

Week 6

Application: Reactor stability analysis $A \rightarrow B$

$$\frac{dc}{dt} = \frac{F}{V} (c_f - c) - r \quad \text{(Component balance)}$$

$$\frac{dT}{dt} = \frac{F}{V} (T_f - T) + \left(\frac{-\Delta H}{\rho C_p} \right) r - \frac{UA}{V \rho C_p} (T - T_j) \quad \text{(Energy balance)}$$

Concentrations & Temp. in the reactor = ?

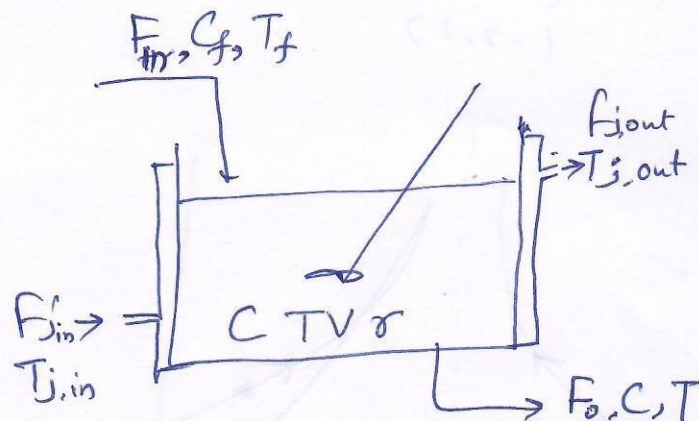
$$\frac{dh}{dt} = \frac{1}{A} (q_1 - q_2)$$

$$\frac{dVp}{dt} = F_{in} p_{in} - F_{out} p$$

$$\frac{dVC}{dt} = F_{in} C_f - F_{out} C - rV$$

$$F_{in} = F_{out} = F \quad ; \quad \frac{dV}{dt} = 0$$

let $p = \text{const}$.



complete mixing

CSTR.

Uniform mixing.

1st order

Irreversible.

$$r = KC_A$$

~~$\frac{dV}{dt} = F_{in} - F_{out}$~~ ①

②

from Component balance & Energy balance

Dynamical ~~balance~~ variable $[C \ T]'$,

2nd order system

Non-linear system

at steady state

$$\frac{dc}{dt} = 0$$

$$\frac{F}{V} (C_f - C_s) - r = 0$$

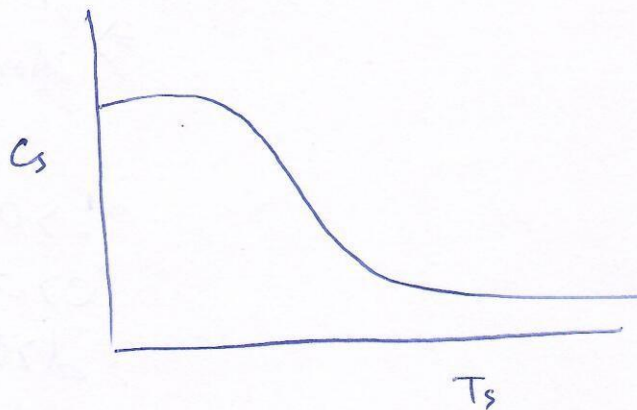
$$\frac{F}{V} (C_f - C_s) - k_0 e^{-\frac{E}{RT_s}} C_s = 0 \Rightarrow \frac{F}{V} C_f - \frac{F}{V} C_s - k_0 e^{-\frac{E}{RT_s}} C_s = 0$$

$$C_s = \frac{\frac{F}{V} C_f}{\frac{F}{V} + k_0 e^{-\frac{E}{RT_s}}}$$

$$\text{let } \frac{F C_f}{V} = a ; \frac{F}{V} = b$$

$$\frac{E}{R} = c$$

$$C_s = \frac{a}{b + k_0 e^{c/T_s}}$$



Also,

$$\frac{dT}{dt} = 0$$

$$\frac{F}{V} T_f - \frac{F}{V} T_s + \left(\frac{-\Delta H}{\rho C_p} \right) k_0 e^{-E/RT_s} \left(\frac{\frac{F}{V} C_f}{\frac{F}{V} + k_0 e^{-E/RT_s}} \right) - \frac{UA}{V \rho C_p} T_s$$

$$+ \frac{UA}{V \rho C_p} T_j = 0$$

$$\left(\frac{F}{V} + \frac{UA}{V \rho C_p} \right) T_s = \left(\frac{F T_s}{V} + \frac{U A T_j}{V \rho C_p} \right) = \frac{\left(\frac{-\Delta H}{\rho C_p} \right) k_0 e^{-E/RT_s} \left(\frac{F C_f}{V} \right)}{\left(\frac{F}{V} \right) + k_0 e^{-E/RT_s}}$$

Let $\frac{F}{V} + \frac{UA}{V \rho C_p} = p$

$$\frac{F T_s}{V} + \frac{U A T_j}{V \rho C_p} = q$$

LHS = $p T_s - q \Rightarrow \text{linear}$

$$\frac{-\Delta H k_0 F C_f}{V \rho C_p} = a$$

$$\frac{E}{R} = b ; \frac{F}{V} = c ;$$

$$k_0 = d$$

$$\text{RHS} = \frac{a e^{-\frac{b}{T_s}}}{c + d e^{-\frac{b}{T_s}}}$$

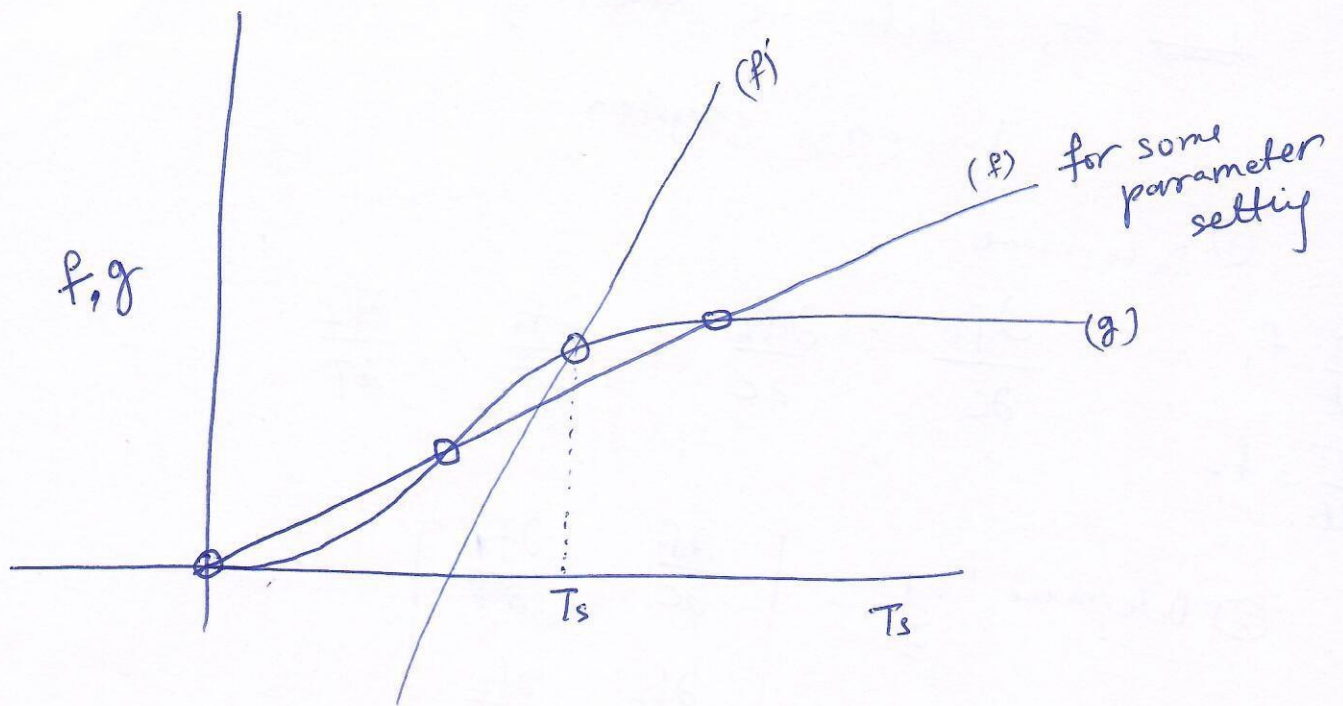
\Rightarrow Non-linear

$$b > 0$$

$$c > 0$$

$$d > 0$$

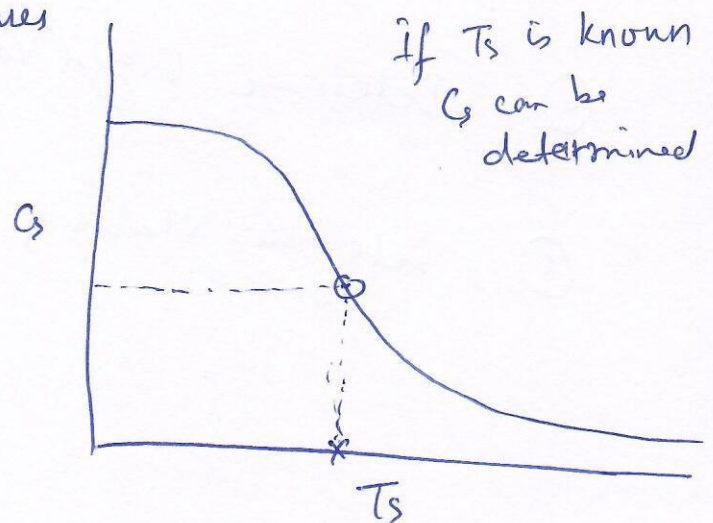
a may be
positive
or
negative
depending
on
exothermic
or
endothermic



Intersection of LHS & RHS should give steady state
 (f) (g)

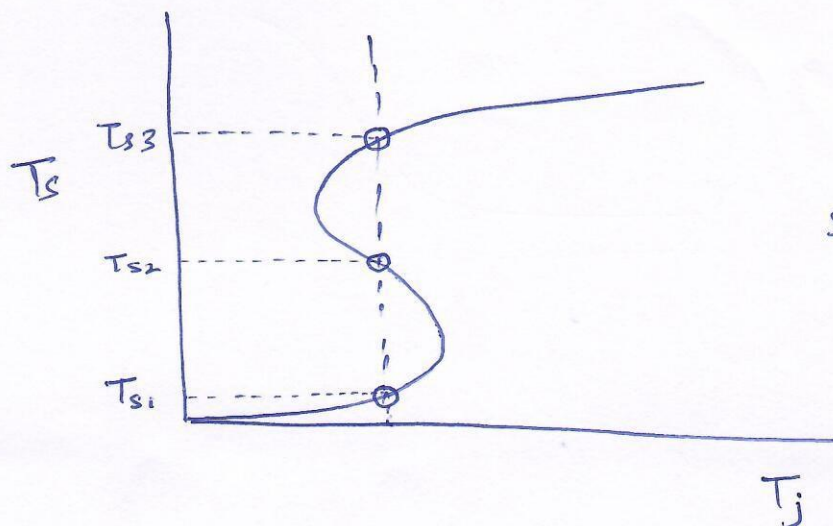
\Rightarrow 3 steady state temperatures
 \Downarrow

WHAT IS THE STABILITY OF THESE SOLUTIONS?



We can draw T_s vs T_j

DIV
 \equiv



~~how~~ To determine stability —

linearize system

① Determine

$$\frac{dc}{dt} = f_1 \quad \frac{\partial f_1}{\partial c} ; \frac{\partial f_1}{\partial T} ; \frac{\partial f_2}{\partial c} ; \frac{\partial f_2}{\partial T}$$
$$\frac{dT}{dt} = f_2$$

② Determine $\underline{J} = \begin{bmatrix} \frac{\partial f_1}{\partial c} & \frac{\partial f_1}{\partial T} \\ \frac{\partial f_2}{\partial c} & \frac{\partial f_2}{\partial T} \end{bmatrix}$

③ Determine \underline{J} at steady states. (T_{s1}, T_{s2}, T_{ss})

④ Determine Eigen Values.

⑤ Determine stability based on Eigen Values.

Example 2 - Analysis of infectious disease dynamics

Population changes w.r.t time

↳ Dynamical system

Kermack - McKendrick (SIR) model (1927)

Assumptions :-

- ✓ ①. Total population is constant
- ✓ ②. Population is divided into 3 compartment
 - S → Susceptibles (can catch disease)
 - I. - Infectives (can transmit)
 - R - Removed. [Recovered, death, etc.]
- ✓ ③. Recovery confers immunity to the individual
- ✓ ④. Incubation period is zero
- ✓ ⑤. Population is well-mixed

Mathematically

Gain in infective class \propto no. of infectives & susceptibles

$$\frac{dI}{dt} = r SI$$

$r = \text{const.}$

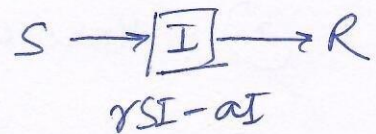
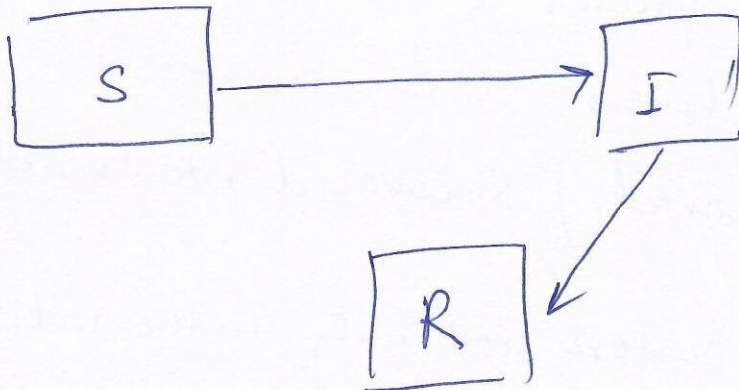
rate of removal of α no. of infectives

$$\frac{dI}{dt} = -aI$$

$a \rightarrow$ parameter constant.

Combining

$$\frac{dI}{dt} = rSI - aI$$



$$\frac{dS}{dt} = -rSI$$

$$\frac{dR}{dt} = aI$$

Initial conditions

$$S(0) = S_0$$

$$I(0) = I_0$$

$$R(0) = 0$$

$$r > 0 \quad \text{infection rate}$$

$$a > 0 \quad \text{removal rate}$$

- Q. Given r, a, S_0 and the initial number of infectives I_0 , whether the infection will spread or not?
- Q. If it spread, How will it develop with time?
- Q. When will it start to decline?
- Q. When do you declare the spread of an infectious disease an epidemic?

Dynamical Variables = $[S \ I \ R]^T$

Order = 3

Non-linear

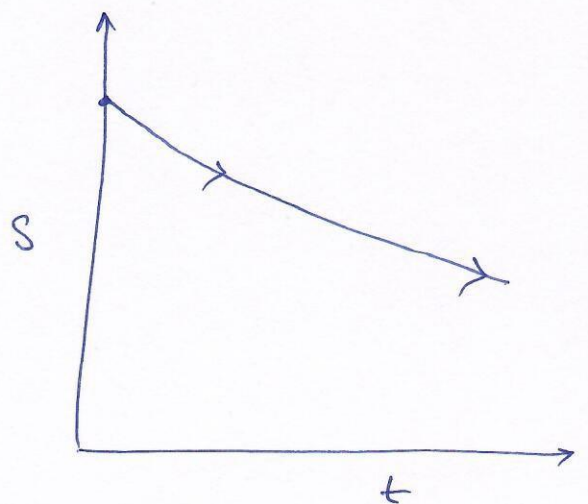
Autonomous system

$$\left. \frac{dS}{dt} \right|_{t=0} = -r S_0 I_0$$

$$r > 0 ; S_0 > 0$$

$$I_0 > 0$$

$$\left. \frac{dS}{dt} \right|_{t=0} < 0$$



$$\left. \frac{dI}{dt} \right|_{t=0} = r S_0 I_0 - a I_0$$

$$= (r S_0 - a) I_0$$

$$r S_0 - a > 0$$

$$\frac{r S_0}{a} > 1$$

$$\begin{cases} (r S_0 - a) > 0 \Rightarrow \left. \frac{dI}{dt} \right|_{t=0} > 0 \\ (r S_0 - a) < 0 \Rightarrow \left. \frac{dI}{dt} \right|_{t=0} < 0 \end{cases}$$

increase in
infection

$$R_0 = \frac{r S_0}{a} \Rightarrow \text{Reproduction number}$$

↓

number of secondary infections
produced by one primary
infection in a wholly susceptible
population.

If $R_0 > 1$
↳ pandemic.

$$R_t = \frac{r S(t)}{a} \Rightarrow \text{Replacement no.}$$

↓

no. of persons getting contaminated
by the disease on coming in
contact with an infectious person
during their course of
infectiousness

$$\frac{ds}{dt} = -rsI$$

$$\frac{dR}{dt} = aI$$

$$I = \left(-\frac{1}{r}\right) \frac{1}{s} \frac{ds}{dt}$$

$$\frac{dR}{dt} = \left(-\frac{a}{r}\right) \frac{d}{dt} \ln(s)$$

$$I = \left(-\frac{1}{r}\right) \frac{d}{dt} (\ln s)$$

$$R = \left(-\frac{a}{r}\right) (\ln s)$$

We know $S + R + I = N$ (total population)

$$\frac{ds}{dt} + \frac{dR}{dt} + \frac{dI}{dt} = 0$$

$$\frac{d}{dt} (S + R + I) = 0$$

$$S + \left(-\frac{a}{r}\right) \ln s + \left(-\frac{1}{r}\right) \frac{d}{dt} (\ln s) = N$$

$$\text{let } \ln s = x$$

$$s = e^x$$

$$e^x - \frac{1}{r} \frac{dx}{dt} - \frac{a}{r} x = N$$

Solve
for x

$$\frac{dx}{dt} = f(x)$$

then
determine

S
R
I

→ Mathematically complex

Alternate Approach is required

$$\frac{ds}{dt} = -rsI$$

$$\frac{dI}{dt} = rsI - aI$$

$$\frac{dk}{dt} = aI$$

$$\frac{dI}{ds} = \frac{rsI - aI}{-rsI}$$

$$\frac{dI}{ds} = -1 + \left(\frac{a}{r}\right) \frac{1}{s}$$

← Variation of no. of
infectives as function of
variation in no. of
Susceptibles

$$dI = \left[-1 + \frac{a}{r} \frac{1}{s} \right] ds$$

$$I = -s + \frac{a}{r} (\ln s) + C$$

$$I_0 = -s_0 + \frac{a}{r} \ln s_0 + C$$

$$C = I_0 + s_0 + \left(\frac{-a}{r}\right) \ln s_0$$

$$C = N + \left(\frac{-a}{r}\right) \ln s_0$$

$$I = -s + \frac{a}{r} \ln s + N + \left(\frac{-a}{r}\right) \ln s_0$$

$$I = -s + C_1 \ln s + N + C_2$$

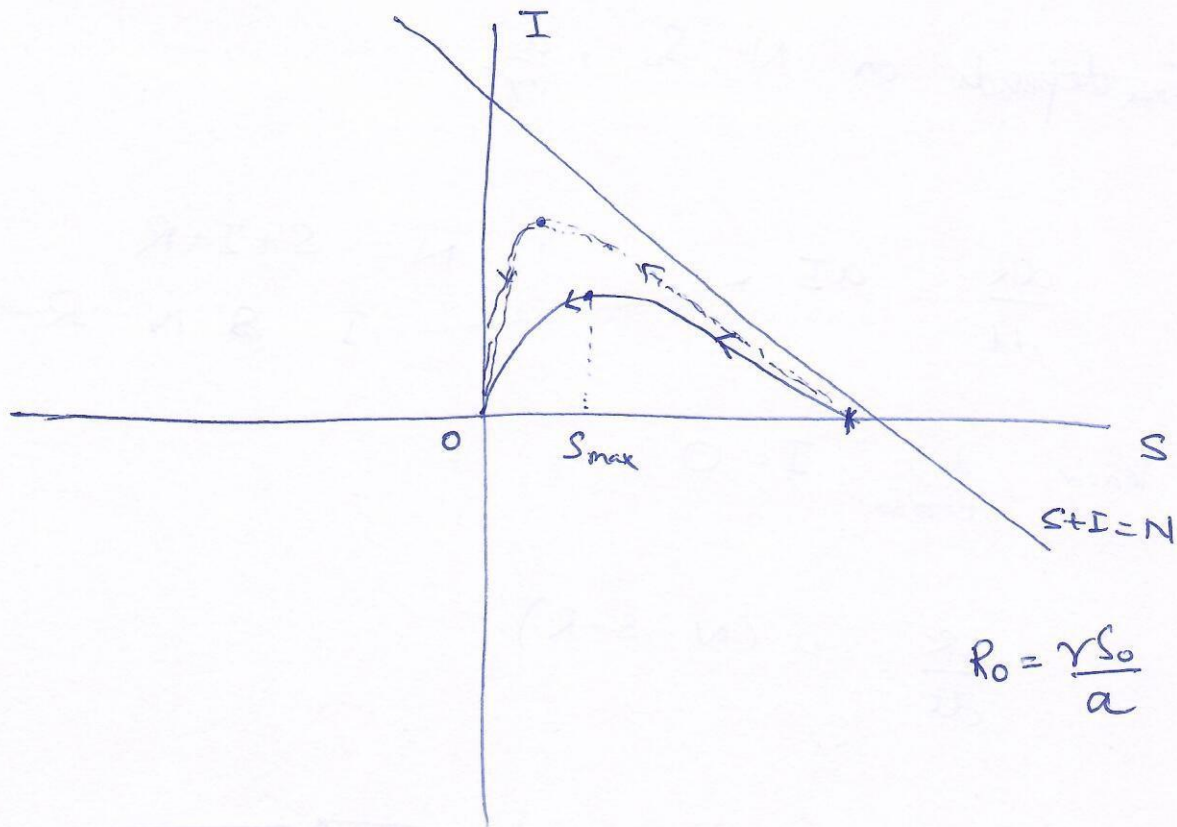
$$S_0 + I_0 = N$$

but

$$s + I < N$$

~~scribble~~

~~scribble~~



$$R_0 = \frac{\gamma S_0}{a}$$

at the peak $\frac{dI}{dt} = 0$

$$\gamma SI - aI = 0$$

$$(\gamma S - a)I = 0$$

$$\gamma S - a = 0$$

At ~~$S = \frac{a}{\gamma}$~~ $S = \frac{a}{\gamma}$ we get peak

$$I = -S + \left(\frac{a}{\gamma}\right) \ln S + N + \left(-\frac{a}{\gamma}\right) \ln S_0$$

for maxima

$$I_{\max} = \left(-\frac{a}{\gamma}\right) + \left(\frac{a}{\gamma}\right) \ln\left(\frac{a}{\gamma}\right) + N + \left(-\frac{a}{\gamma}\right) \ln(S_0)$$

$$I_{\max} = \frac{a}{\gamma} \left(-1 + \ln\left(\frac{a}{\gamma S_0}\right)\right) + N$$

I_{\max} depends on $N, S_0, \frac{a}{r}$

$$\frac{dR}{dt} = aI$$

$$N = S + I + R$$

$$I = N - R - S$$

We know $\lim_{t \rightarrow \infty} I = 0$

$$\frac{dR}{dt} = a(N - S - R)$$

α ————— α ————— α

Use Euler Method : Numerical Method

$$S_{n+1} = S_n + (\Delta t) (-r S_n I_n)$$

$$I_{n+1} = I_n + (\Delta t) (r S_n I_n - a I_n)$$

$$R_{n+1} = R_n + \Delta t (a I_n)$$

$$S_0, I_0, R_0, r, a, \Delta t$$

$$S_1 = S_0 + \Delta t (-r S_0 I_0)$$

$$S_2 = S_1 + \Delta t (-r S_1 I_1)$$

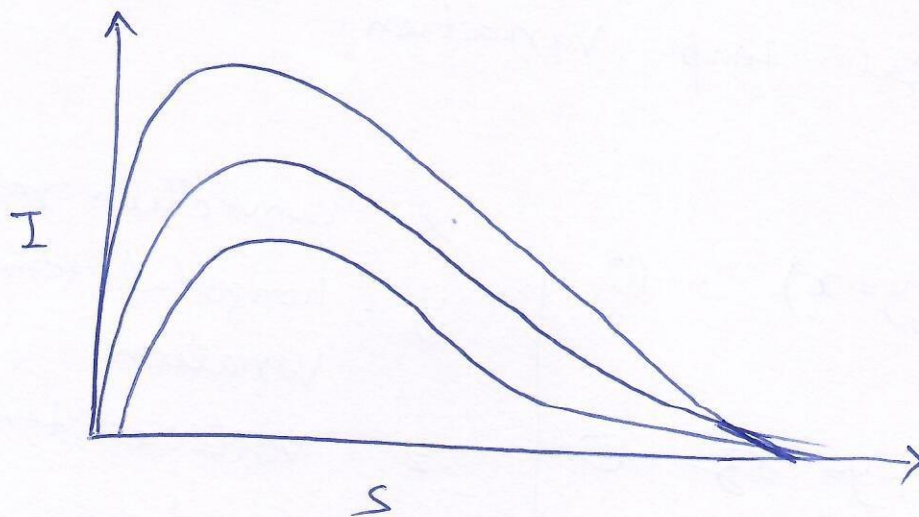
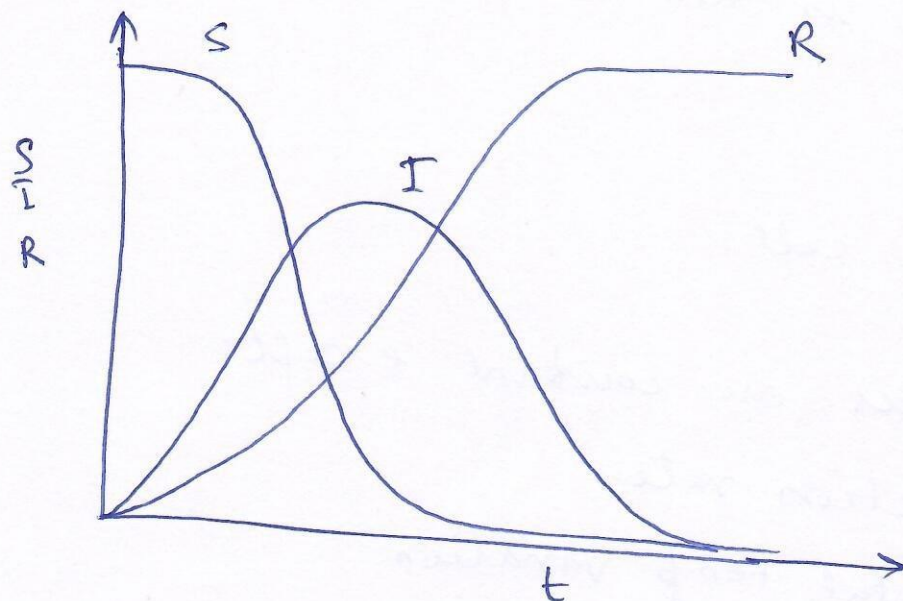
⋮

In discrete t-domain (time domain)

$$S_{t+1} = S_t - rS_t I_t$$

$$I_{t+1} = I_t + rS_t I_t - aI_t$$

$$R_{t+1} = R_t + aI_t$$



Example 3 . Atmosphere dynamics using
Lorenz equation

Assumption

- ① Consider earth's atmosphere to consist of a single fluid particle.
- ② The particle is heated from below & cooled from outside
- ③ 2-D fluid cell
- ④ all variables are constant except
convection rate
horizontal temp. variation
vertical temp. variation

$$f_1 = \frac{dx}{dt} = \sigma(y-x) \quad \text{--- (1)}$$

$$f_2 = \frac{dy}{dt} = rx - y - xz \quad \text{--- (2)}$$

$$f_3 = \frac{dz}{dt} = xy - bz \quad \text{--- (3)}$$

x = convection rate
 y = horizontal temp. variation
 z = vertical temp. variation.

σ = prandtl no.

r = rayleigh no.

b = system size

$$\sigma, r, b > 0$$

$$\sigma > b + 1$$

$$\text{Dyn. variable} = [x \ y \ z]'$$

$$\text{order} = 3$$

Non-linear,

Autonomous.

equilibrium solution

$$f_1 = f_2 = f_3 = 0$$

$$\sigma(y-x) = 0$$

$$x_e = y_e \quad \text{--- (4)}$$

$$rx - y - xz = 0$$

$$rx_e - x_e - x_e z_e = 0$$

$$\left. \begin{array}{l} x_e = 0 \\ y_e = 0 \\ z_e = 0 \end{array} \right\} \text{--- (5) equilibrium sol}$$

$$z_e = r-1$$

$$x_e^2 = b(r-1)$$

$$x_e = y_e = \pm \sqrt{b(r-1)}$$

$$\text{--- (19)} \quad \begin{bmatrix} x_e \\ y_e \\ z_e \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} \sqrt{b(r-1)} \\ \sqrt{b(r-1)} \\ r-1 \end{bmatrix}, \begin{bmatrix} -\sqrt{b(r-1)} \\ -\sqrt{b(r-1)} \\ r-1 \end{bmatrix}$$

If $r < 1$; imaginary solution.

To make realistic solutions, let's say
for $r < 1$; $(0; 0; 0)$ is a solution

If $r = 1$; $(0; 0; 0)$ is solution

If $r \geq 1$ $(0; 0; 0)$

$$\begin{bmatrix} \sqrt{b(r-1)} \\ \sqrt{b(r-1)} \\ (r-1) \end{bmatrix} ; \begin{bmatrix} \sqrt{b(r-1)} \\ -\sqrt{b(r-1)} \\ (r-1) \end{bmatrix}$$

so system has bifurcation at $r = 1$

f_1, f_2, f_3 are complex to solve by hand so
let's linearize

$$\frac{\partial f_1}{\partial x} = -\sigma ; \frac{\partial f_1}{\partial y} = \sigma ; \frac{\partial f_1}{\partial z} = 0$$

$$\frac{\partial f_2}{\partial x} = r-2 ; \frac{\partial f_2}{\partial y} = -1 ; \frac{\partial f_2}{\partial z} = -x$$

$$\frac{\partial f_3}{\partial x} = y ; \frac{\partial f_3}{\partial y} = x ; \frac{\partial f_3}{\partial z} = -b$$

$$J = \begin{bmatrix} -\sigma & \sigma & 0 \\ r-2 & -1 & -x \\ y & x & -b \end{bmatrix}$$

at equilibrium solutions.

$$J = \begin{bmatrix} -\sigma & \sigma & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -b \end{bmatrix}$$

$$\lambda_1 = -b$$

$$\lambda_2 = \frac{1}{2} \left[-(\sigma+1) + \sqrt{(\sigma+1)^2 - 4\sigma(1-r)} \right]$$

$$\lambda_3 = \frac{1}{2} \left[-(\sigma+1) - \sqrt{(\sigma+1)^2 - 4\sigma(1-r)} \right]$$

b is always +ve

$\Rightarrow \lambda_1$ is always -ve

if $0 < r < 1$; λ_2 & $\lambda_3 < 0$

\rightarrow SINK SOLUTION @ $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

$$J = \begin{bmatrix} \sqrt{b(r-1)} \\ \sqrt{b(r-1)} \\ (r-1) \end{bmatrix} =$$

$$\text{let } \sigma = 10$$

$$b = 8/3$$

$$r = 28$$

$$\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}; \begin{bmatrix} 6\sqrt{2} \\ 6\sqrt{2} \\ 27 \end{bmatrix}; \begin{bmatrix} -6\sqrt{2} \\ -6\sqrt{2} \\ 27 \end{bmatrix}$$

$$\lambda_1 = -8/3$$

$$\lambda_2, \lambda_3 = \frac{-11 \pm \sqrt{1201}}{2}$$

$$\lambda_{1,2} = \text{Re} + i\text{Im}$$

$$\text{Re} > 0$$

$$\lambda_3 = -ve$$

↓

~~oscillatory~~
circular/spiral
solution
+ Sink

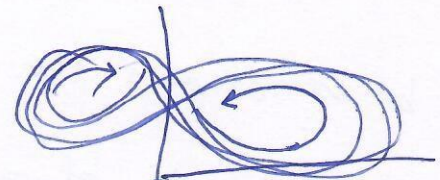
$$\lambda_1 < 0$$

$$\lambda_2 > 0$$

$$\lambda_3 < 0$$

Saddle solution

~~But~~



CHAOTIC
SYSTEM

