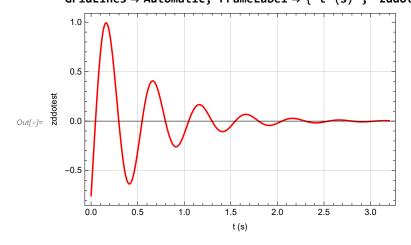
# Impulse Response

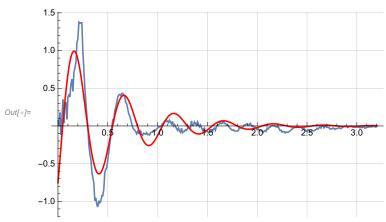
```
Import["C:\\Users\\ambik\\Desktop\\ImpulseInput.xls", {"Data", 1}]
        \{ \{ \text{Time } (s), \text{Linear Acceleration } x (m/s^2), \text{Linear Acceleration } y (m/s^2), \} 
          Linear Acceleration z (m/s^2), Absolute acceleration (m/s^2),
          \{0.0499597, -0.0319996, -0.00270207, 0.000562502, 0.0321184\}, (...5527...)
Out[ • ]=
          {55.1707, -0.0490635, 0.0554145, -0.0286753, 0.0793742}}
        large output
                     show less
                                show more
                                            show all
                                                      set size limit...
ln[e]= rawplotData = Transpose[{accelData[[All, 1]], accelData[[All, 4]]}]
        \{\text{Time (s), Linear Acceleration z } (m/s^2)\}, \{0.0499597, 0.000562502\},
          \{0.0599307, -0.0280339\}, \{0.0699027, -0.00842759\}, \dots 5522 \dots \}, \{55.1408, 0.0321451\},
          \{55.1508, 0.00452224\}, \{55.1608, 0.000874159\}, \{55.1707, -0.0286753\}\}
Out[ • ]=
        large output
                     show less
                                show more
                                            show all
                                                      set size limit...
In[*]:= plotData = rawplotData[[2;;]]
        \{\{0.0499597, 0.000562502\}, \{0.0599307, -0.0280339\}, \{0.0699027, -0.00842759\},
          \{0.0798737, -0.0150116\}, \dots 5521\dots, \{55.1408, 0.0321451\},
         \{55.1508, 0.00452224\}, \{55.1608, 0.000874159\}, \{55.1707, -0.0286753\}\}
Out[ • ]=
                     show less
                                show more
                                                      set size limit...
        large output
                                            show all
In[*]:= accelPlot = ListLinePlot[plotData, PlotRange → {All, All}]
      1.5
      1.0
      0.5
Out[ • ]=
                                                 40
      -0.5
      -1.0
```

```
In[*]:= usefulAccelData = Transpose[plotData[[2980;; 3300]]][[2]];
ln[-]:= tf = (3300 - 2980) * 0.01
In[*]:= time = Range[0, tf, 0.01];
In[*]:= usefulData = Transpose[{time, usefulAccelData}];
In[*]:= zddotPlotImpulse = ListLinePlot[usefulData, PlotRange → All, GridLines → Automatic]
        1.0
        0.5
Out[ • ]=
       -0.5
       -1.0
In[*]:= SetAttributes[{A1, A2, b, c, ωn, ωd, ζ}, Constant]
ln[\circ]:= x[t] = Exp[-\xi \omega n t] (A1 Cos[\omega d t] + A2 Sin[\omega d t])
Outf = e^{-0.140841 t \omega n} (A1 Cos [t \omegad] + A2 Sin [t \omegad])
In[ \circ ] := Dt[Dt[x[t], t], t] // Simplify
Out[*]= e^{-0.140841 t \omega n} \left( \left( -1. A1 \omega d^2 - 0.281681 A2 \omega d \omega n + 0.0198361 A1 \omega n^2 \right) Cos[t \omega d] + 0.0198361 A1 \omega n^2 \right)
            (-1. A2 \omega d^2 + 0.281681 A1 \omega d \omega n + 0.0198361 A2 \omega n^2) Sin[t \omega d])
ln[ \circ ] := A1 = .; A2 = .; b = .; c = .;
In[\bullet]:= \omega \mathbf{n} = .; \mathcal{E} = .;
In[*]:= fitParam = FindFit[(usefulData), { Exp[-bt]
                ((Cos[ct]) (-A1c^2 - 2A2bc + A1b^2) + (Sin[ct]) (-A2c^2 + 2A1bc + A2b^2))},
            {A1, A2, b, c}, t, MaxIterations \rightarrow 1000000] // Chop
\textit{Out[*]=} \quad \{ \texttt{A1} \rightarrow \textbf{0.00641119, A2} \rightarrow -\textbf{0.005293, b} \rightarrow \textbf{1.78688, c} \rightarrow \textbf{12.5608} \}
```

In[\*]:= fitPlotImpulse = Plot[Exp[-bt]  $((Cos[ct])(-A1c^2 - 2A2bc + A1b^2) + (Sin[ct])(-A2c^2 + 2A1bc + A2b^2))//.$ fitParam,  $\{t, 0, tf\}$ , PlotRange  $\rightarrow$  All, PlotStyle  $\rightarrow$  {Red}, Frame  $\rightarrow$  True, GridLines → Automatic, FrameLabel → {"t (s)", "zddotest"}]



### In[@]:= Show[zddotPlotImpulse, fitPlotImpulse]



In[\*]:= Bcoeff = b /. fitParam

Out[\*]= 1.78688

In[\*]:= Ccoeff = c /. fitParam

Out[ ]= 12.5608

 $ln[\circ]:=$  eqn1 = Bcoeff ==  $\mathcal{E} \omega n$ eqn2 = Ccoeff ==  $\omega$ n Sqrt[1 -  $\xi^2$ ]

Out[\*]= 1.78688 ==  $\xi \omega n$ 

Out[\*]= 12.5608 ==  $\sqrt{1-\zeta^2} \omega n$ 

ln[\*]:= solImpulse = Solve[{eqn1, eqn2}, {\mathcal{E}}, \omega n}] // First

Out[\*]= {  $\zeta \rightarrow$  0.140841,  $\omega n \rightarrow$  12.6873 }

```
ln[@] := eqn3 = \omega n == Sqrt[k/m] /. solImpulse
Out[*]= 12.6873 == \sqrt{\frac{k}{-}}
ln[*]:= KsolImpulse = Solve[eqn3, k] /. {m \rightarrow 1200} // First(*N/m*)
Out[\bullet]= { k \to 193160. }
```

# Step Response Data

show less

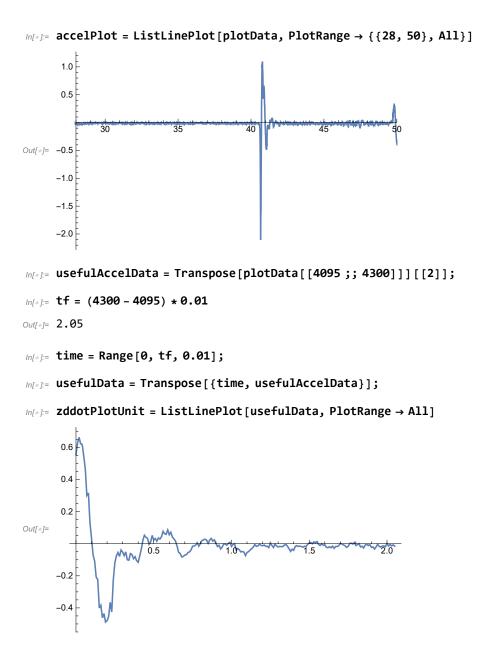
large output

```
Import["C:\\Users\\ambik\\Desktop\\StepInputNew.xls", {"Data", 1}]
        \{ \{ \text{Time (s), Linear Acceleration x (m/s^2), Linear Acceleration y (m/s^2), } \} 
          Linear Acceleration z (m/s^2), Absolute acceleration (m/s^2)},
         \cdots 6581 \cdots , {65.6594, -0.139314, 0.147269, -0.0509082, 0.209017}
Out[ • ]=
                                                     set size limit...
       large output
                    show less
                               show more
                                           show all
In[*]:= rawplotData = Transpose[{accelData[[All, 1]], accelData[[All, 4]]}]
        \{ \{ Time (s), Linear Acceleration z (m/s^2) \}, \{ 0.0473149, -0.0203027 \}, \}
         \{0.0572849, -0.0135895\}, \{0.0672549, -0.00730785\}, (...6575...), \{65.6295, -0.0117319\},
         \{65.6394, -0.038063\}, \{65.6494, -0.0219885\}, \{65.6594, -0.0509082\}\}
Out[ • ]=
                                                     set size limit...
       large output
                    show less
                               show more
                                           show all
In[*]:= plotData = rawplotData[[2;;]]
        \{\{0.0473149, -0.0203027\}, \{0.0572849, -0.0135895\}, \{0.0672549, -0.00730785\},
         \{0.0772249, -0.0109916\}, (...6574...), \{65.6295, -0.0117319\},
         \{65.6394, -0.038063\}, \{65.6494, -0.0219885\}, \{65.6594, -0.0509082\}\}
Out[ • ]=
```

set size limit...

show all

show more



# Canonical 2nd order Transfer **Function**

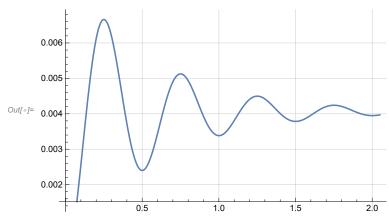
Fitting Transfer function from Impulse Input data to the Unitstep response.

$$log(s) := kdc = 1/(m s^2 + b s + K) /. \{s \rightarrow 0, K \rightarrow k /. KsolImpulse\}$$

$$Out[s] := 5.17705 \times 10^{-6}$$

```
ln[ \circ ] := \mathcal{E} = \mathcal{E} /. solImpulse
                           \omega_n = \omega n /. solImpulse
                           k_{dc} = kdc
Out[*]= 0.140841
Out[*]= 12.6873
Out[\bullet]= 5.17705 \times 10^{-6}
  ln[\bullet]:= GS = \left( k_{dc} (\omega_n)^2 / \left( s^2 + 2 \xi \omega_n S + (\omega_n)^2 \right) \right)
Out[ • ]=
                            160.967 + 3.57377 \text{ s} + \text{s}^2
   ln[*]:= resUnit = OutputResponse[TransferFunctionModel[Gs, s], 80 * 9.81 UnitStep[t], t]
\textit{Out[s]=} \ \left\{ \ (\textbf{0.} + \textbf{0.} \ \dot{\textbf{1}}) \ + \ \textbf{0.00406295} \ e^{(-\textbf{1.78688} - \textbf{12.5608} \ \dot{\textbf{1}}) \ \textbf{t}} \ \left( -\textbf{1.} \ e^{(\textbf{0.} + \textbf{12.5608} \ \dot{\textbf{1}}) \ \textbf{t}} \ \mathsf{Cos} \ [\textbf{12.5608} \ \textbf{t}] \ \mathsf{UnitStep} \ [\textbf{t}] \ + \ \mathsf{UnitStep} \ + \ \mathsf{Uni
                                                          (8.89219 \times 10^{-17} + 2.22305 \times 10^{-17} \text{ i}) \text{ e}^{1.78688 \text{ t}} \text{ Cos} [12.5608 \text{ t}] \text{ UnitStep}[\text{t}] - 10^{-17} \text{ cos} [12.5608 \text{ t}]
                                                          (8.89219 \times 10^{-17} + 2.22305 \times 10^{-17} \text{ i}) e^{(1.78688 + 25.1216 \text{ i}) \text{ t}} \cos [12.5608 \text{ t}] \text{ UnitStep[t]} +
                                                         1. \times 2.71828<sup>1.78688 t</sup> e^{(0.+12.5608 i) t} Cos [12.5608 t] <sup>2</sup> UnitStep[t] -
                                                         0.142259 e^{(0.+12.5608 i) t} Sin[12.5608 t] UnitStep[t] +
                                                          (3.63891 \times 10^{-17} + 0.510119 \text{ i}) \text{ } e^{1.78688 \text{ t}} \text{ Sin} [12.5608 \text{ t}] \text{ UnitStep} [\text{t}] -
                                                          (3.63891 \times 10^{-17} + 0.510119 i) e^{(1.78688+25.1216 i) t} Sin[12.5608t] UnitStep[t] -
                                                         0.0202375 \times 2.71828^{1.78688 \, t} \, e^{(0.+12.5608 \, i) \, t} \, Sin[12.5608 \, t]^2 \, UnitStep[t])
```

#### $ln[\cdot]:=$ Plot[resUnit, {t, 0, tf}, GridLines $\rightarrow$ Automatic]

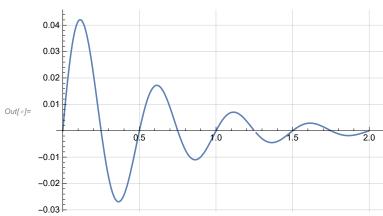


0.142259  $e^{(0.+12.5608 i) t}$  Sin[12.5608 t] UnitStep[t] +

 $(3.63891 \times 10^{-17} + 0.510119 i) e^{1.78688 t} Sin[12.5608 t] UnitStep[t] -$ 

 $0.0202375 \times 2.71828^{1.78688\,t} \, e^{(0.+12.5608\,i)\,t} \, Sin[12.5608\,t]^2 \, UnitStep[t])$ 

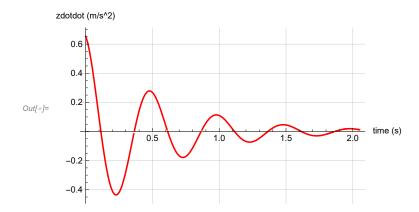
 $(3.63891 \times 10^{-17} + 0.510119 i) e^{(1.78688 + 25.1216 i) t} Sin[12.5608 t] UnitStep[t] -$ 



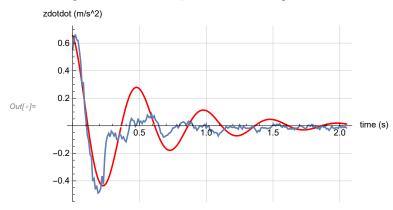
In[@]:= acclresUnit = Dt[velresUnit, t]

```
(8.89219 \times 10^{-17} + 2.22305 \times 10^{-17} \text{ i}) e^{(1.78688 + 25.1216 \text{ i}) \text{ t}} \cos [12.5608 \text{ t}] \text{ UnitStep[t]} +
                1. \times 2.71828<sup>1.78688 t</sup> e^{(0.+12.5608 i) t} Cos[12.5608 t] <sup>2</sup> UnitStep[t] -
                0.142259 e<sup>(0.+12.5608 i) t</sup> Sin[12.5608 t] UnitStep[t] +
                  (3.63891 \times 10^{-17} + 0.510119 i) e^{1.78688 t} Sin[12.5608 t] UnitStep[t] -
                  (3.63891 \times 10^{-17} + 0.510119 \text{ i}) e^{(1.78688 + 25.1216 \text{ i}) \text{ t}} Sin[12.5608 \text{ t}] UnitStep[t] - 0.0202375 \times 10^{-17} + 0.510119 \text{ i}) e^{(1.78688 + 25.1216 \text{ i}) \text{ t}} Sin[12.5608 \text{ t}] UnitStep[t] - 0.0202375 \times 10^{-17} + 0.510119 \text{ i})
                        2.71828^{1.78688\,\text{t}}\,\,\mathrm{e}^{\,(0.\,\text{+}12.5608\,\text{i})\,\,\text{t}}\,\,\mathrm{Sin}\,[\,12.5608\,\,\text{t}\,]^{\,2}\,\,\mathrm{UnitStep}\,[\,\text{t}\,]\,\,\big)\,\,+\,\,0.00406295\,\,\mathrm{e}^{\,(-1.78688\,-\,12.5608\,\,\text{i})\,\,\text{t}}
\left(\textbf{1.32086} \times \textbf{10}^{-15} + \textbf{12.815} \ \dot{\textbf{1}} \right) \ \textbf{e}^{\textbf{1.78688} \, \textbf{t}} \ \textbf{Cos} \, [\, \textbf{12.5608} \, \textbf{t} \, ] \ \left( \left\{ \begin{array}{l} \textbf{Indeterminate} & \textbf{t} = \textbf{0} \\ \textbf{0} & \textbf{True} \end{array} \right) \ - \ \dot{\textbf{Cos}} \, [\, \textbf{1.32086} \times \textbf{10}^{-15} + \textbf{12.815} \, \dot{\textbf{1}} \, ] \ \dot{\textbf{e}}^{\textbf{1.78688} \, \textbf{t}} \ \textbf{Cos} \, [\, \textbf{12.5608} \, \textbf{t} \, ] \ \left( \left\{ \begin{array}{l} \textbf{Indeterminate} & \textbf{t} = \textbf{0} \\ \textbf{0} & \textbf{True} \end{array} \right) \ - \ \dot{\textbf{Cos}} \, [\, \textbf{1.32086} \times \textbf{10}^{-15} + \textbf{12.815} \, \dot{\textbf{1}} \, ] \ \dot{\textbf{e}}^{\textbf{1.78688} \, \textbf{t}} \ \textbf{Cos} \, [\, \textbf{12.5608} \, \textbf{t} \, ] \ \dot{\textbf{E}}^{\textbf{1.78688} \, \textbf{t}} \ \textbf{Cos} \, [\, \textbf{12.5608} \, \textbf{t} \, ] \ \dot{\textbf{E}}^{\textbf{1.78688} \, \textbf{t}} \ \dot{\textbf{E}}^{\textbf{1.786888} \, \textbf{t}} \ \dot{\textbf{E}}^{\textbf{1.78688} \, \textbf{t}} \ \dot{\textbf{E}}^{\textbf{1.786888} \, \textbf{t}} \ \dot{\textbf{E}}^{\textbf{1.78688} \, \textbf{t}} \ \dot{\textbf{E}}^{\textbf{1.786888} \, \textbf{t}} \ \dot{\textbf{E}}^{\textbf{1.78688} \, \textbf{t}} \ \dot{\textbf{E}}^{\textbf
                  \left(\textbf{2.03931} \times \textbf{10}^{-16} + \textbf{12.815} \ \dot{\textbf{1}} \right) \ e^{\,(\textbf{1.78688} + \textbf{25.1216} \, \dot{\textbf{1}}) \ \textbf{t}} \ \text{Cos} \, [\, \textbf{12.5608} \, \textbf{t} \, ] \ \left( \left\{ \begin{array}{l} \textbf{Indeterminate} & \textbf{t} = \textbf{0} \\ \textbf{0} & \textbf{True} \end{array} \right) + \textbf{10.815} \, \dot{\textbf{1}} \right) \ e^{\,(\textbf{1.78688} + \textbf{25.1216} \, \dot{\textbf{1}}) \ \textbf{t}} \ \text{Cos} \, [\, \textbf{12.5608} \, \textbf{t} \, ] \ \left( \left\{ \begin{array}{l} \textbf{Indeterminate} & \textbf{t} = \textbf{0} \\ \textbf{0} & \textbf{True} \end{array} \right) + \textbf{10.815} \, \dot{\textbf{10.816}} \,
                   (\textbf{4.57377} + \textbf{25.1216} \; \dot{\mathbb{1}}) \;\; \textbf{2.71828}^{\textbf{1.78688} \; \textbf{t}} \; \boldsymbol{\mathbb{e}}^{\; (\textbf{0.+12.5608} \; \dot{\mathbb{1}}) \; \textbf{t}}
                \left(2.06743 \times 10^{-15} - 2.33316 \ \text{i}\right) \ \text{e}^{1.78688 \, \text{t}} \ \left( \left\{ \begin{array}{ll} \text{Indeterminate} & \text{t} = 0 \\ \text{0} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{Sin} \left[12.5608 \, \text{t}\right] + \left( \begin{array}{ll} \text{True} & \text{True} \end{array} \right) \ \text{True} \ 
                (25.63 - 2.33316 \, \dot{\mathtt{i}}) \, \, e^{(1.78688 + 25.1216 \, \dot{\mathtt{i}}) \, \, t} \, \left( \, \left\{ \begin{array}{l} \text{Indeterminate} & t == 0 \\ 0 & \text{True} \end{array} \right) \, \text{Sin} \, [12.5608 \, t] \, - \, 51.26 \, \times \, (25.63 - 2.33316 \, \dot{\mathtt{i}}) \, \, e^{(1.78688 + 25.1216 \, \dot{\mathtt{i}}) \, \, t} \, \left( \, \left\{ \begin{array}{l} \text{Indeterminate} & t == 0 \\ 0 & \text{True} \end{array} \right) \, \text{Sin} \, [12.5608 \, t] \, - \, 51.26 \, \times \, (25.63 + 2.33316 \, \dot{\mathtt{i}}) \, \, e^{(1.78688 + 25.1216 \, \dot{\mathtt{i}}) \, \, t} \, \left( \, \left\{ \begin{array}{l} \text{Indeterminate} & t == 0 \\ 0 & \text{True} \end{array} \right) \, \text{Sin} \, [12.5608 \, t] \, - \, 51.26 \, \times \, (25.63 + 2.33316 \, \dot{\mathtt{i}}) \, \, e^{(1.78688 + 25.1216 \, \dot{\mathtt{i}}) \, t} \, \left( \begin{array}{l} \text{Indeterminate} & t == 0 \\ 0 & \text{True} \end{array} \right) \, \text{Sin} \, [12.5608 \, t] \, - \, 51.26 \, \times \, (25.63 + 2.33316 \, \dot{\mathtt{i}}) \, \, e^{(1.78688 + 25.1216 \, \dot{\mathtt{i}}) \, t} \, \left( \begin{array}{l} \text{Indeterminate} & t == 0 \\ 0 & \text{True} \end{array} \right) \, \text{Sin} \, [12.5608 \, t] \, - \, 51.26 \, \times \, (25.63 + 2.33316 \, \dot{\mathtt{i}}) \, \, e^{(1.78688 + 25.1216 \, \dot{\mathtt{i}}) \, t} \, \left( \begin{array}{l} \text{Indeterminate} & t == 0 \\ 0 & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} \\ 0 & \text{Indeterminate} \\ 0 & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} \\ 0 & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} \\ 0 & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} \\ 0 & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} \\ 0 & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} \\ 0 & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} & \text{Indeterminate} \\ 0 & \text{Indeterminate}
                        (\textbf{0.0925618} + \textbf{0.508399} \pm) \ \textbf{2.71828}^{\textbf{1.78688}} \pm e^{\,(\textbf{0.+12.5608}\,\pm)} \pm \left( \left\{ \begin{array}{l} \textbf{Indeterminate} & \textbf{t} == \textbf{0} \\ \textbf{0} & \textbf{True} \end{array} \right)
                          \sin[12.5608 t]^2 + (315.547 - 44.8894 i) e^{(0.+12.5608 i) t} \cos[12.5608 t] UnitStep[t] -
                   (1.21121 \times 10^{-14} - 22.8989 i) e^{1.78688 t} Cos[12.5608 t] UnitStep[t] +
                  (321.933 - 22.8989 i) e^{(1.78688+25.1216 i) t} Cos[12.5608 t] UnitStep[t] -
                   (476.514 - 44.8894 \pm) 2.71828^{1.78688 \pm} e^{(0.+12.5608 \pm) \pm} \cos[12.5608 \pm]^{2}  UnitStep[t] +
                   (44.8894 + 315.547 i) e^{(0.+12.5608 i) t} Sin[12.5608 t] UnitStep[t] -
                  (9.61671 \times 10^{-15} + 78.8546 \text{ i}) \text{ e}^{1.78688 \text{ t}} \text{ Sin} [12.5608 \text{ t}] \text{ UnitStep} [\text{t}] +
                  (45.7978 + 400.788\,\dot{\mathtt{i}})\,\,\,\mathrm{e}^{\,(1.78688 + 25.1216\,\dot{\mathtt{i}})\,\,t}\,\mathsf{Sin}\,[\,12.5608\,t\,]\,\,\mathsf{UnitStep}\,[\,t\,]\,\,-\,\,(91.5956 + 643.867\,\,\dot{\mathtt{i}}\,)
                        \textbf{2.71828}^{\textbf{1.78688}\,\textbf{t}}\,\,\text{e}^{\,(\textbf{0.+12.5608}\,\textbf{i}\,)\,\,\textbf{t}}\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{Sin}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{Cos}\,[\,\textbf{12.5608}\,\textbf{t}\,]\,\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf{t}\,]\,\,+\,\,\text{UnitStep}\,[\,\textbf
                  (325.062 - 0.90845 \pm) \ \ 2.71828^{1.78688 \, t} \, e^{\,(0.+12.5608 \, \pm) \, \, t} \, \, \text{Sin} \, [\, 12.5608 \, t\,]^{\, 2} \, \, \text{UnitStep} \, [\, t\,] \, \, \bigg) \bigg\}
```

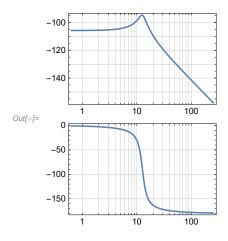
ln[\*]:= acclResUnitPlot = Plot[acclresUnit, {t, 0, tf}, PlotRange  $\rightarrow$  All, GridLines  $\rightarrow$  Automatic, AxesLabel  $\rightarrow$  {"time (s)", "zdotdot (m/s^2)"}, PlotStyle  $\rightarrow$  Red]



# In[@] := Show[acclResUnitPlot, zddotPlotUnit]

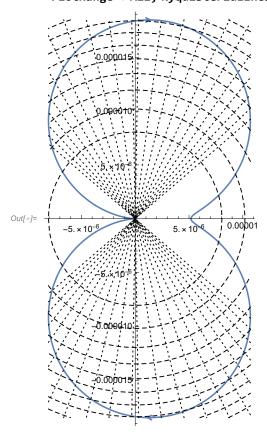


# log[\*]:= BodePlot[Gs, GridLines $\rightarrow$ Automatic, StabilityMarginsStyle $\rightarrow$ {Red, Green}]

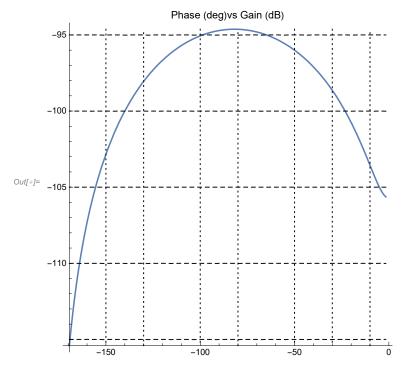


```
\label{eq:local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_
```

 $log(*) := NyquistPlot[TransferFunctionModel[Gs, s], StabilityMargins <math>\rightarrow \{gm, pm\}, f(*) := f($  $Stability \texttt{MarginsStyle} \rightarrow \{\texttt{Directive}[\texttt{Red}, \texttt{Thick}], \texttt{Directive}[\texttt{Green}, \texttt{Thick}]\},$ PlotRange → All, NyquistGridLines → Automatic]

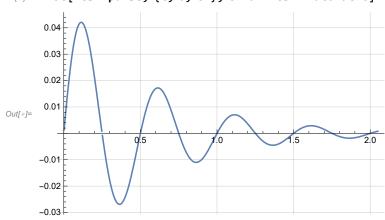


# In[\*]:= NicholsPlot[TransferFunctionModel[Gs, s], PlotLabel → "Phase (deg) vs Gain (dB)", NicholsGridLines → Automatic, PlotRange → All]



 $\begin{array}{l} \textit{In[o]:=} \ \ \textbf{resImpulse} = \textbf{OutputResponse}[\textbf{TransferFunctionModel[Gs,s], 80 * 9.81 DiracDelta[t],t]} \\ \textit{Out[o]:=} \ \left\{ \ (\textbf{0.} + \textbf{0.} \ \dot{\textbf{1.}}) \ + \ \textbf{0.} \ \textbf{0.$ 

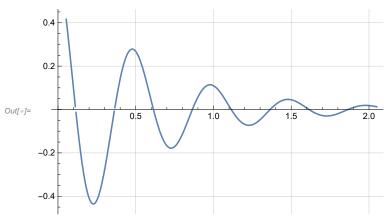
ln[\*]:= Plot[resImpulse, {t, 0, tf}, GridLines  $\rightarrow$  Automatic]



#### In[@]:= velresImpulse = Dt[resImpulse, t]

```
Out[*]= \{0.0008333333 e^{-1.78688 t} ((5.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos [12.5608 t] \text{ DiracDelta[t]} + (5.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos [12.5608 t] \}
                                                                            (784.8 - 7.54449 \times 10^{-14} i) \cos [12.5608 t] \text{ HeavisideTheta}[t] +
                                                                            (62.4801 - 6.00637 \times 10^{-15} i) DiracDelta[t] Sin[12.5608 t] -
                                                                              (6.84017 \times 10^{-14} - 2.73607 \times 10^{-13} i) HeavisideTheta[t] Sin[12.5608 t]) - 0.00148907
                                                         e^{-1.78688 t} ((0.+0.i) + (5.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.+0.i) + (0.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.+0.i) + (0.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.+0.i) + (0.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.+0.i) + (0.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.+0.i) + (0.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.+0.i) + (0.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.44564 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.44564 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.44564 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.44564 \times 10^{-14} i) \cos[12.5608 t] \text{ HeavisideTheta[t]} + (0.44564 \times 10^{-14} i) \cos[12.5608 t] + (0
                                                                            (62.4801 - 6.00637 \times 10^{-15} i) HeavisideTheta[t] Sin[12.5608 t])
```

#### ln[\*]:= Plot[velresImpulse, {t, 0, tf}, GridLines → Automatic]



#### In[\*]:= acclresImpulse = Dt[velresImpulse, t]

```
Out[*] = \left\{-0.00297814 \, e^{-1.78688 \, \text{t}} \, \left( \left(5.44564 \times 10^{-15} - 2.17826 \times 10^{-14} \, \text{i} \right) \, \text{Cos} \, [12.5608 \, \text{t}] \, \, \text{DiracDelta} \, [\,\text{t}\,] + \right\} \right\} = \left\{-0.00297814 \, e^{-1.78688 \, \text{t}} \, \left( \left(5.44564 \times 10^{-15} - 2.17826 \times 10^{-14} \, \text{i} \right) \, \text{Cos} \, [\,12.5608 \, \text{t}\,] \, \, \text{DiracDelta} \, [\,\text{t}\,] + \right\} \right\} = \left\{-0.00297814 \, e^{-1.78688 \, \text{t}} \, \left( \left(5.44564 \times 10^{-15} - 2.17826 \times 10^{-14} \, \text{i} \right) \, \text{Cos} \, [\,12.5608 \, \text{t}\,] \, \, \text{DiracDelta} \, [\,\text{t}\,] + \right\} \right\} = \left\{-0.00297814 \, e^{-1.78688 \, \text{t}} \, \left( \left(5.44564 \times 10^{-15} - 2.17826 \times 10^{-14} \, \text{i} \right) \, \text{Cos} \, [\,12.5608 \, \text{t}\,] \, \, \text{DiracDelta} \, [\,\text{t}\,] + \right\} \right\} = \left\{-0.00297814 \, e^{-1.78688 \, \text{t}} \, \left( \left(5.44564 \times 10^{-15} - 2.17826 \times 10^{-14} \, \text{i} \right) \, \, \text{Cos} \, [\,12.5608 \, \text{t}\,] \, \, \text{DiracDelta} \, [\,\text{t}\,] + \right\} \right\} = \left\{-0.00297814 \, e^{-1.786888 \, \text{t}} \, \left( \left(5.44564 \times 10^{-15} - 2.17826 \times 10^{-14} \, \text{i} \right) \, \, \text{Cos} \, [\,12.5608 \, \text{t}\,] \, \, \text{DiracDelta} \, [\,\text{t}\,] + \right\} \right\} = \left\{-0.00297814 \, e^{-1.786888 \, \text{t}} \, \left( \left(5.44564 \times 10^{-15} - 2.17826 \times 10^{-14} \, \text{i} \right) \, \, \text{Cos} \, [\,12.5608 \, \text{t}\,] \, \, \text{DiracDelta} \, [\,\text{t}\,] + \right\} \right\} = \left\{-0.00297814 \, e^{-1.786888 \, \text{t}} \, \left( \left(5.44564 \times 10^{-15} - 2.17826 \times 10^{-14} \, \text{i} \right) \, \, \text{Cos} \, [\,12.5608 \, \text{t}\,] \, \, \text{DiracDelta} \, [\,\text{t}\,] + \right\} \right\}
                                     (784.8 - 7.54449 \times 10^{-14} i) Cos[12.5608t] HeavisideTheta[t] +
                                     (62.4801 - 6.00637 \times 10^{-15} i) \text{ DiracDelta[t] Sin[12.5608t]} -
                                      (6.84017 \times 10^{-14} - 2.73607 \times 10^{-13} i) HeavisideTheta[t] Sin[12.5608 t]) + 0.00266079
                             (62.4801 - 6.00637 \times 10^{-15} i) HeavisideTheta[t] Sin[12.5608 t]) +
                        0.000833333 e^{-1.78688 t} ((1569.6 - 1.5089 \times 10^{-13} i) Cos[12.5608 t] DiracDelta[t] - 1.5089 \times 10^{-13} i)
                                      (8.5918 \times 10^{-13} - 3.43672 \times 10^{-12} i) Cos[12.5608 t] HeavisideTheta[t] -
                                      (1.36803 \times 10^{-13} - 5.47213 \times 10^{-13} i) DiracDelta[t] Sin[12.5608 t] -
                                      (9857.72 - 9.47648 × 10<sup>-13</sup> i) HeavisideTheta[t] Sin[12.5608 t] +
                                      (5.44564 \times 10^{-15} - 2.17826 \times 10^{-14} i) \cos[12.5608t] \text{ DiracDelta}'[t] +
                                      (62.4801 - 6.00637 \times 10^{-15} i) Sin[12.5608 t] DiracDelta'[t])
```

 $ln[\circ]:=$  Plot[acclresImpulse, {t, 0, tf}, GridLines  $\rightarrow$  Automatic]

