3.2 rospd

rospd is the pushd equivalent of roscd. It allows you to keep multiple locations in a directory-stack while still using ros package names. You can then use the number of any directory in your directory stack to jump back there.

For example:

```
leibs@bar:~$ rospd hokuyo_node/
0 ~/ros/pkgs/laser_drivers/hokuyo_node
1 ~
leibs@bar:~/ros/pkgs/laser_drivers/hokuyo_node$ rospd roscpp_tutorials/
0 ~/ros/pkgs/ros_tutorials/roscpp_tutorials
1 ~/ros/pkgs/laser_drivers/hokuyo_node
2 ~
leibs@bar:~/ros/pkgs/ros_tutorials/roscpp_tutorials$ rospd laser_pipeline/
0 ~/ros/dev/laser_pipeline
1 ~/ros/pkgs/ros_tutorials/roscpp_tutorials
2 ~/ros/pkgs/laser_drivers/hokuyo_node
3 ~
leibs@bar:~/ros/dev/laser_pipeline$ rospd 1
0 ~/ros/pkgs/ros_tutorials/roscpp_tutorials
1 ~/ros/pkgs/laser_drivers/hokuyo_node
2 ~
3 ~/ros/dev/laser_pipeline
```