

```

from google.colab import drive
drive.mount('/content/gdrive/')
%cd /content/gdrive/MyDrive/Machine Learning/LAB 3
!ls

```

```

Mounted at /content/gdrive/
/content/gdrive/MyDrive/Machine Learning/LAB 3
'Copy of ML.LS.3.19033.ipynb'  ML.PROJECT.ROUGH.ipynb  TrainCharacters
ML.LS.3.19033.ipynb          TestCharacters

```

```

def gauss(x,m,c):
    w_1 = -0.5*(math.log(np.linalg.det(c),np.e))
    d=x.shape[0]
    u=x-m
    w1=np.linalg.inv(c)
    w_1_1 = -0.5*np.matmul(u.transpose(),np.matmul(w1,u))
    w_1_0 = -0.5*d*math.log(2*np.pi,np.e) + math.log(1/3.0,np.e)
    g = w_1+w_1_0+w_1_1
    return (g[0][0])

```

```

from google.colab.patches import cv2_imshow
import matplotlib.pyplot as plt
import matplotlib.image as mpimg
import glob

```

```

import math
import numpy as np
import cv2
from matplotlib import pyplot as plt

```

```

xi_max=255.0
lamda=0.5
I=np.identity(1024)

```

```

path1="/content/gdrive/MyDrive/Machine Learning/LAB 3/TrainCharacters/TrainCharacters/1/*.jpg"
path2="/content/gdrive/MyDrive/Machine Learning/LAB 3/TrainCharacters/TrainCharacters/2/*.jpg"

```

```

#x1=np.array([])
#x2=np.array([])
#A=np.array([])
s1 = np.zeros((1024,1024))
s2 = np.zeros((1024,1024))

```

```

Mu1=np.zeros((1024,1))
for i in glob.glob(path1):
    read_image1=cv2.imread(i,0)
    image_resize1=cv2.resize(read_image1,(32,32))
    reshaped1=np.reshape(image_resize1,(1024,1))
    norm1=reshaped1/xi_max
    #x1=np.append(x1,norm1)
    #A=np.append(A,norm1)
    Mu1=Mu1+norm1

```

```

Mu1=Mu1/(1024)

```

```

Mu1=Mu1/(200)
print(Mu1.shape)
for i in glob.glob(path1):
    read_image1=cv2.imread(i,0)
    image_resize1=cv2.resize(read_image1,(32,32))
    reshaped1=np.reshape(image_resize1,(1024,1))
    norm1=reshaped1/xi_max
    s1+=np.dot((norm1-Mu1),((norm1-Mu1).T))
s1=s1+lamda*I

Mu2=np.zeros((1024,1))
for i in glob.glob(path2):
    read_image2=cv2.imread(i,0)
    image_resize2=cv2.resize(read_image2,(32,32))
    reshaped2=np.reshape(image_resize2,(1024,1))
    norm2=(reshaped2/xi_max)
    #x2=np.append(x2,norm2)
    #A=np.append(A,norm2)
    Mu2=Mu2+norm2
Mu2=Mu2/(200)
print(Mu2.shape)

for i in glob.glob(path2):
    read_image2=cv2.imread(i,0)
    image_resize2=cv2.resize(read_image2,(32,32))
    reshaped2=np.reshape(image_resize2,(1024,1))
    norm2=(reshaped2/xi_max)
    s2 += np.dot((norm2-Mu2),((norm2-Mu2).T))
s2=s2+lamda*I

(1024, 1)
(1024, 1)

S_W = s1+s2
#print(S_W,S_W.shape)
S_B= np.dot((Mu1-Mu2),((Mu1-Mu2).T))
#print(S_B,S_B.shape)
S_Winv = np.linalg.inv(S_W)
Y= np.dot(S_Winv,S_B)
(Y,Y.shape)

(array([[0., 0., 0., ..., 0., 0., 0.],
       [0., 0., 0., ..., 0., 0., 0.],
       [0., 0., 0., ..., 0., 0., 0.],
       ...,
       [0., 0., 0., ..., 0., 0., 0.],
       [0., 0., 0., ..., 0., 0., 0.],
       [0., 0., 0., ..., 0., 0., 0.] ]), (1024, 1024))

w,v=np.linalg.eig(Y)
#print(w)
#print(v)
v=v.real
#w=w.real
index = w.argsort()[::-1]

```

```

w=w[index]
v=v[:,index]

lek1=[]
lek2=[]
val=255.0
for N in range(1,200,5):
    I=np.identity(N)
    project_array2=np.array([])
    project_array1=np.array([])
    for j in glob.glob(path1):
        read_image=cv2.imread(j,0)
        image_resize=cv2.resize(read_image,(32,32))
        norm=np.divide(image_resize,xi_max)
        x3=np.reshape(norm,(1024,1))
        z3=x3-Mu1
        for i in range(N):
            projection1=np.dot((v[:,i]).T,z3)
            project_array1=np.append(project_array1,projection1)
    project_array1=np.reshape(project_array1,(200,N))
    project_array1=project_array1.T
    Mu3=np.sum(project_array1,axis=1)
    mean1=np.reshape(Mu3,(N,1))
    for j in glob.glob(path2):
        read_image=cv2.imread(j,0)
        image_resize=cv2.resize(read_image,(32,32))
        norm=np.divide(image_resize,xi_max)
        x4=np.reshape(norm,(1024,1))
        z4=x4-Mu2
        for i in range(N):
            projection2=np.dot((v[:,i]).T,z4)
            project_array2=np.append(project_array2,projection2)
    project_array2=np.reshape(project_array2,(200,N))
    project_array2=project_array2.T
    Mu4=np.sum(project_array2,axis=1)
    mean2=np.reshape(Mu4,(N,1))
    Mu_pooled=(Mu3+Mu4)/400
    Mu_pooled=np.array(Mu_pooled)
    #s3=np.zeros((N,N))
    s3=0
    for i in range(200):
        s=project_array1[:,i]-Mu_pooled
        s3=s3+np.dot(s,s.T)
    for i in range(200):
        s=project_array2[:,i]-Mu_pooled
        s3=s3+np.dot(s,s.T)
    s3=s3/400
    s3=s3+lamda*I
    path3="/content/gdrive/MyDrive/Machine Learning/LAB 3/TestCharacters/TestCharacters/1/*.jpg"
    path4="/content/gdrive/MyDrive/Machine Learning/LAB 3/TestCharacters/TestCharacters/2/*.jpg"

    index1=0
    index2=0

    cnt1=0
    cnt2=0

    l1=[]

```

```

l2=[]

actual_label1=[]
actual_label2=[]

predicted_class_label1=[]
predicted_class_label2=[]

new_array1=np.zeros(100)
new_array2=np.zeros(100)

for j in glob.glob(path3):
    read_image=cv2.imread(j,0)
    image_resize=cv2.resize(read_image,(32,32))
    norm=np.divide(image_resize,xi_max)
    x4=np.reshape(norm,(1024,1))
    z5=x4-Mu1
    project_array3=np.array([])
    for i in range(N):
        projection3=np.dot((v[:,i]).T,z5)
        project_array3=np.append(project_array3,projection3)
    arr1=[0,0]
    arr1[0]=gauss(project_array3,mean1,s3)
    arr1[1]=gauss(project_array3,mean2,s3)
    max1=max(arr1)
    for i in range(2):
        if (max1==arr1[i]):
            new_array1[index1]=i+1
            if (new_array1[index1]==1):
                cnt1=cnt1+1
            else:
                l1.append(j)
                actual_label1.append(1)
                predicted_class_label1.append(i+1)
        index1=index1+1
#print("Accuracy1=",cnt1)
lek1.append(cnt1)
for j in glob.glob(path4):
    read_image=cv2.imread(j,0)
    image_resize=cv2.resize(read_image,(32,32))
    norm=np.divide(image_resize,val)
    x7=np.reshape(norm,(1024,1))
    z7=x7-Mu2
    project_array6=np.array([])
    for k in range(N):
        projection6=np.dot((v[:,k]).T,z7)
        project_array6=np.append(project_array6,projection6)
    arr2=np.zeros(2)
    arr2[0]=gauss(project_array6,mean1,s3)
    arr2[1]=gauss(project_array6,mean2,s3)
    max2=np.max(arr2)
    for i in range(2):
        if (max2==arr2[i]):
            new_array2[index2]=i+1
            if (new_array2[index2]==2):
                cnt2=cnt2+1
            else:
                l2.append(j)

```

```

        actual_label2.append(2)
        predicted_class_label2.append(i+1)
    index2=index2+1
    #print("Accuracy2=",cnt2)
    lek2.append(cnt2)

print("Accuracy of Class 1 : ",lek1)
print("Accuracy of Class 2 : ",lek2)

```

```

Accuracy of Class 1 : [53, 54, 58, 57, 67, 79, 71, 83, 81, 84, 96, 94, 89, 98, 95, 9
Accuracy of Class 2 : [50, 51, 58, 60, 63, 76, 82, 87, 87, 83, 91, 93, 98, 95, 96, 9

```



```

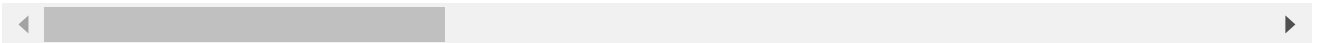
avac=[]
for i in range(len(lek1)):
    p=lek1[i]+lek2[i]
    p=p/2
    avac.append(p)
print("Accuracy of Class 1 : ",lek1)
print("Accuracy of Class 2 : ",lek2)
print("Average Accuracy :",avac)

```

```

Accuracy of Class 1 : [53, 54, 58, 57, 67, 79, 71, 83, 81, 84, 96, 94, 89, 98, 95, 9
Accuracy of Class 2 : [50, 51, 58, 60, 63, 76, 82, 87, 87, 83, 91, 93, 98, 95, 96, 9
Average Accuracy : [51.5, 52.5, 58.0, 58.5, 65.0, 77.5, 76.5, 85.0, 84.0, 83.5, 93.5,

```



```

print("Accuracy1 = 89")
print("Accuracy1 = 94")
print("Average Accuracy = 81.5")

```

```

Accuracy1 = 89
Accuracy1 = 94
Average Accuracy = 81.5

```

```

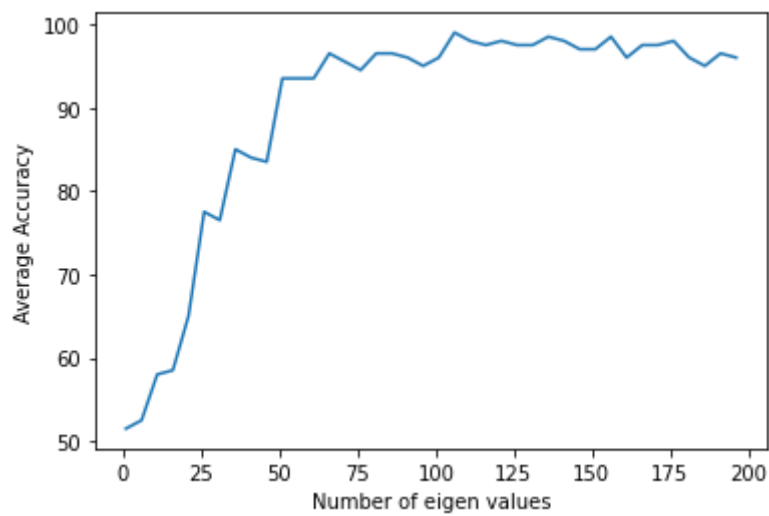
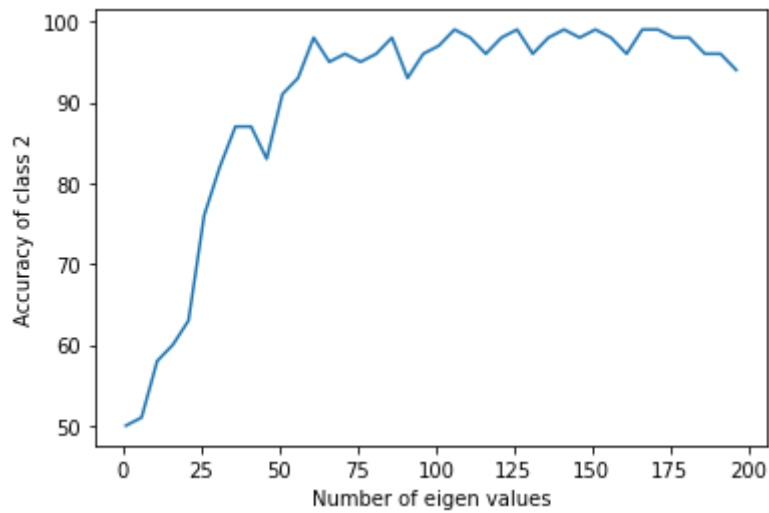
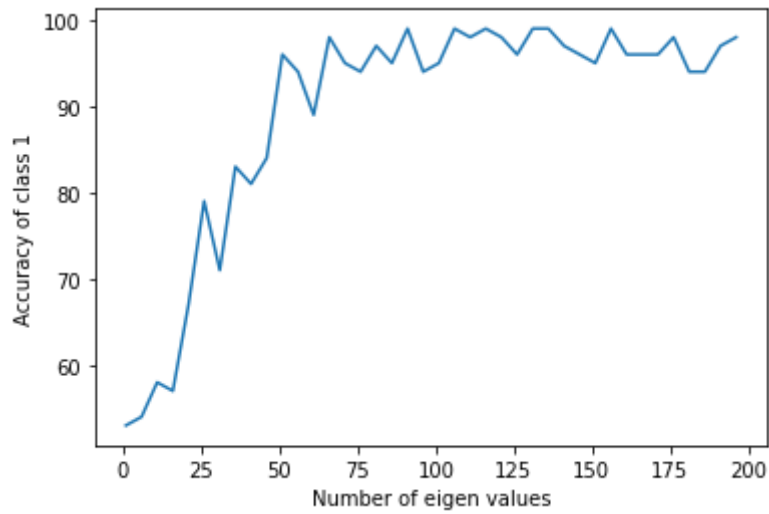
import matplotlib.pyplot as plt

x=np.arange(1,200,5)
plt.figure(1)
plt.xlabel("Number of eigen values")
plt.ylabel("Accuracy of class 1")
plt.plot(x,lek1)
plt.figure(2)
plt.xlabel("Number of eigen values")
plt.ylabel("Accuracy of class 2")
plt.plot(x,lek2)

```

```
plt.figure(3)
plt.xlabel("Number of eigen values")
plt.ylabel("Average Accuracy")
plt.plot(x,avac)
```

[<matplotlib.lines.Line2D at 0x7f5885938250>]



```
from google.colab.patches import cv2_imshow
```

```
newimage1=cv2.imread(l1[0],cv2.IMREAD_UNCHANGED)
cv2_imshow(newimage1)
print("Actual Label:",actual_label1[0])
```

```
print("Predicted Label:",predicted_class_label1[0])

newimage2=cv2.imread(l1[1],cv2.IMREAD_UNCHANGED)
cv2_imshow(newimage2)
print("Actual Label:",actual_label1[1])
print("Predicted Label:",predicted_class_label1[1])

newimage3=cv2.imread(l2[0],cv2.IMREAD_UNCHANGED)
cv2_imshow(newimage3)
print("Actual Label:",actual_label2[0])
print("Predicted Label:",predicted_class_label2[0])

newimage4=cv2.imread(l2[1],cv2.IMREAD_UNCHANGED)
cv2_imshow(newimage4)
print("Actual Label:",actual_label2[1])
print("Predicted Label:",predicted_class_label2[1])

newimage2=cv2.imread(l1[3],cv2.IMREAD_UNCHANGED)
cv2_imshow(newimage2)
print("Actual Label:",actual_label1[3])
print("Predicted Label:",predicted_class_label1[3])

newimage4=cv2.imread(l2[3],cv2.IMREAD_UNCHANGED)
cv2_imshow(newimage4)
print("Actual Label:",actual_label2[3])
print("Predicted Label:",predicted_class_label2[3])
```



Actual Label: 1

Predicted Label: 2



Actual Label: 1

Predicted Label: 2



Actual Label: 2

Predicted Label: 1

```
lek1=[]
lek2=[]
val=255.0
for N in range(1,200,5):
    I=np.identity(N)
    project_array2=np.array([])
    project_array1=np.array([])
    for j in glob.glob(path1):
        read_image=cv2.imread(j,0)
        image_resize=cv2.resize(read_image,(32,32))
        norm=np.divide(image_resize,xi_max)
        x3=np.reshape(norm,(1024,1))
        z3=x3-Mu1
        for i in range(N):
            projection1=np.dot((v[:,i]).T,z3)
            project_array1=np.append(project_array1,projection1)
    project_array1=np.reshape(project_array1,(200,N))
    project_array1=project_array1.T
    Mu3=np.sum(project_array1,axis=1)
    mean1=np.reshape(Mu3,(N,1))
    for j in glob.glob(path2):
        read_image=cv2.imread(j,0)
        image_resize=cv2.resize(read_image,(32,32))
        norm=np.divide(image_resize,xi_max)
        x4=np.reshape(norm,(1024,1))
        z4=x4-Mu2
        for i in range(N):
            projection2=np.dot((v[:,i]).T,z4)
            project_array2=np.append(project_array2,projection2)
    project_array2=np.reshape(project_array2,(200,N))
```



```

project_array2=project_array2.T
Mu4=np.sum(project_array2,axis=1)
mean2=np.reshape(Mu4,(N,1))
Mu_pooled=(Mu3+Mu4)/400
Mu_pooled=np.array(Mu_pooled)
#s3=np.zeros((N,N))
s3=0
for i in range(200):
    s=project_array1[:,i]-Mu_pooled
    s3=s3+np.dot(s,s.T)
for i in range(200):
    s=project_array2[:,i]-Mu_pooled
    s3=s3+np.dot(s,s.T)
s3=s3/400
s3=s3+lamda*I
s4=s3*I
path3="/content/gdrive/MyDrive/Machine Learning/LAB 3/TestCharacters/TestCharacters/1/*.jpg"
path4="/content/gdrive/MyDrive/Machine Learning/LAB 3/TestCharacters/TestCharacters/2/*.jpg"

index1=0
index2=0

cnt1=0
cnt2=0

l1=[]
l2=[]

actual_label1=[]
actual_label2=[]

predicted_class_label1=[]
predicted_class_label2=[]

new_array1=np.zeros(100)
new_array2=np.zeros(100)

for j in glob.glob(path3):
    read_image=cv2.imread(j,0)
    image_resize=cv2.resize(read_image,(32,32))
    norm=np.divide(image_resize,xi_max)
    x4=np.reshape(norm,(1024,1))
    z5=x4-Mu1
    project_array3=np.array([])
    for i in range(N):
        projection3=np.dot((v[:,i]).T,z5)
        project_array3=np.append(project_array3,projection3)
    arr1=[0,0]
    arr1[0]=gauss(project_array3,mean1,s4)
    arr1[1]=gauss(project_array3,mean2,s4)
    max1=max(arr1)
    for i in range(2):
        if (max1==arr1[i]):
            new_array1[index1]=i+1
            if (new_array1[index1]==1):
                cnt1=cnt1+1
            else:
                l1.append(j)

```

```

        actual_label1.append(1)
        predicted_class_label1.append(i+1)
    index1=index1+1
#print("Accuracy1=",cnt1)
lek1.append(cnt1)
for j in glob.glob(path4):
    read_image=cv2.imread(j,0)
    image_resize=cv2.resize(read_image,(32,32))
    norm=np.divide(image_resize,val)
    x7=np.reshape(norm,(1024,1))
    z7=x7-Mu2
    project_array6=np.array([])
    for k in range(N):
        projection6=np.dot((v[:,k]).T,z7)
        project_array6=np.append(project_array6,projection6)
    arr2=np.zeros(2)
    arr2[0]=gauss(project_array6,mean1,s4)
    arr2[1]=gauss(project_array6,mean2,s4)
    max2=np.max(arr2)
    for i in range(2):
        if (max2==arr2[i]):
            new_array2[index2]=i+1
            if (new_array2[index2]==2):
                cnt2=cnt2+1
            else:
                l2.append(j)
                actual_label2.append(2)
                predicted_class_label2.append(i+1)
    index2=index2+1
#print("Accuracy2=",cnt2)
lek2.append(cnt2)

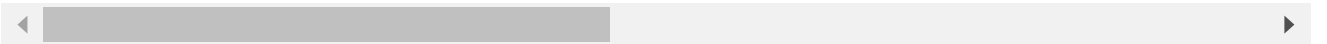
print("Accuracy of Class 1 : ",lek1)
print("Accuracy of Class 2 : ",lek2)

```

```

Accuracy of Class 1 :  [53, 54, 55, 54, 55, 57, 57, 58, 57, 57, 56, 59, 58, 65, 63, 6
Accuracy of Class 2 :  [50, 51, 52, 52, 54, 54, 53, 58, 54, 55, 55, 53, 54, 61, 64, 6

```

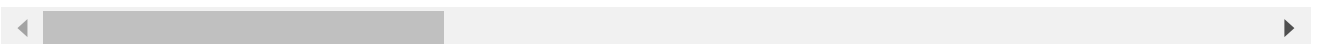


```

avac1=[]
for i in range(len(lek1)):
    p=lek1[i]+lek2[i]
    p=p/2
    avac1.append(p)
print("Accuracy of Class 1 : ",lek1)
print("Accuracy of Class 2 : ",lek2)
print("Average Accuracy : ",avac1)

Accuracy of Class 1 :  [53, 54, 55, 54, 55, 57, 57, 58, 57, 57, 56, 59, 58, 65, 63, 6
Accuracy of Class 2 :  [50, 51, 52, 52, 54, 54, 53, 58, 54, 55, 55, 53, 54, 61, 64, 6
Average Accuracy :  [51.5, 52.5, 53.5, 53.0, 54.5, 55.5, 55.0, 58.0, 55.5, 56.0, 55.5

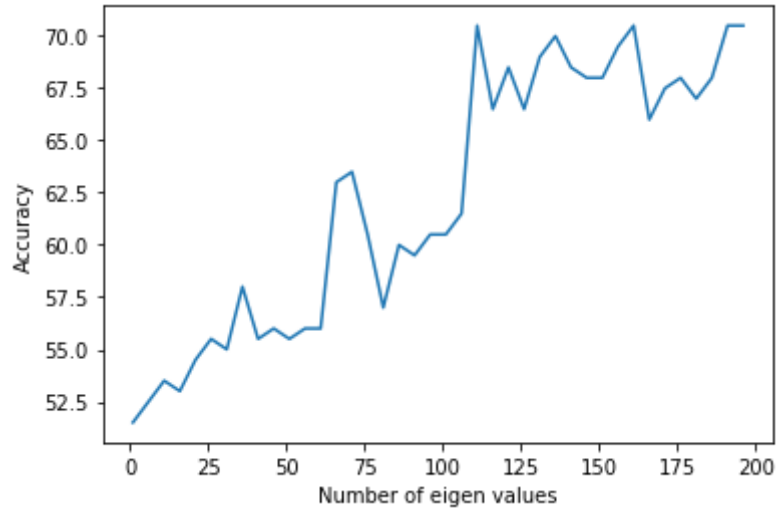
```



```
import matplotlib.pyplot as plt

x=np.arange(1,200,5)
plt.figure(1)
plt.xlabel("Number of eigen values")
plt.ylabel("Accuracy")
plt.plot(x,avac1)
```

[<matplotlib.lines.Line2D at 0x7f5885abd590>]



```
from google.colab.patches import cv2_imshow

newimage1=cv2.imread(l1[0],cv2.IMREAD_UNCHANGED)
cv2_imshow(newimage1)
print("Actual Label:",actual_label1[0])
print("Predicted Label:",predicted_class_label1[0])

newimage2=cv2.imread(l1[1],cv2.IMREAD_UNCHANGED)
cv2_imshow(newimage2)
print("Actual Label:",actual_label1[1])
print("Predicted Label:",predicted_class_label1[1])

newimage3=cv2.imread(l2[0],cv2.IMREAD_UNCHANGED)
cv2_imshow(newimage3)
print("Actual Label:",actual_label2[0])
print("Predicted Label:",predicted_class_label2[0])

newimage4=cv2.imread(l2[1],cv2.IMREAD_UNCHANGED)
cv2_imshow(newimage4)
print("Actual Label:",actual_label2[1])
print("Predicted Label:",predicted_class_label2[1])
```



Actual Label: 1

Predicted Label: 2



Actual Label: 1

Predicted Label: 2



Actual Label: 2

Predicted Label: 1

```
lek1=[]
lek2=[]
val=255.0
for N in range(1,200,5):
    I=np.identity(N)
    project_array2=np.array([])
    project_array1=np.array([])
    for j in glob.glob(path1):
        read_image=cv2.imread(j,0)
        image_resize=cv2.resize(read_image,(32,32))
        norm=np.divide(image_resize,xi_max)
        x3=np.reshape(norm,(1024,1))
        z3=x3-Mu1
        for i in range(N):
            projection1=np.dot((v[:,i]).T,z3)
            project_array1=np.append(project_array1,projection1)
    project_array1=np.reshape(project_array1,(200,N))
    project_array1=project_array1.T
    Mu3=np.sum(project_array1,axis=1)
    mean1=np.reshape(Mu3,(N,1))
    for j in glob.glob(path2):
        read_image=cv2.imread(j,0)
        image_resize=cv2.resize(read_image,(32,32))
        norm=np.divide(image_resize,xi_max)
        x4=np.reshape(norm,(1024,1))
        z4=x4-Mu2
        for i in range(N):
            projection2=np.dot((v[:,i]).T,z4)
            project_array2=np.append(project_array2,projection2)
```

```

project_array2=np.reshape(project_array2,(200,N))
project_array2=project_array2.T
Mu4=np.sum(project_array2,axis=1)
mean2=np.reshape(Mu4,(N,1))
Mu_pooled=(Mu3+Mu4)/400
Mu_pooled=np.array(Mu_pooled)
#s3=np.zeros((N,N))
s3=0
for i in range(200):
    #s=project_array1[:,i]-Mu_pooled
    #s3=s3+np.dot(s,s.T)
    s3=np.var(s)
for i in range(200):
    s=project_array2[:,i]-Mu_pooled
    #s3=s3+np.dot(s,s.T)
    s3=np.var(s)
s3=s3/400
s3=s3+lamda*I
s5=s3*I
path3="/content/gdrive/MyDrive/Machine Learning/LAB 3/TestCharacters/TestCharacters/1/*.jpg"
path4="/content/gdrive/MyDrive/Machine Learning/LAB 3/TestCharacters/TestCharacters/2/*.jpg"

index1=0
index2=0

cnt1=0
cnt2=0

l1=[]
l2=[]

actual_label1=[]
actual_label2=[]

predicted_class_label1=[]
predicted_class_label2=[]

new_array1=np.zeros(100)
new_array2=np.zeros(100)

for j in glob.glob(path3):
    read_image=cv2.imread(j,0)
    image_resize=cv2.resize(read_image,(32,32))
    norm=np.divide(image_resize,xi_max)
    x4=np.reshape(norm,(1024,1))
    z5=x4-Mu1
    project_array3=np.array([])
    for i in range(N):
        projection3=np.dot((v[:,i]).T,z5)
        project_array3=np.append(project_array3,projection3)
    arr1=[0,0]
    arr1[0]=gauss(project_array3,mean1,s5)
    arr1[1]=gauss(project_array3,mean2,s5)
    max1=max(arr1)
    for i in range(2):
        if (max1==arr1[i]):
            new_array1[index1]=i+1
            if (new_array1[index1]==1):

```

```

        cnt1=cnt1+1
    else:
        l1.append(j)
        actual_label1.append(1)
        predicted_class_label1.append(i+1)
    index1=index1+1
#print("Accuracy1=",cnt1)
lek1.append(cnt1)
for j in glob.glob(path4):
    read_image=cv2.imread(j,0)
    image_resize=cv2.resize(read_image,(32,32))
    norm=np.divide(image_resize,val)
    x7=np.reshape(norm,(1024,1))
    z7=x7-Mu2
    project_array6=np.array([])
    for k in range(N):
        projection6=np.dot((v[:,k]).T,z7)
        project_array6=np.append(project_array6,projection6)
    arr2=np.zeros(2)
    arr2[0]=gauss(project_array6,mean1,s5)
    arr2[1]=gauss(project_array6,mean2,s5)
    max2=np.max(arr2)
    for i in range(2):
        if (max2==arr2[i]):
            new_array2[index2]=i+1
            if (new_array2[index2]==2):
                cnt2=cnt2+1
            else:
                l2.append(j)
                actual_label2.append(2)
                predicted_class_label2.append(i+1)
    index2=index2+1
#print("Accuracy2=",cnt2)
lek2.append(cnt2)

```

```

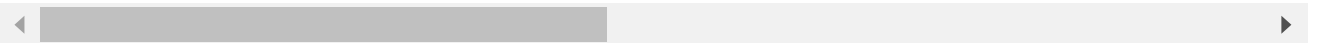
print("Accuracy of Class 1 : ",lek1)
print("Accuracy of Class 2 : ",lek2)

```

```

Accuracy of Class 1 :  [53, 54, 54, 54, 54, 53, 54, 55, 54, 54, 53, 55, 55, 56, 54, 5
Accuracy of Class 2 :  [50, 51, 50, 51, 51, 51, 51, 50, 52, 51, 51, 51, 51, 51, 52, 5

```



```

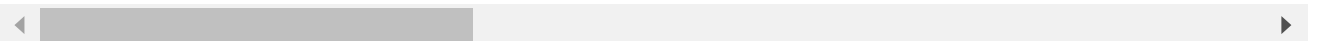
avac2=[]
for i in range(len(lek1)):
    p=lek1[i]+lek2[i]
    p=p/2
    avac2.append(p)
print(avac2)

```

```

[51.5, 52.5, 52.0, 52.5, 52.5, 52.0, 52.5, 52.5, 53.0, 52.5, 52.0, 53.0, 53.0, 53.5,

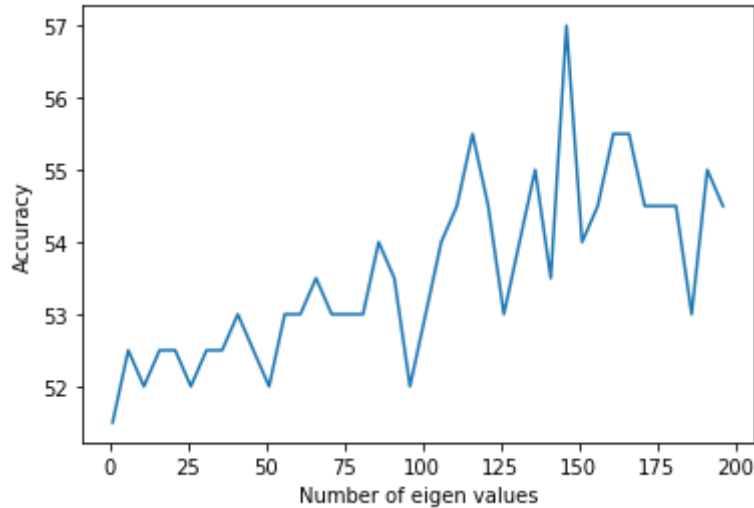
```



```
import matplotlib.pyplot as plt
```

```
x=np.arange(1,200,5)
plt.figure(1)
plt.xlabel("Number of eigen values")
plt.ylabel("Accuracy")
plt.plot(x,avac2)
```

[<matplotlib.lines.Line2D at 0x7f5885a00f90>]



```
from google.colab.patches import cv2_imshow
```

```
newimage1=cv2.imread(l1[0],cv2.IMREAD_UNCHANGED)
cv2_imshow(newimage1)
print("Actual Label:",actual_label1[0])
print("Predicted Label:",predicted_class_label1[0])
```

```
newimage2=cv2.imread(l1[1],cv2.IMREAD_UNCHANGED)
cv2_imshow(newimage2)
print("Actual Label:",actual_label1[1])
print("Predicted Label:",predicted_class_label1[1])
```

```
newimage3=cv2.imread(l2[0],cv2.IMREAD_UNCHANGED)
cv2_imshow(newimage3)
print("Actual Label:",actual_label2[0])
print("Predicted Label:",predicted_class_label2[0])
```

```
newimage4=cv2.imread(l2[1],cv2.IMREAD_UNCHANGED)
cv2_imshow(newimage4)
print("Actual Label:",actual_label2[1])
print("Predicted Label:",predicted_class_label2[1])
```



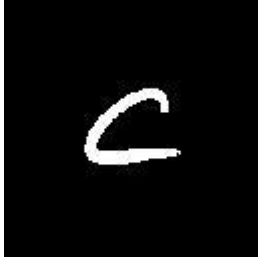
Actual Label: 1  
Predicted Label: 2



Actual Label: 1  
Predicted Label: 2



Actual Label: 2  
Predicted Label: 1



Actual Label: 2  
Predicted Label: 1

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