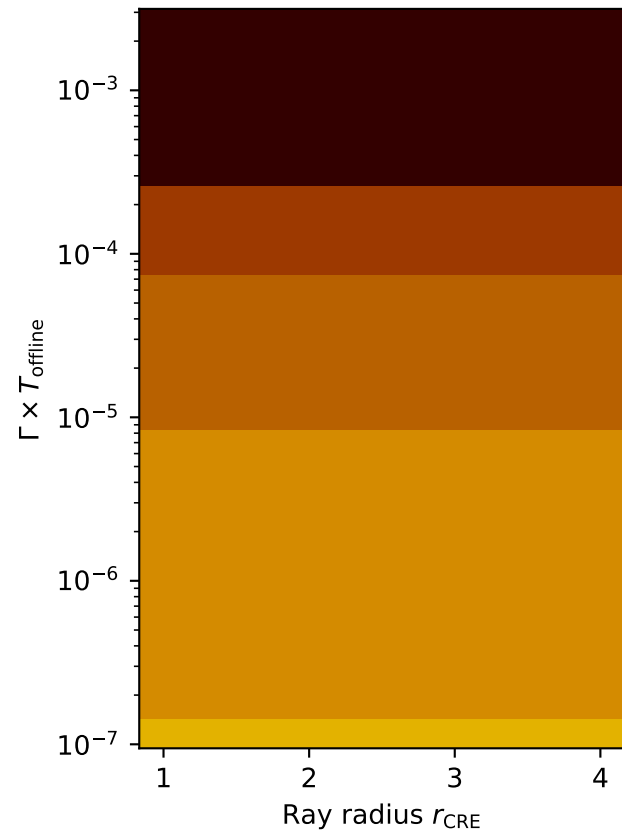
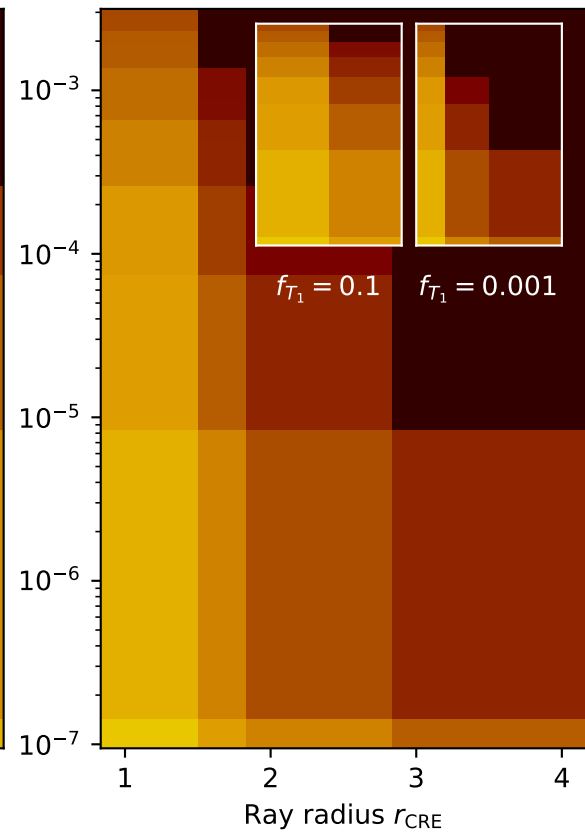


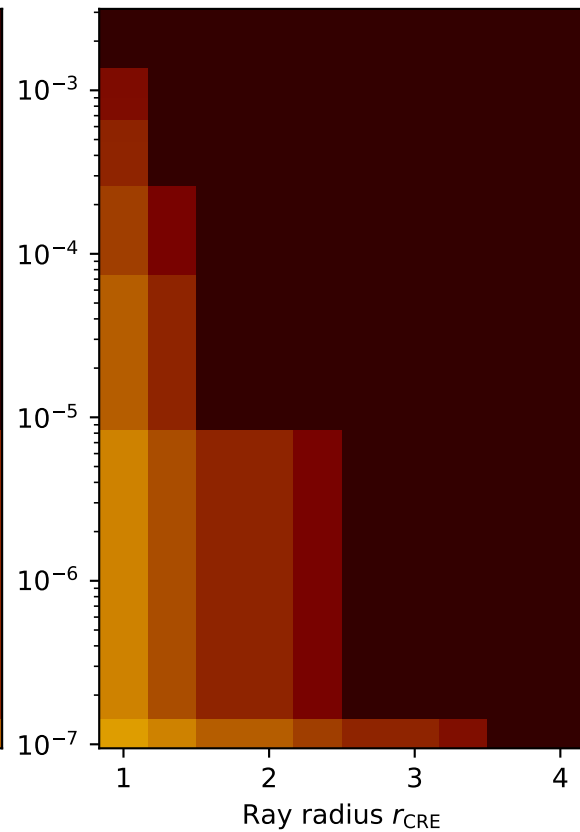
a) *Distributed* baseline



b) *Code expansion* baseline
(**Direct** noise model, $f_{T_1} = 0.01$)



c) *Code expansion* baseline
(**Scrambling** noise model)



d) *Re-mapping* (ours)

