

Laplacian Subdivision Surface

Alexander Pinzón Fernandez Advisor: Eduardo Romero

Universidad Nacional de Colombia

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Outline



Introduction

2 Normalized LBO over triangles and quads

3 GSOC 2012 Mesh Smoothing

Laplacian smooth



The functional used in many laplacian smoothing approach to constrain energy minimization is based on a total curvature of a surface S.

$$E(S) = \int_{S} \kappa_1^2 + \kappa_2^2 dS \tag{1}$$

Gradient of Voronoi Area



Consider a surface S compound by a set of triangles around vertex v_i . We can define the *Voronoi region* of v_i , the change in area produced by move v_i is named gradient of *Voronoi region*.

$$\nabla A = \frac{1}{2} \sum_{j} \left(\cot \alpha_j + \cot \beta_j \right) \left(v_i - v_j \right) \tag{2}$$

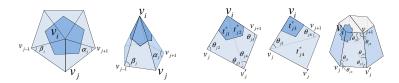


Figure: Area of Voronoi region around v_i in dark blue. v_j 1-ring neighbors around v_i . α_j and β_j opposite angles to edge $\overrightarrow{v_j - v_i}$.



Laplace Beltrami Operator



If we normalize this gradient in equation (2) by the total area in 1-ring around v_i , we have the *discrete mean curvature normal* of a surface S.

$$2\kappa \mathbf{n} = \frac{\nabla A}{A} \tag{3}$$

The LBO has desirable features, one feature of the LBO is in direction of surface area minimization, allowing us to minimize energy using it on a total curvature of a surface S equation (1).

$$\triangle_{g}S = 2\kappa \mathbf{n} \tag{4}$$



Normalized LBO over triangles and quads



$$L(i,j) = \begin{cases} -\frac{w_{ij}}{\sum w_{ij}} & \text{if } j \in N(v_i) \\ \delta_{ij} & \text{otherwise} \end{cases}$$

Where $N(v_i)$ is the 1-ring neighbors with shared face to v_i , and δ_{ij} being the Kronecker delta function.

The 5 basic triangle-quad cases



$$w_{ij} = \begin{cases} \frac{1}{2} \left(\cot \alpha_j + \cot \beta_j \right) & \text{case a.} \\ \frac{1}{4} \left(\cot \theta_{(j-1)1} + \cot \theta_{(j-1)4} + \cot \theta_{j3} + \cot \theta_{j6} \right) & \text{case b.} \\ \frac{1}{4} \left(\cot \theta_{j2} + \cot \theta_{j5} \right) & \text{case c.} \\ \frac{1}{4} \left(\cot \theta_{j3} + \cot \theta_{j6} \right) + \frac{1}{2} \cot \beta_j & \text{case d.} \\ \frac{1}{4} \left(\cot \theta_{(j-1)1} + \cot \theta_{(j-1)4} \right) + \frac{1}{2} \cot \alpha_j & \text{case e.} \end{cases}$$

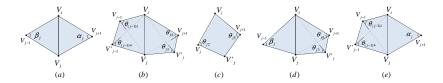


Figure: The 5 basic triangle-quad cases with common vertex V_i and the relationship with V_j and V'_j . (a) Two triangles. (b) (c) Two quads and one quad. (d) (e) Triangles and quads.



Results Enhancing Features

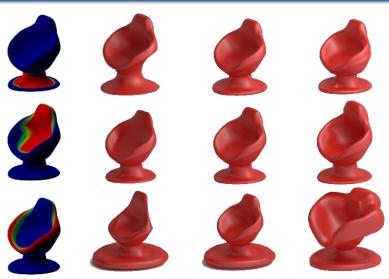






Results Enhancing Features





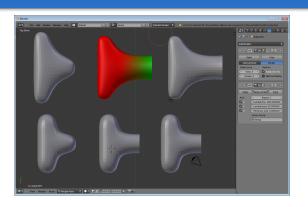
Results Enhancing Features





Blender





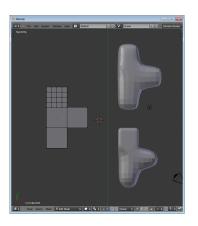
- Blender is the free open source 3D content creation suite, available for all major operating systems under the GNU General Public License..
- Use OpenNL for solve sparse system





Results





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