beta = 1.827$ for QSS maps, which is okay
- ▶ Some statistics with the white noise realisations are in the making
- ▶ The difference of the CMB maps is non zero and the difference between the FS maps and the results of FGBuster.
- ▶ Maybe apply the procedure to the full pipeline and not to the sky simulator.