# **Apollo Jain**

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## Technical Skills

Languages: Python, Matlab, Java, C++, Go, Rust

Frameworks: PyTorch, TensorFlow, SciKitLearn, CVXPy, OpenCV, ROS, Gazebo, ZeroMQ

**Other:** Active DoD Top Secret Clearance

# **Professional Experience**

STR
Arlington, VA
February 2021 – Present
Scientist

- Worked on a Space-based AMTI/GMTI Radar, primarily on the beam planner and command-and-control interface (MATLAB, Python, C++).
- Conducted Program Management and 6-DOF Simulation Development for a program that aims to build AI that can design all aspects of an unmanned underwater vehicle (UUV), including navigation, energy, and 3D model constraints verification.
- Developing a system to catch rogue IMSI catchers in order to prevent tracking of USG officials. Awarded the STR Spotlight Award for my technical contributions. Technologies used include Flask, SQLite, FastAPI, and React.
- Worked on a number of other programs related to geospatial pattern-of-life (Java, PostgreSQL, PostGIS, ArcGIS), and
  rogue sensor detection, but they are classified
- Co-host of *First Mondays*, where the company brings in a speaker to talk about a strategic topic related to defense or the intelligence community.

Anduril Industries

November 2018 – October 2020
Irvine, CA

Software Engineer

- Built out radar integrations, tracking models, and software infrastructure for the company's drone tracking tower.
   Integrated various third-party RF Detection Sensors in order to improve the algorithm's confidence. Written in C++,
   Golang, and NixOS. Deployed both domestically and internationally.
- Built out the company's maritime tower product, which includes radar and VHF transceiver serial processing code, general
  infrastructure, a boat-specific sensor fusion tracking model, a CV boat classifier, and a sigmoid-based hostile boat
  classifier. Currently used in the field for drug trafficking prevention on the California coast. Written in C++, Golang, and
  NixOS.
- Created an EKF-based general purpose model for fusing high-confidence measurements (ADSB, AIS, GPS) into the system's global tracker. Prototyped in Matlab and written in C++.

UC San Francisco

Research Engineer
San Francisco, CA

August 2017 – November 2018

- Created an infrastructure pipeline in order to identify features to compute visual and text based features of MRIs using Python.
  - Created a SVM-based classification model to differentiate between MRI DICOM image types and refined a CNN-based model for the same purpose. Recorded accurate classification rate of >90%, while reducing false-positive rate by 30% by fusing aforementioned text-based features. Used Python in conjunction with ScikitLearn and PyTorch frameworks.

#### **Projects**

# **Mediate (2019)**

Worked in a four person team for YCombinator Hacks in order to build a pair of glasses for recording, searching, and querying conversations. Used an Arduino Feather, Bluetooth Module, Google Cloud Speech, and MongoDB.

### Brainwalk (2018)

Worked in a four person team on a neurodegenerative disease diagnostics project in conjunction with the UCSF Bove Lab and the Fung Fellowship. Created infrastructure in Python (Scikitlearn and SciPy) to connect the three portions of the project: Eye tracking data, sound-based signal processing, and gait data.

### Education

 UC Berkeley
 May 2018

 M.S. EECS
 GPA: 3.9

Teaching: Designing Information Devices and Systems II (Circuits, Controls, and Signal Processing)

Thesis: EV Infrastructure Planning and Grid Impact Assessment: A Case for Mexico

UC Berkeley
B.S. EECS
May 2017
GPA: 3.6

**Organizations:** ASUC Student Government (CTO), Robotics at Berkeley (Co-Founder, Vice President), Hackers at Berkeley (Director), Kairos Society

Awards: Cal Alumni Association Leadership Award, Oski Student Leadership Award, Fung Fellowship for Wellness and Technology