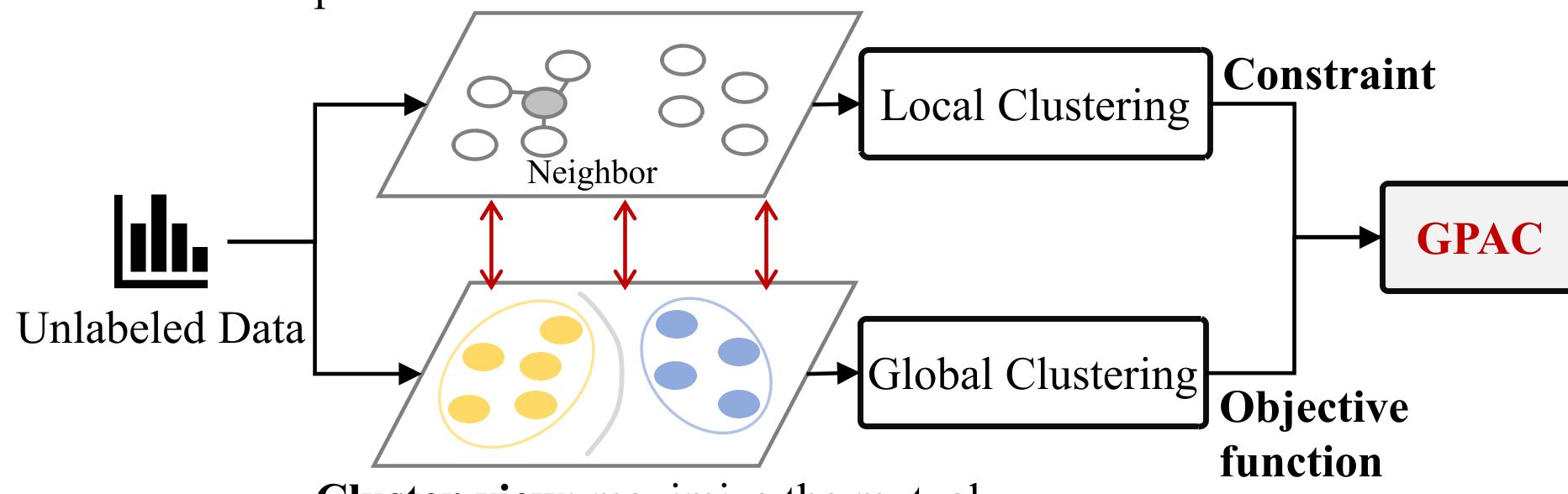
Point-view: keep the consistency of predictions over *k*-NN



Cluster-view: maximize the mutual similarities over clusters