

Two-dimensional linear geometric noise model

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In[1]:= $Assumptions = a ≠ -d & b ≠ 0;

In[2]:= (* System *)
A = {{a, b}, {c, d}}; B = {e, f}; S = {{p, 0}, {r, s}};
F[x_] := -A.(x - B)
G[x_] := DiagonalMatrix[x].S

In[5]:= (* Moment equations *)
expr =
  D[x[t]^i y[t]^j, {{x[t], y[t]}}].F[{x[t], y[t]}] +
  1/2 Tr[G[{x[t], y[t]}]^T.D[x[t]^i y[t]^j, {{x[t], y[t]}, 2}].G[{x[t], y[t]}]];
mex[i_, j_] := Evaluate[Expand[expr] /.
  Flatten[Table[x[t]^(i+p) y[t]^(j+q) → m[i+p, j+q][t], {p, -2, 4}, {q, -2, 4}]]]

In[7]:= meq[i_, j_] := m[i, j]'[t] == FullSimplify[mex[i, j]]

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First order necessarily satisfied equation

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In[8]:= m01sol = Solve[meq[1, 0], m0,1[t]] [[1]] /. m0,0[t] → 1

Out[8]= {m0,1[t] → (a e + b f - a m1,0[t] - m1,0'[t]) / b}

In[9]:= eq1 = FullSimplify[
  MultiplySides[meq[0, 1], b] /. m01sol /. D[m01sol, t] /. m0,0[t] → 1 /. m0,0'[t] → 0]

Out[9]= b c e + (-b c + a d) m1,0[t] + (a + d) m1,0'[t] + m1,0''[t] == a d e

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Second order necessarily satisfied equation

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In[10]:= m02eq = meq[0, 2]

Out[10]= m0,2'[t] == 2 (c e + d f) m0,1[t] + (-2 d + r^2 + s^2) m0,2[t] - 2 c m1,1[t]

In[11]:= (* Solve for one column in terms of the previous *)
solmij[i_, j_] := Solve[meq[i + 1, j - 1], m[i, j][t]] [[1]]
solcolj[j_] := Flatten[Table[solmij[i, j], {i, 0, 5}]]

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In[13]:= (* Substitute recursively *)
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eq2 = FullSimplify[
  m02eq /. solcolj[2] /. D[solcolj[2], t]
    /. solcolj[1] /. D[solcolj[1], t] /. D[solcolj[1], {t, 2}]
    /. m0,0[t] -> 1 /. Table[D[m0,0[t], {t, i}] -> 0, {i, 1, 5}]]];
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ex2 = eq2[[1]] - eq2[[2]]
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Out[14]=
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$$\begin{aligned} & \frac{1}{2b^2} \left(-4b(c e + d f) (a e + b f - a m_{1,0}[t] - m_{1,0}'[t]) + \right. \\ & 2(-2a^2 e + b c e - a d e - 2 a b f + a e p r + b f p r) m_{1,0}'[t] + \\ & 2 b c (2(a e + b f) m_{1,0}[t] + (-2 a + p^2) m_{2,0}[t] - m_{2,0}'[t]) + \\ & (-2 b c + (2 a - p^2) (a + d - p r)) m_{2,0}'[t] - 4 a e m_{1,0}''[t] - \\ & 4 b f m_{1,0}''[t] + 3 a m_{2,0}''[t] + d m_{2,0}''[t] - p^2 m_{2,0}''[t] - p r m_{2,0}''[t] + \\ & (2 d - r^2 - s^2) (2(a e + b f)^2 + 2(-2 a^2 e + b c e - a d e - 2 a b f + a e p r + b f p r) m_{1,0}[t] + \\ & (-2 b c + (2 a - p^2) (a + d - p r)) m_{2,0}[t] - 4(a e + b f) m_{1,0}'[t] + \\ & \left. (3 a + d - p(p + r)) m_{2,0}'[t] + m_{2,0}''[t] \right) + m_{2,0}^{(3)}[t] \end{aligned}$$

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In[15]:= vars = Quiet[Select[Variables[ex2], #[[0]][1] === m || #[[0]][1][1] === m &]]
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Out[15]=
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{m1,0[t], m1,0'[t], m2,0[t], m2,0'[t], m1,0''[t], m2,0''[t], m2,0^(3)[t]}
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In[16]:= FullSimplify[Collect[2 b^2 ex2, vars]]
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Out[16]=
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$$\begin{aligned} & -4 a b e (c e + d f) - 4 b^2 f (c e + d f) + \\ & 2(a e + b f)^2 (2 d - r^2 - s^2) + (4 b c (a e + b f) + 4 a b (c e + d f) + \\ & 2(-2 a^2 e + b c e - a d e - 2 a b f + a e p r + b f p r) (2 d - r^2 - s^2)) m_{1,0}[t] + \\ & (2 b c (-2 a + p^2) + (-2 b c + (2 a - p^2) (a + d - p r)) (2 d - r^2 - s^2)) m_{2,0}[t] + \\ & 2(-2 a^2 e + 3 b c e + a(-5 d e - 2 b f + e r(p + 2 r) + 2 e s^2) + b f(-2 d + p r + 2(r^2 + s^2))) \\ & m_{1,0}'[t] + (-4 b c + (2 a - p^2) (a + d - p r) + (3 a + d - p(p + r)) (2 d - r^2 - s^2)) m_{2,0}'[t] - \\ & 4(a e + b f) m_{1,0}''[t] + (3 a + 3 d - p^2 - p r - r^2 - s^2) m_{2,0}''[t] + m_{2,0}^{(3)}[t] \end{aligned}$$