

TOPP-Profile non-holonomic differential drive (deform)

Acceleration

Control

Position

Velocity

Acceleration

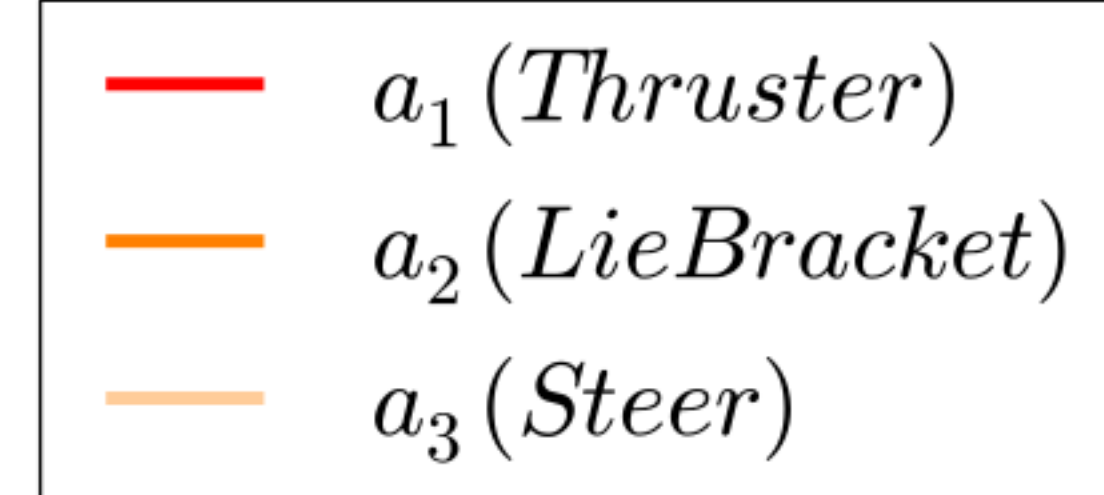
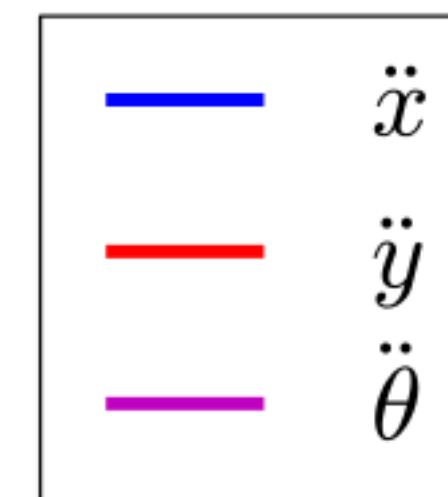
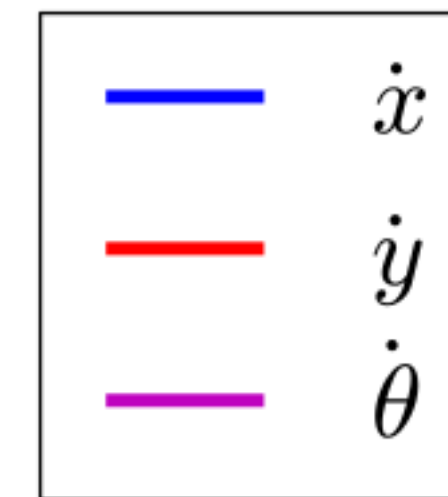
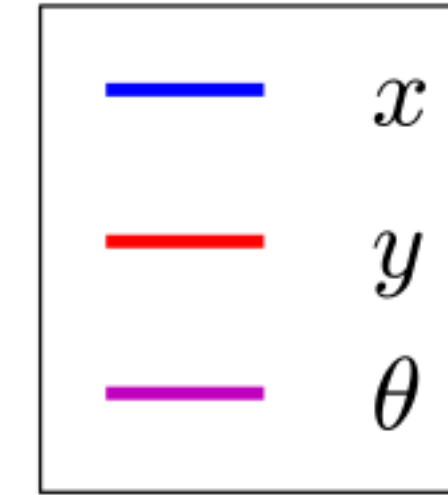
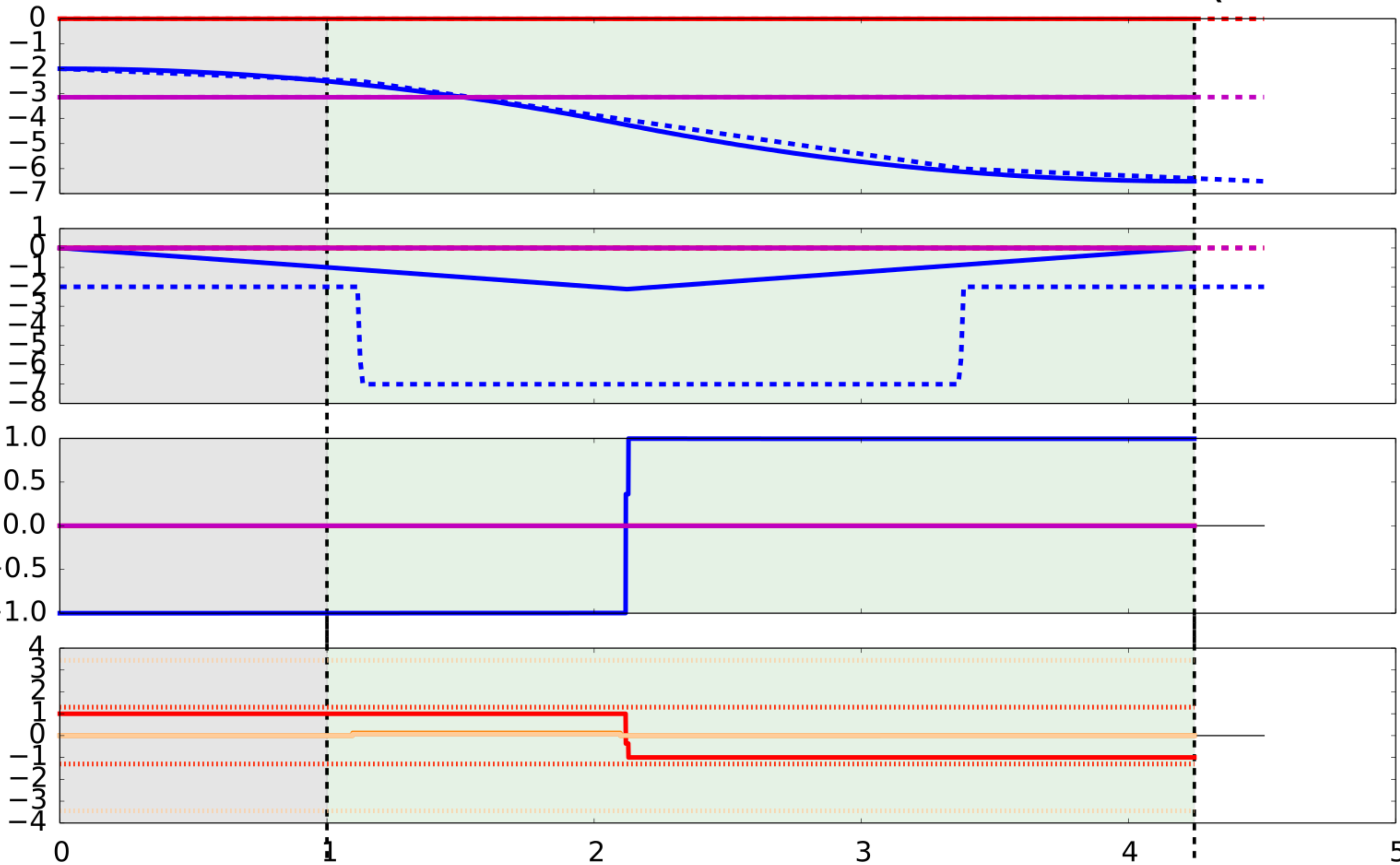
Control

$(m), (rad)$

$(\frac{m}{s}), (\frac{rad}{s})$

$(\frac{m}{s^2}), (\frac{rad}{s^2})$

$(\frac{m}{s^2}), (\frac{rad}{s^2})$



Time (s)