# CS122A: Intermediate Embedded and Real Time Operating Systems

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► Redundancy checks

- Redundancy checks
  - Parity

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  - ► Checksum

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- Gray code

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  - Parity
  - Checksum
- ► Hamming Distance
- ► Gray code
- ► Forward Error Correction

7 bits of data	(Count of 1 bits)	8 bits including parity	
7 Dits of data	(Count of 1 bits)	even	odd
000 0000	0	<b>0</b> 00 0000 <b>0</b>	000 0000 <b>1</b>
101 0001	3	101 0001 <b>1</b>	101 0001 <b>0</b>
110 1001	4	110 1001 <b>0</b>	110 1001 <b>1</b>
111 1111	7	111 1111 <b>1</b>	111 1111 <b>0</b>

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- ▶ Indicates if the number of bits with a 1 is even or odd
- Used as the simplest form of error detection
- Single errors are identified, but the error cannot be recovered without re-sending data

Type of bit parity	Successful transmission scenario
Even Parity	
Odd Parity	

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Even Parity	A wants to transmit: $1001$ A computes parity bit: $(1+0+0+1)\%2=0$ A adds parity bit and sends: $10010$
Odd Parity	A wants to transmit: $1001$ A computes parity bit: $(1+0+0+1+1)\%2=1$ A adds parity bit and sends: $10011$

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	B computes parity: $(1+0+0+1+0)\%2 = 0$
	B reports correct transmission.
	A wants to transmit: 1001
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Odd Parity	A adds parity bit and sends: 10011
	B receives: 10011
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	A wants to transmit: 1001
Even Parity	A computes parity bit: $(1 \land 0 \land 0 \land 1) = 0$
	A adds parity bit and sends: 10010
	TRANSMISSION ERROR
	B receives: 1001 <b>1</b>
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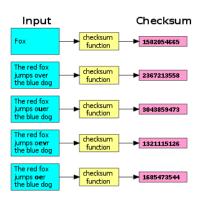
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Even Parity	A wants to transmit: $1001$ A computes parity bit: $(1 \land 0 \land 0 \land 1) = 0$ A adds parity bit and sends: $10010$ <b>TRANSMISSION ERROR</b> B receives: $11011$

# Parity Bits - Failed Transmission

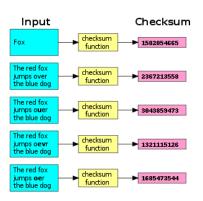
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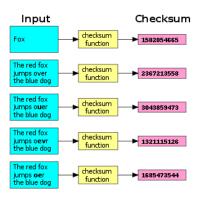
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	B reports <b>correct</b> transmission.	



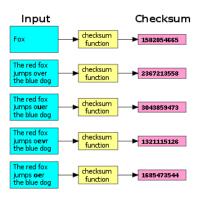
Checksum function gives checksum from data input



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- Produces significantly different data even for small changes



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- Checksum function gives checksum from data input
- Produces significantly different data even for small changes
- Parity bits are simple checksum functions
- Some error-correcting codes are based on checksums

► Parity byte or word

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  - ▶ Break data into words

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  - ► Break data into words
  - ► Compute **XOR** of words
  - ► Check if resulting word has *n* zeros

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- Modular sum

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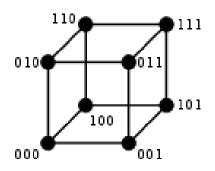
- Parity byte or word
- Modular sum
  - ► Variant to above
  - ► Add all "words" as unsigned binary numbers

- Parity byte or word
- Modular sum
- Position-dependent

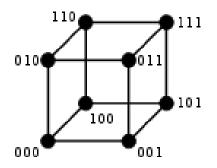
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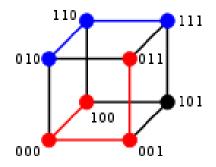
- Parity byte or word
- ► Modular sum
- Position-dependent
  - Above algorithms fail to detect common errors which affect many bits
  - Position dependent algorithms look not just at values, but position as well
  - ▶ Generally increases the cost of computing the checksum



 Hamming distance between two strings of equal length is the number of positions at which they differ

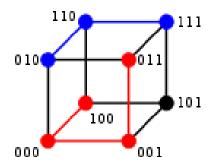


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 $100 \rightarrow 011$  has distance 3 (red)  $010 \rightarrow 111$  has distance 2 (blue)

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- Or the minimum number of errors that could have occurred

2-bit	4-bit
00	0000
01	0001
11	0011
10	0010
	0110
	0111
3-bit	0101
000	0100
001	1100
011	1101
010	1111
110	1110
111	1010
101	1011
100	1001
	1000

▶ Also known as reflected binary code

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- Changes only one bit at a time
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- ► The value 7 can be changed to 0 with only one bit change

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- Code allows limited number of errors to be detected
- Often those errors can be corrected without needing the data to be resent or recalculated
- Systematic codes include the data in the output without modification
- ▶ Non-systematic codes modify the data before output

Triplet received	Interpreted as
000	0 (error free)
001	0
010	0
100	0
111	1 (error free)
110	1
101	1
011	1

► Simple FEC (3,1) repetition code

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- ► Transmits each data bit 3 times

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- Transmits each data bit 3 times
- Errors corrected by "majority vote"

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#### Shannon Limit

For any given degree of noise contamination Data can be communicated nearly error-free up to a computable maximum rate

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- ▶ Due to "risk-pooling", FEC works well above a minimal signal-to-noise ratio
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- ▶ Below the signal-to-noise ratio FEC systems don't work at all
- More advanced techniques can be used here, or hybrid approaches

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  - Work on fixed-size blocks
  - Can be hard-decoded in polynomial time to block length
  - ▶ Hard-decision algorithm, makes a decision for each bit
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  - Work on arbitrary length streams
  - Soft-decoded, processes discretized analog signals
  - ► Higher error-correction performance

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- Viterbi algorithm commonly used for Convolutional codes

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  - ▶ Parity bit 4 covers all bit positions which have the third least significant bit set: 4–7, 12–15
  - ▶ Parity bit 8 covers all bit positions which have the fourth least significant bit set: 8–15, 24–31, etc.

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  - ▶ Parity bit 8 covers all bit positions which have the fourth least significant bit set: 8–15, 24–31, etc.
  - ▶ In general each parity bit covers all bits where the bitwise AND of the parity position and the bit position is non-zero

Bit position		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	
Encoded data bits		р1	p2	d1	p4	d2	d3	d4	p8	d5	d6	d7	d8	d9	d10	d11	p16	d12	d13	d14	d15	
Parity bit coverage	p1	X		X		X		X		X		X		X		X		X		X		
	p2		X	X			X	X			X	X			X	X			X	X		
	p4				X	X	X	X					X	X	X	X					X	
	р8								X	X	X	X	X	X	X	X						
	p16																X	X	X	X	X	

- ▶ Parity bit 1 covers positions with the least significant bit set: 1, 3, 5, 7, etc.
- ▶ Parity bit 2 covers positions with the second least significant bit set: 2, 3, 6, 7, 10, 11,etc.
- ▶ Parity bit 4 covers all bit positions which have the third least significant bit set: 4–7, 12–15
- ▶ Parity bit 8 covers all bit positions which have the fourth least significant bit set: 8–15, 24–31, etc.
- ► In general each parity bit covers all bits where the bitwise AND of the parity position and the bit position is non-zero

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