Capstone Project

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Title: Facial Keypoint Detection

Definition

Project Overview

Face detection is a computer technology being used in a variety of applications that identifies human faces in digital images. Face detection also refers to the psychological process by which humans locate and attend to faces in a visual scene.

Face detection is used in biometrics, often as a part of (or together with) a facial recognition system. It is also used in video surveillance, human computer interface and image database management.

Problem Statement

The objective of this task is to predict keypoint positions on face images. This can be used as a building block in several applications, such as:

- 1. Tracking faces in images and video
- 2. Analysing facial expressions
- 3. Detecting dysmorphic facial signs for medical diagnosis
- 4. Biometrics / face recognition

Detecting facial key-points is a very challenging problem. Facial features vary greatly from one individual to another, and even for a single individual, there is a large amount of variation due to 3D pose, size, position, viewing angle, and illumination conditions. Computer vision research has come a long way in addressing these difficulties, but there remain many opportunities for improvement.

To tackle this problem, I will use three base models:

- 1. A fully connected model
- 2. A Simple CNN
- 3. Using Image Augmentation with a CNN

Metrics

Mean Squared Error (MSE)

MSE =
$$\frac{1}{n} \sum_{i=1}^{n} (Y_i - \hat{Y}_i)^2$$
.

In statistics, the mean squared error (MSE) or mean squared deviation (MSD) of an estimator (of a procedure for estimating an unobserved quantity) measures the average of the squares of the errors—that is, the average squared difference between the estimated values and what is estimated. MSE is a risk function, corresponding to the expected value of the squared error loss. The fact that MSE is almost always strictly positive (and not zero) is because of randomness or because the estimator does not account for information that could produce a more accurate estimate.[1]

The MSE is a measure of the quality of an estimator—it is always non-negative, and values closer to zero are better.

Analysis

Data Exploration

The Dataset is collected from kaggle.

Each predicted keypoint is specified by an (x,y) real-valued pair in the space of pixel indices. There are 15 keypoints, which represent the following elements of the face:

left_eye_center, right_eye_center, left_eye_inner_corner, left_eye_outer_corner, right_eye_inner_corner, right_eye_outer_corner, left_eyebrow_inner_end, left_eyebrow_outer_end, right_eyebrow_outer_end, nose_tip, mouth_left_corner, mouth_right_corner, mouth_center_top_lip, mouth_center_bottom_lip

Left and right here refers to the point of view of the subject.

In some examples, some of the target keypoint positions are missing (encoded as missing entries in the csv, i.e., with nothing between two commas).

The input image is given in the last field of the data files, and consists of a list of pixels (ordered by row), as integers in (0,255). The images are 96x96 pixels.

Data files

training.csv: list of training 7049 images. Each row contains the (x,y) coordinates for 15 keypoints, and image data as row-ordered list of pixels.

test.csv: list of 1783 test images. Each row contains ImageId and image data as row-ordered list of pixels **submissionFileFormat.csv**: list of 27124 keypoints to predict. Each row contains a RowId, ImageId, FeatureName, Location. FeatureName are "left_eye_center_x," "right_eyebrow_outer_end_y," etc.

Exploratory Visualization

Location is what you need to predict.

The Dataset looks like this:

```
index
                                 0
0
           left_eye_center_x 7039
1
           left_eye_center_y 7039
2
          right_eye_center_x 7036
3
          right_eye_center_y 7036
4
     left_eye_inner_corner_x 2271
5
     left_eye_inner_corner_y 2271
6
     left_eye_outer_corner_x 2267
7
     left_eye_outer_corner_y 2267
8
    right_eye_inner_corner_x 2268
9
    right_eye_inner_corner_y 2268
10
    right_eye_outer_corner_x 2268
11
    right_eye_outer_corner_y 2268
12
    left_eyebrow_inner_end_x 2270
13
    left_eyebrow_inner_end_y 2270
14
    left_eyebrow_outer_end_x 2225
15
    left_eyebrow_outer_end_y 2225
16
   right_eyebrow_inner_end_x 2270
    right_eyebrow_inner_end_y 2270
17
   right_eyebrow_outer_end_x 2236
18
   right_eyebrow_outer_end_y 2236
19
20
                  nose_tip_x 7049
21
                  nose_tip_y 7049
22
         mouth_left_corner_x 2269
23
         mouth_left_corner_y 2269
24
        mouth_right_corner_x 2270
25
        mouth_right_corner_y 2270
26
       mouth_center_top_lip_x 2275
27
       mouth_center_top_lip_y
                              2275
28
   mouth_center_bottom_lip_x 7016
29
   mouth_center_bottom_lip_y 7016
30
                       Image 7049
```

This dataset has missing values so I will train my base models on 20% of the dataset and the rest I will use afterwards.

I have explained this process in detail in the data preprocessing section.

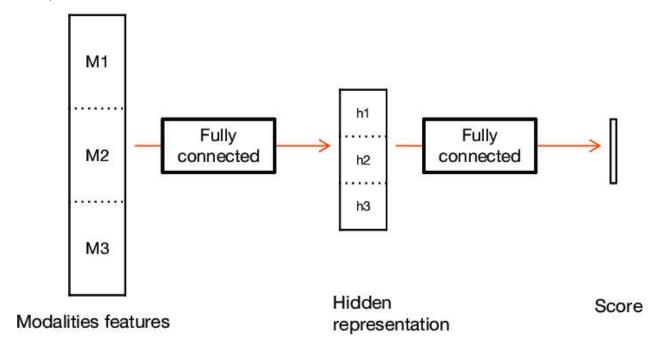
Algorithms and Techniques

For this problem, I will basically use 3 different techniques:

Fully connected model:

In this, I will use a Sequential model with 3 different layers followed by an activation function "**Relu**", and I will also add a dropout after the first layer. I have used SGD optimizer for this using 50 epochs and a batch size of 128.

A fully connected model looks like this:



A Simple CNN:

In this, I will use a Sequential model with 3 different Conv2D layers each having a max pooling layer having a pool size and stride of 2*2. Each layer I have also added batch normalization and dropouts to avoid overfitting. At the end, I have also added 3 fully connected layers with dropouts.

In this, I have used adam optimizer having epochs set to 200 and a batch size of 128.

A CNN model looks like this:

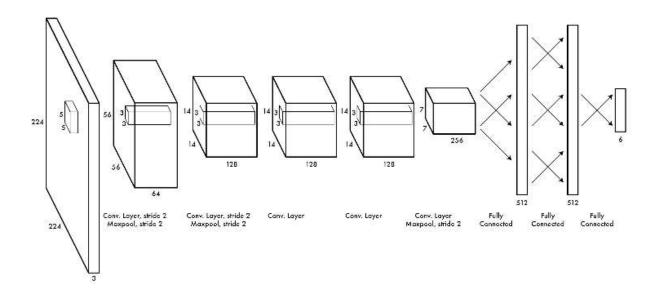


Image Augmentation:

In this, I have used the Flipping Technique to flip the images but used the same model architecture as the previous model. The number of epochs being 200.

Benchmark

I have created 3 benchmark models for this problem:

A fully connected model:

```
%%time
from keras.models import Sequential
from keras.layers import Dense, Activation
from keras.optimizers import SGD
from keras.layers import Dropout

model = Sequential()
model.add(Dense(128,input_dim=X.shape[1]))
model.add(Activation('relu'))
model.add(Dropout(0.1))
model.add(Dense(64))
model.add(Dense(64))
model.add(Dense(30))
```

```
sgd = SGD(lr=0.01, momentum=0.9, nesterov=True)
model.compile(loss='mean_squared_error', optimizer=sgd)
hist = model.fit(X, y, nb_epoch=50,batch_size=128, validation_split=0.2,verbose=False)
```

A Simple CNN:

```
def CNN():
    model2 = Sequential()
    model2.add(Conv2D(filters=16,kernel_size=2,padding="same",activation="relu",input_shape
=(96,96,1)))
   model2.add(Dropout(0.1))
    model2.add(MaxPooling2D(pool_size=(2, 2), strides=(2, 2), border_mode="valid"))
    model2.add(BatchNormalization())
    model2.add(Conv2D(32, 5, 5,activation="relu"))
    # model.add(Activation("relu"))
    model2.add(MaxPooling2D(pool_size=(2, 2), strides=(2, 2), border_mode="valid"))
    model2.add(Dropout(0.2))
    model2.add(BatchNormalization())
    model2.add(Conv2D(64, 5, 5, activation="relu"))
    # model.add(Activation("relu"))
    model2.add(MaxPooling2D(pool_size=(2, 2), strides=(2, 2), border_mode="valid"))
    model2.add(BatchNormalization())
    model2.add(Conv2D(128, 3, 3,activation="relu"))
    # model.add(Activation("relu"))
    model2.add(MaxPooling2D(pool_size=(2, 2), strides=(2, 2), border_mode="valid"))
    model2.add(Dropout(0.4))
    model2.add(BatchNormalization())
```

```
model2 = CNN()
hist2 = model2.fit(X, y, nb_epoch=500,batch_size=128, validation_split=0.2,verbose=False)
```

A Simple CNN after Flipping the Images:

Methodology

Data Preprocessing

By looking at this dataset we can see that there are many missing values.

```
index
                                 0
0
           left_eye_center_x 7039
1
           left_eye_center_y 7039
2
           right_eye_center_x 7036
3
           right_eye_center_y 7036
4
     left_eye_inner_corner_x 2271
5
     left_eye_inner_corner_y 2271
6
     left_eye_outer_corner_x 2267
7
     left_eye_outer_corner_y 2267
8
    right_eye_inner_corner_x 2268
9
    right_eye_inner_corner_y 2268
10
    right_eye_outer_corner_x 2268
11
    right_eye_outer_corner_y 2268
12
    left_eyebrow_inner_end_x 2270
13
    left_eyebrow_inner_end_y 2270
14
    left_eyebrow_outer_end_x 2225
15
    left_eyebrow_outer_end_y 2225
   right_eyebrow_inner_end_x 2270
16
17
   right_eyebrow_inner_end_y 2270
18
   right_eyebrow_outer_end_x 2236
   right_eyebrow_outer_end_y 2236
19
20
                  nose_tip_x 7049
21
                  nose_tip_y 7049
22
         mouth_left_corner_x 2269
23
         mouth_left_corner_v 2269
24
        mouth_right_corner_x 2270
25
        mouth_right_corner_y 2270
26
      mouth_center_top_lip_x 2275
       mouth_center_top_lip_y 2275
27
28
   mouth_center_bottom_lip_x 7016
   mouth_center_bottom_lip_y 7016
29
30
                       Image 7049
```

So I used only 20% of the dataset which doesn't have any missing values.

I will use this 20% to create my base model and after that use the entire dataset for training.

```
dtype: int64
X.shape == (2140, 9216); X.min == 0.000; X.max == 1.000
y.shape == (2140, 30); y.min == -0.920; y.max == 0.996
```

From the above figure I can see that there are 2140 samples and for X: 9216 columns [96*96] and for y: 30 columns [x and y co-ordinates each having 15 keypoints].

```
df = df.dropna() # drop all rows that have missing values in them
```

After this we are left with only 2140 samples.

After creating my base models, I divided the 15 Landmarks into 6 different groups as shown below:

```
SPECIALIST_SETTINGS = [
    dict(
        columns=(
            'left_eye_center_x', 'left_eye_center_y',
            'right_eye_center_x', 'right_eye_center_y',
            ),
        flip_indices=((0, 2), (1, 3)),
       ),
    dict(
        columns=(
            'nose_tip_x', 'nose_tip_y',
            ),
        flip_indices=(),
        ),
    dict(
        columns=(
            'mouth_left_corner_x', 'mouth_left_corner_y',
            'mouth_right_corner_x', 'mouth_right_corner_y',
            'mouth_center_top_lip_x', 'mouth_center_top_lip_y',
            ),
        flip_indices=((0, 2), (1, 3)),
```

```
dict(
    columns=(
        'mouth_center_bottom_lip_x',
        'mouth_center_bottom_lip_y',
        ),
    flip_indices=(),
    ),
dict(
    columns=(
        'left_eye_inner_corner_x', 'left_eye_inner_corner_y',
        'right_eye_inner_corner_x', 'right_eye_inner_corner_y',
        'left_eye_outer_corner_x', 'left_eye_outer_corner_y',
        'right_eye_outer_corner_x', 'right_eye_outer_corner_y',
    flip_indices=((0, 2), (1, 3), (4, 6), (5, 7)),
    ),
dict(
    columns=(
        'left_eyebrow_inner_end_x', 'left_eyebrow_inner_end_y',
        'right_eyebrow_inner_end_x', 'right_eyebrow_inner_end_y',
        'left_eyebrow_outer_end_x', 'left_eyebrow_outer_end_y',
        'right_eyebrow_outer_end_x', 'right_eyebrow_outer_end_y',
        ),
    flip_indices=((0, 2), (1, 3), (4, 6), (5, 7)),
```

I will train my model on each of these 6 groups separately.

All 6 models contains the same CNN architecture but the final output layer is adjusted for different number of outputs: for example we have a model for left eye and right eye center landmark prediction. As there are x and y coordinates for both eye centers, we have 4 nodes in the output layer of this model.

Implementation

As stated earlier I have created 3 base models with 20% of the dataset.

After that as explained in the Data Preprocessing section, I created a specialist list containing the rest of the dataset and trained model2 and model3 using the same.

With model3:

With model2:

Refinement

I experimented with my models quite a bit.

I increased the number of epochs from 200 to 500 for my base model2 and it subsequently made my special model2 models performance better.

I also increased the number of epochs from 200 to 300 for my base model3 but it made my special model3 performance worse.

Results

Model Evaluation and Validation

The final model ie, Special model2 was derived from the base model2 which I made using 20% of the dataset.

As stated in the previous section I experimented with the base model's by increasing its epochs from 200 to 500 and the performance was slightly better than the previous one.

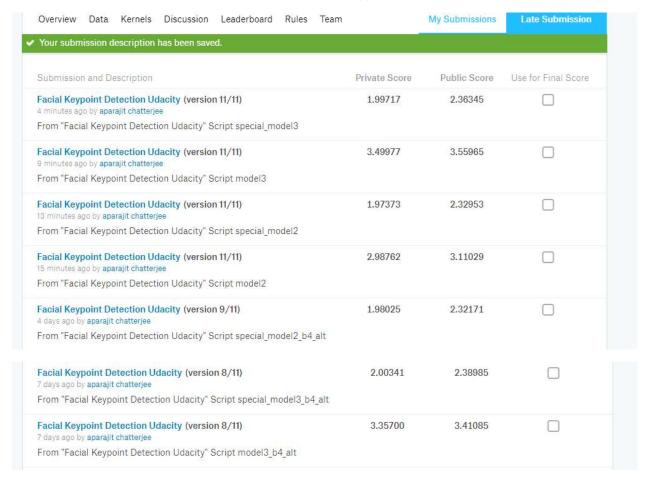
Note: Please check the justification section.

This model's performance after tuning it can be trusted.

Justification

The final model's result is stronger than the base model's result.

To prove my point I am attaching my submissions from Kaggle:



Conclusion

Free Form Visualization

These two images shows the final models performance in comparison to its base model.

[&]quot;best" - The two model results agree the most.

[&]quot;worst" - The two model results disagree the most.

Good:model2:pic80



Good:model2:pic20



Good:model2:pic88



Good:model2:pic92



Good:special:pic80



Good:special:pic20



Good:special:pic88



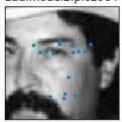
Good:special:pic92



Bad:model2:pic1116



Bad:model2:pic1064



Bad:model2:pic524



Bad:model2:pic1206



Bad:special:pic1116



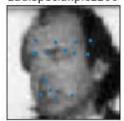
Bad:special:pic1064



Bad:special:pic524



Bad:special:pic1206





Reflection

The following steps were taken to complete this process:

- 1. Downloaded the dataset from kaggle.
- 2. Scaled the pixel values.
- 3. Used 20% of the dataset to train the base models.
- 4. Created special models by dividing the dataset into 6 different groups and trained the base models separately on them.
- 5. Converted the files to csv and compared their scores on kaggle.

As this was the second time apart from dog breed classifier I dealt with image classification problem, I have learned a lot from this project. The most challenging part was to create the third base model I tried using the Keras image flipping inbuilt technique but to flip the keypoints I had to flip them manually.

Improvement

There are a few ways in which I can suggest some improvements:

- 1. Tuning/Experimenting with the number of epochs.
- 2. Using different optimizers.
- 3. Tuning/Experimenting with batch size.
- 4. Using different image augmentation techniques such as shifting, scaling etc.

One technique I would I like to use in particular is OpenCV but I am not too much familiar with it.