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1 Bike

```
using System;
using System.Collections.Generic;
using UnityEngine;

namespace TubeRace
{
    [Serializable]
    public class BikeParametersInitial
    {
        [Range(100.0f, 1000.0f)] public float maxVelocity;
        [Range(0.0f, 100.0f)] public float thrust;
        [Range(0.0f, 1.0f)] public float bounceFactor;

        [Range(100.0f, 1000.0f)] public float maxAngularVelocity;
        [Range(0.0f, 100.0f)] public float angularThrust;
        [Range(0.0f, 1.0f)] public float angularDrag;

        public float afterburnerThrust;
        public float afterburnerMaxVelocityBonus;

        public float afterburnerCoolSpeed;
        public float afterburnerHeatSpeed;
        public float afterburnerMaxHeat;
    }

    public class Bike : MonoBehaviour
    {
        private const string Tag = "Bike";
        public static GameObject[] BikesAsGameObjects;

        #region Сериализуемые поля

        [SerializeField] private Track track;
        public Track Track => track;

        [SerializeField] private AudioSource collisionSfx;
        [SerializeField] private AnimationCurve collisionVolumeCurve;

        [SerializeField] private bool isPlayerBike;
        public bool IsPlayerBike => isPlayerBike;

        [SerializeField] private BikeParametersInitial initial;

        #endregion

        #region Управление

        public bool IsMovementControlsActive { get; set; }

        private float forwardThrustAxis;

        public void SetForwardThrustAxis(float val)
        {
            forwardThrustAxis = val;
        }

        private float horizontalThrustAxis;

        public void SetHorizontalThrustAxis(float val)
        {
            horizontalThrustAxis = val;
        }
    }
}
```

```

    }

    #endregion

    #region Топливо

    public float Fuel { get; private set; }

    public void AddFuel(float amount)
    {
        Fuel += amount;
        Fuel = Mathf.Clamp(Fuel, 0, 100);
    }

    private bool CanConsumeFuel(float amount)
    {
        if (Fuel < amount)
            return false;

        Fuel -= amount;
        return true;
    }

    #endregion

    #region Скорости

    public float Velocity { get; private set; }

    public float NormalizedVelocity()
    {
        return Mathf.Clamp01(Velocity / initial.maxVelocity);
    }

    public void Slowdown(int percent)
    {
        Velocity -= Velocity * percent / 100.0f;
    }

    public float Angle { get; private set; }
    private float angularVelocity;

    #endregion

    #region Форсаж

    public bool EnableAfterburner { get; set; }
    private float afterburnerHeat;

    public float NormalizedHeat
    {
        get
        {
            if (initial.afterburnerMaxHeat > 0)
                return afterburnerHeat / initial.afterburnerMaxHeat;

            return 0.0f;
        }
    }

    private void HeatAfterburner()
    {
        afterburnerHeat += Velocity;
    }

```

```

public void CoolAfterburner()
{
    afterburnerHeat = 0;
}

#endregion

#region Статистика

public class BikeStatistics
{
    public int RacePlace;
    public float BestVelocity;
    public float BestSeconds;
    public float TotalSeconds;
}

public BikeStatistics Stats { get; private set; }

private float raceStartTime;

private int lapNum;
private List<float> lapDurations;
private float lapStartTime;

public float Distance { get; private set; }
public float PrevDistance { get; private set; }

#endregion

#region Гонка

public void OnRaceStart()
{
    Stats.RacePlace = 0;
    Stats.BestSeconds = 0;
    Stats.TotalSeconds = 0;

    raceStartTime = Time.time;
    lapStartTime = raceStartTime;
}

public void OnRaceEnd()
{
    Stats.TotalSeconds = Time.time - raceStartTime;
}

#endregion

#region Обновления

private void UpdateHeat()
{
    afterburnerHeat -= initial.afterburnerCoolSpeed * Time.deltaTime;

    if (afterburnerHeat < 0)
        afterburnerHeat = 0;

    if (afterburnerHeat > initial.afterburnerMaxHeat)
        Slowdown(100);
}

private void UpdateVelocity()

```

```

{
    float dt = Time.deltaTime;

    float forceThrustMax = initial.thrust;
    float velocityMax = initial.maxVelocity;
    float force = forwardThrustAxis * initial.thrust;

    if (EnableAfterburner
        && CanConsumeFuel(1.0f * Time.deltaTime))
    {
        afterburnerHeat += initial.afterburnerHeatSpeed *
Time.deltaTime;

        force += initial.afterburnerThrust;
        velocityMax += initial.afterburnerMaxVelocityBonus;
        forceThrustMax += initial.afterburnerThrust;
    }

    float forceDrag = -Velocity * (forceThrustMax / velocityMax);
    force += forceDrag;

    Velocity += force * dt;
    if (Stats.BestVelocity < Mathf.Abs(Velocity))
        Stats.BestVelocity = Mathf.Abs(Velocity);

    float ds = Velocity * dt;
    if (Physics.Raycast(transform.position, transform.forward, ds))
    {
        HeatAfterburner();

        collisionSfx.volume =
collisionVolumeCurve.Evaluate(NormalizedVelocity());
        collisionSfx.Play();

        Velocity = -Velocity * initial.bounceFactor;
        ds = Velocity * dt;
    }

    PrevDistance = Distance;
    Distance += ds;
}

private void UpdateAngle()
{
    float dt = Time.deltaTime;
    angularVelocity += horizontalThrustAxis * initial.angularThrust;
    Angle += angularVelocity * dt;

    if (Angle > 180.0f)
        Angle -= 360.0f;
    else if (Angle < -180.0f)
        Angle += 360.0f;

    angularVelocity += -angularVelocity * initial.angularDrag * dt;
    angularVelocity = Mathf.Clamp(angularVelocity,
        -initial.maxAngularVelocity, initial.maxAngularVelocity);
}

private void UpdatePhysics()
{
    UpdateVelocity();
    UpdateAngle();

    if (Distance < 0)

```

```

        Distance = 0;

        Vector3 bikePos = track.Position(Distance);
        transform.position = bikePos;
        transform.rotation = track.Rotation(Distance);
        transform.Rotate(Vector3.forward, Angle, Space.Self);
        transform.Translate(-Vector3.up * track.Radius, Space.Self);
    }

    private void UpdateBestTime()
    {
        int currLap = (int) (Distance / track.Length()) + 1;
        if (currLap <= lapNum)
            return;

        float lapDuration = Time.time - lapStartTime;
        lapStartTime = Time.time;

        lapDurations.Add(lapDuration);
        lapNum++;

        if (lapDuration > Stats.BestSeconds)
            Stats.BestSeconds = lapDuration;
    }

    #endregion

    #region ЮНИТИ

    private void Awake()
    {
        Stats = new BikeStatistics();
        lapDurations = new List<float>();
    }

    private void Start()
    {
        BikesAsGameObjects = GameObject.FindGameObjectsWithTag(Tag);
    }

    private void Update()
    {
        UpdateHeat();
        UpdatePhysics();
        UpdateBestTime();
    }

    #endregion
}

```

2 BikeHudViewController

```

using UnityEngine;
using UnityEngine.UI;

namespace TubeRace
{
    public class BikeHudViewController : MonoBehaviour
    {
        [SerializeField] private Bike bike;
    }
}

```

```

[SerializeField] private Text labelVelocity;
[SerializeField] private Text labelDistance;
[SerializeField] private Text labelLapNum;

[SerializeField] private Text labelRollAngle;

[SerializeField] private Text labelHeat;
[SerializeField] private Text labelFuel;

private void Update()
{
    labelVelocity.text = "Speed: " + (int) (bike.Velocity) + " m/s";
    labelDistance.text = "Distance: " + (int) (bike.Distance) + " m";

    int laps = (int) (bike.Distance / bike.Track.Length()) + 1;
    labelLapNum.text = "Lap: " + laps;

    labelRollAngle.text = "Angle: " + (int) (bike.Angle) + " deg";

    labelHeat.text = "Heat: " + (int) (bike.NormalizedHeat * 100.0f);
    labelFuel.text = "Fuel: " + (int) bike.Fuel;
}
}
}

```

3 GazeInput

```

using UnityEngine;

namespace TubeRace
{
    public class GazeInput : NewInput
    {
        [SerializeField] private NavigationPanel navigationPanel;

        public override Vector3 MoveDirection()
        {
            return navigationPanel.MoveDirection();
        }

        public override bool EnableAfterburner()
        {
            return false;
        }
    }
}

```

4 KeyboardInput

```

using UnityEngine;

namespace TubeRace
{
    public class KeyboardInput : NewInput
    {
        public override Vector3 MoveDirection()
        {
            Vector3 direction = new Vector3();

```



```

        if (Input.GetKey(KeyCode.W))
            direction.y = 1;

        if (Input.GetKey(KeyCode.S))
            direction.y = -1;

        if (Input.GetKey(KeyCode.A))
            direction.x = -1;

        if (Input.GetKey(KeyCode.D))
            direction.x = 1;

        return direction;
    }

    public override bool EnableAfterburner()
    {
        return Input.GetKey(KeyCode.Space);
    }
}

```

5 NewInput

```

using UnityEngine;

namespace TubeRace
{
    public abstract class NewInput : MonoBehaviour
    {
        public abstract Vector3 MoveDirection();

        public abstract bool EnableAfterburner();
    }
}

```

6 VrDeviceInput

```

using System;
using UnityEngine;

namespace TubeRace
{
    public class VrDeviceInput : NewInput
    {
        [SerializeField] private Lever lever;

        public override Vector3 MoveDirection()
        {
            throw new NotImplementedException();
        }

        public override bool EnableAfterburner()
        {
            throw new NotImplementedException();
        }
    }
}

```

7 MainMenuViewConroller

```
using UnityEngine;

namespace TubeRace
{
    public class MainMenuViewController : MonoBehaviour
    {
        [SerializeField] private TrackSelectionViewController
trackSelectionViewController;
        [SerializeField] private OptionsViewController optionsViewController;

        public void OnButtonNewGame()
        {
            trackSelectionViewController.gameObject.SetActive(true);
            gameObject.SetActive(false);
        }

        public void OnButtonOptions()
        {
            optionsViewController.gameObject.SetActive(true);
            gameObject.SetActive(false);
        }

        public void OnButtonExit()
        {
            Application.Quit();
        }
    }
}
```

8 OptionsViewConroller

```
using UnityEngine;
using UnityEngine.UI;

namespace TubeRace
{
    public class OptionsViewController : MonoBehaviour
    {
        [SerializeField] private MainMenuViewController
mainMenuViewController;

        [SerializeField] private bool isFullScreen = true;
        [SerializeField] private Dropdown dropdown;

        private readonly int[] width = {1920, 1366, 1440};
        private readonly int[] height = {1080, 768, 900};

        private void InitDropdownOptions()
        {
            for (int i = 0; i < height.Length; i++)
            {
                Dropdown.OptionData optionData = new Dropdown.OptionData
                {
                    text = $"{width[i]} x {height[i]}"
                };
            }
        }
    }
}
```

```

        dropdown.options.Add(optionData);
    }
}

private void SetScreenResolution()
{
    int option = dropdown.value;
    Screen.SetResolution(width[option], height[option],
isFullScreen);
}

public void OnButtonExit()
{
    SetScreenResolution();

    gameObject.SetActive(false);
    mainMenuViewController.gameObject.SetActive(true);
}

private void Awake()
{
    gameObject.SetActive(false);

    InitDropdownOptions();
    dropdown.value = 0;

    SetScreenResolution();
}
}
}

```

9 TrackDescription

```

using UnityEngine;

namespace TubeRace
{
    [CreateAssetMenu]
    public class TrackDescription : ScriptableObject
    {
        [SerializeField] private string title;
        public string Title => title;

        [SerializeField] private string sceneName;
        public string SceneName => sceneName;

        [SerializeField] private Sprite preview;
        public Sprite Preview => preview;

        [SerializeField] private float length;
        public float Length => length;

        public void SetLength(float newLength)
        {
            length = newLength;
        }
    }
}

```

10 TrackEntryViewController

```
using System.Globalization;
using UnityEngine;
using UnityEngine.SceneManagement;
using UnityEngine.UI;

namespace TubeRace
{
    public class TrackEntryViewController : MonoBehaviour
    {
        [SerializeField] private TrackDescription trackDescription;
        private TrackDescription activeDescription;

        [SerializeField] private Text labelTitle;
        [SerializeField] private Text labelLength;
        [SerializeField] private GameObject labelImage;

        private void SetViewFields(TrackDescription description)
        {
            activeDescription = description;

            labelTitle.text = description.Title;
            labelLength.text =
description.Length.ToString(CultureInfo.InvariantCulture);
            labelImage.GetComponent<Image>().sprite = description.Preview;
        }

        public void OnButtonStartLevel()
        {
            SceneManager.LoadScene(activeDescription.SceneName);
        }

        private void Start()
        {
            if (trackDescription != null)
                SetViewFields(trackDescription);
        }
    }
}
```

11 TrackSelectionViewController

```
using UnityEngine;

namespace TubeRace
{
    public class TrackSelectionViewController : MonoBehaviour
    {
        [SerializeField] private MainMenuViewController
mainMenuViewController;

        public void OnButtonExit()
        {
            gameObject.SetActive(false);
            mainMenuViewController.gameObject.SetActive(true);
        }

        private void Awake()
        {

```

```

        gameObject.SetActive(false);
    }
}

```

12 Obstacle

```

using UnityEngine;

namespace TubeRace
{
    public class Obstacle : MonoBehaviour
    {
        [SerializeField] private Track track;
        [SerializeField] private float distance;

        [Range(0.0f, 20.0f)] [SerializeField] private float radiusModifier =
1.0f;
        [SerializeField] private float angle;
        [Range(0.0f, 100.0f)] public float angularThrust;

        private Vector3 obstacleDirection;
        private Vector3 trackPosition;

        private Quaternion quater;
        private Vector3 trackOffset;

        private void UpdateAngle()
        {
            angle += angularThrust * Time.deltaTime;
            if (angle > 180.0f)
                angle -= 360.0f;
            else if (angle < -180.0f)
                angle = 360.0f + angle;
        }

        private void UpdatePosition()
        {
            quater = Quaternion.AngleAxis(angle, Vector3.forward);
            trackOffset = quater * (Vector3.up * (radiusModifier *
track.Radius));

            transform.position = trackPosition - trackOffset;
            transform.rotation = Quaternion.LookRotation(obstacleDirection,
trackOffset);
        }

        private void OnDrawGizmos()
        {
            Gizmos.color = Color.red;

            Vector3 centerlinePos = track.Position(distance);
            Gizmos.DrawSphere(centerlinePos, track.Radius);
        }

        private void OnValidate()
        {
            obstacleDirection = track.Direction(distance);
            trackPosition = track.Position(distance);
            UpdatePosition();
        }
    }
}

```

```

        private void Update()
        {
            UpdateAngle();
            UpdatePosition();
        }
    }
}

```

13 Powerup

```

using UnityEngine;

namespace TubeRace
{
    public abstract class Powerup : MonoBehaviour
    {
        [SerializeField] private Track track;
        [SerializeField] private float distance;
        [SerializeField] private float angle;

        protected abstract void OnPicked(Bike bike);

        private void SetPosition()
        {
            Vector3 obstacleDir = track.Direction(distance);
            Vector3 trackPosition = track.Position(distance);

            Quaternion quater = Quaternion.AngleAxis(angle, Vector3.forward);
            Vector3 trackOffset = quater * (Vector3.up * 0);

            transform.position = trackPosition - trackOffset;
            transform.rotation = Quaternion.LookRotation(obstacleDir,
trackOffset);
        }

        private void UpdateBikes()
        {
            foreach (GameObject bikeGo in Bike.BikesAsGameObjects)
            {
                Bike bike = bikeGo.GetComponent<Bike>();

                float prev = bike.PrevDistance;
                float curr = bike.Distance;

                if (prev < distance && curr > distance)
                {
                    // limit angles
                    OnPicked(bike);
                }
            }
        }

        private void OnValidate()
        {
            SetPosition();
        }

        private void Update()
        {
            UpdateBikes();
        }
    }
}

```

```

    }
}

```

14 PowerupCoolant

```

using UnityEngine;

namespace TubeRace
{
    public class PowerupCoolant : Powerup
    {
        protected override void OnPicked(Bike bike)
        {
            bike.CoolAfterburner();
            Debug.Log("PowerupCoolant picked up by " + bike.name);
        }
    }
}

```

15 PowerupFuel

```

using UnityEngine;

namespace TubeRace
{
    public class PowerupFuel : Powerup
    {
        [Range(0.0f, 100.0f)]
        [SerializeField] private float fuelAmount;

        protected override void OnPicked(Bike bike)
        {
            bike.AddFuel(fuelAmount);
        }
    }
}

```

16 PowerupSlowdown

```

using UnityEngine;

namespace TubeRace
{
    public class PowerupSlowdown : Powerup
    {
        [Range(0, 100)] [SerializeField] private int slowdownPercent;

        protected override void OnPicked(Bike bike)
        {
            bike.Slowdown(slowdownPercent);
        }
    }
}

```

17 BotController

```
using System;
using UnityEngine;

namespace TubeRace
{
    public enum BotBehaviour
    {
        Nothing,
        Behave
    }

    public enum TimerType
    {
        Nothing,

        ReactionDelay,
        MoveOn,
        Rotate,

        MaxValues
    }

    [RequireComponent(typeof(Bike))]
    public class BotController : MonoBehaviour
    {
        [SerializeField] private bool isEnabled;
        [SerializeField] private BotBehaviour behaviour;

        [Range(1, 100)] [SerializeField] private int predictionTimeSteps;

        [Range(0.0f, 10.0f)] [SerializeField] private float
reactionDelayTime;
        [Range(0.0f, 10.0f)] [SerializeField] private float moveForwardTime;

        private Bike bike;
        private Transform bikeTransform;

        private float[] timers;

        private void InitTimers()
        {
            timers = new float[(int) TimerType.MaxValues];

            SetTimer(TimerType.ReactionDelay, reactionDelayTime);
        }

        private void SetTimer(TimerType e, float time)
        {
            timers[(int) e] = time;
        }

        private bool IsTimerFinished(TimerType e)
        {
            return timers[(int) e] <= 0;
        }

        private void MoveForward()
        {
            bike.SetForwardThrustAxis(1);
        }
    }
}
```



```

private void StallForward()
{
    bike.SetForwardThrustAxis(0);
}

private void MoveForwardOrStall()
{
    if (!IsTimerFinished(TimerType.MoveOn))
    {
        MoveForward();
    }
    else
    {
        StallForward();
        SetTimer(TimerType.ReactionDelay, reactionDelayTime);
    }
}

private void MoveHorizontal()
{
    bike.SetHorizontalThrustAxis(1);
}

private void StallHorizontal()
{
    bike.SetHorizontalThrustAxis(0);
}

private void Move()
{
    float dt = Time.deltaTime * predictionTimeSteps;
    float ds = bike.Velocity * dt;
    bool isCollision = Physics.Raycast(bikeTransform.position,
bikeTransform.forward, ds);

    if (!isCollision)
    {
        StallHorizontal();
        MoveForwardOrStall();
    }
    else
    {
        MoveForward();
        MoveHorizontal();
    }
}

private void Behave()
{
    if (!bike.IsMovementControlsActive)
        return;

    if (IsTimerFinished(TimerType.ReactionDelay))
        Move();
    else
        SetTimer(TimerType.MoveOn, moveForwardTime);
}

private void UpdateBot()
{
    if (!isEnabled)
        return;

    switch (behaviour)

```

```

        {
            case BotBehaviour.Nothing:
                break;

            case BotBehaviour.Behave:
                Behave();
                break;

            default:
                throw new ArgumentOutOfRangeException();
        }
    }

    private void UpdateTimers()
    {
        for (int i = 0; i < timers.Length; i++)
            if (timers[i] > 0)
                timers[i] -= Time.deltaTime;
    }

    private void Start()
    {
        bike = GetComponent<Bike>();
        bikeTransform = bike.transform;

        InitTimers();
    }

    private void Update()
    {
        UpdateBot();
        UpdateTimers();
    }
}

```

18 CameraController

```

using UnityEngine;

namespace TubeRace
{
    public class CameraController : MonoBehaviour
    {
        [SerializeField] private Bike bike;

        [SerializeField] private float minViewField = 60;
        [SerializeField] private float maxViewField = 85;
        [SerializeField] private float shakeFactor;
        [SerializeField] private AnimationCurve shakeCurve;

        private Camera thisCamera;
        private Vector3 initialLocalPosition;

        private void UpdateViewField()
        {
            float t = bike.NormalizedVelocity();
            thisCamera.fieldOfView = Mathf.Lerp(minViewField, maxViewField,
t);
        }
    }
}

```

```

private void UpdateCameraShake()
{
    if (Time.timeScale <= 0)
        return;

    float t = bike.NormalizedVelocity();
    float curveValue = shakeCurve.Evaluate(t);

    Vector3 randomVector = Random.insideUnitSphere * shakeFactor;
    randomVector.z = 0;

    thisCamera.transform.localPosition = initialLocalPosition +
randomVector * curveValue;
}

private void Start()
{
    thisCamera = Camera.main;
    initialLocalPosition = thisCamera.transform.localPosition;
}

private void Update()
{
    UpdateViewField();
    UpdateCameraShake();
}
}

```

19 Player

```

using UnityEngine;

namespace TubeRace
{
    public class Player : MonoBehaviour
    {
        [SerializeField] private NewInput newInput;

        [SerializeField] private Bike activeBike;

        private void CheckInput()
        {
            if (!activeBike.IsMovementControlsActive)
                return;

            Vector3 direction = newInput.MoveDirection();

            activeBike.SetForwardThrustAxis(direction.y);
            activeBike.SetHorizontalThrustAxis(direction.x);

            activeBike.EnableAfterburner = newInput.EnableAfterburner();
        }

        private void Update()
        {
            CheckInput();
        }
    }
}

```

20 RaceCondition

```
using UnityEngine;

namespace TubeRace
{
    public abstract class RaceCondition : MonoBehaviour
    {
        public bool IsTriggered { get; protected set; }

        public virtual void OnRaceStart()
        {
        }

        public virtual void OnRaceEnd()
        {
        }
    }
}
```

21 RaceConditionLaps

```
using UnityEngine;

namespace TubeRace
{
    public class RaceConditionLaps : RaceCondition
    {
        [SerializeField] private RaceController raceController;

        private void UpdateConditionLaps()
        {
            if (!raceController.IsRaceActive && IsTriggered)
                return;

            var bikes = raceController.Bikes;
            foreach (Bike bike in bikes)
            {
                int laps = (int) (bike.Distance / bike.Track.Length()) + 1;
                if (laps < raceController.MaxLaps)
                    return;
            }

            IsTriggered = true;
        }

        private void Update()
        {
            UpdateConditionLaps();
        }
    }
}
```

22 RaceController

```
using System.Collections.Generic;
using UnityEngine;
using UnityEngine.Events;
```

```

namespace TubeRace
{
    public enum RaceMode
    {
        Laps,
        Time,
        LastStanding
    }

    public class RaceController : MonoBehaviour
    {
        [SerializeField] private RaceResultsViewController
raceResultsViewController;
        [SerializeField] private Track track;

        [SerializeField] private Bike[] bikes;
        private List<Bike> activeBikes;
        private List<Bike> finishedBikes;
        public IEnumerable<Bike> Bikes => bikes;

        [SerializeField] private RaceMode raceMode;
        [SerializeField] private RaceCondition[] conditions;

        [SerializeField] private UnityEvent eventRaceStart;
        [SerializeField] private UnityEvent eventRaceFinished;
        public bool IsRaceActive { get; private set; }

        [SerializeField] private int maxLaps;
        public int MaxLaps => maxLaps;

        [SerializeField] private int countdownTimer;
        public float CountTimer { get; private set; }

        private void StartRace()
        {
            activeBikes = new List<Bike>(bikes);
            finishedBikes = new List<Bike>();

            IsRaceActive = true;
            CountTimer = countdownTimer;

            foreach (RaceCondition condition in conditions)
                condition.OnRaceStart();

            foreach (Bike bike in bikes)
                bike.OnRaceStart();

            eventRaceStart?.Invoke();
        }

        private void EndRace()
        {
            IsRaceActive = false;

            foreach (RaceCondition condition in conditions)
                condition.OnRaceEnd();

            eventRaceFinished?.Invoke();
        }

        private void UpdatePositions()
        {
            foreach (Bike bike in activeBikes)

```

```

        {
            if (finishedBikes.Contains(bike))
                continue;

            float currDistance = bike.Distance;
            float totalRaceDistance = maxLaps * track.Length();

            if (currDistance > totalRaceDistance)
            {
                finishedBikes.Add(bike);
                bike.Stats.RacePlace = finishedBikes.Count;
                bike.OnRaceEnd();

                if (bike.IsPlayerBike)
                    raceResultsController.Show(bike.Stats);
            }
        }
    }

    private void UpdatePrestart()
    {
        if (CountTimer > 0)
        {
            CountTimer -= Time.deltaTime;

            if (CountTimer <= 0)
            {
                foreach (Bike bike in bikes)
                    bike.IsMovementControlsActive = true;
            }
        }
    }

    private void UpdateConditions()
    {
        if (IsRaceActive)
            return;

        foreach (RaceCondition condition in conditions)
        {
            if (!condition.IsTriggered)
                return;
        }

        EndRace();
    }

    private void Start()
    {
        StartRace();
    }

    private void Update()
    {
        if (!IsRaceActive)
            return;

        UpdatePositions();
        UpdatePrestart();
        UpdateConditions();
    }
}

```

23 RaceResultsViewController

```
using System.Globalization;
using UnityEngine;
using UnityEngine.SceneManagement;
using UnityEngine.UI;

namespace TubeRace
{
    public class RaceResultsViewController : MonoBehaviour
    {
        [SerializeField] private Text place;
        [SerializeField] private Text topVelocity;
        [SerializeField] private Text totalSeconds;
        [SerializeField] private Text bestSeconds;

        public void Show(Bike.BikeStatistics stats)
        {
            gameObject.SetActive(true);

            place.text = "Place: " + stats.RacePlace;
            topVelocity.text = "Top speed: " + ((int) stats.BestVelocity) + "
m/s";
            totalSeconds.text = "Time: " +
stats.TotalSeconds.ToString(CultureInfo.CurrentCulture) + " seconds";
            bestSeconds.text = "Best lap: " +
stats.BestSeconds.ToString(CultureInfo.CurrentCulture) + " seconds";
        }

        public void OnButtonQuit()
        {
            SceneManager.LoadScene(PauseViewController.MainMenuScene);
        }

        private void Awake()
        {
            gameObject.SetActive(false);
        }
    }
}
```

24 CountdownViewController

```
using UnityEngine;
using UnityEngine.UI;

namespace TubeRace
{
    public class CountdownViewController : MonoBehaviour
    {
        [SerializeField] private RaceController raceController;
        [SerializeField] private Text label;

        private void DisableCountdown()
        {
            label.text = "";
            gameObject.SetActive(false);
        }
    }
}
```

```

private void UpdateCountdown()
{
    float currSeconds = raceController.CountTimer + 1;

    if (currSeconds > 0.0f && currSeconds < 1.0f)
    {
        label.text = "GO";
        Invoke(nameof(DisableCountdown), 1.0f);
    }
    else
    {
        label.text = ((int) currSeconds).ToString();
    }
}

private void Update()
{
    UpdateCountdown();
}
}

```

25 PauseViewController

```

using UnityEngine;
using UnityEngine.SceneManagement;

namespace TubeRace
{
    public class PauseViewController : MonoBehaviour
    {
        public const string MainMenuScene = "scene_main_menu";

        [SerializeField] private RaceController raceController;
        [SerializeField] private RectTransform content;

        public void OnButtonContinue()
        {
            Time.timeScale = 1;
            content.gameObject.SetActive(false);
        }

        public void OnButtonEndRace()
        {
            SceneManager.LoadScene(MainMenuScene);
        }

        private void Start()
        {
            content.gameObject.SetActive(false);
        }

        private void Update()
        {
            if (Input.GetKeyDown(KeyCode.Escape))
            {
                if (raceController.IsRaceActive)
                {
                    GameObject go = content.gameObject;
                    go.SetActive(!go.activeInHierarchy);
                }
            }
        }
    }
}

```



```

        return;
    }

    float t = Mathf.Clamp01(bike.Velocity / superSonicSpeed);

    sfxLow.volume = curveLow.Evaluate(t);
    sfxLow.pitch = 1.0f + PitchFactor * t;

    sfxHigh.volume = curveHigh.Evaluate(t);
    sfxHigh.pitch = 1.0f + PitchFactor * t;

    sfxLoud.volume = curveLoud.Evaluate(t);
}

private void Update()
{
    // UpdateSuperSonicSound();
    UpdateEngineSound();
}
}

```

27 EngineSfxController

```

using UnityEngine;

namespace TubeRace
{
    public class EngineSfxController : MonoBehaviour
    {
        [SerializeField] private Bike bike;
        [SerializeField] private AudioSource engineSource;

        [Range(0.0f, 1.0f)] [SerializeField] private float pitchModifier;

        private void UpdateEngineSound()
        {
            engineSource.pitch = 1.0f + pitchModifier *
bike.NormalizedVelocity();
        }

        private void Update()
        {
            UpdateEngineSound();
        }
    }
}

```

28 BezierTrackPoint

```

using UnityEngine;

namespace TubeRace
{
    public class BezierTrackPoint : MonoBehaviour
    {
        [SerializeField] private float length = 1.0f;
        public float Length => length;
    }
}

```

```

        private void OnDrawGizmos()
        {
            Gizmos.color = Color.cyan;
            Gizmos.DrawSphere(transform.position, 10.0f);
        }
    }
}

```

29 Track

```

using UnityEngine;

namespace TubeRace
{
    public abstract class Track : MonoBehaviour
    {
        [Header("Base track properties")] [SerializeField]
        private float radius;

        public float Radius => radius;

        public abstract float Length();

        public abstract Vector3 Position(float distance);

        public abstract Vector3 Direction(float distance);

        public virtual Quaternion Rotation(float distance)
        {
            return Quaternion.identity;
        }
    }
}

```

30 TrackCircle

```

using System.Collections.Generic;
using UnityEngine;
#if UNITY_EDITOR
using UnityEditor;

#endif

namespace TubeRace
{
    #if UNITY_EDITOR
    [CustomEditor(typeof(TrackCircle))]
    public class RaceTrackRoundEditor : Editor
    {
        public override void OnInspectorGUI()
        {
            base.OnInspectorGUI();

            if (GUILayout.Button("Generate"))
            {
                ((TrackCircle) target).GenerateTrackData();
            }
        }
    }
    #endif
}

```

```

    }
#endif

public class TrackCircle : Track
{
    [SerializeField] private float circleRadius;
    [SerializeField] private int division;

    [SerializeField] private Quaternion[] trackSampledRotations;
    [SerializeField] private Vector3[] trackSampledPoints;
    [SerializeField] private float[] trackSampledSegmentLengths;
    [SerializeField] private float trackSampledLength;

    public override float Length()
    {
        return trackSampledLength;
    }

    public override Vector3 Position(float distance)
    {
        distance = Mathf.Repeat(distance, trackSampledLength);

        for (int i = 0; i < trackSampledSegmentLengths.Length; i++)
        {
            float diff = distance - trackSampledSegmentLengths[i];

            if (diff < 0)
            {
                float t = distance / trackSampledSegmentLengths[i];
                return Vector3.Lerp(trackSampledPoints[i],
trackSampledPoints[i + 1], t);
            }

            distance -= trackSampledSegmentLengths[i];
        }

        return Vector3.zero;
    }

    public override Vector3 Direction(float distance)
    {
        distance = Mathf.Repeat(distance, trackSampledLength);

        for (int i = 0; i < trackSampledSegmentLengths.Length; i++)
        {
            float diff = distance - trackSampledSegmentLengths[i];
            if (diff < 0)
                return (trackSampledPoints[i + 1] -
trackSampledPoints[i]).normalized;

            distance -= trackSampledSegmentLengths[i];
        }

        return Vector3.forward;
    }

    public override Quaternion Rotation(float distance)
    {
        distance = Mathf.Repeat(distance, trackSampledLength);

        for (int i = 0; i < trackSampledSegmentLengths.Length; i++)
        {
            float diff = distance - trackSampledSegmentLengths[i];
            if (diff < 0)

```

```

        {
            float t = distance / trackSampledSegmentLengths[i];

            return Quaternion.Slerp(
                trackSampledRotations[i],
                trackSampledRotations[i + 1], t
            );
        }

        distance -= trackSampledSegmentLengths[i];
    }

    return Quaternion.identity;
}

#if UNITY_EDITOR
[SerializeField] private bool debugDrawCircle;
[SerializeField] private bool debugDrawSampledPoints;

private static Quaternion GenerateRotation(Vector3 a, Vector3 b,
float t)
{
    Vector3 dir = (b - a).normalized;
    Vector3 up = Vector3.Lerp(a, b, t);

    Quaternion rotation = Quaternion.LookRotation(dir, up);
    return rotation;
}

private static IEnumerable<Quaternion>
GenerateRotations(IReadOnlyList<Vector3> points)
{
    var rotations = new List<Quaternion>();
    float t = 0;

    for (int i = 0; i < points.Count - 1; i++)
    {
        Quaternion rotation = GenerateRotation(points[i], points[i +
1], t);
        rotations.Add(rotation);

        t += 1.0f / (points.Count - 1);
    }

    rotations.Add(GenerateRotation(points[points.Count - 1],
points[0], t));
    return rotations.ToArray();
}

public void GenerateTrackData()
{
    Debug.Log("Generating track data");

    var points = new List<Vector3>();
    var rotations = new List<Quaternion>();

    float divisionf = division;
    for (int i = 0; i < division; i++)
    {
        float angle = 2.0f * Mathf.PI * i / divisionf;
        Vector3 newPoints = new Vector3(
            Mathf.Cos(angle) * circleRadius, 0, Mathf.Sin(angle) *
circleRadius);

```

```

        points.Add(newPoints);
    }

    trackSampledPoints = points.ToArray();
    rotations.AddRange(GenerateRotations(trackSampledPoints));
    trackSampledRotations = rotations.ToArray();

    trackSampledSegmentLengths = new float[trackSampledPoints.Length
- 1];

    trackSampledLength = 0;

    for (int i = 0; i < trackSampledPoints.Length - 1; i++)
    {
        Vector3 a = trackSampledPoints[i];
        Vector3 b = trackSampledPoints[i + 1];

        float segmentLength = (b - a).magnitude;
        trackSampledSegmentLengths[i] = segmentLength;
        trackSampledLength += segmentLength;
    }

    EditorUtility.SetDirty(this);
}

private void DrawSampledTrackPoints()
{
    Handles.DrawAAPolyLine(trackSampledPoints);
}

private void DrawCircleGizmos()
{
    Handles.DrawWireDisc(Vector3.zero, Vector3.up, circleRadius);
}

private void OnDrawGizmos()
{
    if (debugDrawCircle)
        DrawCircleGizmos();

    if (debugDrawSampledPoints)
        DrawSampledTrackPoints();
}
#endif
}

```

31 TrackCloseBezierCurve

```

using System.Collections.Generic;
using UnityEngine;
#if UNITY_EDITOR
using UnityEditor;

#endif

namespace TubeRace
{
    #if UNITY_EDITOR
    [CustomEditor(typeof(TrackClosedBezierCurve))]
    public class TrackClosedBezierCurveEditor : Editor
    {

```

```

public override void OnInspectorGUI()
{
    base.OnInspectorGUI();

    if (GUILayout.Button("Generate"))
    {
        ((TrackClosedBezierCurve) target).GenerateTrackData();
    }
}
}
#endif

public class TrackClosedBezierCurve : Track
{
    [SerializeField] private TrackDescription trackDescription;
    [SerializeField] private BezierTrackPoint[] trackPoints;

    [SerializeField] private int division;

    [SerializeField] private Quaternion[] trackSampledRotations;
    [SerializeField] private Vector3[] trackSampledPoints;
    [SerializeField] private float[] trackSampledSegmentLengths;
    [SerializeField] private float trackSampledLength;

    public override float Length()
    {
        return trackSampledLength;
    }

    public override Vector3 Position(float distance)
    {
        distance = Mathf.Repeat(distance, trackSampledLength);

        for (int i = 0; i < trackSampledSegmentLengths.Length; i++)
        {
            float diff = distance - trackSampledSegmentLengths[i];

            if (diff < 0)
            {
                float t = distance / trackSampledSegmentLengths[i];
                return Vector3.Lerp(trackSampledPoints[i],
trackSampledPoints[i + 1], t);
            }

            distance -= trackSampledSegmentLengths[i];
        }

        return Vector3.zero;
    }

    public override Vector3 Direction(float distance)
    {
        distance = Mathf.Repeat(distance, trackSampledLength);

        for (int i = 0; i < trackSampledSegmentLengths.Length; i++)
        {
            float diff = distance - trackSampledSegmentLengths[i];
            if (diff < 0)
                return (trackSampledPoints[i + 1] -
trackSampledPoints[i]).normalized;

            distance -= trackSampledSegmentLengths[i];
        }
    }
}

```

```

        return Vector3.forward;
    }

    public override Quaternion Rotation(float distance)
    {
        distance = Mathf.Repeat(distance, trackSampledLength);

        for (int i = 0; i < trackSampledSegmentLengths.Length; i++)
        {
            float diff = distance - trackSampledSegmentLengths[i];

            if (diff < 0)
            {
                float t = distance / trackSampledSegmentLengths[i];

                return Quaternion.Slerp(
                    trackSampledRotations[i],
                    trackSampledRotations[i + 1],
                    t);
            }

            distance -= trackSampledSegmentLengths[i];
        }

        return Quaternion.identity;
    }

    private static IEnumerable<Quaternion> GenerateRotations(
        Transform a,
        Transform b,
        IReadOnlyList<Vector3> points)
    {
        var rotations = new List<Quaternion>();
        float t = 0;

        for (int i = 0; i < points.Count - 1; i++)
        {
            Vector3 direction = (points[i + 1] - points[i]).normalized;
            Vector3 up = Vector3.Lerp(a.up, b.up, t);

            Quaternion rotation = Quaternion.LookRotation(direction, up);
            rotations.Add(rotation);

            t += 1.0f / (points.Count - 1);
        }

        rotations.Add(b.rotation);
        return rotations.ToArray();
    }

    private void Start()
    {
        if (trackDescription != null)
            trackDescription.SetLength(trackSampledLength);
    }

#if UNITY_EDITOR
    [SerializeField] private bool debugDrawBezier;
    [SerializeField] private bool debugDrawSampledPoints;

    private static Vector3[] GenerateBezierPoints(
        BezierTrackPoint a,
        BezierTrackPoint b,
        int division)

```



```

{
    Transform aTransform = a.transform;
    Transform bTransform = b.transform;

    Vector3 aPosition = aTransform.position;
    Vector3 bPosition = bTransform.position;

    float aLength = a.Length;
    float bLength = b.Length;

    return Handles.MakeBezierPoints(
        aPosition,
        bPosition,
        aPosition + aTransform.forward * aLength,
        bPosition - bTransform.forward * bLength,
        division);
}

public void GenerateTrackData()
{
    Debug.Log("Generating track data");

    var points = new List<Vector3>();
    var rotations = new List<Quaternion>();

    if (trackPoints.Length < 3)
        return;

    for (int i = 0; i < trackPoints.Length - 1; i++)
    {
        var newPoints = GenerateBezierPoints(trackPoints[i],
trackPoints[i + 1], division);
        var newRotations = GenerateRotations(
            trackPoints[i].transform,
            trackPoints[i + 1].transform,
            newPoints);

        rotations.AddRange(newRotations);
        points.AddRange(newPoints);
    }

    var lastNewPoints = GenerateBezierPoints(
        trackPoints[trackPoints.Length - 1],
        trackPoints[0],
        division);
    var lastNewRotations = GenerateRotations(
        trackPoints[trackPoints.Length - 1].transform,
        trackPoints[0].transform,
        lastNewPoints);

    points.AddRange(lastNewPoints);
    rotations.AddRange(lastNewRotations);

    trackSampledRotations = rotations.ToArray();
    trackSampledPoints = points.ToArray();

    trackSampledSegmentLengths = new float[trackSampledPoints.Length
- 1];

    trackSampledLength = 0;

    for (int i = 0; i < trackSampledPoints.Length - 1; i++)
    {
        Vector3 a = trackSampledPoints[i];
        Vector3 b = trackSampledPoints[i + 1];

```

```

        float segmentLength = (b - a).magnitude;
        trackSampledSegmentLengths[i] = segmentLength;
        trackSampledLength += segmentLength;
    }

    if (trackDescription != null)
        trackDescription.SetLength(trackSampledLength);

    EditorUtility.SetDirty(this);
}

private static void DrawTrackPartGizmos(BezierTrackPoint a,
BezierTrackPoint b)
{
    Transform aTransform = a.transform;
    Transform bTransform = b.transform;

    Vector3 aPosition = aTransform.position;
    Vector3 bPosition = bTransform.position;

    float aLength = a.Length;
    float bLength = b.Length;

    Handles.DrawBezier(
        aPosition,
        bPosition,
        aPosition + aTransform.forward * aLength,
        bPosition - bTransform.forward * bLength,
        Color.green, Texture2D.whiteTexture, 1.0f);
}

private void DrawBezierCurveGizmos()
{
    if (trackPoints.Length < 3)
        return;

    for (int i = 0; i < trackPoints.Length - 1; i++)
        DrawTrackPartGizmos(trackPoints[i], trackPoints[i + 1]);

    DrawTrackPartGizmos(trackPoints[trackPoints.Length - 1],
trackPoints[0]);
}

private void DrawSampledTrackPoints()
{
    Handles.DrawAAPolyLine(trackSampledPoints);
}

private void OnDrawGizmos()
{
    if (debugDrawBezier)
        DrawBezierCurveGizmos();

    if (debugDrawSampledPoints)
        DrawSampledTrackPoints();
}
#endif
}
}

```

32 TrackLine

```
using UnityEngine;

namespace TubeRace
{
    public class TrackLine : Track
    {
        [Header("Linear track properties")] [SerializeField]
        private Transform start;

        [SerializeField] private Transform end;

        public override float Length()
        {
            return (end.position - start.position).magnitude;
        }

        public override Vector3 Position(float distance)
        {
            Vector3 startPosition = start.position;
            Vector3 direction = end.position - startPosition;

            return startPosition + direction.normalized * distance;
        }

        public override Vector3 Direction(float distance)
        {
            Mathf.Clamp(distance, 0, Length());

            return (end.position - start.position).normalized;
        }

        private void OnDrawGizmos()
        {
            Gizmos.color = Color.green;
            Gizmos.DrawLine(start.position, end.position);
        }
    }
}
```

33 ObjectPlacer

```
using UnityEngine;

namespace TubeRace
{
    public class ObjectPlacer : MonoBehaviour
    {
        [SerializeField] private GameObject prefab;
        [SerializeField] private int numObjects;
        [SerializeField] private Track track;

        [SerializeField] private int seed;
        [SerializeField] private bool canRadomizeRotation;
        [Range(0.0f, 1.0f)] [SerializeField] private float skipProbability;

        private void Start()
        {
            Random.InitState(seed);
        }
    }
}
```

```

        float distance = 0;

        for (int i = 0; i < numObjects; i++)
        {
            if (!(Random.Range(0.0f, 1.0f) <= skipProbability))
            {
                GameObject go = Instantiate(prefab);
                go.transform.position = track.Position(distance);
                go.transform.rotation = track.Rotation(distance);

                if (canRadomizeRotation)
                    go.transform.Rotate(Vector3.forward, Random.Range(0,
360), Space.Self);
            }

            distance += track.Length() / numObjects;
        }
    }
}

```

34 SplineMeshProxy

```

using SplineMesh;
using UnityEngine;
#if UNITY_EDITOR
using UnityEditor;

#endif

namespace TubeRace
{
    #if UNITY_EDITOR
        [CustomEditor(typeof(SplineMeshProxy))]
        public class SplineMeshProxyEditor : Editor
        {
            public override void OnInspectorGUI()
            {
                base.OnInspectorGUI();

                if (GUILayout.Button("Update"))
                {
                    ((SplineMeshProxy) target).UpdatePoints();
                }
            }
        }
    #endif

    [RequireComponent(typeof(Spline))]
    public class SplineMeshProxy : MonoBehaviour
    {
        [SerializeField] private BezierTrackPoint pointA;
        [SerializeField] private BezierTrackPoint pointB;
        private Spline spline;

        public void UpdatePoints()
        {
            spline = GetComponent<Spline>();

            SplineNode nodeA = spline.nodes[0];
            Transform transformA = pointA.transform;

```

```

        Vector3 positionA = transformA.position;

        nodeA.Position = positionA;
        nodeA.Direction = positionA + transformA.forward * pointA.Length;

        SplineNode nodeB = spline.nodes[1];
        Transform transformB = pointB.transform;
        Vector3 positionB = transformB.position;

        nodeB.Position = positionB;
        nodeB.Direction = positionB + transformB.forward * pointB.Length;
    }
}

```

35 ControlDevice

```

using UnityEngine;

namespace TubeRace
{
    public abstract class ControlDevice : MonoBehaviour
    {
        private HandController handController;

        public void StartMovement(HandController hand)
        {
            handController = hand;
        }

        public void StopMovement()
        {
            handController = null;
        }

        protected abstract void UpdateMovement(HandController hand);

        private void Update()
        {
            if (handController == null)
                return;

            UpdateMovement(handController);
        }
    }
}

```

36 GazePointer

```

using UnityEngine;

namespace TubeRace
{
    public class GazePointer : MonoBehaviour
    {
        [SerializeField] private Camera thisCamera;
        [Range(1, 50)] [SerializeField] private float gazeRange;

        public Vector3 DirectionRelativePlane(Vector3 planePosition)
        {

```

```

        {
            Transform transformCamera = thisCamera.transform;
            Ray ray = new Ray(transformCamera.position,
transformCamera.forward);

            bool isCollision = Physics.Raycast(
                ray, out RaycastHit rayHit,
                gazeRange,
                LayerMask.GetMask("NavigationPanel")
            );

            if (isCollision)
            {
                Vector3 hitPosition = rayHit.point;
                Debug.DrawLine(transform.position, hitPosition);

                Vector3 relativePanel = hitPosition - planePosition;
                return relativePanel;
            }

            return Vector3.zero;
        }
    }
}

```

37 HandController

```

using System;
using UnityEngine;
using UnityEngine.InputSystem;

namespace TubeRace
{
    public enum HandType
    {
        Default = 0,
        Right = 1,
        Left = 2
    }

    public class HandController : MonoBehaviour,
        WrapperInputActions.IXRIRightHandActions,
        WrapperInputActions.IXRILeftHandActions
    {
        [SerializeField] private HandType handType;

        private Transform thisTransform;
        private WrapperInputActions inputActions;

        private Vector3 InputPosition { get; set; }
        private Quaternion InputRotation { get; set; }

        private float inputSelect;

        private Vector3 lastFramePosition;
        private bool canUpdatePositionAndRotation;

        private ControlDevice pickedDevice;

        public Vector3 DeltaS()
        {

```

```

        return InputPosition - lastFramePosition;
    }

    private void PickupDevice(ControlDevice device)
    {
        canUpdatePositionAndRotation = false;
        pickedDevice = device;
        device.StartMovement(this);
    }

    private void ReleaseDevice()
    {
        canUpdatePositionAndRotation = true;
        pickedDevice.StopMovement();
        pickedDevice = null;
    }

    public void OnPosition(InputAction.CallbackContext context)
    {
        if (lastFramePosition == Vector3.zero)
            lastFramePosition = InputPosition;

        lastFramePosition = InputPosition;
        InputPosition = context.ReadValue<Vector3>();
    }

    public void OnRotation(InputAction.CallbackContext context)
    {
        InputRotation = context.ReadValue<Quaternion>();
    }

    public void OnSelect(InputAction.CallbackContext context)
    {
        inputSelect = context.ReadValue<float>();

        if (pickedDevice && inputSelect == 0)
            ReleaseDevice();
    }

    private void OnTriggerStay(Collider other)
    {
        if (pickedDevice != null)
            return;

        if (other.gameObject.CompareTag("ControlDevice") && inputSelect >
0)
        {
            ControlDevice controlDevice =
other.GetComponentInParent<ControlDevice>();
            PickupDevice(controlDevice);
        }
    }

    private void Awake()
    {
        thisTransform = transform;
        canUpdatePositionAndRotation = true;
    }

    private void Start()
    {
        inputActions = new WrapperInputActions();

        switch (handType)

```

```

        {
            case HandType.Default:
                throw new Exception("Choose hand type");
            case HandType.Right:
                inputActions.XRIRightHand.SetCallbacks(this);
                break;
            case HandType.Left:
                inputActions.XRILeftHand.SetCallbacks(this);
                break;
            default:
                throw new ArgumentOutOfRangeException();
        }

        inputActions.Enable();
    }

    private void Update()
    {
        if (!canUpdatePositionAndRotation)
            return;

        thisTransform.localPosition = InputPosition;
        thisTransform.localRotation = InputRotation;
    }
}

```

38 Lever

```

using UnityEngine;

namespace TubeRace
{
    public class Lever : ControlDevice
    {
        [SerializeField] private Transform thisMoveDirection;
        [SerializeField] private Transform thisRotationAxis;
        [SerializeField] private float speed;

        protected override void UpdateMovement(HandController hand)
        {
            Vector3 handDeltaS = hand.DeltaS();

            float moveCoeff = Vector3.Dot(
                thisMoveDirection.forward,
                handDeltaS);

            transform.rotation *= Quaternion.AngleAxis(
                moveCoeff * speed * Time.deltaTime,
                thisRotationAxis.forward);
        }
    }
}

```

39 NavigationPanel

```

using UnityEngine;

namespace TubeRace

```



```

{
    public class NavigationPanel : MonoBehaviour
    {
        [SerializeField] private GazePointer gazePointer;
        [Range(0.05f, 5f)] [SerializeField] private float deadZoneRadius;
        [Range(1f, 5f)] [SerializeField] private float maxRadius;

        public Vector3 MoveDirection()
        {
            Vector3 relPos =
gazePointer.DirectionRelativePlane(transform.position);
            relPos = Vector3.ClampMagnitude(relPos, maxRadius);

            if (relPos.magnitude < deadZoneRadius)
                relPos = Vector3.zero;

            relPos = new Vector3(
                Vector3.Dot(transform.right, relPos),
                Vector3.Dot(transform.up, relPos));

            return relPos;
        }

        private void OnDrawGizmos()
        {
            Vector3 position = transform.position;

            Gizmos.color = Color.red;
            Gizmos.DrawSphere(position, deadZoneRadius);

            Gizmos.color = new Color(0, 0, 1, 0.3f);
            Gizmos.DrawSphere(position, maxRadius);
        }
    }
}

```