

# HW9

November 13, 2020

## Numerical Computation: HW9

Andrew Pickner I worked alone on this assignment.

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```
[1]: # global imports

import numpy as np

%matplotlib inline
import matplotlib.pyplot as plt
plt.style.use('seaborn-whitegrid')

[2]: def get_error(obs, truth):
    diff = np.subtract(obs, truth)
    return np.sqrt(np.linalg.norm(diff, ord=2) / np.linalg.norm(truth, ord=2))

def get_size(matrix):
    return matrix.shape[0], matrix.shape[1]

def is_symmetric(matrix):
    if matrix.shape[0] == matrix.shape[1]:
        if isinstance(matrix[0][0], float):
            return np.allclose(matrix, matrix.T, atol=1e-05)
        return np.array_equal(matrix, matrix.T)
    return False

def get_rank(matrix):
    if is_symmetric(matrix):
        return np.linalg.matrix_rank(matrix, tol=None, hermitian=True)
    return np.linalg.matrix_rank(matrix, tol=None, hermitian=False)

def get_condition_number(matrix):
    return np.linalg.cond(matrix)

# reworked a function from homework 5 where we use cholesky or LU decomp.
# → depending on what
```

```

def NE_solve1(A,b):
    if is_symmetric(A) and get_rank(A) == get_size(A)[1]:
        print("NE used: Cholesky")
        return cholesky_solve(A,b)
    print("NE used: LU")
    return lu_solve(A,b)

# reworked a function from homework 5 where we use cholesky or LU decomp.
# → depending on what
def NE_solve2(A,b):
    if is_symmetric(A) and get_rank(A) == get_size(A)[1]:
        print("NE used: Cholesky")
        return cholesky_solve2(A,b)
    print("NE used: LU")
    return lu_solve2(A,b)

def lu(A):
    # n = number of rows
    n = A.shape[0]
    U = A.copy()
    L = np.eye(n, dtype=np.double)
    # Loop over rows
    for i in range(n):
        # Eliminate entries below i with row operations
        # on U and reverse the row operations to
        # manipulate L
        factor = U[i+1:, i] / U[i, i]
        L[i+1:, i] = factor
        U[i+1:] -= factor[:, np.newaxis] * U[i]
    return L, U

def lu_solve(A, b):
    new_A = np.matmul(A.T, A)
    new_b = np.matmul(A.T, b)
    L, U = lu(new_A)
    # solve Ly=b for y using forward sub
    y = forward_sub(L, new_b)
    # then solve Ux=y for x using back sub
    return back_sub(U, y)
    # seemed rather consistent with the scipy method so I kept the forward and
    # backward that I have.
    # return solve_triangular(U, b)

def lu_solve2(A, b):
    L, U = lu(A)
    # solve Ly=b for y using forward sub
    y = forward_sub(L, b)

```

```

    # then solve  $Ux=y$  for  $x$  using back sub
    return back_sub(U, y)
    # seemed rather consistent with the scipy method so I kept the forward and
    ↪ backward that I have.
    # return solve_triangular(U, b)

def cholesky(A):
    # n = number of rows
    n = A.shape[0]
    L = np.zeros((n, n), dtype=np.double)
    for k in range(n):
        L[k, k] = np.sqrt(A[k, k] - np.sum(L[k, :] ** 2))
        L[(k+1):, k] = (A[(k+1):, k] - L[(k+1):, :] @ L[:, k]) / L[k, k]
    return L

def cholesky_solve(A, b):
    new_A = np.matmul(A.T, A)
    new_b = np.matmul(A.T, b)
    L = cholesky(new_A)
    # y = np.linalg.solve(L, new_b)
    # return np.linalg.solve(L.T, y)
    # just special case of LU decomp where  $U = L.T$ 
    y = forward_sub(L, new_b)
    return back_sub(L.T, y)

def cholesky_solve2(A, b):
    L = cholesky(A)
    # y = np.linalg.solve(L, new_b)
    # return np.linalg.solve(L.T, y)
    # just special case of LU decomp where  $U = L.T$ 
    y = forward_sub(L, b)
    return back_sub(L.T, y)

def forward_sub(L, b):
    # n = number of rows
    n = L.shape[0]
    # allocating space for the solution vector
    y = np.zeros_like(b, dtype=np.double);
    #Here we perform the forward-substitution.
    #Initializing with the first row.
    y[0] = b[0] / L[0, 0]
    #Looping over rows in reverse (from the bottom up),
    #starting with the second to last row, because the
    #last row solve was completed in the last step.
    for i in range(1, n):
        y[i] = (b[i] - np.dot(L[i, :i], y[:i])) / L[i, i]
    return y

```

```

def back_sub(U, y):
    # n = number of rows
    n = U.shape[0]
    # allocating space for the solution vector
    x = np.zeros_like(y, dtype=np.double);
    #Here we perform the back-substitution.
    #Initializing with the last row.
    x[-1] = y[-1] / U[-1, -1]
    #Looping over rows in reverse (from the bottom up),
    #starting with the second to last row, because the
    #last row solve was completed in the last step.
    for i in range(n-2, -1, -1):
        x[i] = (y[i] - np.dot(U[i,i:], x[i:])) / U[i,i]
    return x

# 1 NE
def NE_solver1(A, b):
    return NE_solve1(A,b)

def NE_solver2(A, b):
    new_A = np.matmul(A.T, A)
    new_b = np.matmul(A.T, b)
    return NE_solve1(new_A,new_b)

# 2 QR
def QR_solver(A, b):
    Q, R = np.linalg.qr(A)
    return np.linalg.solve(R, Q.T.dot(b))

```

```
[3]: f = lambda x: np.sin(2 * np.pi * x) + np.cos(3 * np.pi * x)
```

```
[4]: num_points = 33
interval = -1, 1

xs = np.linspace(interval[0], interval[1], num=num_points)
```

```
[5]: # degree of p(x)
d = 7

# vandermonde matrix to represent our over-determined system
A = np.vander(xs, N=d+1, increasing=True)

# actual values of f(x) that were trying to approximate
ys = np.array([f(x) for x in xs])

# our coefficients for the polynomial of
```

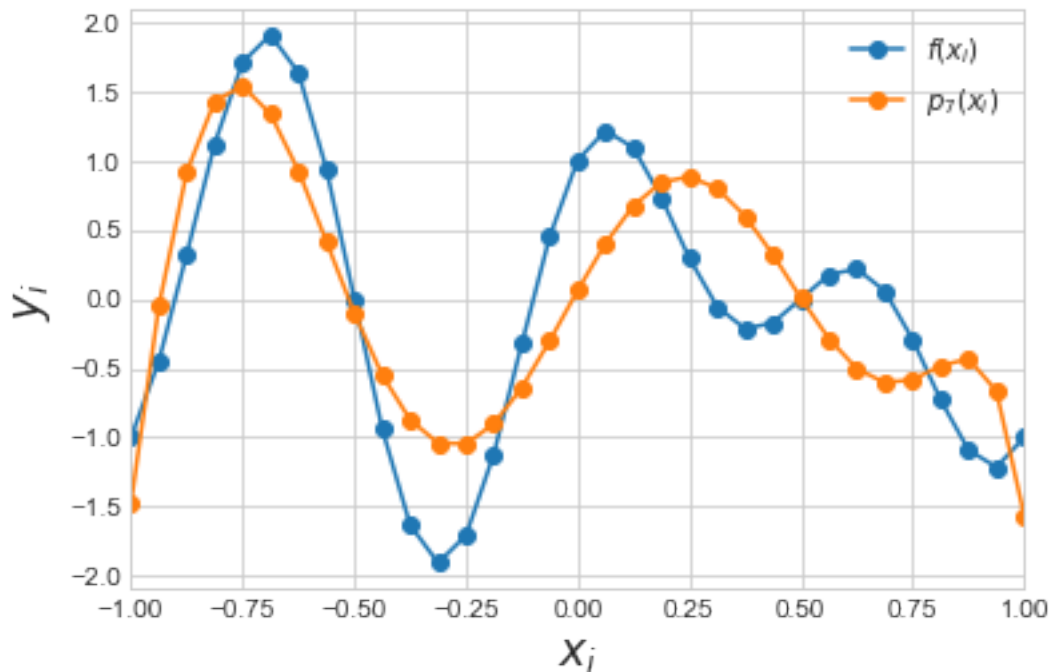
```
cs = np.linalg.lstsq(A, ys, rcond=None)[0]
```

```
[6]: def f_tilde(cs, x):  
      return sum([cs[i] * (x ** i) for i in range(len(cs))])
```

```
[7]: approx = [f_tilde(cs, x) for x in xs]
```

```
[8]: plt.plot(xs, ys, '-o', label='$f(x_{i})$')  
plt.plot(xs, approx, '-o', label='$p_7(x_{i})$')  
plt.xlim([interval[0], interval[1]])  
plt.xlabel("$x_{i}$", fontsize='xx-large')  
plt.ylabel("$y_{i}$", fontsize='xx-large')  
plt.legend()
```

```
[8]: <matplotlib.legend.Legend at 0x10b186710>
```



```
[9]: def generate_random_xs(low=-1, high=1, n=100):  
      l1 = np.append(np.array([low]), low * np.random.rand(n//2 - 1))  
      l2 = np.append(np.array([high]), high * np.random.rand(n//2 - 1))  
      ret = np.append(l1, l2)  
      return np.sort(ret)
```

```
[10]: new_size = 100
```

```

# i
new_xs = generate_random_xs()

# ii
new_ys = np.array([f(x) for x in new_xs])

```

```

[11]: d_upper = 31

qr_error = []
ne_error = []

for i in range(1, d_upper + 1):
    print(i)
    ai = np.vander(new_xs, N=i+1, increasing=True)

    qr_cs = QR_solver(ai, new_ys)
    ne_cs = NE_solver1(ai, new_ys)

    qr_approx = [f_tilde(qr_cs, x) for x in new_xs]
    ne_approx = [f_tilde(ne_cs, x) for x in new_xs]

    qr_error.append(get_error(qr_approx, new_ys))
    ne_error.append(get_error(ne_approx, new_ys))

```

```

1
NE used: LU
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NE used: LU
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NE used: LU
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NE used: LU
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NE used: LU
6
NE used: LU
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NE used: LU
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NE used: LU
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NE used: LU
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NE used: LU
11
NE used: LU
12

```

```

NE used: LU
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NE used: LU
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NE used: LU
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NE used: LU
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NE used: LU
31
NE used: LU

```

```

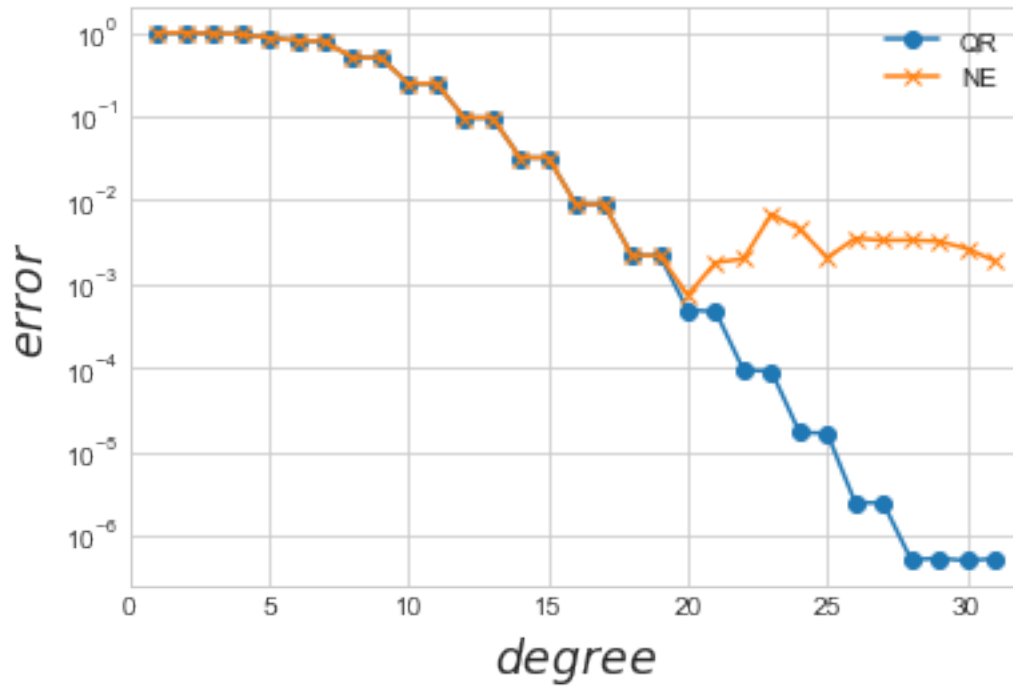
[12]: k = [n for n in range(1, d_upper + 1)]
plt.semilogy(k, qr_error, '-o', label='QR')
plt.semilogy(k, ne_error, '-x', label='NE')

plt.xlim([0, d_upper + 1])
plt.xlabel("$degree$", fontsize='xx-large')
plt.ylabel("$error$", fontsize='xx-large')

```

```
plt.legend()
```

```
[12]: <matplotlib.legend.Legend at 0x10d350650>
```



```
[13]: d_upper = 31

qr_error = []
ne_error = []

for i in range(1, d_upper + 1):
    print(i)
    ai = np.vander(new_xs, N=i+1, increasing=True)

    qr_cs = QR_solver(ai, new_ys)
    ne_cs = NE_solver2(ai, new_ys)

    qr_approx = [f_tilde(qr_cs, x) for x in new_xs]
    ne_approx = [f_tilde(ne_cs, x) for x in new_xs]

    qr_error.append(get_error(qr_approx, new_ys))
    ne_error.append(get_error(ne_approx, new_ys))
```

1

NE used: Cholesky



2  
NE used: Cholesky  
3  
NE used: Cholesky  
4  
NE used: Cholesky  
5  
NE used: Cholesky  
6  
NE used: Cholesky  
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NE used: Cholesky  
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NE used: LU  
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NE used: LU  
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NE used: LU  
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NE used: LU  
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NE used: LU  
25  
NE used: LU

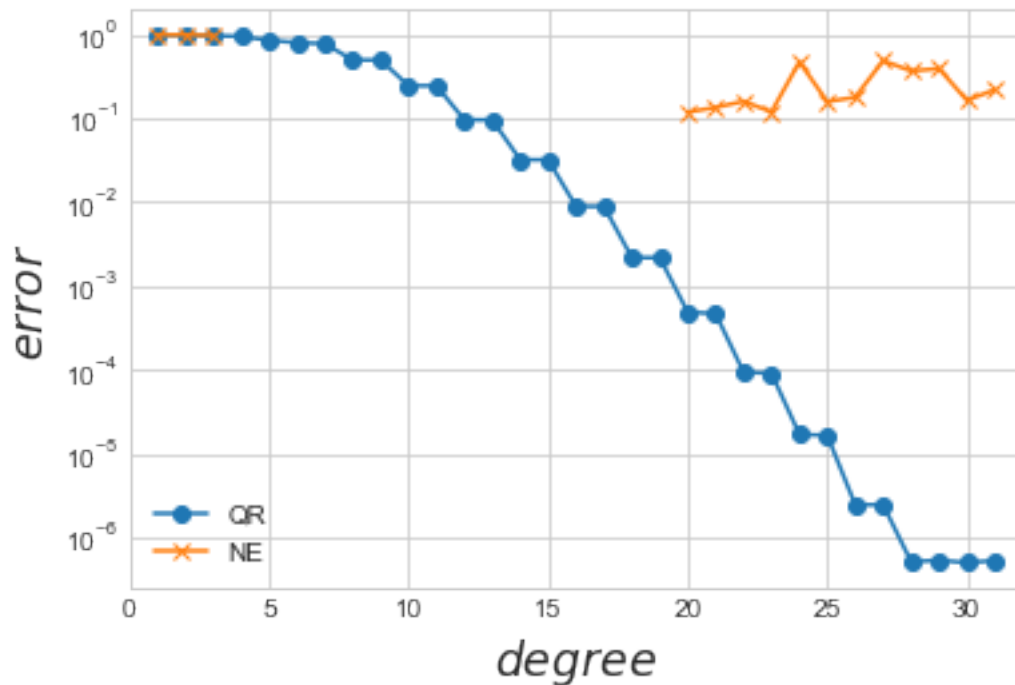
```
26
NE used: LU
27
NE used: LU
28
NE used: LU
29
NE used: LU
30
NE used: LU
31
NE used: LU
```

```
/usr/local/lib/python3.7/site-packages/ipykernel_launcher.py:79: RuntimeWarning:
invalid value encountered in sqrt
```

```
[14]: k = [n for n in range(1, d_upper + 1)]
plt.semilogy(k, qr_error, '-o', label='QR')
plt.semilogy(k, ne_error, '-x', label='NE')

plt.xlim([0, d_upper + 1])
plt.xlabel("$degree$", fontsize='xx-large')
plt.ylabel("$error$", fontsize='xx-large')
plt.legend()
```

```
[14]: <matplotlib.legend.Legend at 0x10d519f50>
```



---

### 0.0.1 BONUS

Here some US COVID case counts from back in March:

Days since Feb 29	Case count
1	89
2	105
3	125
4	159
5	227
6	331
7	444
8	564
9	728
10	1000
11	1267
12	1645
13	2204
14	2826
15	3485
17	7038

Derive the linear least-squares system whose solution contains the coefficients of a log-linear model for case count over time. Plot the data on top of the model on a log scale. How well does the log-linear model (which represents exponential growth) appear to model the growth in the case count? What was the case doubling time over this roughly two week period?

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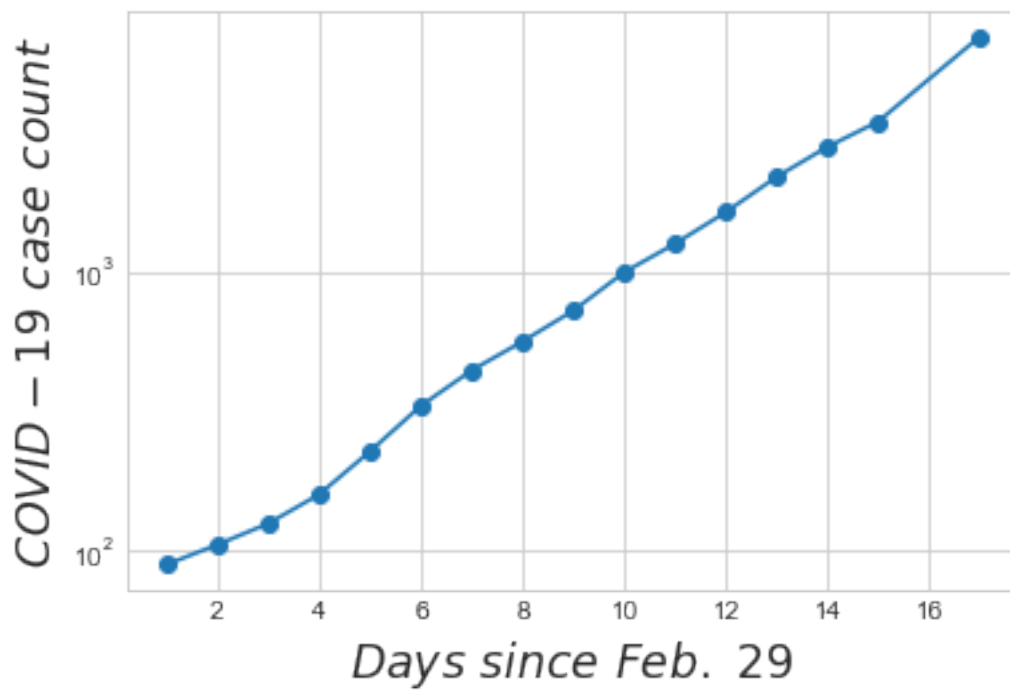
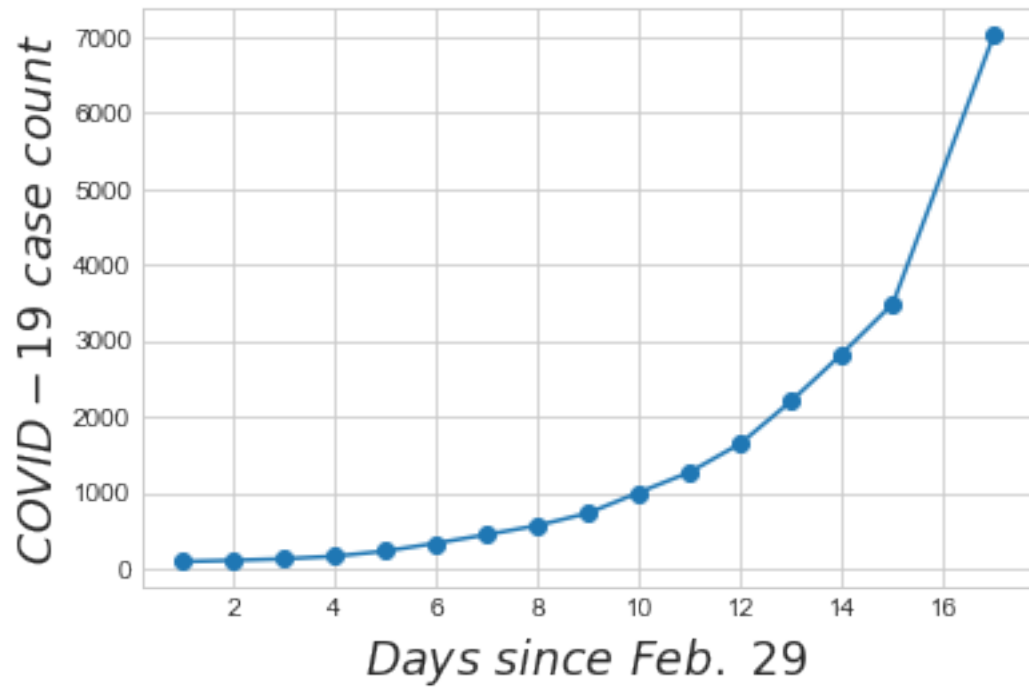
Essentially, we are going to need to ‘linearize’ a exponential model:  $y = c_1 e^{c_2 \cdot t}$ .

We can do this like so:  $\ln(y) = \ln(c_1) + c_2 \cdot t = k + c_2 \cdot t$

```
[15]: days_since_feb_29 = [day for day in range(1, 16)] + [17]
      case_count       = [89, 105, 125, 159, 227, 331, 444, 564, 728, 1000, 1267, 1645, 2204, 2826, 3485, 7038]

      plt.plot(days_since_feb_29, case_count, '-o')
      plt.xlabel("$Days\ since\ Feb.\ 29$", fontsize='xx-large')
      plt.ylabel("$COVID-19\ case\ count$", fontsize='xx-large')
      plt.show()
      plt.semilogy(days_since_feb_29, case_count, '-o')
      plt.xlabel("$Days\ since\ Feb.\ 29$", fontsize='xx-large')
      plt.ylabel("$COVID-19\ case\ count$", fontsize='xx-large')
```

```
plt.show()
```



```
[16]: b = np.array([np.log(y) for y in case_count])
      print(b)
      A = np.array([[float(1), float(x)] for x in days_since_feb_29])
      print(A)

[4.48863637 4.65396035 4.82831374 5.0689042  5.42495002 5.80211838
 6.09582456 6.33505425 6.59030105 6.90775528 7.14440718 7.40549566
 7.69802917 7.94661756 8.15622332 8.85907932]
[[ 1.  1.]
 [ 1.  2.]
 [ 1.  3.]
 [ 1.  4.]
 [ 1.  5.]
 [ 1.  6.]
 [ 1.  7.]
 [ 1.  8.]
 [ 1.  9.]
 [ 1. 10.]
 [ 1. 11.]
 [ 1. 12.]
 [ 1. 13.]
 [ 1. 14.]
 [ 1. 15.]
 [ 1. 17.]]
```

```
[17]: print(NE_solver1(A, b))
```

```
NE used: LU
[4.0920173  0.27688609]
```

```
[18]: print(QR_solver(A, b))
```

```
[4.0920173  0.27688609]
```

```
[19]: print(np.linalg.lstsq(A, b, rcond=None)[0])
```

```
[4.0920173  0.27688609]
```

```
[20]: print(np.exp(4.0920173))
```

```
59.860526625182786
```

---

All three solvers produce the same output, thus we can proceed and solve  $k$  for  $c_1$ :

$$c_1 \approx e^k$$

$$c_1 \approx e^{4.0920173}$$

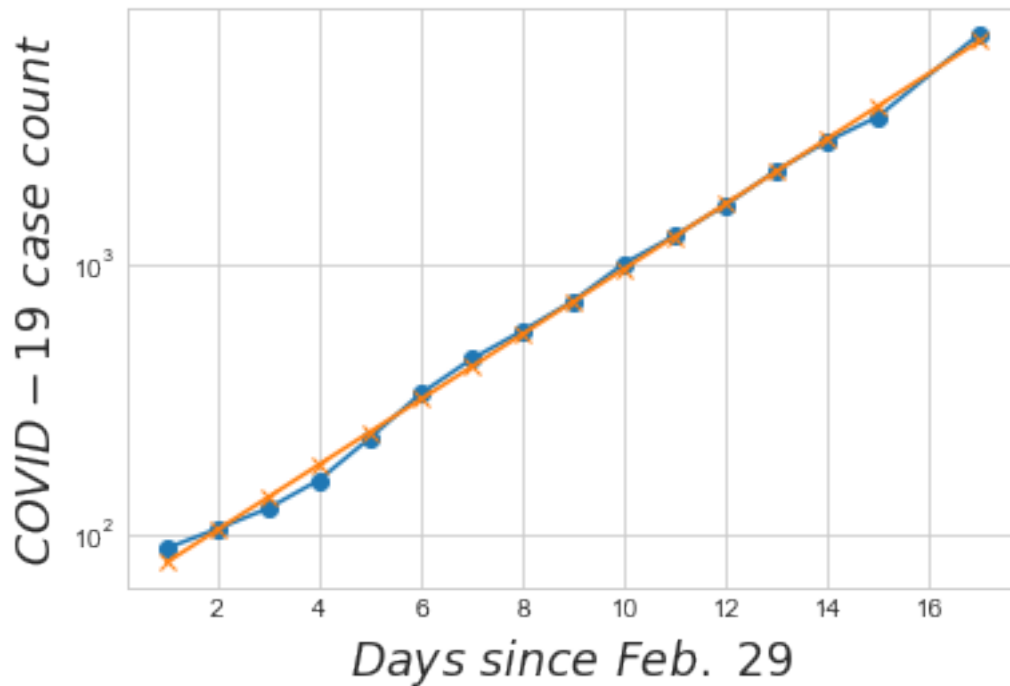
$$c_1 \approx 59.8605266$$

```
[21]: approx_f = lambda t: 59.8605266 * np.exp(0.27688609 * t)
```

```
[22]: approx = [approx_f(x) for x in days_since_feb_29]

plt.semilogy(days_since_feb_29, case_count, '-o')
plt.semilogy(days_since_feb_29, approx, '-x')

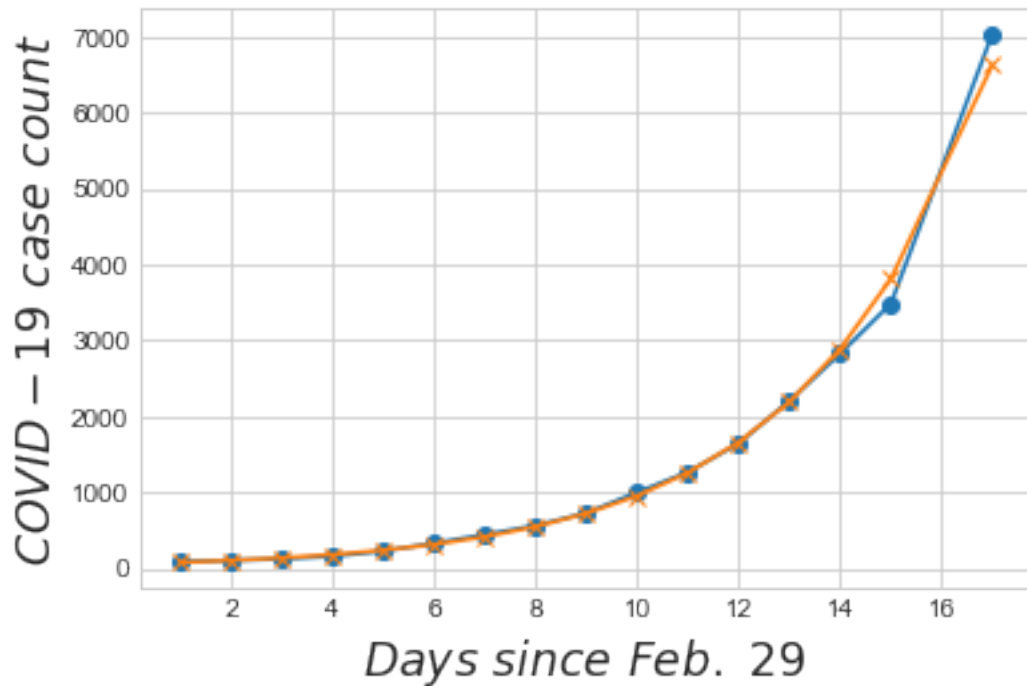
plt.xlabel("$Days\ since\ Feb.\ 29$", fontsize='xx-large')
plt.ylabel("$COVID-19\ case\ count$", fontsize='xx-large')
plt.show()
```



```
[23]: approx = [approx_f(x) for x in days_since_feb_29]

plt.plot(days_since_feb_29, case_count, '-o')
plt.plot(days_since_feb_29, approx, '-x')

plt.xlabel("$Days\ since\ Feb.\ 29$", fontsize='xx-large')
plt.ylabel("$COVID-19\ case\ count$", fontsize='xx-large')
plt.show()
```




---

For starters, I always like to see the data on a log and linear scale. The log-linear model appears to model the growth of COVID-19 cases extremely well for the first two weeks and we find a tiny bit of error as we extend into the last few data points, but overall, this seems like a great model.

The simple way I remember calculating half life is by setting the equation we have above:  $y = 59.8605266 \cdot e^{0.27688609 \cdot t}$  into  $2 = e^{0.27688609 \cdot t}$ . Which, can be further simplified into:  $\frac{\ln(2)}{0.27688609} = t$ .

So the doubling time turns out to around 2 and a half days, and this seems to check out when looking at the data: it appears to double every 2 or 3 days.

---

```
[24]: print(np.log(2) / 0.27688609)
```

```
2.503365844632879
```

```
[ ]:
```