```
2.7
```

2.7.1

U=1+e Linu -- (2.228) t)

Uo=l

U1=1+e. Sinlla

Uz=l+ClinU,

Un+1 = I + e Lin Un ... (2.229)

の近似の精度を調べる

Un=U+En ... (2.230)

宋长(2.229)人代入了3

Ut Enti = Ite Lin (Ut En) ... (2.231)

f(e)= Lin(U+En) x tin(2712-1)/展開 f(e) = Cel(U+En) f(e) = f(o) + f(o) En + O(En2) = Linu+(Celu) En + O(En2)

U+ Enti = I + e Linu + (eadu) En + O (e2) ... (2.232)

Eller

こで、U=l+e Linux 柱辺に代入

It e Linu + Enti = It e Linu + (ecolu) En + O(E2)

Enti = (ecodu) En ... (2.233)

$$A - f(x_0) = f'(x_0)(x - x_0)$$

 $A - f'(x_0)(x - x_0) + f(x_0)$

なっとなるなの値をないとはくと、

$$f'(x_0)(x_1-x_0)+f(x_0)=0$$

$$= \chi_1 = \chi_0 - \frac{f(x_0)}{f'(x_0)}$$

このようたして、順次な、光。…とよれていけば、

$$\chi_{n+1} = \chi_n - \frac{f(\chi_n)}{f'(\chi_n)}$$
 ... (2.234)

根这个第八近似作的誤差をEnytox.

$$\chi_{n} = \chi^{*} + \epsilon_{n} - (2.235)$$

f(x)を x* 周りでライラー展開

$$f(\chi_n) = f(\chi^*) + E_n f'(\chi^*) + \frac{E_n^2}{2} f'(\chi^*) + O(E_n^3) \cdots (2.236)$$

$$= E_n f'(\chi^*) + \frac{E_n^3}{2} f'(\chi^*) + O(E_n^3) \cdots (2.237) \quad (:'f(\chi^*) = 0)$$

$$f(\chi_n) = f(\chi^*) + E_n f'(\chi^*) + O(E_n^3) \cdots (2.237) \quad (:'f(\chi^*) = 0)$$

これい、

(2.235), (2.237), (2.238) を(2.234) 人代入

$$\chi^{*} + \varepsilon_{n+1} = \chi^{*} + \varepsilon_{n} - \frac{\varepsilon_{n} f'(\chi^{*}) + \frac{\varepsilon_{n}^{2}}{2} f''(\chi^{*})}{f'(\chi^{*}) + \varepsilon_{n} f''(\chi^{*})}$$

$$\begin{aligned}
&\text{Entil} = \text{En} - \text{En} \left(1 + \frac{\text{En}}{2} \frac{\text{F''}}{\text{F'}} \right) \left(1 - \text{En} \frac{\text{F''}}{\text{F'}} + O(\text{En}^2) \right) \\
&= \text{En} - \text{En} \left(1 - \text{En} \frac{\text{F''}}{\text{F'}} + \frac{\text{En}}{2} \frac{\text{F''}}{\text{F'}} + O(\text{En}^2) \right) \\
&= \text{En} \left(1 - 1 + \frac{\text{En}}{2} \frac{\text{F''}}{\text{F''}} + O(\text{En}^2) \right) \\
&= \frac{\text{En}^2 \text{F''}}{2 \text{F''}} \quad \dots \quad (2.239)
\end{aligned}$$

ケプラー方程式に(2,239)を適用すると、

$$E_{n+1} = \frac{f''(u^*)}{2f'(u^*)} E_n^2$$

$$= \frac{e \sin u^*}{2(1 - e \cos u^*)} E_n^2 \cdots (2.240)$$