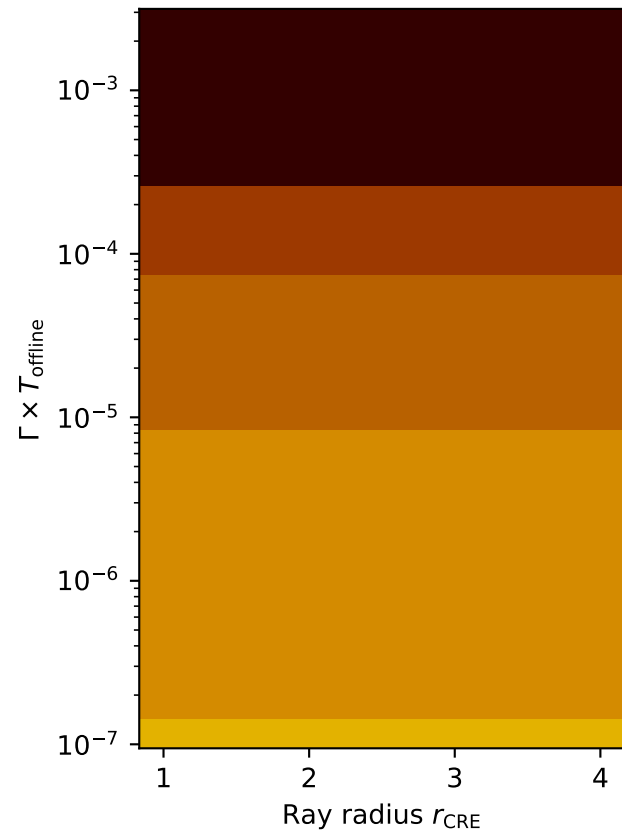
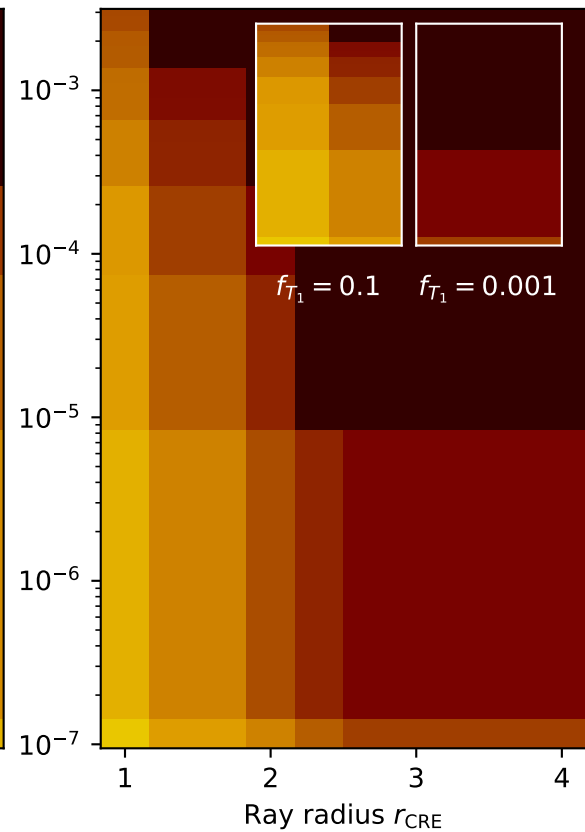


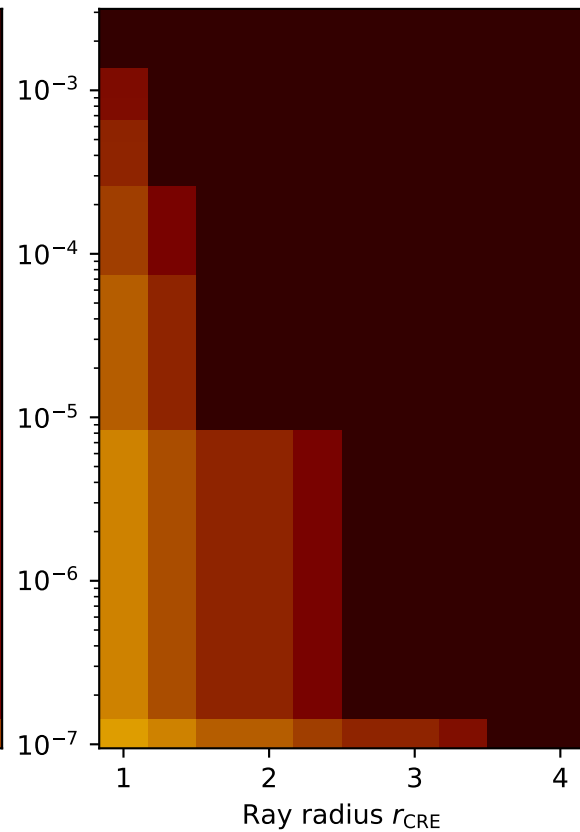
a) *Distributed* baseline



b) *Code expansion* baseline  
(**Direct** noise model,  $f_{T_1} = 0.01$ )



c) *Code expansion* baseline  
(**Scrambling** noise model)



d) Re-mapping (ours)

