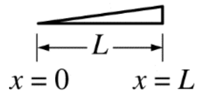
$$\lambda = \left(\frac{2M}{L^2}\right)x$$



3. A triangular rod, shown above, has length L, mass M, and a nonuniform linear mass density given by the equation $\lambda = \dfrac{2M}{L^2}x$, where x is the distance from one end of the rod.

   (a) Using integral calculus, show that the rotational inertia of the rod about its left end is $ML^2/2$.

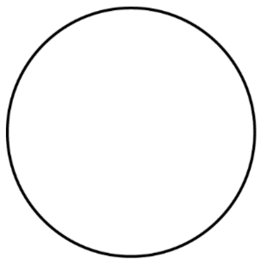


Figure 1

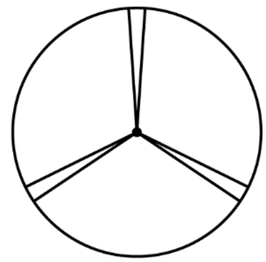


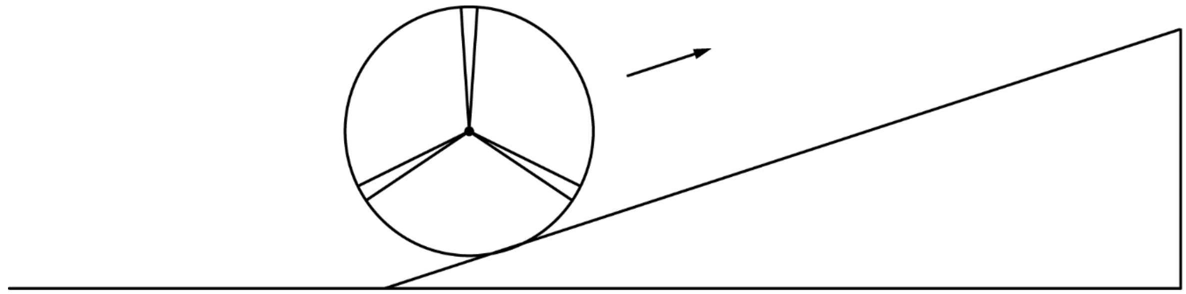
Figure 2

The thin hoop shown above in Figure 1 has a mass M, radius L, and a rotational inertia around its center of ML^2. Three rods identical to the rod from part (a) are now fastened to the thin hoop, as shown in Figure 2 above.

   (b) Derive an expression for the rotational inertia I_{tot} of the hoop-rods system about the center of the hoop. Express your answer in terms of M, L, and physical constants, as appropriate.

The hoop-rods system is initially at rest and held in place but is free to rotate around its center. A constant force F is exerted tangent to the hoop for a time Δt.

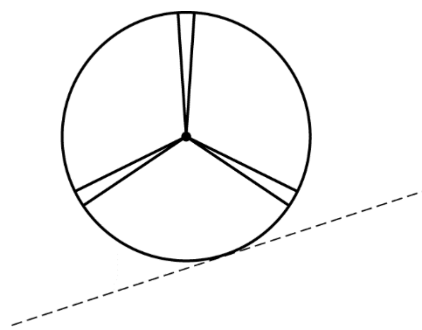
   (c) Derive an expression for the final angular speed ω of the hoop-rods system. Express your answer in terms of M, L, F, Δt, and physical constants, as appropriate.



The hoop-rods system is rolling without slipping along a level horizontal surface with the angular speed ω found in part (c). At time $t = 0$, the system begins rolling without slipping up a ramp, as shown in the figure above.

(d)

i. On the figure of the hoop-rods system below, draw and label the forces (not components) that act on the system. Each force must be represented by a distinct arrow starting at, and pointing away from, the point at which the force is exerted on the system.



ii. Justify your choice for the direction of each of the forces drawn in part (d)i.

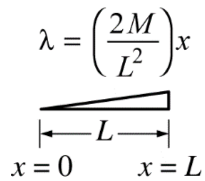
(e) Derive an expression for the change in height of the center of the hoop from the moment it reaches the bottom of the ramp until the moment it reaches its maximum height. Express your answer in terms of M, L, I_{tot}, ω, and physical constants, as appropriate.

STOP

END OF EXAM

Question 3

15 points total | **Distribution of points**



A triangular rod, shown above, has length L, mass M, and a nonuniform linear mass density given by the equation $\lambda = \frac{2M}{L^2}x$, where x is the distance from one end of the rod.

(a) 3 points

Using integral calculus, show that the rotational inertia of the rod about its left end is $ML^2/2$.

For relating x to r properly in an integral to calculate the moment of inertia		1 point
$I = \int r^2 dm = \int x^2 dm$		
For correctly using the linear mass density to substitute into the equation above		1 point
$m = \int \lambda dx = \int \left(2M/L^2\right) x dx \therefore dm = \left(2M/L^2\right) x dx$		
$I = \int \left(2M/L^2\right) x^3 dx$		
For integrating using the correct limits or constant of integration		1 point
$I = \int_{x=0}^{x=L} \left(2M/L^2\right) x^3 dx = \left[\frac{\left(2M/L^2\right) x^4}{4}\right]_{x=0}^{x=L} = \frac{2M}{L^2}\left(\frac{L^4}{4} - 0\right) = ML^2/2$		

Question 3 (continued)

Distribution of points

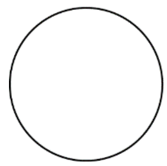


Figure 1

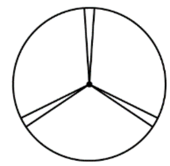


Figure 2

The thin hoop shown above in Figure 1 has a mass M, radius L, and a rotational inertia around its center of ML^2. Three rods identical to the rod from part (a) are now fastened to the thin hoop, as shown in Figure 2 above.

(b) 2 points

Derive an expression for the rotational inertia I_{tot} of the hoop-rods system about the center of the hoop. Express your answer in terms of M, L, and physical constants, as appropriate.

For setting the total rotational inertia for the hoop-rod system equal to the sum of the rotational inertias of the hoop and the three rods		1 point
$I = 3I_{rod} + I_{hoop}$		
$I = 3\left(ML^2/2\right) + ML^2$		
For a correct answer with work		1 point
$I = \frac{5}{2}ML^2$		

The hoop-rods system is initially at rest and held in place but is free to rotate around its center. A constant force F is exerted tangent to the hoop for a time Δt.

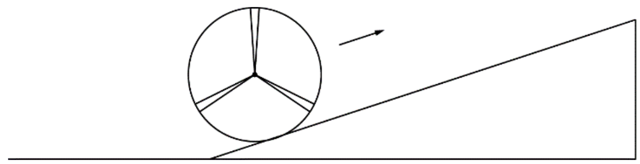
(c) 3 points

Derive an expression for the final angular speed ω of the hoop-rods system. Express your answer in terms of M, L, F, Δt, and physical constants, as appropriate.

For using an appropriate equation to determine the final angular speed of the hoop		1 point
$\tau\Delta t = I(\omega_2 - \omega_1)$		
$Fr\Delta t = I\omega$		
$\omega = \frac{Fr\Delta t}{I}$		
For relating the lever arm to the length of the rod		1 point
$\omega = \frac{FL\Delta t}{I}$		
For correct substitution from part (b)		1 point
$\omega = \frac{FL\Delta t}{\left(\frac{5}{2}\right)ML^2} = \frac{2F\Delta t}{5ML}$		

Question 3 (continued)

Distribution of points

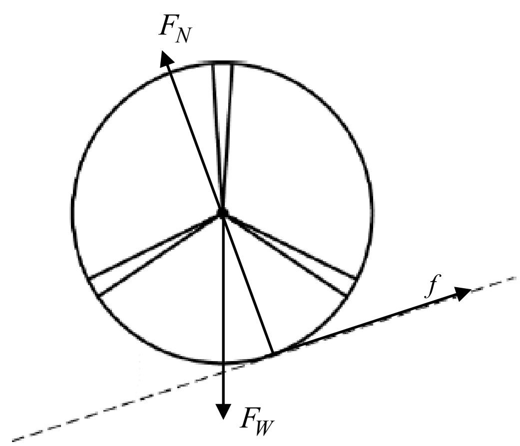


The hoop-rods system is rolling without slipping along a level horizontal surface with the angular speed ω found in part (c). At time $t = 0$, the system begins rolling without slipping up a ramp, as shown in the figure above.

(d)

i. 3 points

On the figure of the hoop-rods system below, draw and label the forces (not components) that act on the system. Each force must be represented by a distinct arrow starting at, and pointing away from, the point at which the force is exerted on the system.



For drawing the weight of the hoop-rod system in the correct direction		1 point
For drawing the normal force in the correct direction		1 point
For drawing the frictional force in the correct direction		1 point
Note: A maximum of two points can be earned if there are any extraneous vectors or any vector has an incorrect point of exertion.		

Question 3 (continued)

Distribution of points

ii. 1 point

Justify your choice for the direction of each of the forces drawn in part (d)(i).

For a correct justification of the direction of the forces in part (d)(i)		1 point
Example: The normal force is always perpendicular to the surface, so it will be directed up and to the left. The gravitational force is always vertically downward. The friction will be opposite of the direction of rotation; therefore, it is directed up the incline.		

(e) 3 points

Derive an expression for the change in height of the center of the hoop from the moment it reaches the bottom of the ramp until the moment it reaches its maximum height. Express your answer in terms of M, L, I_{tot}, ω, and physical constants, as appropriate.

For including both linear and rotational kinetic energy in an equation for the conservation of energy to determine the final height of the hoop		1 point
$K_1 = U_{g2}$		
$\frac{1}{2}mv^2 + \frac{1}{2}I\omega^2 = mgH$		
$H = \dfrac{\frac{1}{2}mv^2 + \frac{1}{2}I\omega^2}{mg}$		
For correct substitution of $v = L\omega$		1 point
$H = \dfrac{\frac{1}{2}m(L\omega)^2 + \frac{1}{2}I_{tot}\omega^2}{mg}$		
$H = \dfrac{\frac{1}{2}\left(m_{tot}L^2 + I_{tot}\right)\omega^2}{m_{tot}g}$		
For correct substitution of inertias into energy equation		1 point
$H = \dfrac{\frac{1}{2}\left((3M + M)L^2 + I_{tot}\right)\omega^2}{(3M + M)g} = \dfrac{\left(4ML^2 + I_{tot}\right)\omega^2}{8Mg}$		