

Homework Sheet 4

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Exercise 13

We are given the function:

$$f : \mathbb{R}^2 \rightarrow \mathbb{R}, \quad f(x_1, x_2) := |x_1 - x_2|$$

and the points:

$$a := (0, 1), \quad b := (1, 2)$$

(i)

Choose the G :

$$G := \{(x_1, x_2) \in \mathbb{R}^2 \mid x_1 - x_2 < 0\}$$

It is obvious that $a, b \in G$.

Now we need to show that the line segment connecting a and b lies in G .

$$\begin{aligned} \text{line segment} &= \{a + t(b - a) \mid t \in [0, 1]\} \\ &= \{(0, 1) + t(1 - 0, 2 - 1) \mid t \in [0, 1]\} \\ &= \{(t, 1 + t) \mid t \in [0, 1]\} \end{aligned}$$

which obviously is in G .

(ii)

When we consider the function f in the domain G , f is equal to

$$f(x_1, x_2) = x_2 - x_1$$

Lets calculate the gradient of f

$$\nabla f(x_1, x_2) = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

Now we need to find $\theta \in (0, 1)$ such that

$$f(b) - f(a) = \langle \nabla f(\xi), b - a \rangle$$

where $\xi := a + \theta(b - a)$.

Calculating the left hand side:

$$\begin{aligned} f(b) - f(a) &= f(1, 2) - f(0, 1) \\ &= 1 - 1 = 0 \end{aligned}$$

Calculating the right hand side:

$$\begin{aligned}
\langle \nabla f(\xi), b - a \rangle &= \langle \nabla f(a + \theta(b - a)), b - a \rangle \\
&= \langle \nabla f((0, 1) + \theta(1, 1)), (1, 1) \rangle \\
&= \langle \nabla f(\theta, 1 + \theta), (1, 1) \rangle \\
&= \left\langle \begin{pmatrix} -1 \\ 1 \end{pmatrix}, (1, 1) \right\rangle \\
&= 0
\end{aligned}$$

We get $0 = 0$ which is true always and doesn't depend on what θ is. So any $\theta \in (0, 1)$ satisfies the equation.

(iii)

We are given the points:

$$\tilde{a} := (-1, -1), \quad \tilde{b} := (1, 1)$$

No, we can't directly use the part (ii) here because simply the points \tilde{a} and \tilde{b} are not in G we chose. And actually there is no G that contains a point in the diagonal line (where $x_1 = x_2$) because f is not differentiable on that line.

Exercise 14

We are given the function

$$f : \mathbb{R}^2 \rightarrow \mathbb{R}, \quad f(x_1, x_2) := e^{1+x_1} + x_1 \sin(\pi x_2)$$

Taylor polynomial of order 1 and 2 is given by

$$\begin{aligned}
T_1^f(x^0; y) &= f(x^0) + \nabla f(x^0) \cdot (y - x^0) \\
T_2^f(x^0; y) &= T_1(x^0; y) + \frac{1}{2}(y - x^0)^T H_f(x^0)(y - x^0)
\end{aligned}$$

First and second order derivatives of f exist and given by

$$\begin{aligned}
\frac{\partial f}{\partial x_1} &= e^{1+x_1} + \sin(\pi x_2) \\
\frac{\partial f}{\partial x_2} &= \pi x_1 \cos(\pi x_2) \\
\frac{\partial^2 f}{\partial x_1^2} &= e^{1+x_1} \\
\frac{\partial^2 f}{\partial x_2^2} &= -\pi^2 x_1 \sin(\pi x_2) \\
\frac{\partial^2 f}{\partial x_2 \partial x_1} &= \frac{\partial^2 f}{\partial x_1 \partial x_2} = \pi \cos(\pi x_2)
\end{aligned}$$

Since all the partial derivatives are addition and multiplication of other continuous functions, they are continuous as well.

$T_1^f(x^0; y)$ at $(0, \frac{1}{2})$:

$$\begin{aligned} f(0, \tfrac{1}{2}) &= e^{1+0} + 0 \cdot \sin(\pi \cdot \tfrac{1}{2}) = e \\ \nabla f(0, \tfrac{1}{2}) &= \begin{pmatrix} e^{1+0} + \sin(\pi \cdot \tfrac{1}{2}) \\ \pi \cdot 0 \cdot \cos(\pi \cdot \tfrac{1}{2}) \end{pmatrix} = \begin{pmatrix} e+1 \\ 0 \end{pmatrix} \\ T_1^f((0, \tfrac{1}{2}); (y_1, y_2)) &= e + \begin{pmatrix} e+1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} y_1 - 0 \\ y_2 - \tfrac{1}{2} \end{pmatrix} = e + (e+1)y_1 \end{aligned}$$

$T_2^f(x^0; y)$ at $(0, \frac{1}{2})$:

$$\begin{aligned} H_f(0, \tfrac{1}{2}) &= \begin{pmatrix} e^{1+0} & \pi \cos(\pi \cdot \tfrac{1}{2}) \\ \pi \cos(\pi \cdot \tfrac{1}{2}) & -\pi^2 \cdot 0 \cdot \sin(\pi \cdot \tfrac{1}{2}) \end{pmatrix} = \begin{pmatrix} e & 0 \\ 0 & 0 \end{pmatrix} \\ T_2^f((0, \tfrac{1}{2}); (y_1, y_2)) &= T_1^f((0, \tfrac{1}{2}); (y_1, y_2)) + \frac{1}{2} \begin{pmatrix} y_1 - 0 & y_2 - \tfrac{1}{2} \end{pmatrix} \begin{pmatrix} e & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} y_1 - 0 \\ y_2 - \tfrac{1}{2} \end{pmatrix} \\ &= e + (e+1)y_1 + \frac{1}{2}e(y_1)^2 \end{aligned}$$