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A Data-Driven Two-Stage Distributionally Robust Planning Tool for Sustainable Microgrids

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Motivation and Background

Input

Microgrid Planning Tool

Output

Network Topology

Forecast demand

Forecast production

Investment candidates

Minimise Total Costs

Adequacy

Security

Resilience



Infeasible!

Uncertain!

Uncertainty Management

Stochastic Optimisation

Distributionally Robust Optimisation

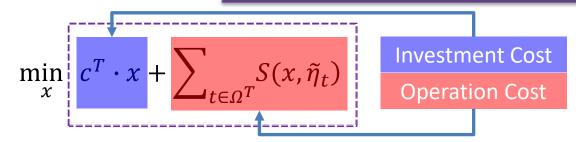
Robust Optimisation





Problem Formulation

Deterministic Model

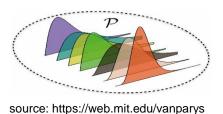


Uncertainty Vector

$$S(x, \tilde{\eta}_t) = \min_{y_t} \{ d^T \cdot y_t | E(x) + F \cdot y_t \ge G(x) \cdot \tilde{\eta}_t \}$$

Distributionally Robust Model

Ambiguity Set



$$\Theta_{W} = \{ \mathbb{P} \in \Xi(\Omega) : dist_{W}(\mathbb{P}, \widehat{\mathbb{P}}_{N_{s}}) \leq \rho \}$$

Wasserstain Metric

$$\min_{x} c^{T} \cdot x + \max_{\mathbb{P} \in \Theta_{W}} \mathbb{E} \left[\sum_{t \in \Omega^{T}} S(x, \tilde{\eta}_{t}) \right]$$

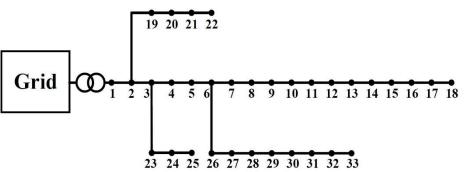
A tractable MILP counterpart can be obtained by using the duality theory *.





^{*} G. A. Hanasusanto and D. Kuhn, Oper. Res., vol. 66, no. 3, pp. 849-869, 2018.

Case Study

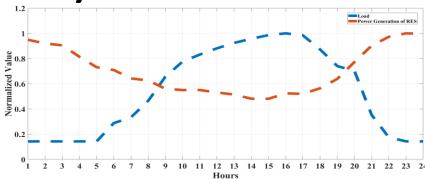


Total Costs of Different Planning Models

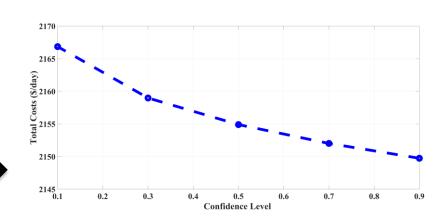
Model	Total Costs (\$/Day)	Computation Time (s)
Deterministic	1667	34
Distributionally robust	2155	128
Robust	2333	184

Total Costs in DR-MIRP vs. Number of Training Samples

Training Sample (#)	Total Costs (\$/Day)	Computation Time (s)
5	2155	128
10	2141	295



Daily Patterns of Loads and RES Power Generations



Total Costs vs. Values of Confidence Level





Conclusions

- Bridge between SO and RO
 - Present a DRO-based microgrid planning tool
- Introduce a tractable MILP counterpart
- Control conservatism-level by
 - Increasing/decreasing the number of training samples
 - Increasing/decreasing the confidence level

Future works

- Implement the proposed model in PyEPLAN
- Increase the accuracy of network modeling
- Include static/dynamic security constraints under islanding



