

# Design document

**Group Nr. 3**

**Timur Ali Basnakajev  
Tobias König  
Jessica Marban  
Patrick Neumann**

# Contents

1	Project description	3
2	Software architecture and design	4
3	Program flowchart	5
4	Hazard identification	6
5	Threat identification	7
6	Requirements	8

# 1 Project description

## 1.1 Problem description

When the CO2 level in a room reaches a certain level, a window should automatically open and a fresh air fan should switch on. After a certain lower CO2 level is reached and a certain run-on time has elapsed, the window is closed again and the fan is switched off again.

## 1.2 Hardware

1. MH-Z19 CO2 Sensor
2. Arduino with bluetooth module
3. Raspberry
4. Electric motor

## 1.3 Hardware

1. Analog input for measuring the CO2 contentr
2. Digital output for controlling a window opener
3. Digital output to control a fan

## 1.4 Schema

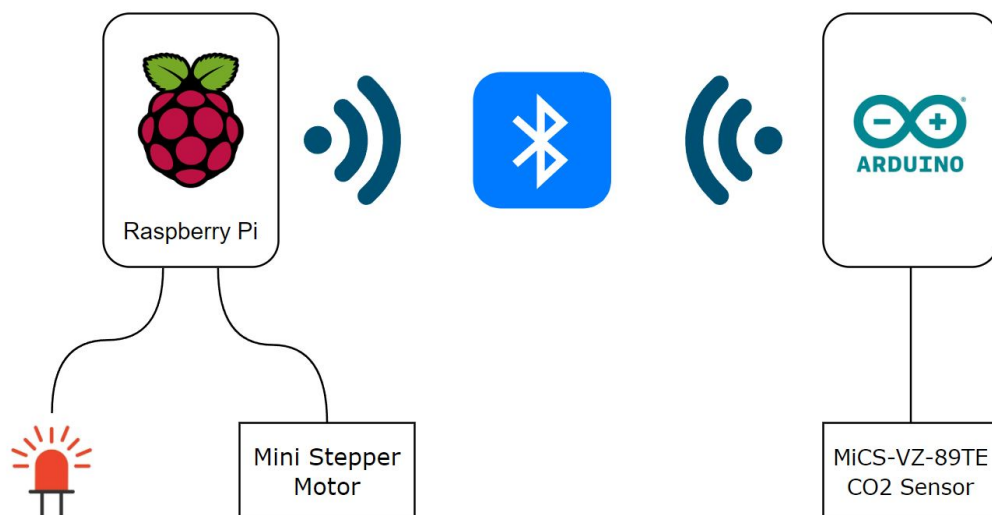


Figure 1: system description

## **2 Software architecture and design**

### **2.1 Software modules**

#### **Safety related modules**

1. Modul x:  
Description:  
Functions:  
Data:  
Requirements see: 1.1., ....

#### **Security related modules**

#### **Modules with no influence on Safety and Security**

### **2.2 Libraries**

Description of used function with parameters.

### **2.3 Interrupts**

Definition of priorities.

### **2.4 Pinout**

### 3 Program flowchart

Hier bitte Sequenzdiagramme, bzw. Programmablaufdiagramme

## **4 Hazard identification**

### **4.1 Identified hazards and countermeasures**

1. Hazard 1:

Co2 sensor delivers incorrect values 2.

2. Hazard 2:

The window is stuck and does not open or close 3.

3. Hazard 3:

Arduino fails 4.

### **4.2 Identified hazards without countermeasures**

1. Hazard 1:

The Co2 sensor fails and does not provide data

2. Hazard 2:

The power supply fails

3. Hazard 3:

The engine fails

## 5 Threat identification

### 5.1 Identified threats and countermeasures

1. Threat 1:
2. Threat 2:
3. Threat 3:

### 5.2 Identified threats without countermeasures

1. Threat 1:
2. Threat 2:
3. Threat 3:

## 6 Requirements

### 6.1 Safety related requirements

1. Requirement:  
At program start all safety related functions must be tested.
  - 1.1. Requirement:  
If an error occurs during program start, this must be indicated by an LED (flashing at 1 second intervals)
  - 1.2. Requirement:  
Communication between Raspberry and Arduino must be established.
  - 1.3. Requirement:  
When the system starts, the window must be successfully opened and closed once.
2. Requirement:  
The values of the CO2 sensor must be continuously checked for their validity 1:
  - 2.1. Requirement:  
If the sensor value is outside the typical range, the value must be marked as invalid.
  - 2.2. Requirement:  
If the sensor values are invalid an email must be sent.
3. Requirement:  
It must be checked whether the window has been opened or closed sufficiently 2:
  - 3.1. Requirement:  
If the measured position of the stepper motor deviates by 5 mm when opening, the motor must stop immediately and go into error state (obstacle was detected).
  - 3.2. Requirement:  
If the measured position of the stepper motor deviates by 5 mm when closing, the motor must stop immediately and the window must open again (obstacle has been detected).



3.3. Requirement:

If an obstacle is detected during opening or closing, the system must report an error (email and LED).

4. Requirement:

It must be checked whether the Arduino is working properly 1:

4.1. Requirement:

The communication between Raspberry and Arduino must be checked cyclically (10 second interval).

4.2. Requirement:

If the communication between the Raspberry and the Arduino is interrupted for more than 30 seconds, the system must go into error state (Email and LED).

## 6.2 Security related requirements

1. Requirement:

The communication between the Raspberry and the Arduino must be encrypted.

2. Requirement:

The Raspberry PI must be hardened against cybersecurity attacks.

## 6.3 Requirements with no influence on Safety and Security

1. Requirement:

The system should be installed in an inaccessible location.