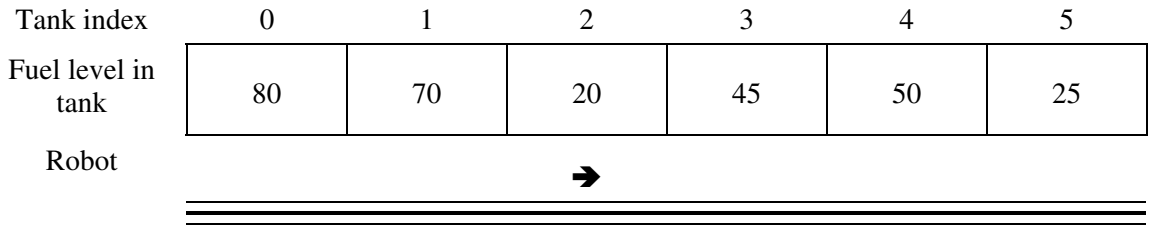
3. A fuel depot has a number of fuel tanks arranged in a line and a robot that moves a filling mechanism back and forth along the line so that the tanks can be filled. A fuel tank is specified by the `FuelTank` interface below.

```
public interface FuelTank
{
  /** @return an integer value that ranges from 0 (empty) to 100 (full) */
  int getFuelLevel();
}
```

A fuel depot keeps track of the fuel tanks and the robot. The following figure represents the tanks and the robot in a fuel depot. The robot, indicated by the arrow, is currently at index 2 and is facing to the right.



The state of the robot includes the index of its location and the direction in which it is facing (to the right or to the left). This information is specified in the `FuelRobot` interface as shown in the following declaration.

```
public interface FuelRobot
{
  /** @return the index of the current location of the robot */
  int getCurrentIndex();


  /** Determine whether the robot is currently facing to the right
   *  @return true  if the robot is facing to the right (toward tanks with larger indexes)
   *          false if the robot is facing to the left (toward tanks with smaller indexes)
   */
  boolean isFacingRight();


  /** Changes the current direction of the robot */
  void changeDirection();


  /** Moves the robot in its current direction by the number of locations specified.
   *  @param numLocs the number of locations to move. A value of 1 moves
   *                 the robot to the next location in the current direction.
   *          Precondition: numLocs > 0
   */
  void moveForward(int numLocs);
}
```

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A fuel depot is represented by the `FuelDepot` class as shown in the following class declaration.

```
public class FuelDepot
{
  /** The robot used to move the filling mechanism */
  private FuelRobot filler;

  /** The list of fuel tanks */
  private List<FuelTank> tanks;

  /** Determines and returns the index of the next tank to be filled.
   *  @param threshold fuel tanks with a fuel level ≤ threshold may be filled
   *  @return index of the location of the next tank to be filled
   *  Postcondition: the state of the robot has not changed
   */
  public int nextTankToFill(int threshold)
  {  /* to be implemented in part (a) */  }


  /** Moves the robot to location locIndex.
   *  @param locIndex the index of the location of the tank to move to
   *         Precondition: 0 ≤ locIndex < tanks.size()
   *  Postcondition: the current location of the robot is locIndex
   */
  public void moveToLocation(int locIndex)
  {  /* to be implemented in part (b) */  }

  // There may be instance variables, constructors, and methods that are not shown.
}
```

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