# Lecture 3: Autoregressive Distributed Lag Model (ADL)

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Econometrics 2

#### **Administrative**

- Recommended Reading: Hanck, Arnold, Gerber and Schmelzer: Chapter 14.5
- Problem Set 3 Deadline: June 4th at 9:00 am

# Outline

1. Motivation

2. Definitions and Models

- ARMA(p,q) models uses a variable's own lags to forecast its future values.
- ullet ARMA(p,q) is too simple and ignores data that may be readily available.
- An ADL model uses lags of other variables for forecasting.

• Example 1: We may use inflation and exchange rates to forecast GDP growth in Brazil. (Problem Set)

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- Example 2: What is the relationship between the population sizes of jaguatiricas and cutias?





# Definitions and Models

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1. Motivation

2. Definitions and Models

#### Model 1: ADL with a single extra predictor

An ADL(p,q) model assumes that a time series  $\{Y_t\}$  can be represented by a linear function of p of its lagged values and q lags of another time series  $\{X_t\}$ :

$$Y_{t} = \alpha + \left(\sum_{l=1}^{p} \phi_{l} \cdot Y_{t-l}\right) + \left(\sum_{m=1}^{q} \beta_{m} \cdot X_{t-m}\right) + \epsilon_{t},$$

where

$$\mathbb{E}\left[\epsilon_{t}|Y_{t-1},Y_{t-2},\ldots,X_{t-1},X_{t-2},\ldots\right]=0.$$

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# **Definition: Joint Stationarity**

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Two stochastic processes  $\{Y_t\}$  and  $\{X_t\}$  are jointly stationary if, for any values of  $j_1, j_2, \ldots, j_n$ , the joint distribution of  $Y_t, X_t, Y_{t+j_1}, X_{t+j_1}, \ldots, Y_{t+j_n}, X_{t+j_n}$  depends only on the intervals separating the dates  $(j_1, j_2, \ldots, j_n)$  and not on the date itself (t).

The general time series regression model extends the ADL model such that multiple regressors and their lags are included. It uses P lags of the dependent variable and  $Q_I$  lags of L additional predictors, where  $I \in \{1, \ldots, L\}$ :

$$Y_{t} = \alpha + \left(\sum_{p=1}^{P} \phi_{p} \cdot Y_{t-p}\right) + \left[\sum_{l=1}^{L} \left(\sum_{q=1}^{Q_{l}} \beta_{l,q} \cdot X_{l,t-q}\right)\right] + \epsilon_{t}$$

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For estimation, we will make five assumptions.

#### Assumption 1 (Exogeneity)

$$\mathbb{E}\left[\epsilon_{t}|Y_{t-1},Y_{t-2},\ldots,X_{1,t-1},X_{1,t-2},\ldots,X_{L,t-1},X_{L,t-2},\ldots\right]=0$$

#### Assumption 2 (Stationarity)

 $\{(Y_t, X_{1,t}, \dots, X_{L,t})\}$  are jointly stationary.

#### Assumption 3 (Weak Dependence Formal Definition )

 $(Y_t, X_{1,t}, \dots, X_{L,t})$  and  $(Y_{t-j}, X_{1,t-j}, \dots, X_{L,t-j})$  become independent as j gets large.

#### Assumption 4 (Large Outliers are Unlikely)

 $(Y_t, X_{1,t}, \dots, X_{L,t})$  have nonzero, finite fourth moments.

#### Assumption 5

No perfect multicollinearity.

# Thank you!

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# References

#### Formal Definition: Weak Dependence

Fix a set S, a sequence of sets of measurable functions  $\{\mathcal{F}_d\}_{d=1}^{\infty} \in \prod_{d=1}^{\infty} \left(S^d \to \mathbb{R}\right)$ , a positive sequence  $\{\theta_{\delta}\}_{\delta=1}^{\infty} \to 0$ , and a function  $\psi \in \mathcal{F}^2 \times (\mathbb{Z}^+)^2 \to \mathbb{R}^+$ . A sequence  $\{X_n\}_{n=1}^{\infty}$  of random variables is  $(\{\mathcal{F}_d\}_{d=1}^{\infty}, \{\theta_{\delta}\}_{\delta}, \psi)$ -weakly dependent if, for all  $j_1 \leq j_2 \leq \cdots \leq j_d < j_d + \delta \leq k_1 \leq k_2 \leq \cdots \leq k_e$ , for all  $\phi \in \mathcal{F}_d$ , and  $\tau \in \mathcal{F}_e$ , we have  $|\operatorname{Cov}(\phi(X_{i_1}, \dots, X_{i_d}), \tau(X_{k_1}, \dots, X_{k_e}))| \leq \psi(\phi, \tau, d, e) \cdot \theta_{\delta}$ .

**Intuition:** The covariance between any function of the variables goes to zero when the distance between the time periods grows.

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