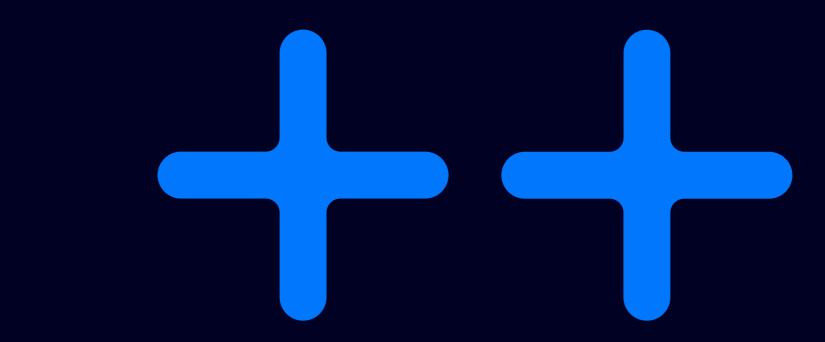
C++ZeroCost
Conf



Асинхронные фреймворки

Анатомия

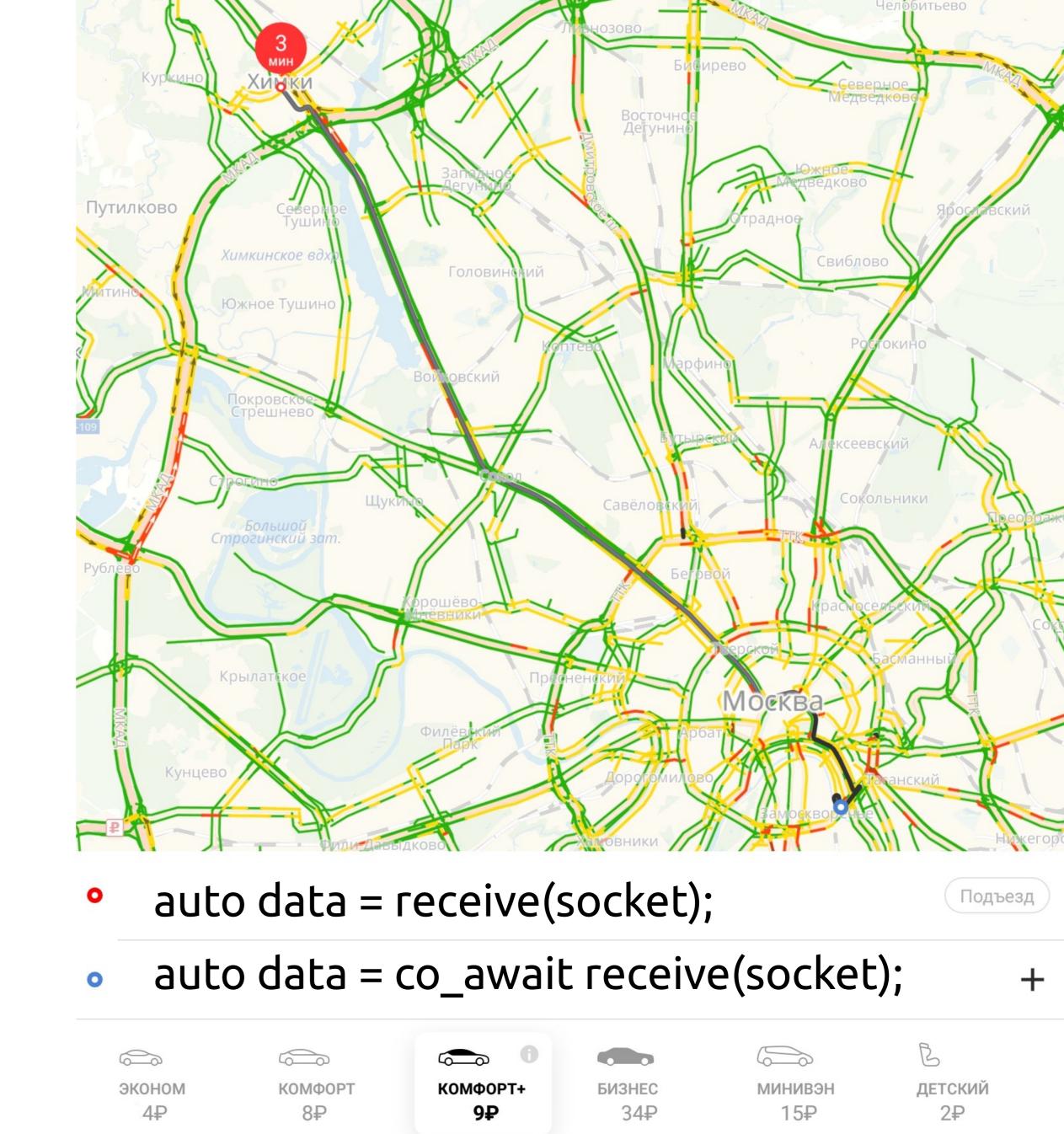


Полухин Антон Эксперт разработчик C++

Yandex for developers *//>

Содержание

- IO bound архитектуры
 - 1 поток на запрос
 - callbacks
 - корутины
- Устройство движка
- Хитрости / Хардкор
 - стек вместо «кучи»
 - неблокирующие мьютексы



Способ оплаты

Команда Яндекс.Такси

Комментарий, пожелания

Пишем синхронный сервер

```
void naive_accept() {
 for (;;) {
    auto new_socket = accept(listener);
    std::thread thrd([socket = std::move(new_socket)] {
      auto data = socket.receive();
      process(data);
      socket.send(data);
    });
    thrd.detach();
```

4/223

```
void naive_accept() {
 for (;;) {
    auto new_socket = accept(listener);
    std::thread thrd([socket = std::move(new_socket)] {
      auto data = socket.receive();
      process(data);
      socket.send(data);
    });
    thrd.detach();
```

```
void naive_accept() {
 for (;;) {
    auto new_socket = accept(listener);
    std::thread thrd([socket = std::move(new_socket)] {
      auto data = socket.receive();
      process(data);
      socket.send(data);
    });
    thrd.detach();
```

```
void naive_accept() {
 for (;;) {
    auto new_socket = accept(listener);
    std::thread thrd([socket = std::move(new_socket)] {
      auto data = socket.receive();
      process(data);
      socket.send(data);
    });
    thrd.detach();
```

7/223

```
void naive_accept() {
 for (;;) {
    auto new_socket = accept(listener);
    std::thread thrd([socket = std::move(new_socket)] {
      auto data = socket.receive();
      process(data);
      socket.send(data);
    });
    thrd.detach();
```

```
void naive_accept() {
 for (;;) {
    auto new_socket = accept(listener);
    std::thread thrd([socket = std::move(new_socket)] {
      auto data = socket.receive();
      process(data);
      socket.send(data);
    });
    thrd.detach();
```

```
void naive_accept() {
 for (;;) {
    auto new_socket = accept(listener);
    std::thread thrd([socket = std::move(new_socket)] {
      auto data = socket.receive();
      process(data);
      socket.send(data);
    });
    thrd.detach();
```

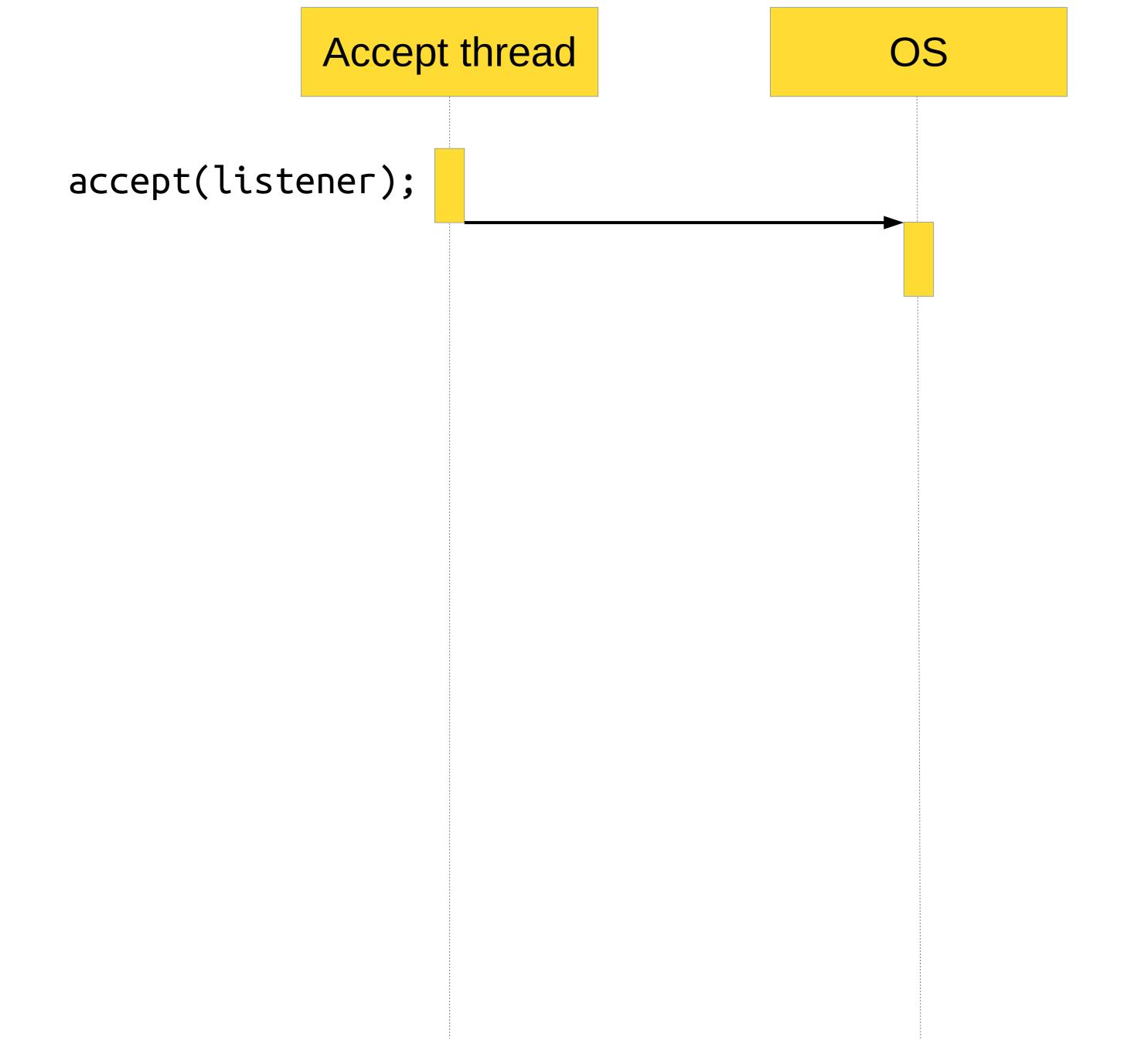
```
void naive_accept() {
 for (;;) {
    auto new_socket = accept(listener);
    std::thread thrd([socket = std::move(new_socket)] {
      auto data = socket.receive();
      process(data);
      socket.send(data);
    });
    thrd.detach();
```

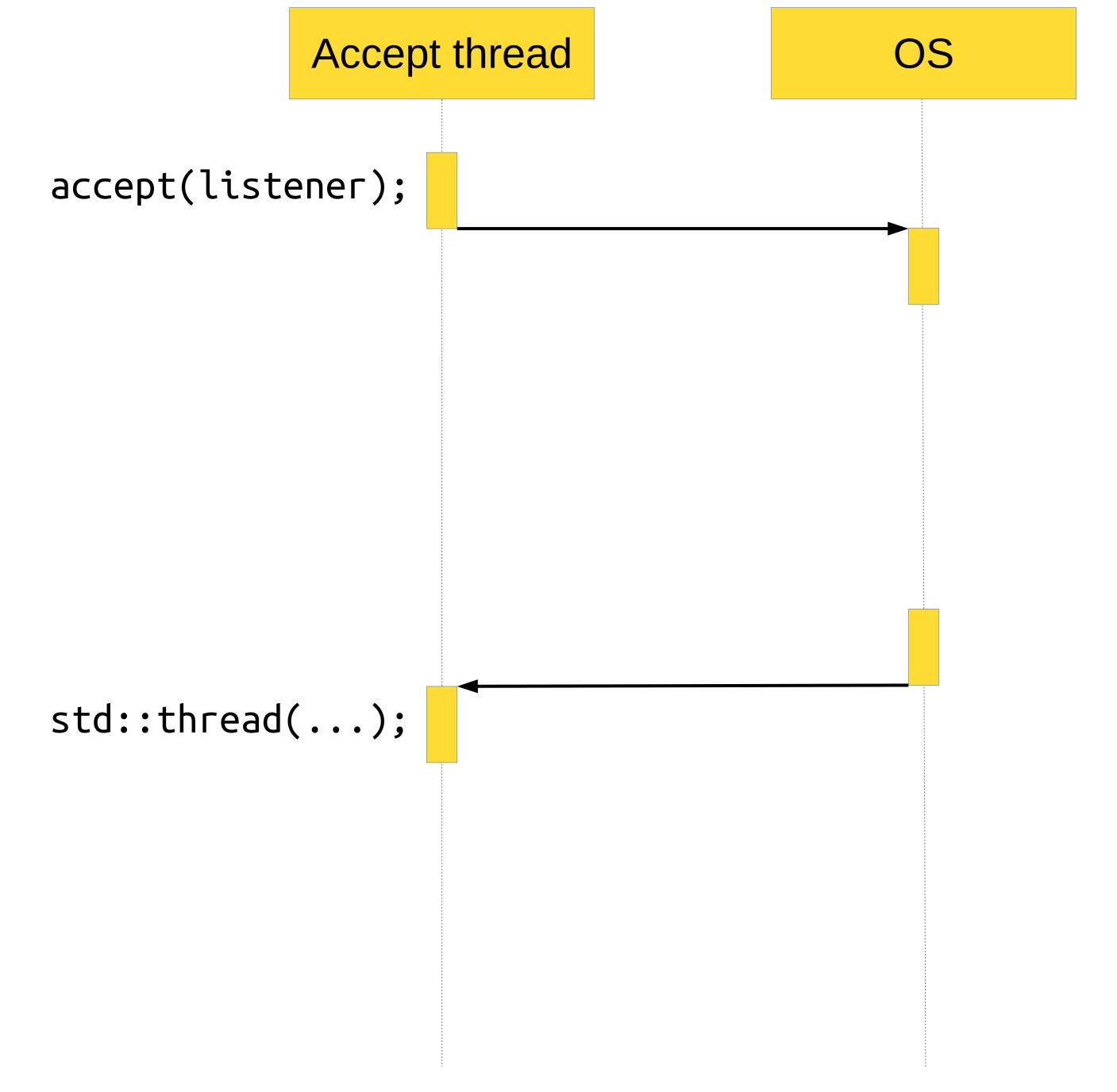
```
void naive_accept() {
 for (;;) {
    auto new_socket = accept(listener);
    std::thread thrd([socket = std::move(new_socket)] {
      auto data = socket.receive();
      process(data);
      socket.send(data);
    });
    thrd.detach();
```

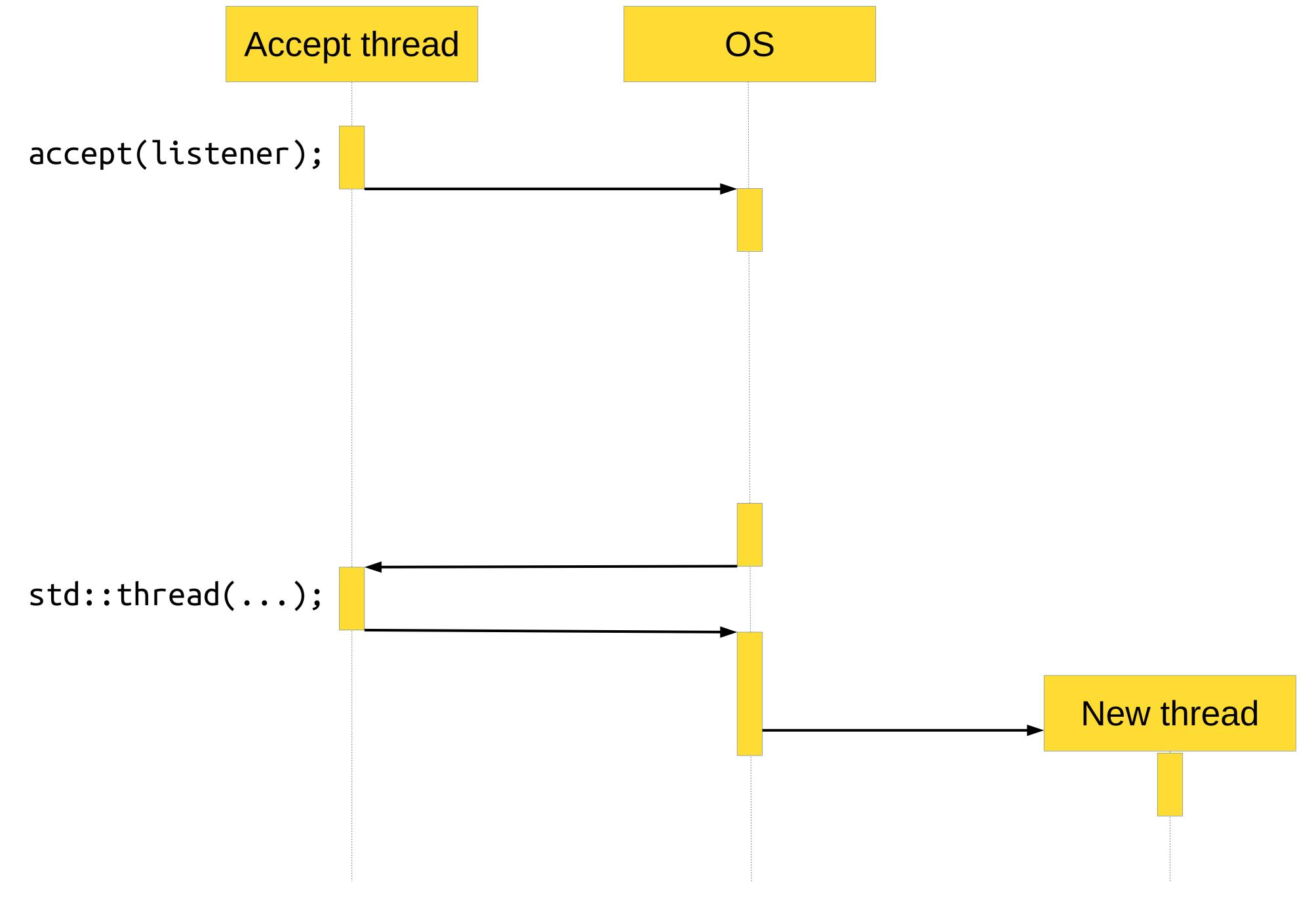
```
void naive_accept() {
 for (;;) {
    auto new_socket = accept(listener);
    std::thread thrd([socket = std::move(new_socket)] {
      auto data = socket.receive();
      process(data);
      socket.send(data);
    });
    thrd.detach();
```

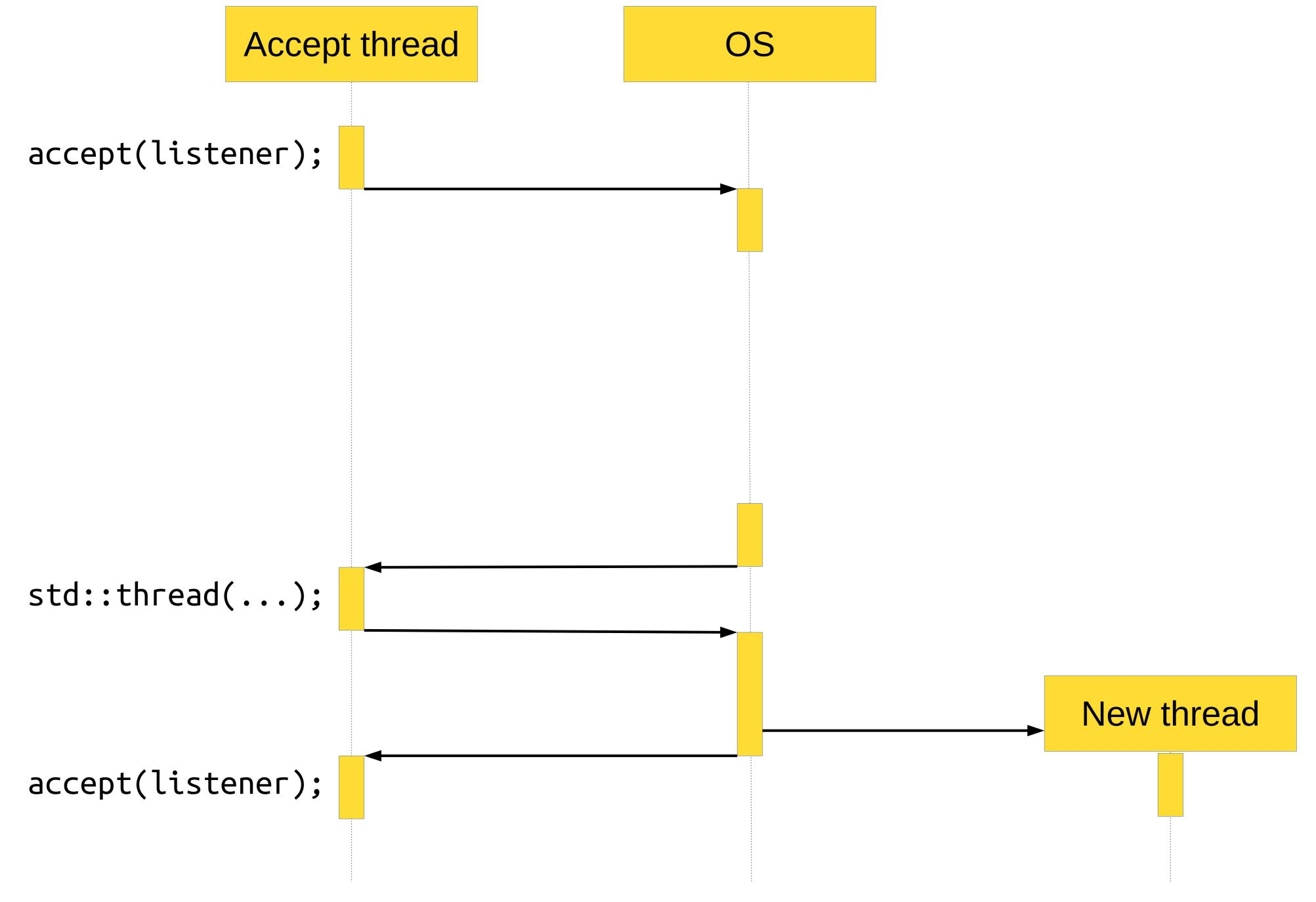
```
void naive_accept() {
 for (;;) {
    auto new_socket = accept(listener);
    std::thread thrd([socket = std::move(new_socket)] {
      auto data = socket.receive();
      process(data);
      socket.send(data);
    });
    thrd.detach();
```

Accept t	thread	0	S



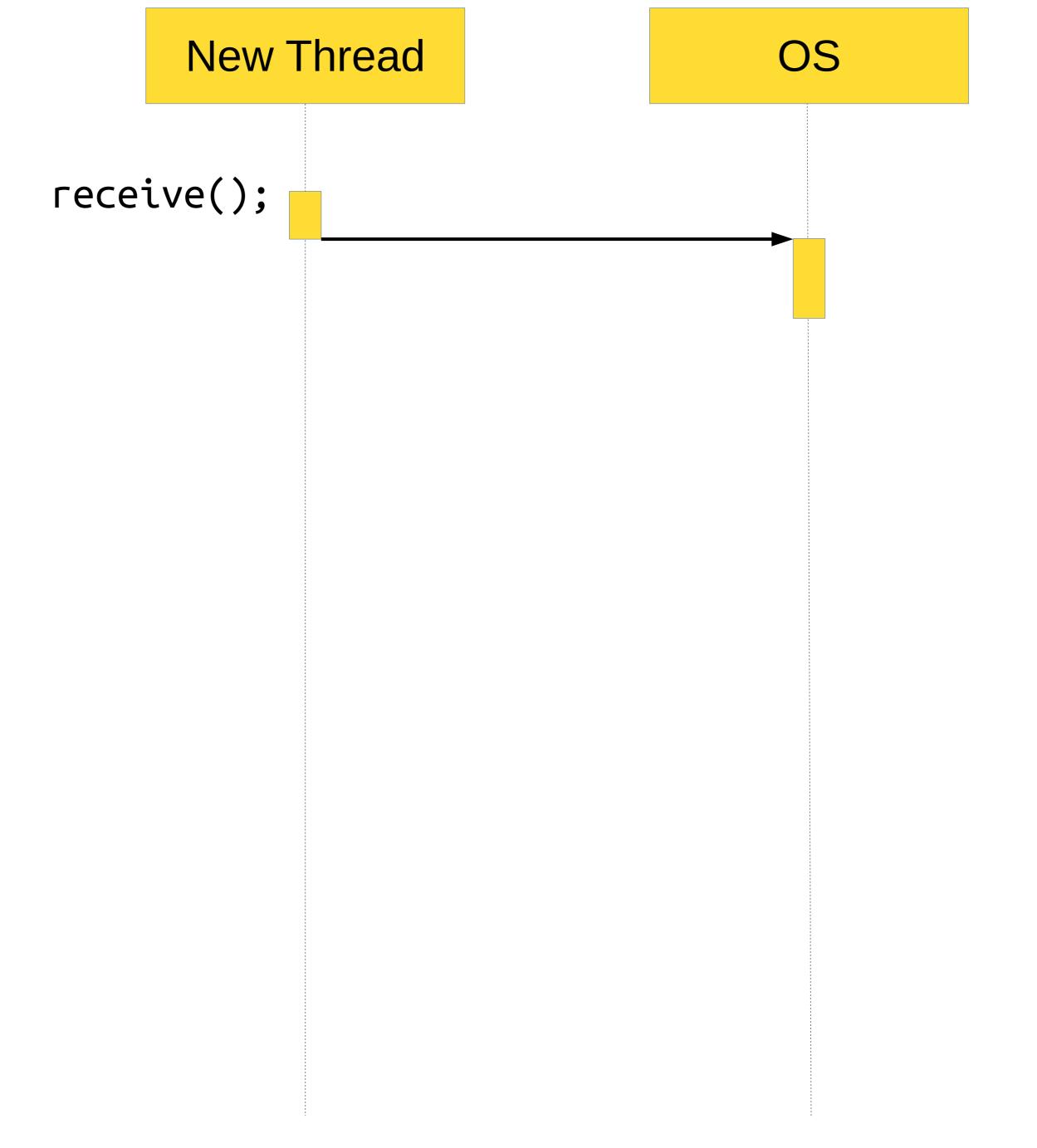


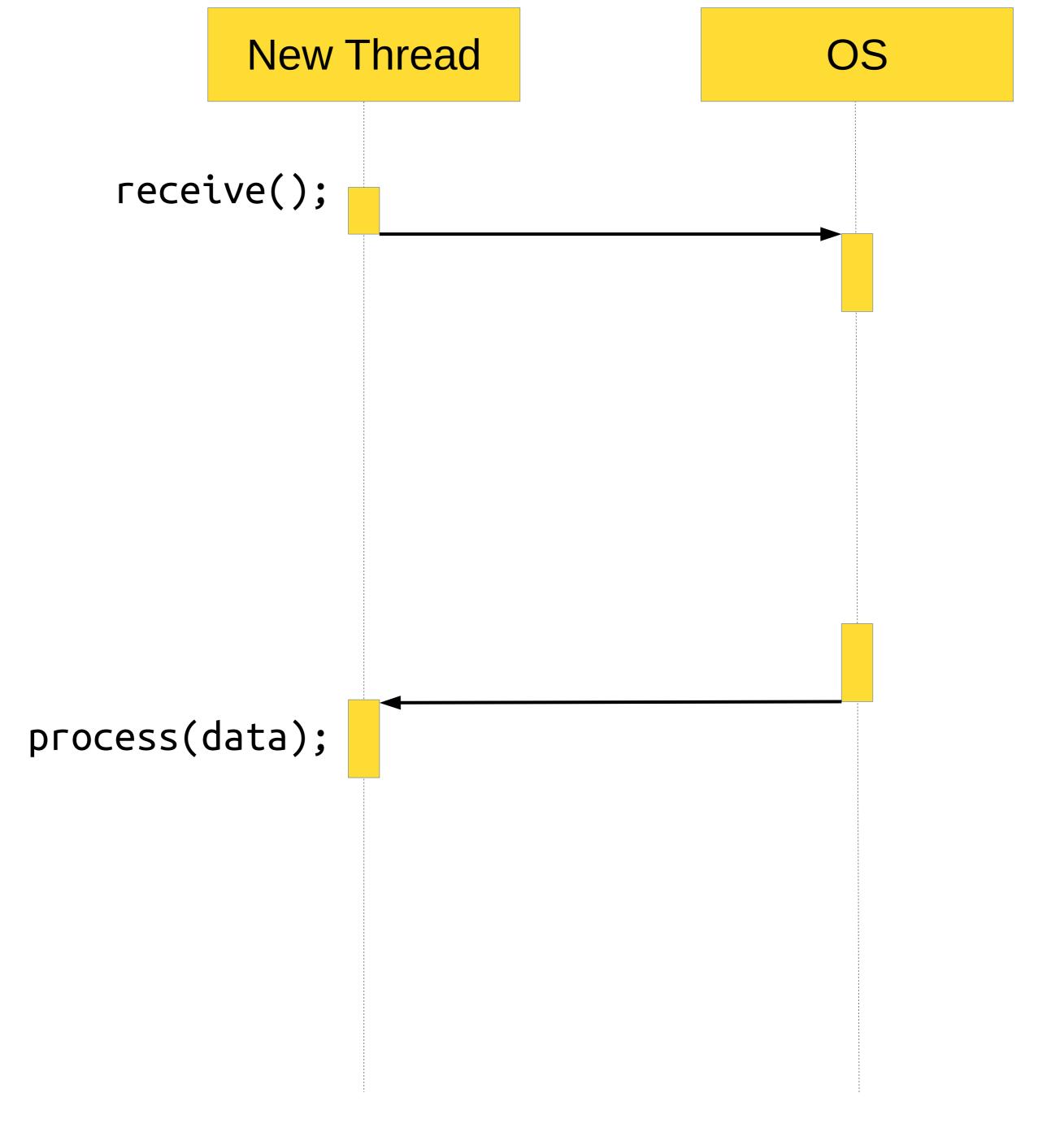


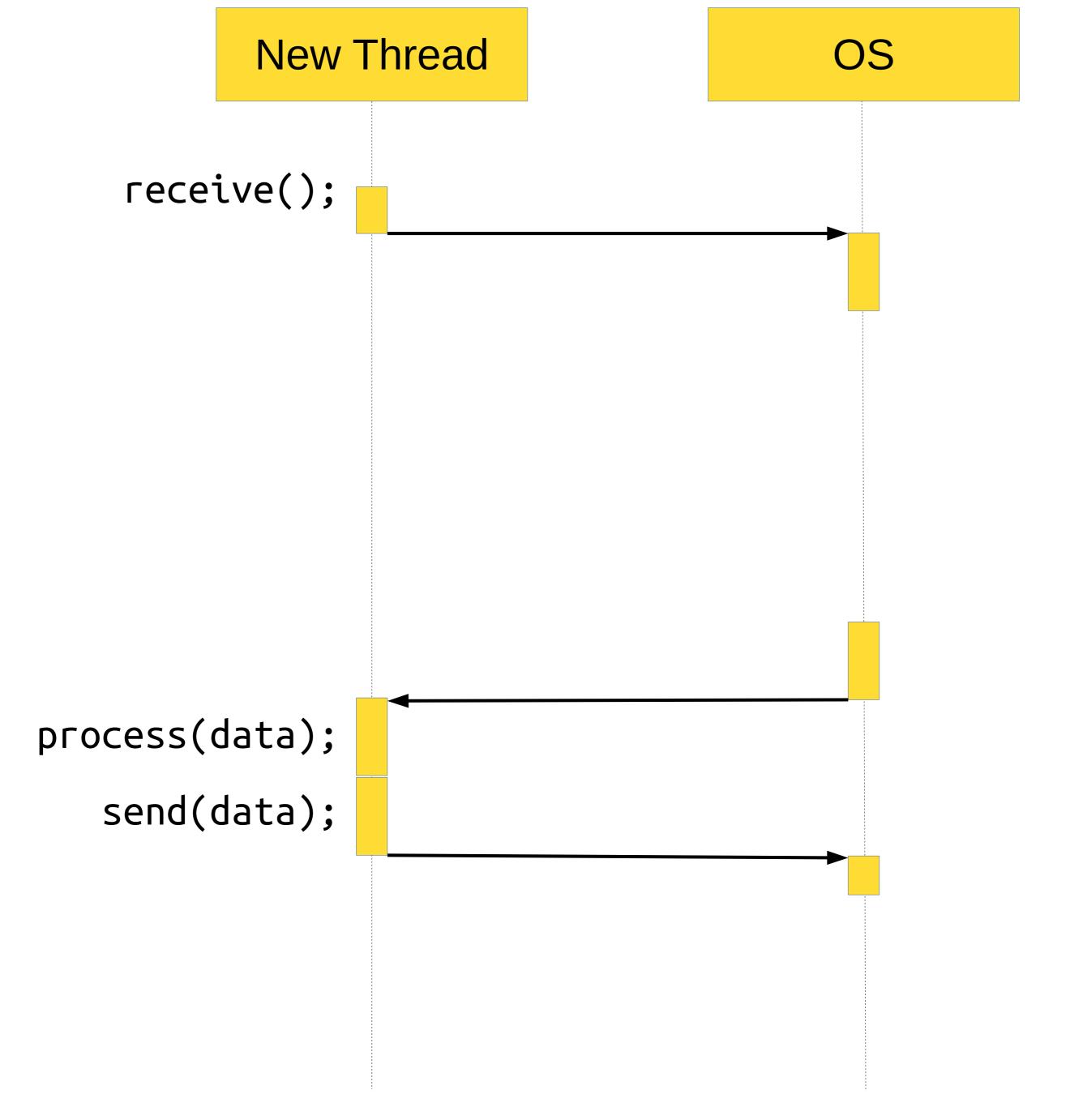


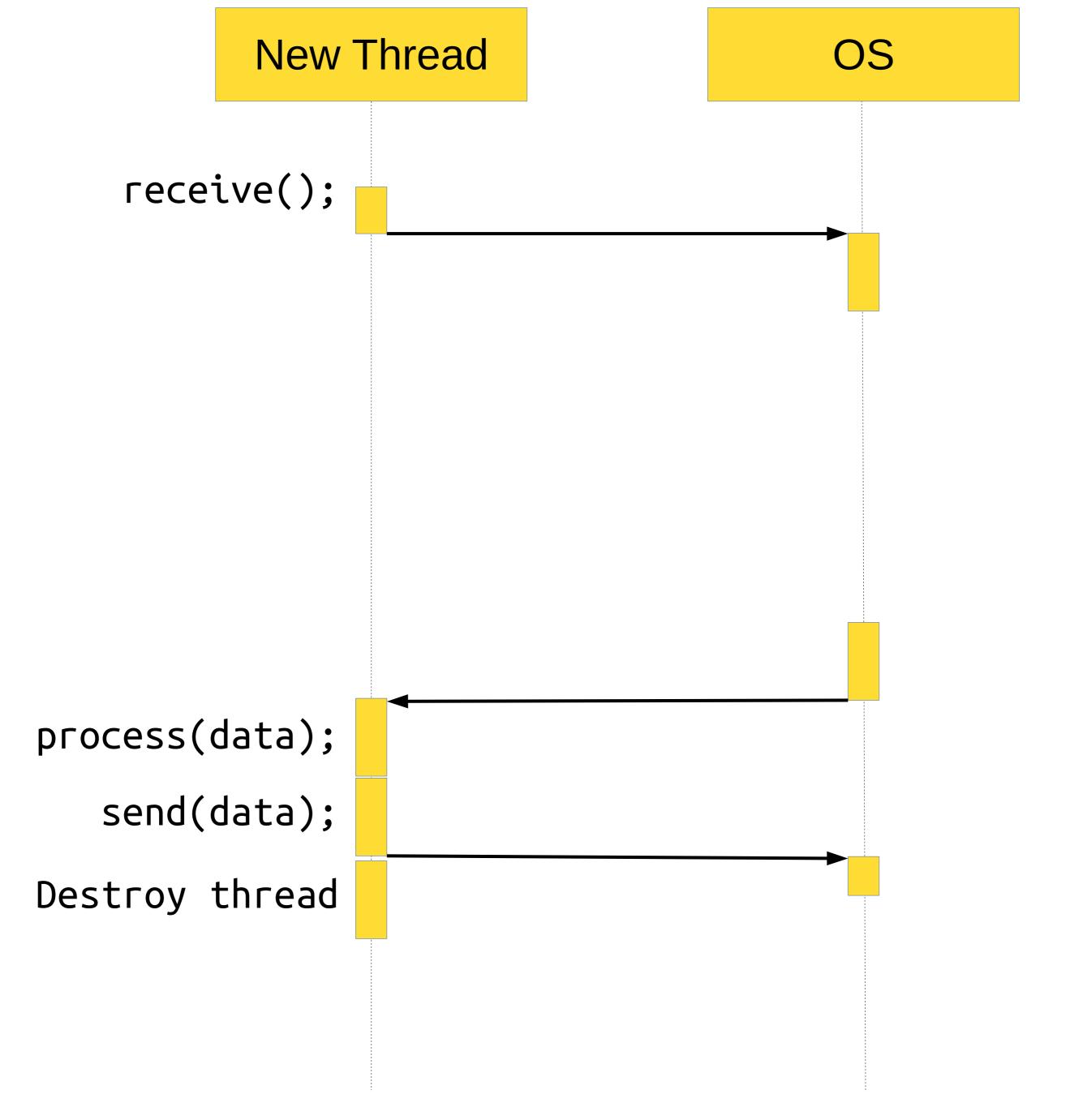
Что там делает новый поток?

New Thread	OS	









Плюсы:

Плюсы:

• Всё просто и читаемо

Плюсы:

• Всё просто и читаемо

Минусы:

Плюсы:

• Всё просто и читаемо

Минусы:

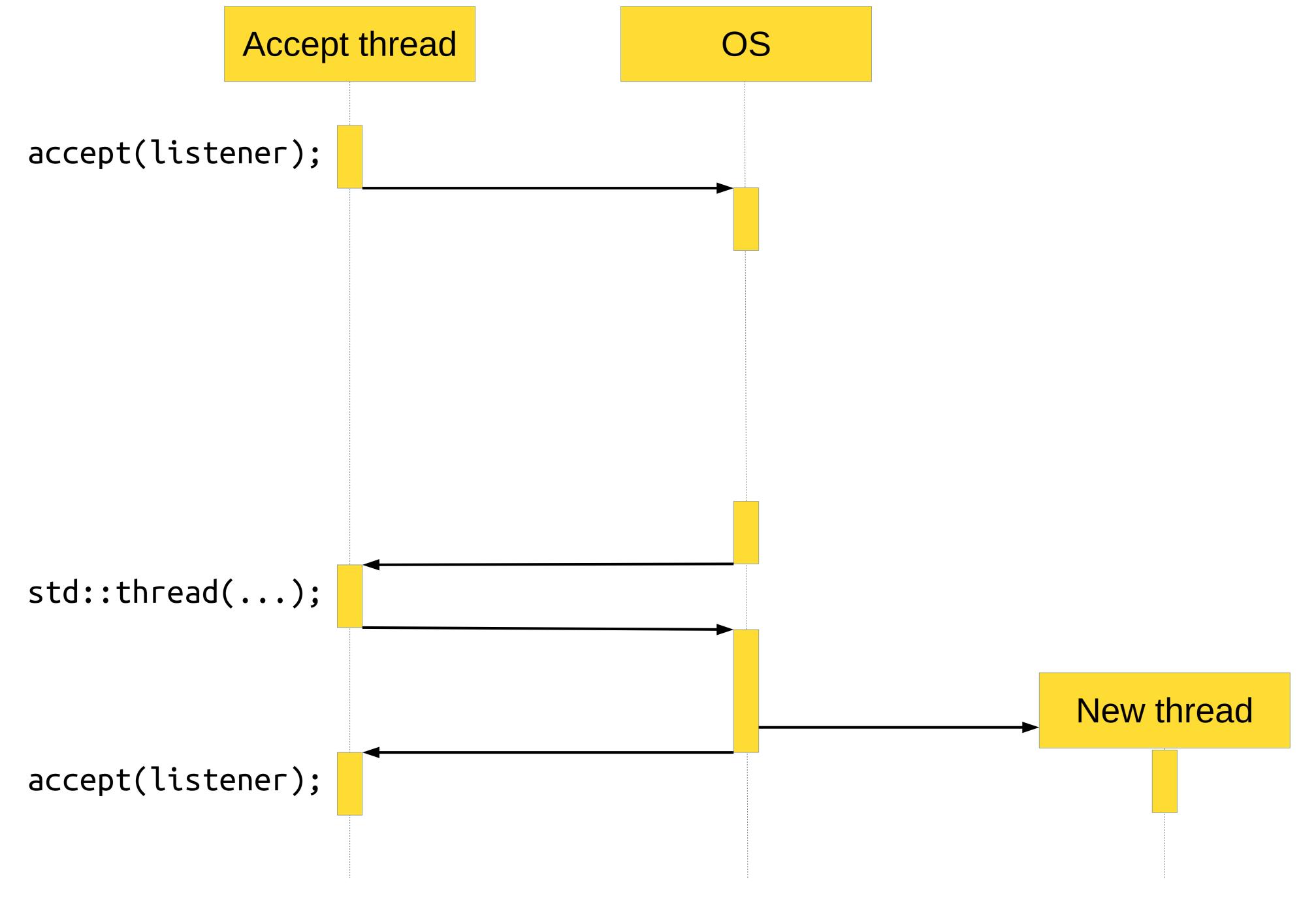
• Не эффективно, потому что...

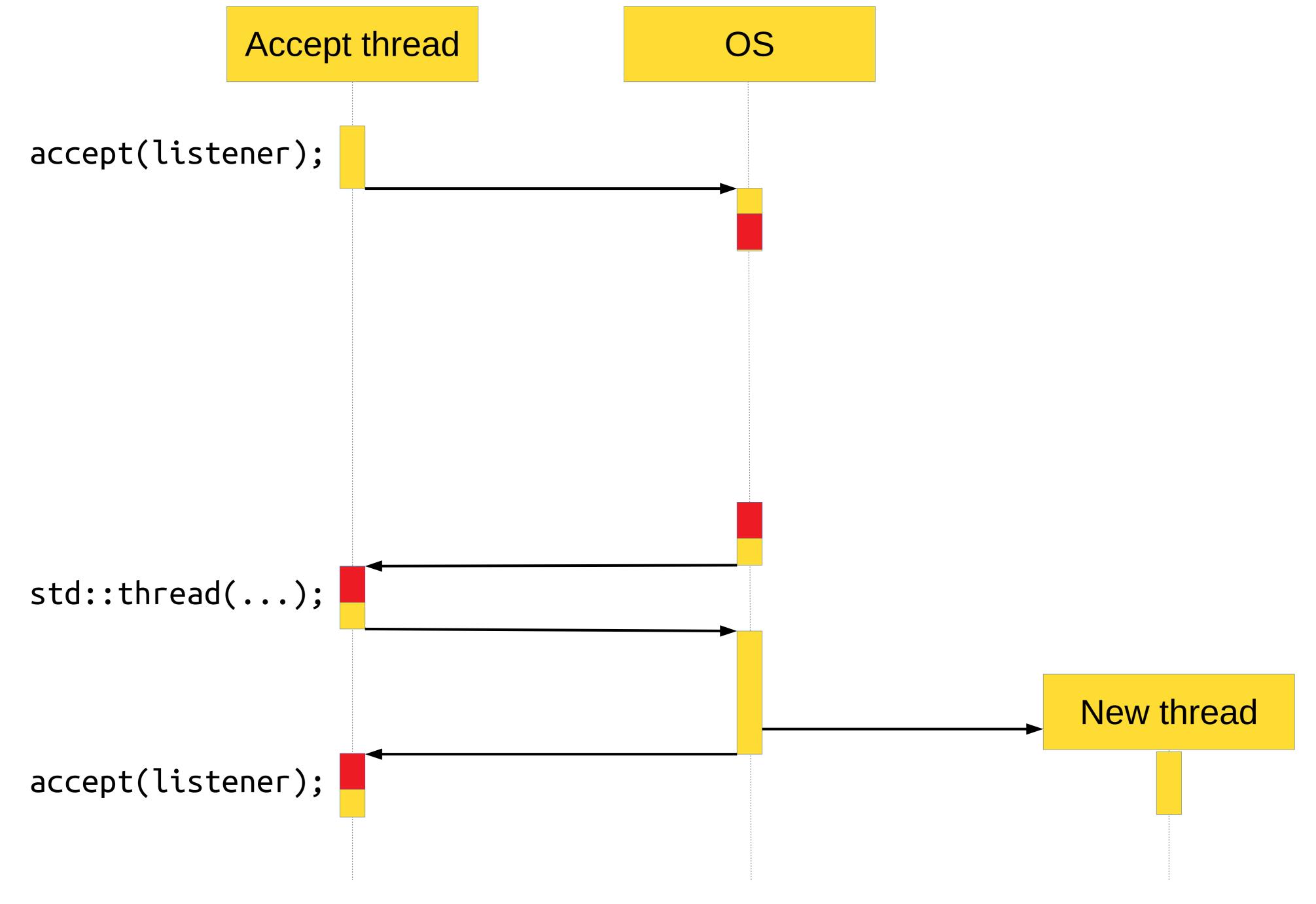
«Цена» операции

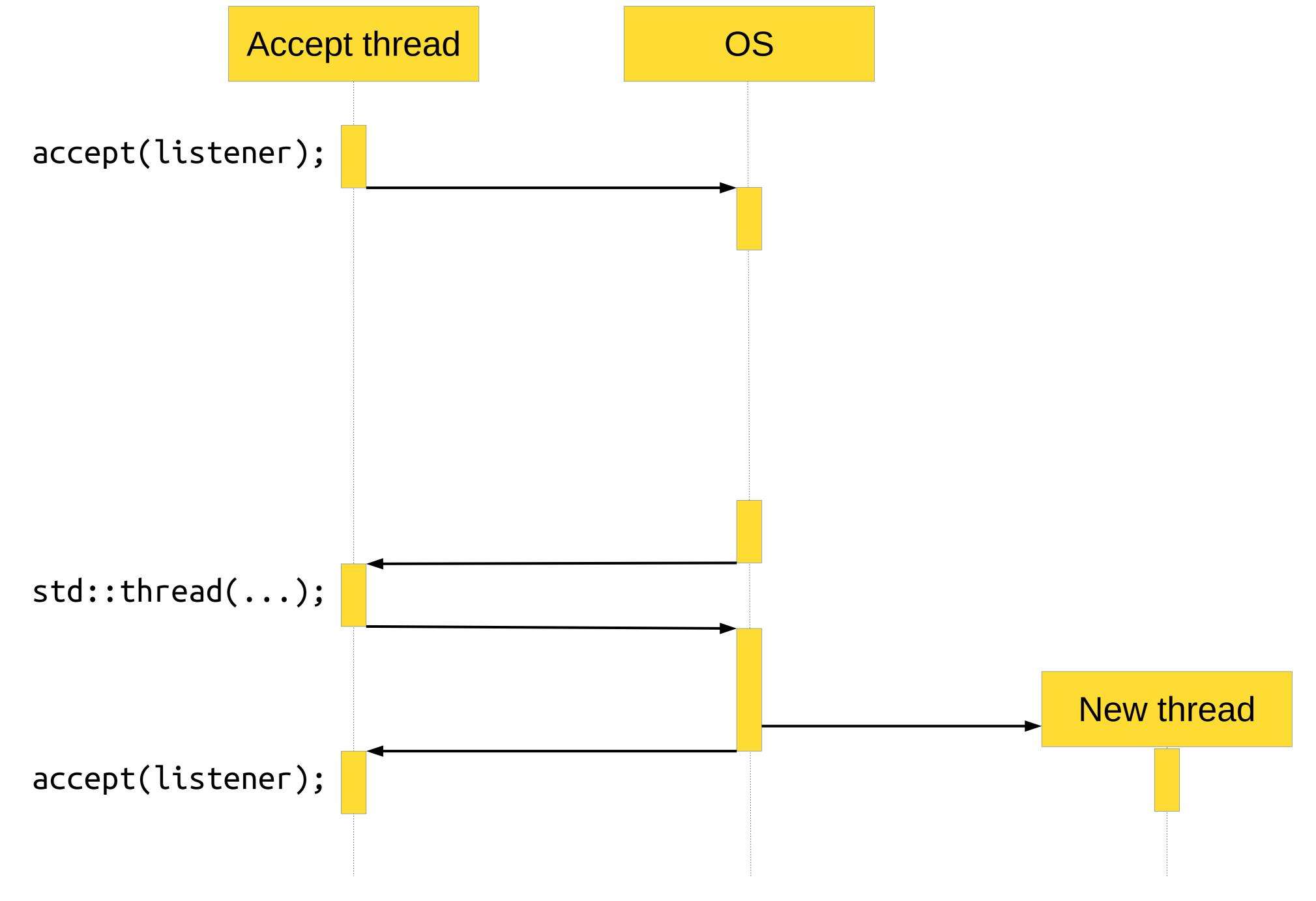
ithare.com	Operation Cost in CPU Cycles	10°	10¹	10 ²	10³	104	10⁵	10 ⁶
"Simple"	"Simple" register-register op (ADD,OR,etc.)							
Memory write		~1						
	Bypass delay: switch between							
	integer and floating-point units							
	"Right" branch of "if"							
	Floating-point/vector addition							
	Multiplication (integer/float/vector)							
	Return error and check	1-7						
	L1 read	3-4						
	TLB miss		7-21					
	L2 read		10-12					
"Wrong" b	oranch of "if" (branch misprediction)		10-20					
	Floating-point division		10-40					
	128-bit vector division		10-70					
	Atomics/CAS		15-30					
	C function direct call		15-30					
	Integer division		15-40					
	C function indirect call		20-5	0				
	C++ virtual function call		30	0-60				
	L3 read		30	0-70				
	Main RAM read			100-150				
N	UMA: different-socket atomics/CAS			100-300				
	(guesstimate)			100-300				
	NUMA: different-socket L3 read			100-300				
	on+deallocation pair (small objects)			200-500				
NUM	AA: different-socket main RAM read			300-	500			
	Kernel call				1000-1500			
٦	Thread context switch (direct costs)				2000			
	C++ Exception thrown+caught				5000-1	0000		
	Thread context switch (total costs, including cache invalidation)					10000 -	1 million	

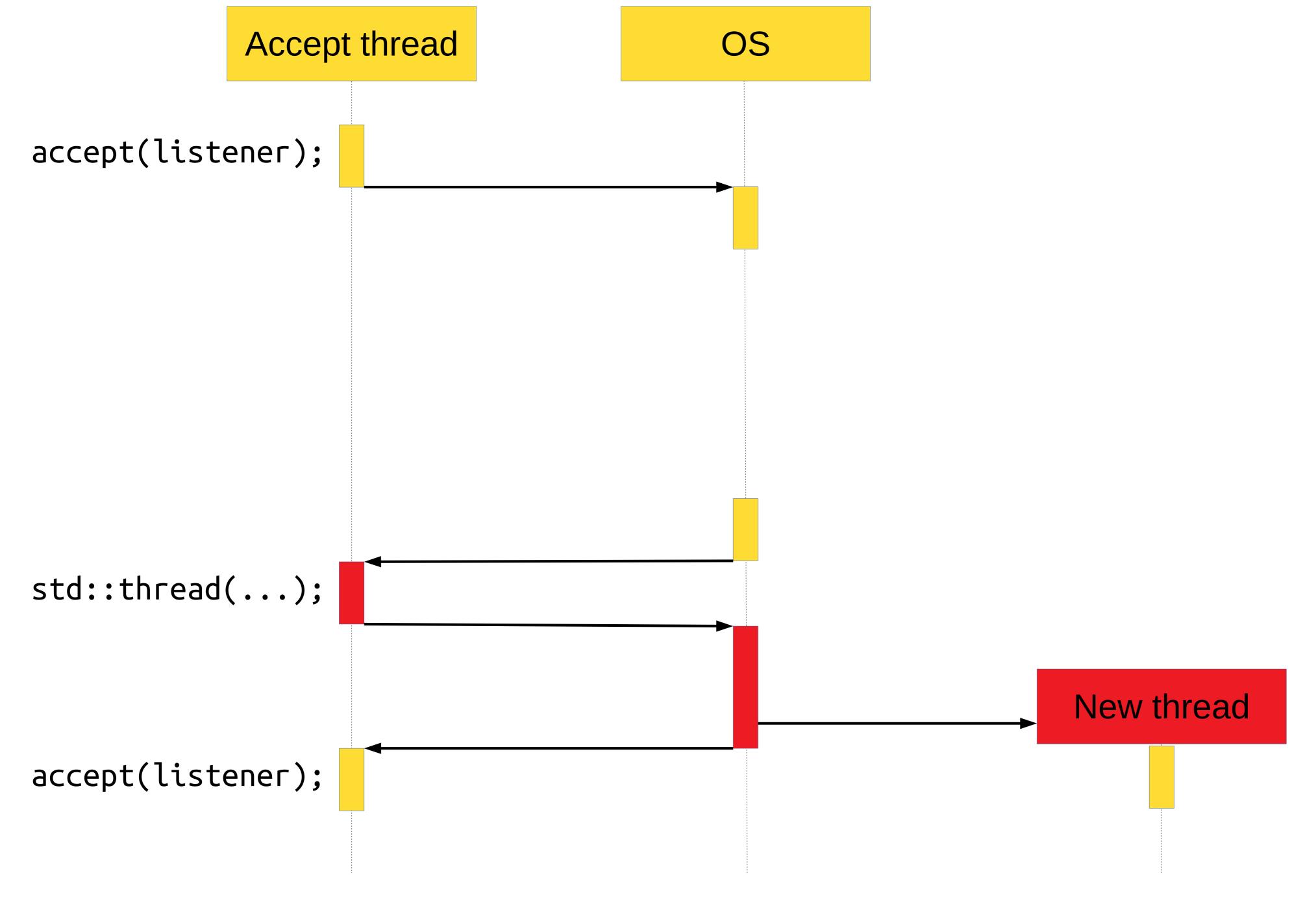
Kernel call / Context Switch

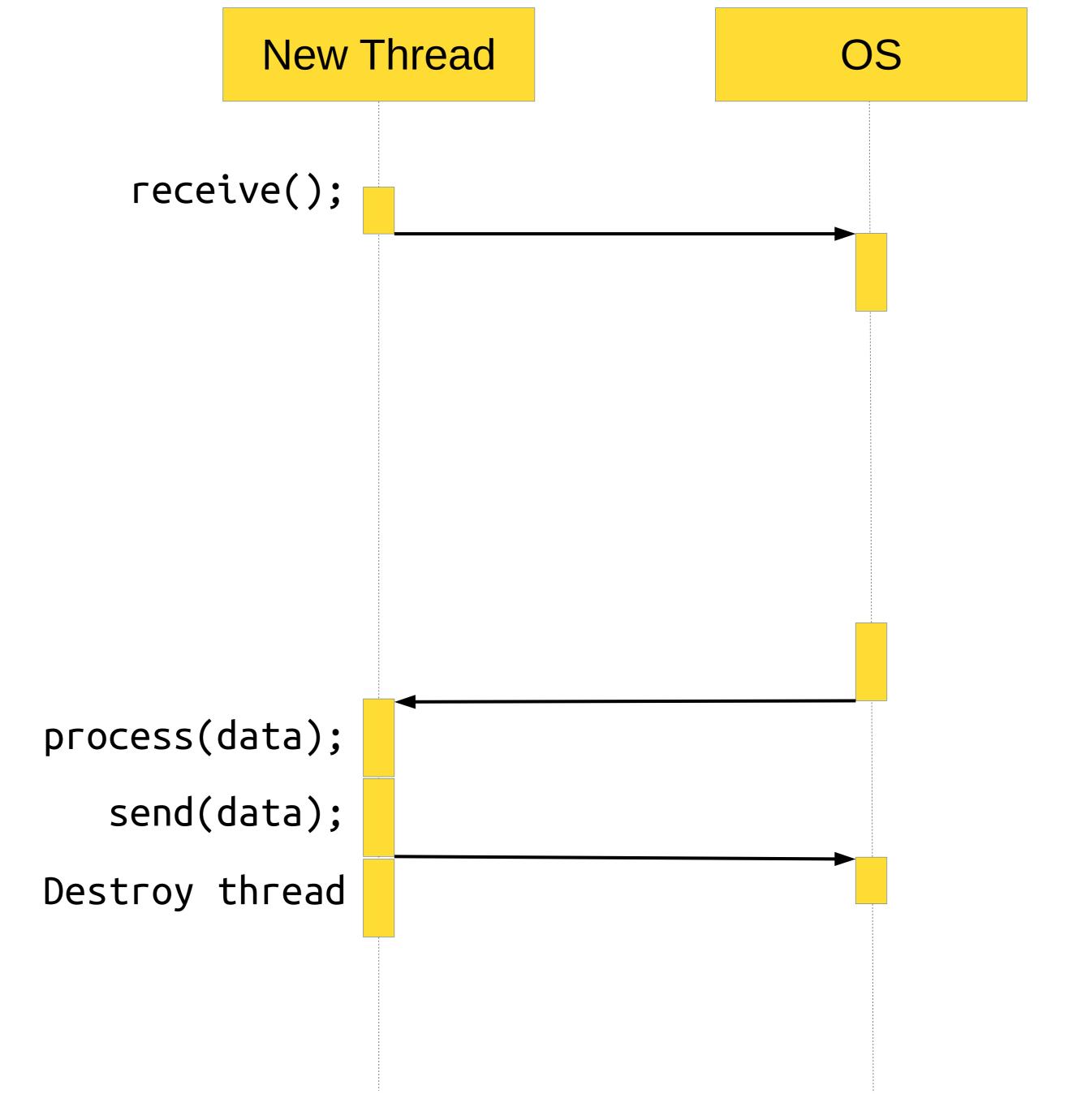
	111				
Allocation+deallocation pair (small objects)		200-500			
NUMA: different-socket main RAM read		300-500			
Kernel call			1000-1500		
Thread context switch (direct costs)			2000		
C++ Exception thrown+caught			5000-10000		
Thread context switch (total costs,				40000 4 111	
including cache invalidation)				10000 - 1 million	

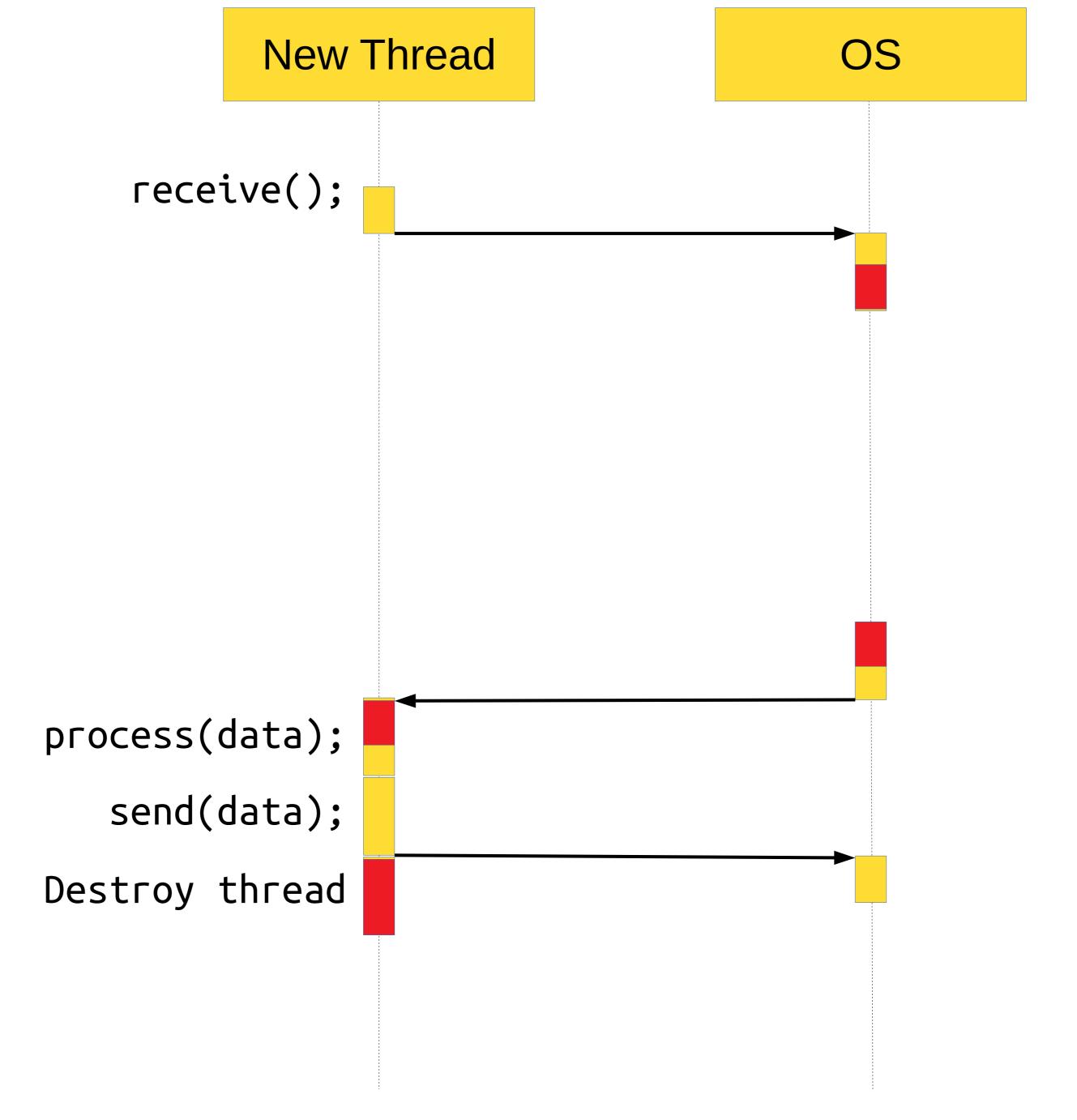












Пишем асинхронный сервер

Было:

Было:

• Отдаём управление ОС при системном вызове

Было:

- Отдаём управление ОС при системном вызове
- Ждём пока событие случится

Было:

- Отдаём управление ОС при системном вызове
- Ждём пока событие случится
- ОС будит поток

Было:

- Отдаём управление ОС при системном вызове
- Ждём пока событие случится
- ОС будит поток

Станет:

Было:

- Отдаём управление ОС при системном вызове
- Ждём пока событие случится
- ОС будит поток

Станет:

• «Забираем» случившиеся события

Было:

- Отдаём управление ОС при системном вызове
- Ждём пока событие случится
- ОС будит поток

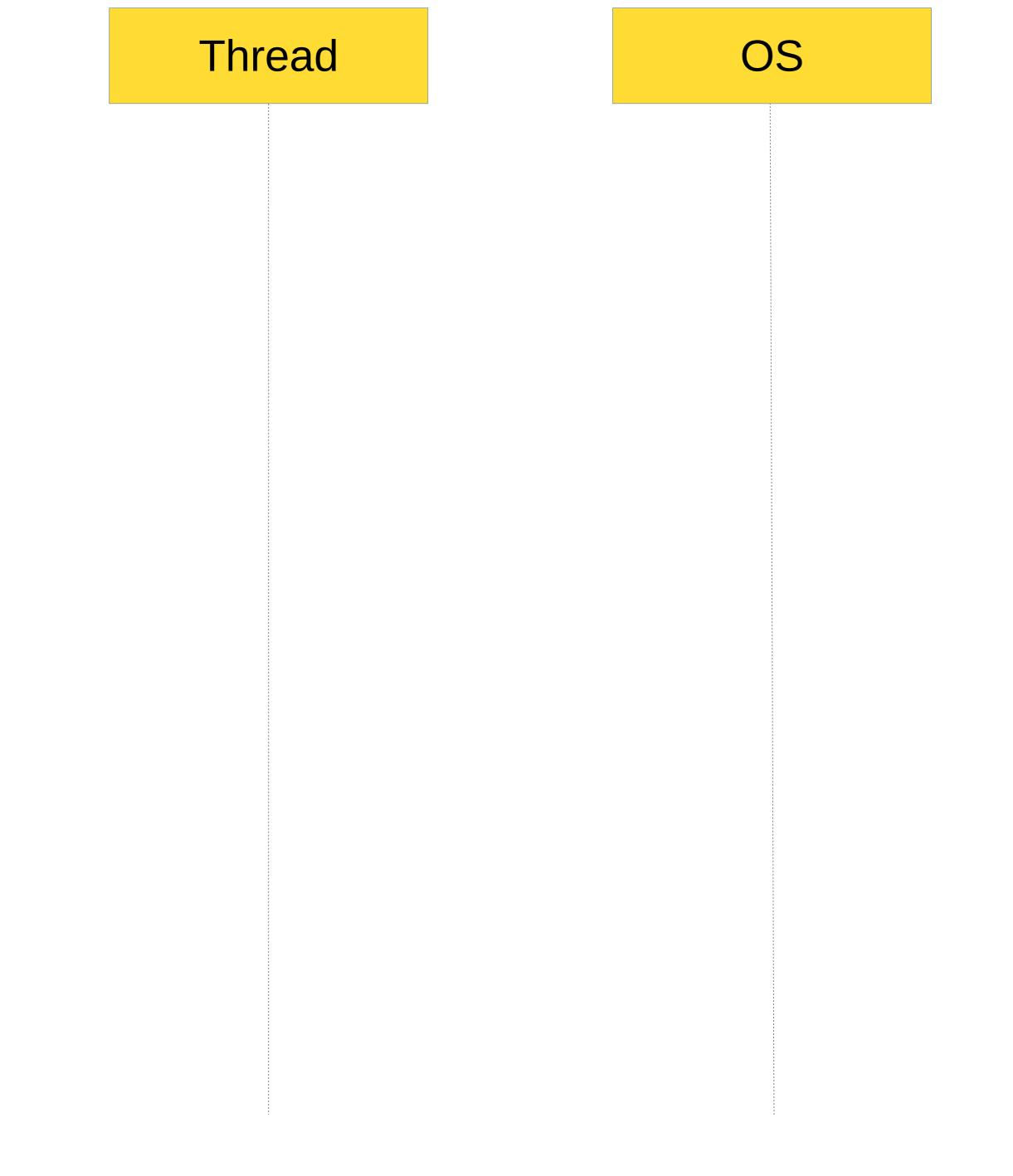
Станет:

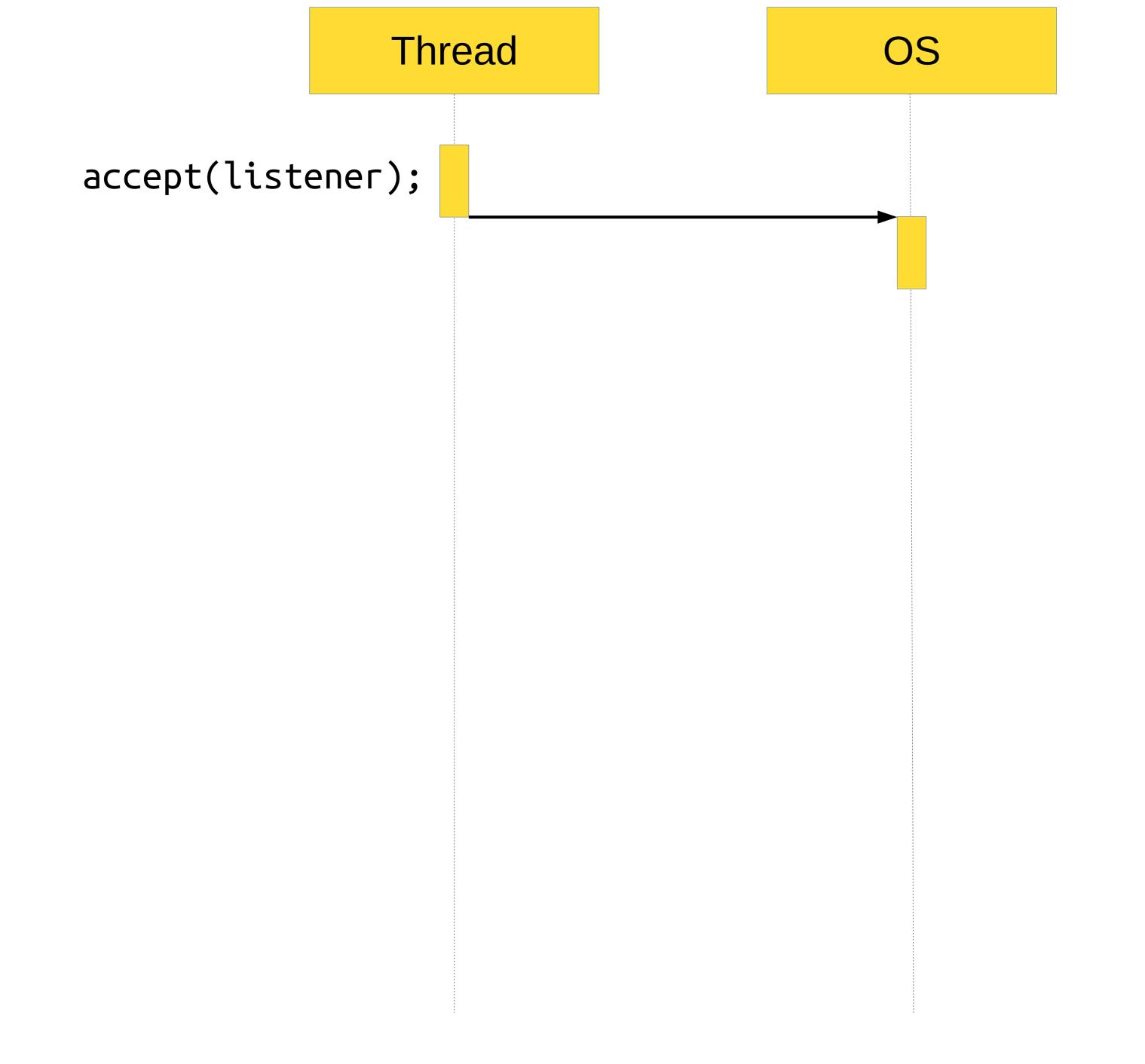
- «Забираем» случившиеся события
- Выполняем коллбеки, связанные с этим событиями

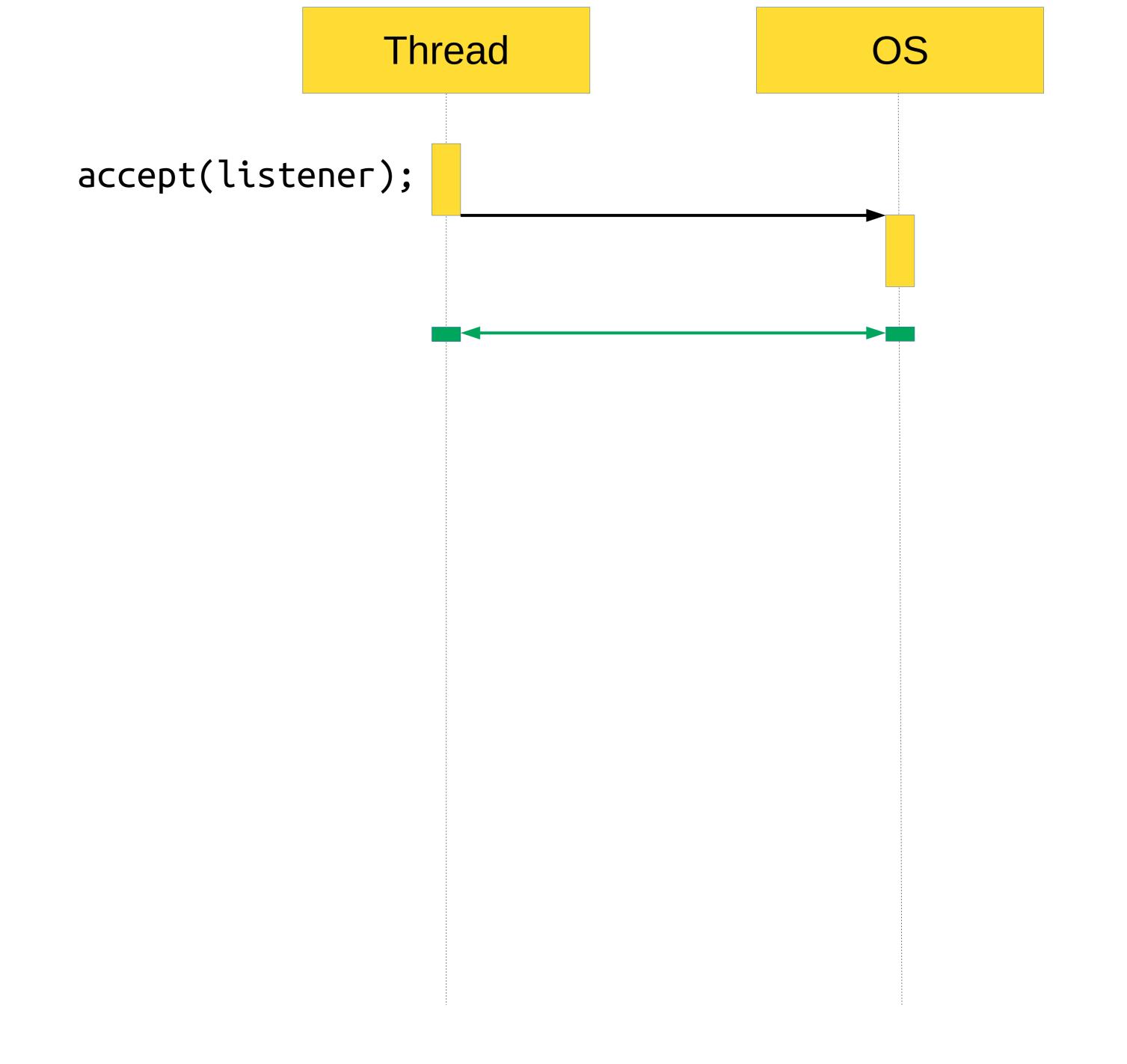
```
void async_accept() {
   accept(listener, [](socket_t socket) {
       async_accept();
       socket.receive(
            [socket](std::vector<unsigned char> data) {
            process(data);
            socket.send(data, kNoCallback);
            });
      });
}
```

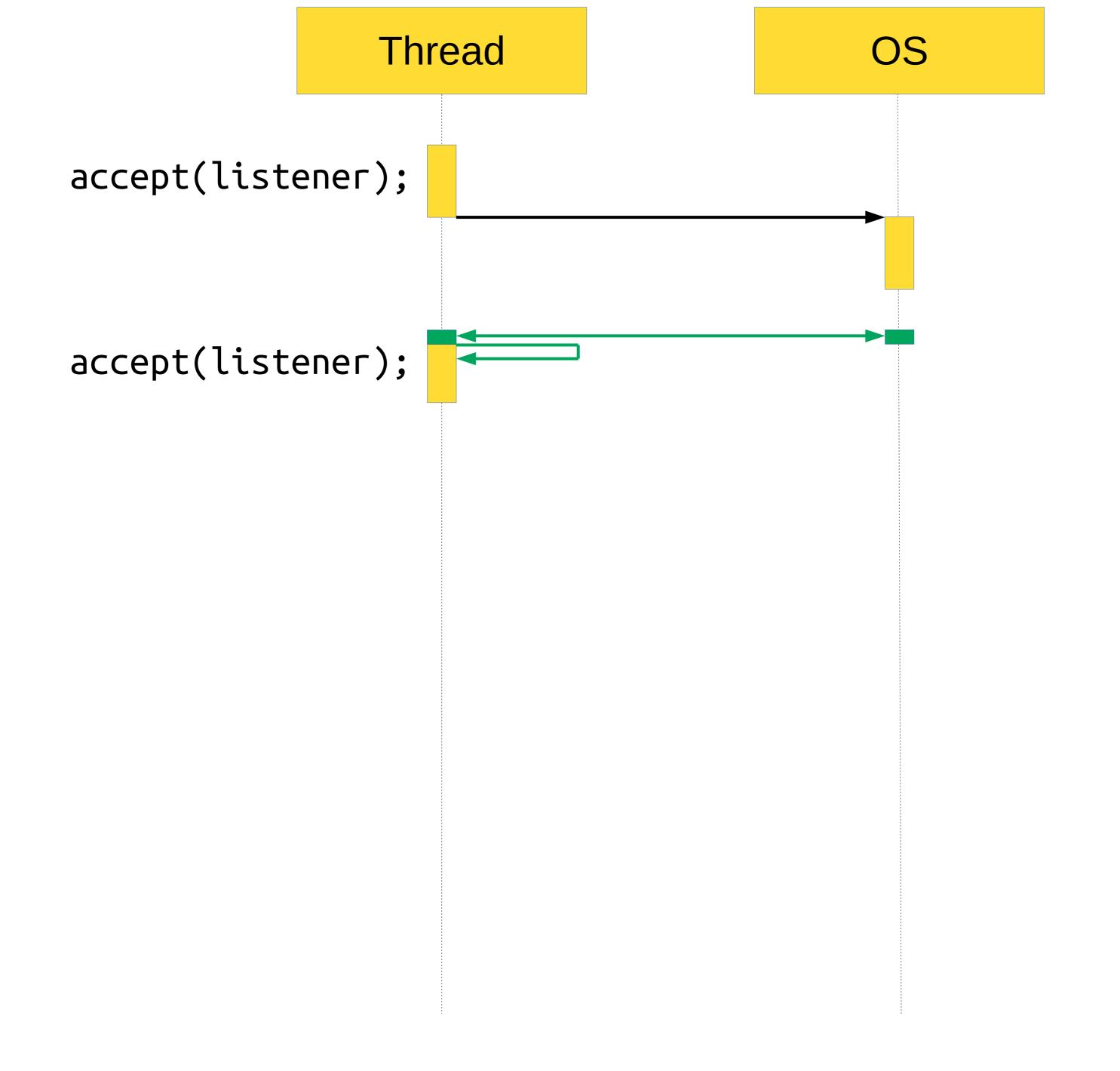
```
void async_accept() {
   accept(listener, [](socket_t socket) {
       async_accept();
       socket.receive(
        [socket](std::vector<unsigned char> data) {
            process(data);
            socket.send(data, kNoCallback);
        });
   });
}
```

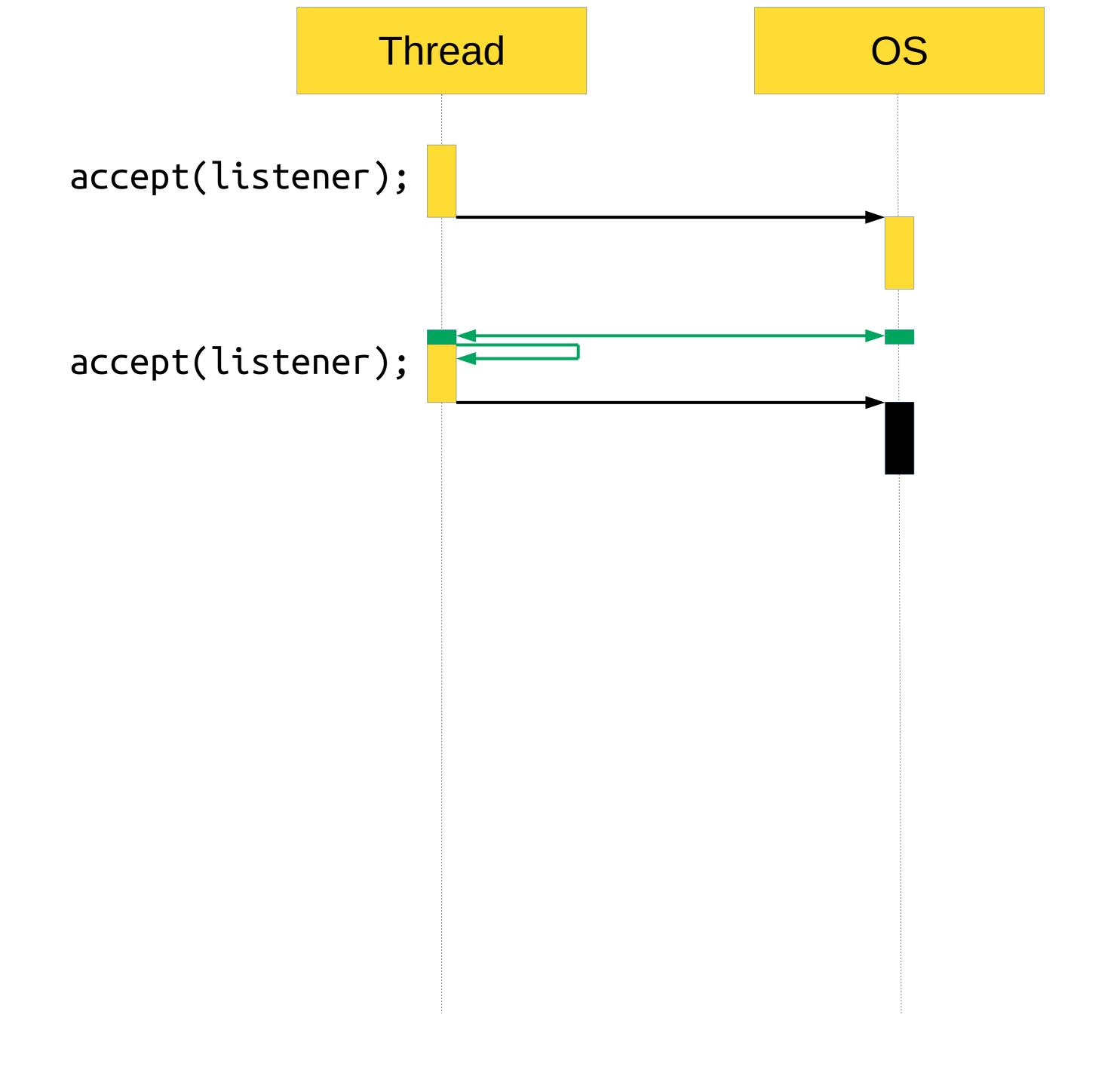
```
void async_accept() {
   accept(listener, [](socket_t socket) {
       async_accept();
       socket.receive(
            [socket](std::vector<unsigned char> data) {
            process(data);
            socket.send(data, kNoCallback);
            });
      });
}
```

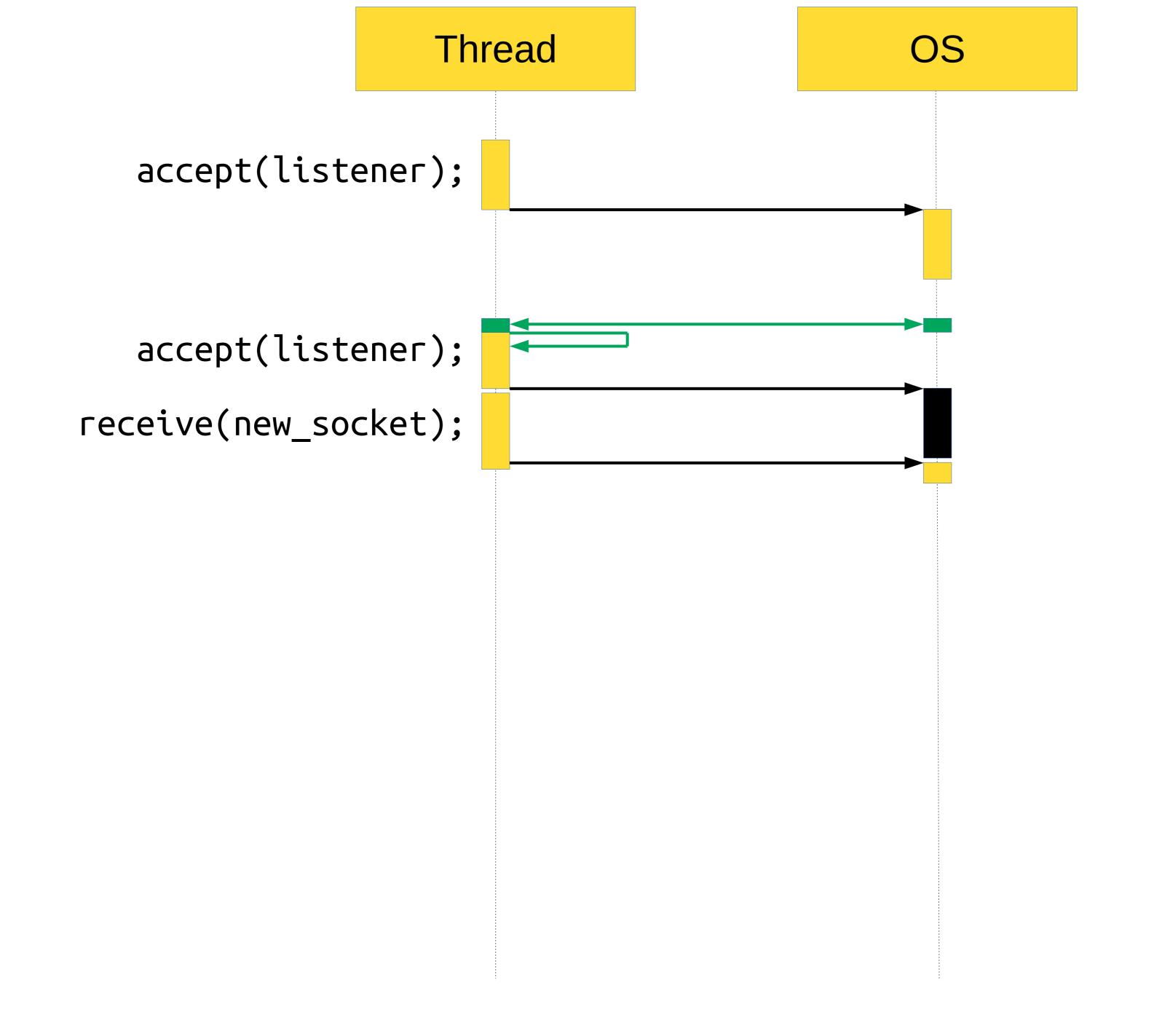


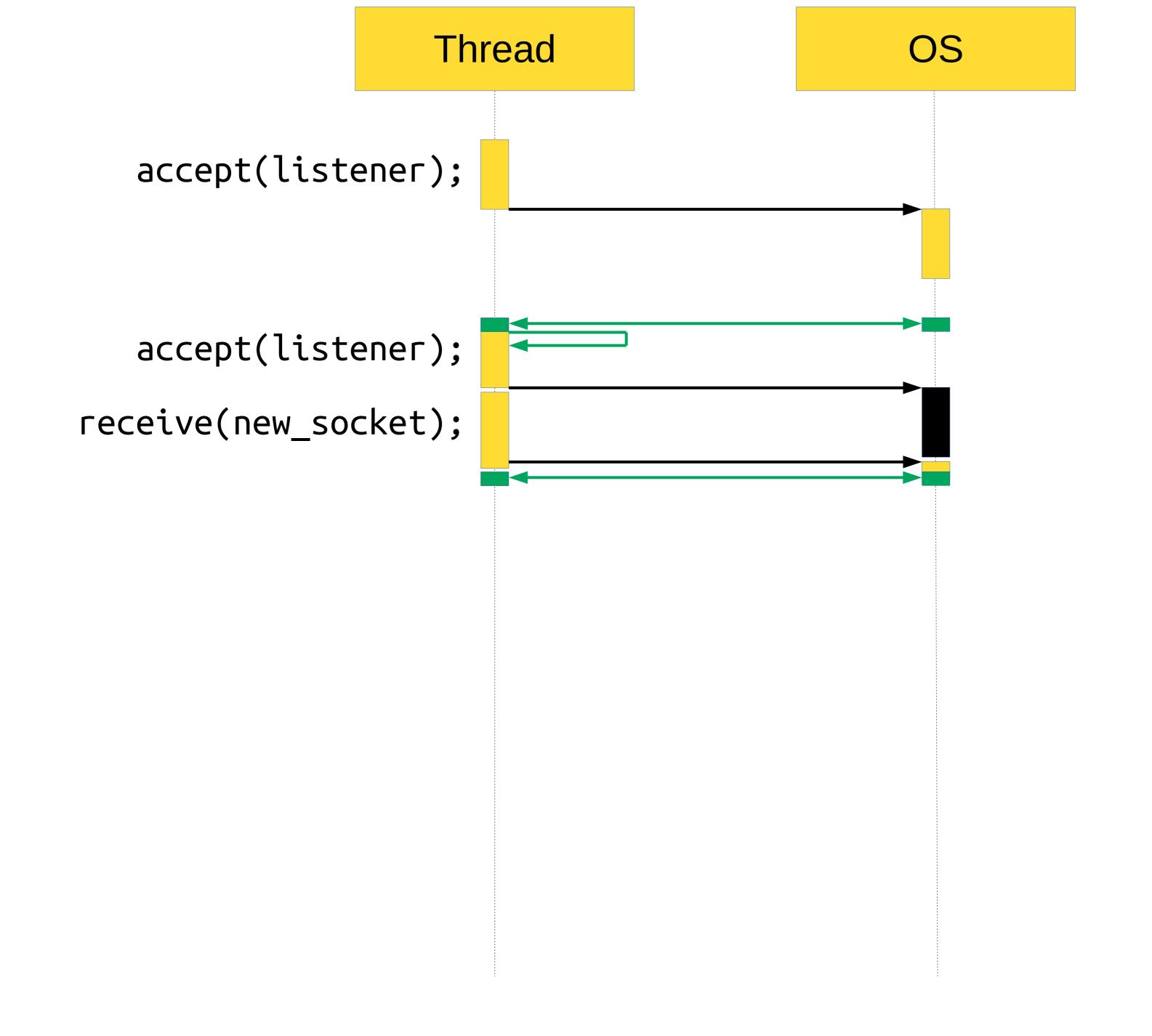


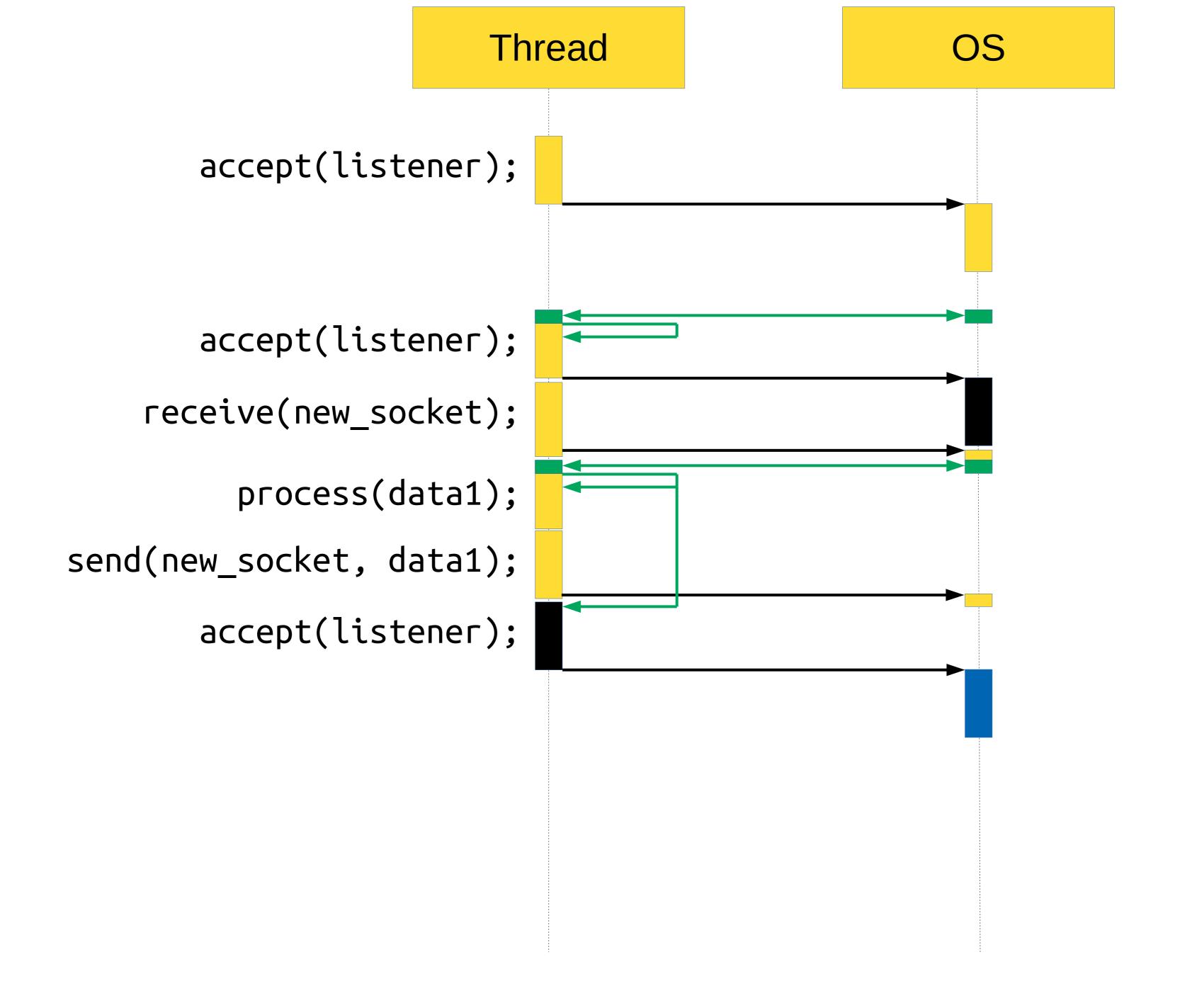


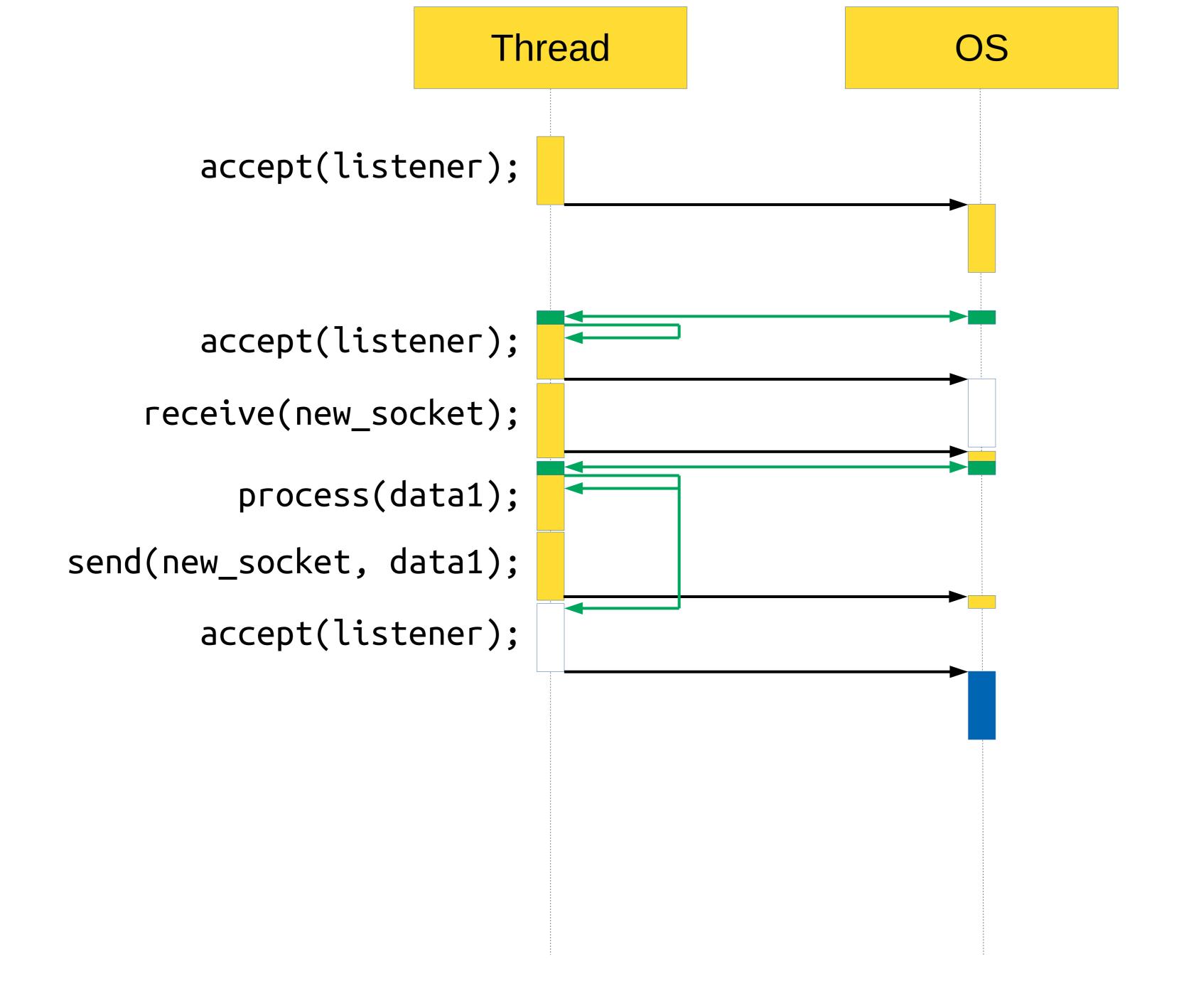


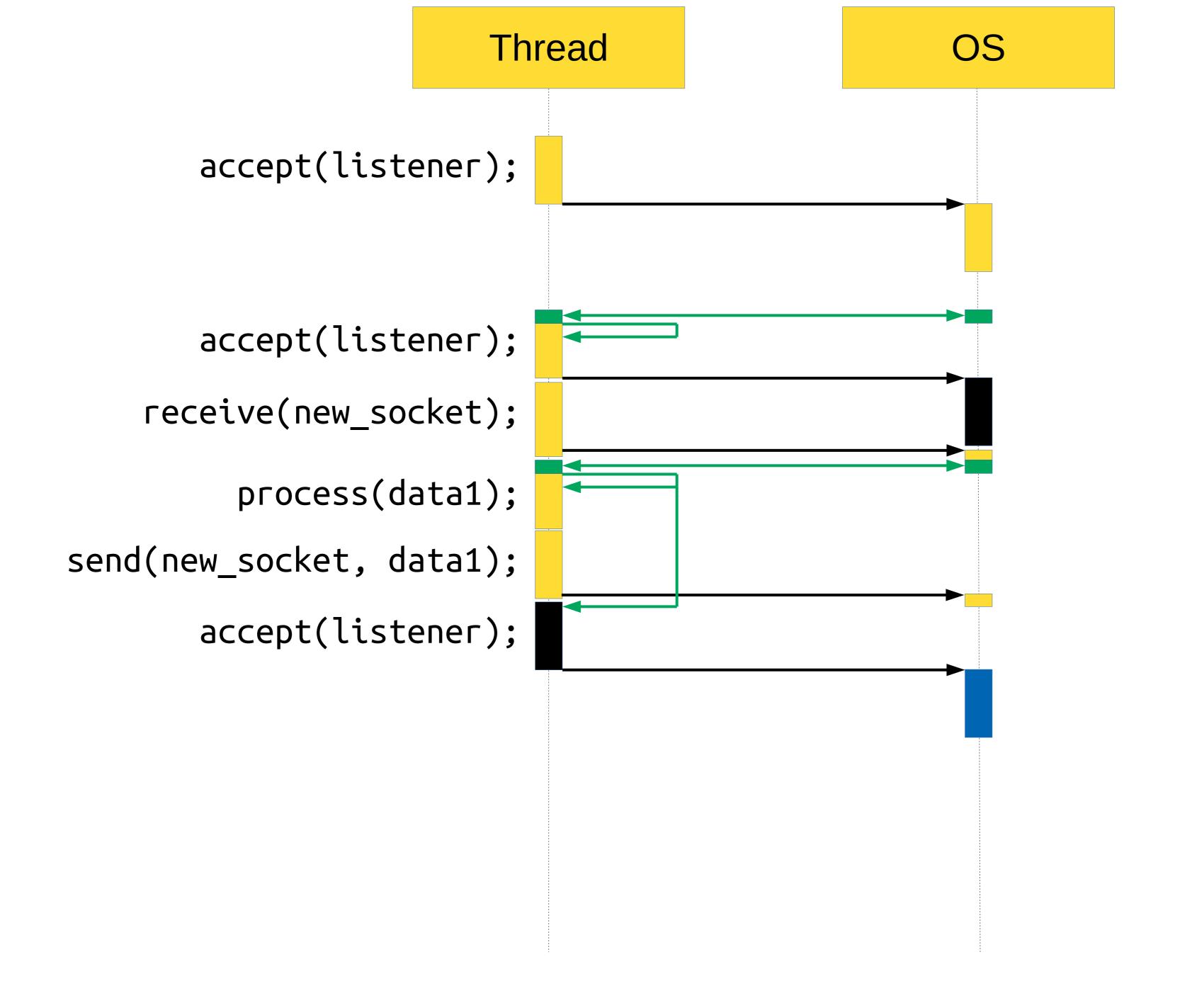


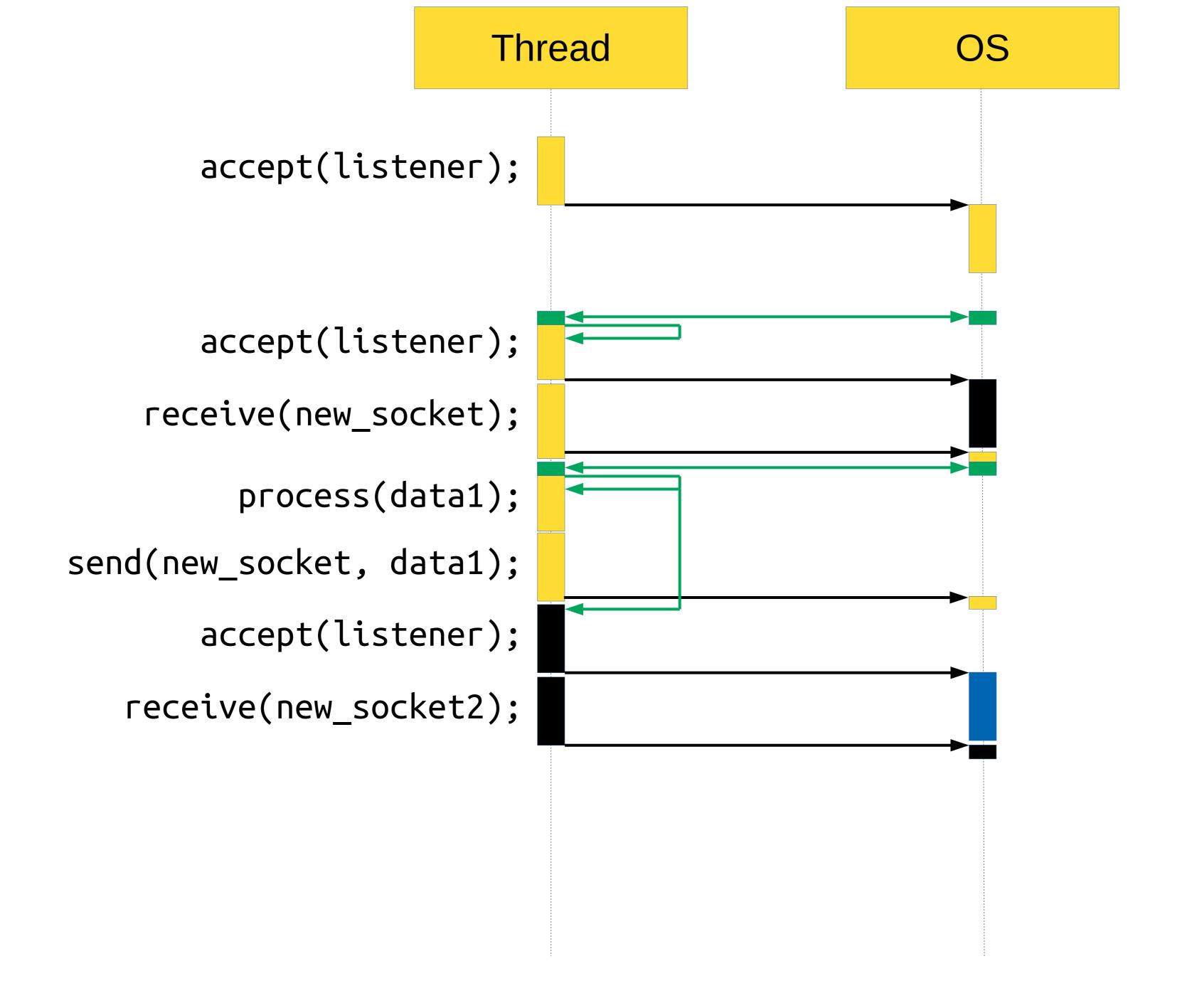












Есть ньюанс...

Запуск пользовательских задач

```
void async_accept() {
  accept(listener, [](socket_t socket) {
    async_accept();
    socket.receive(
        [socket](std::vector<unsigned char> data) {
          auto task = Async(process1, data);
          process(data);
          task.wait();
          socket.send(data, kNoCallback);
        });
  });
```

Запуск пользовательских задач

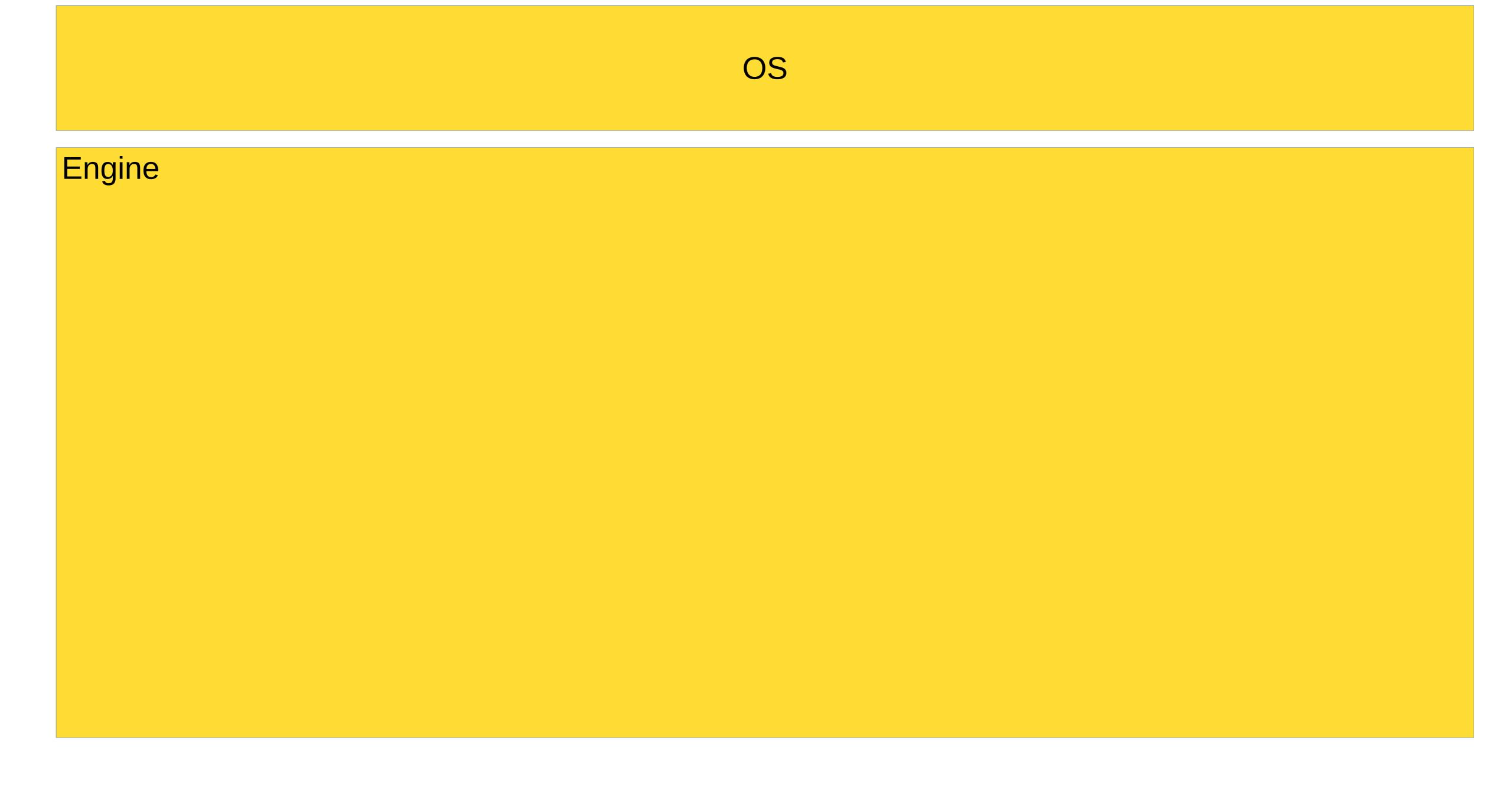
```
void async_accept() {
  accept(listener, [](socket_t socket) {
    async_accept();
    socket.receive(
        [socket](std::vector<unsigned char> data) {
          auto task = Async(process1, data);
          process(data);
          task.wait();
          socket.send(data, kNoCallback);
        });
  });
```

Запуск пользовательских задач

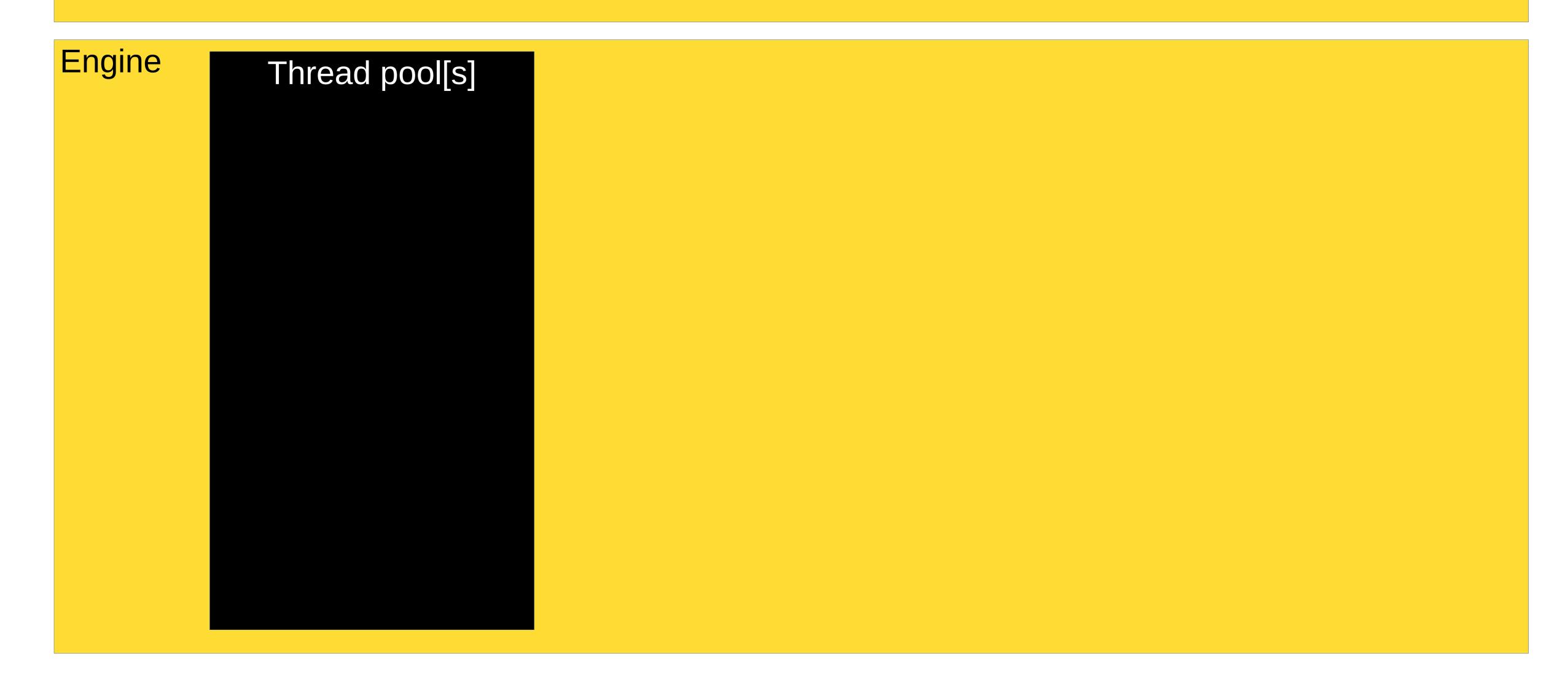
```
void async_accept() {
  accept(listener, [](socket_t socket) {
    async_accept();
    socket.receive(
        [socket](std::vector<unsigned char> data) {
          auto task = Async(process1, data);
          process(data);
          task.wait();
          socket.send(data, kNoCallback);
        });
  });
```

Нужны очереди

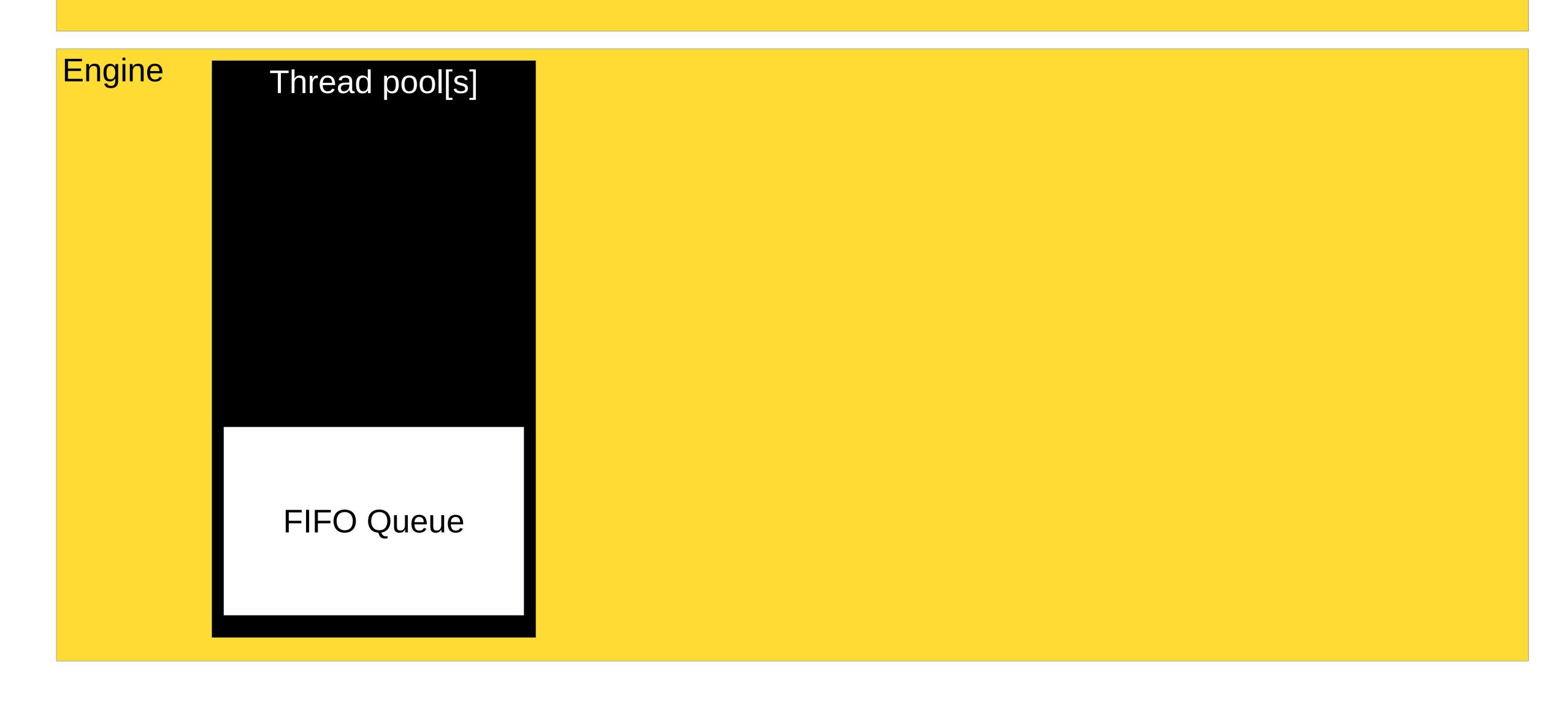
OS



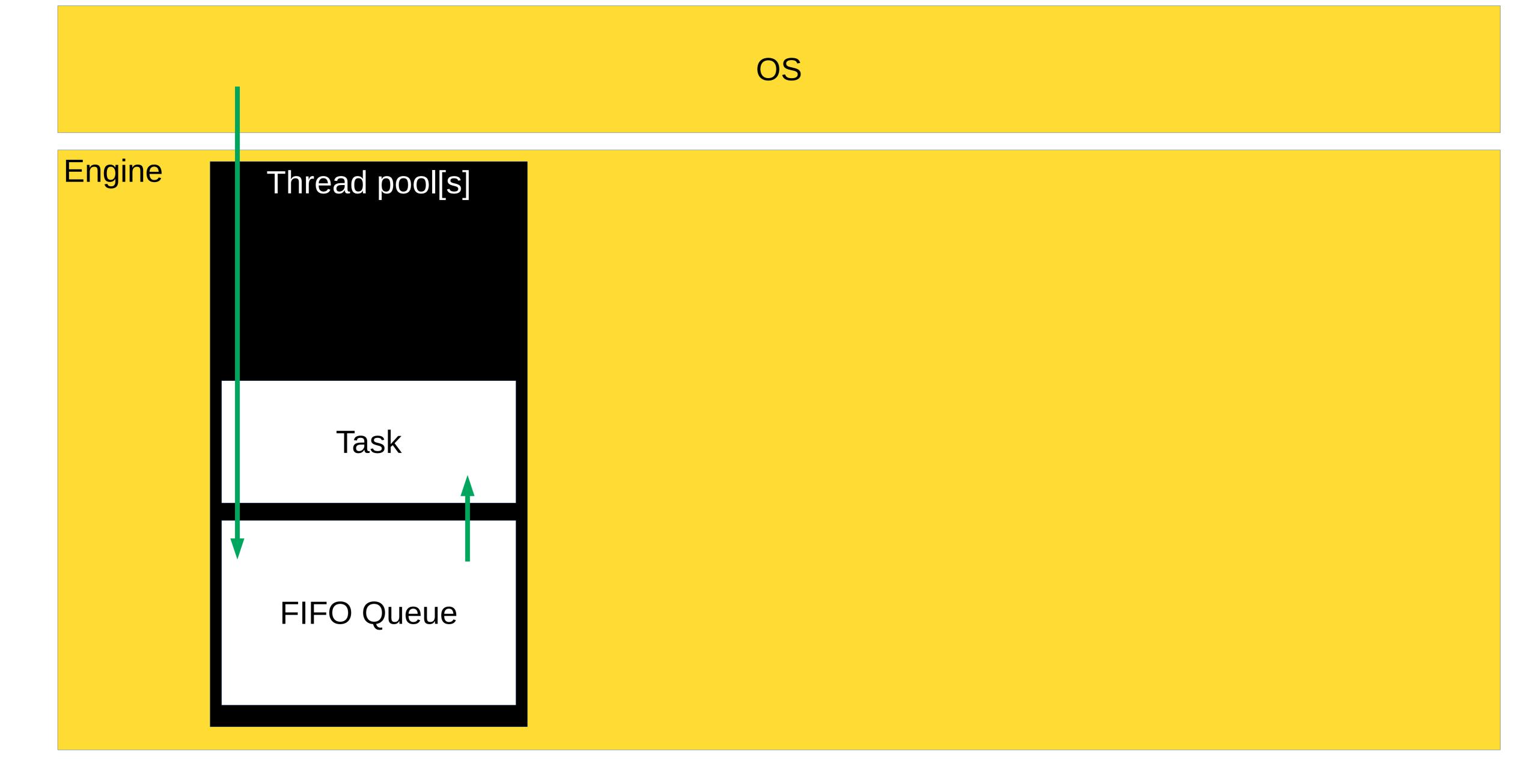
OS

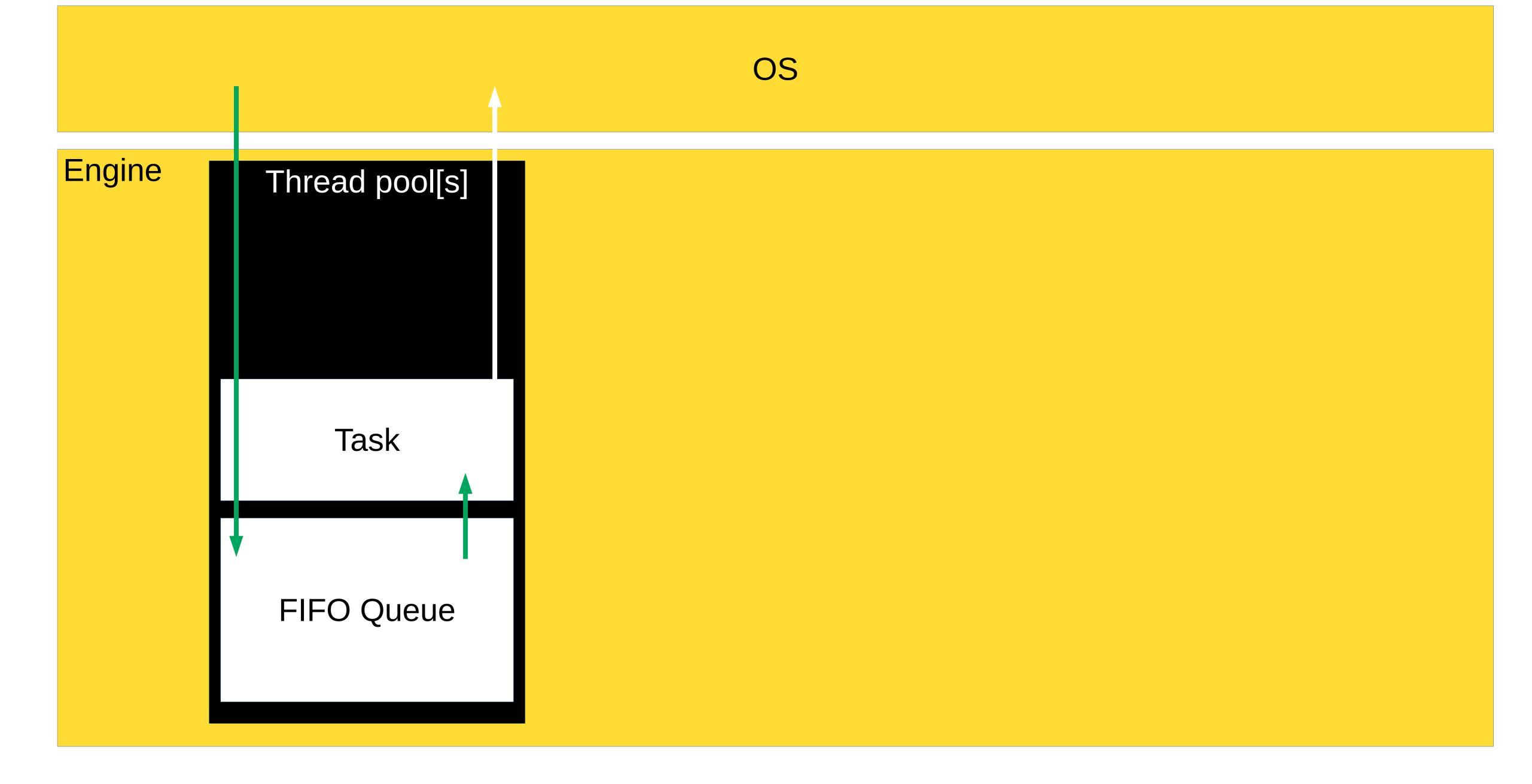


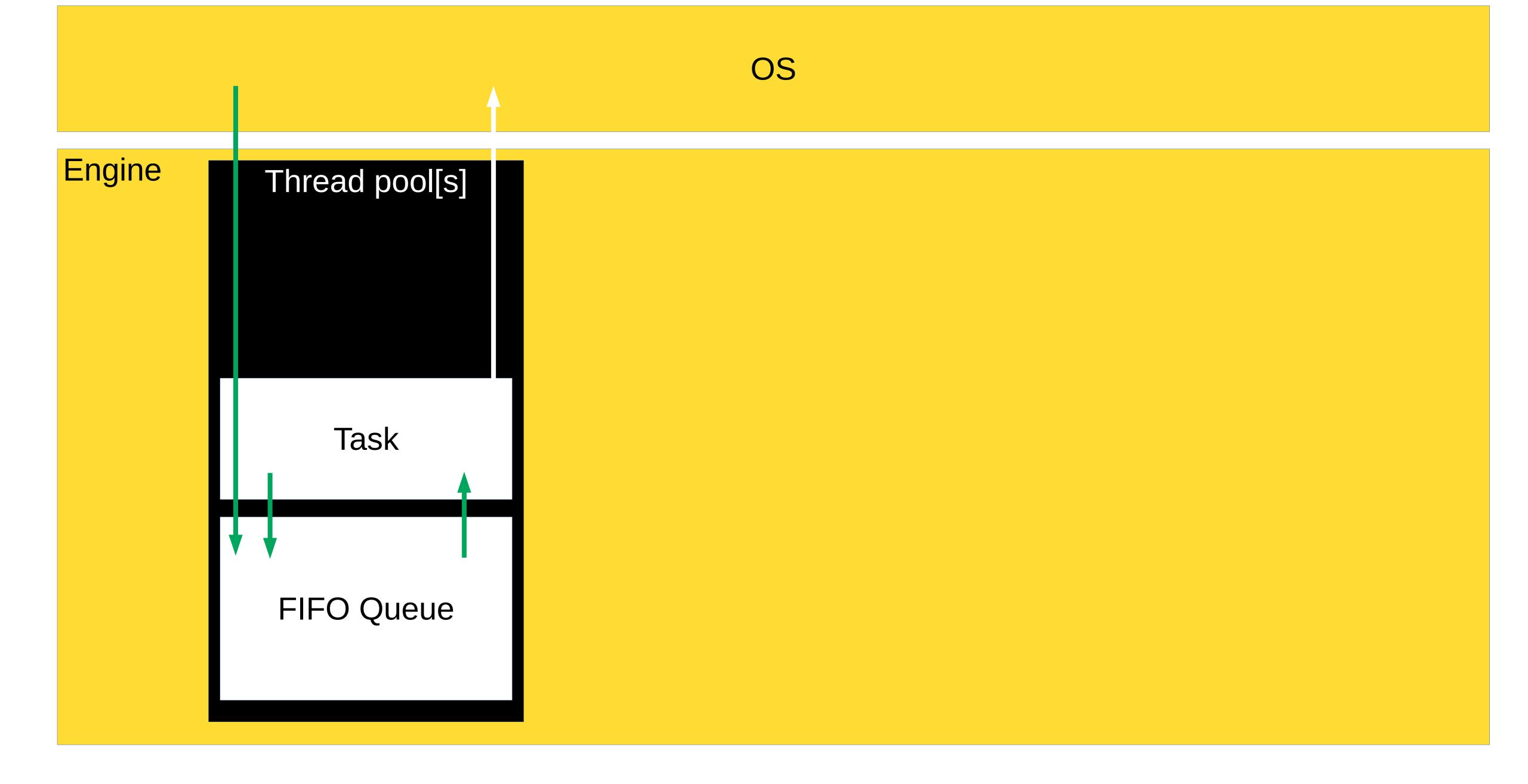
OS

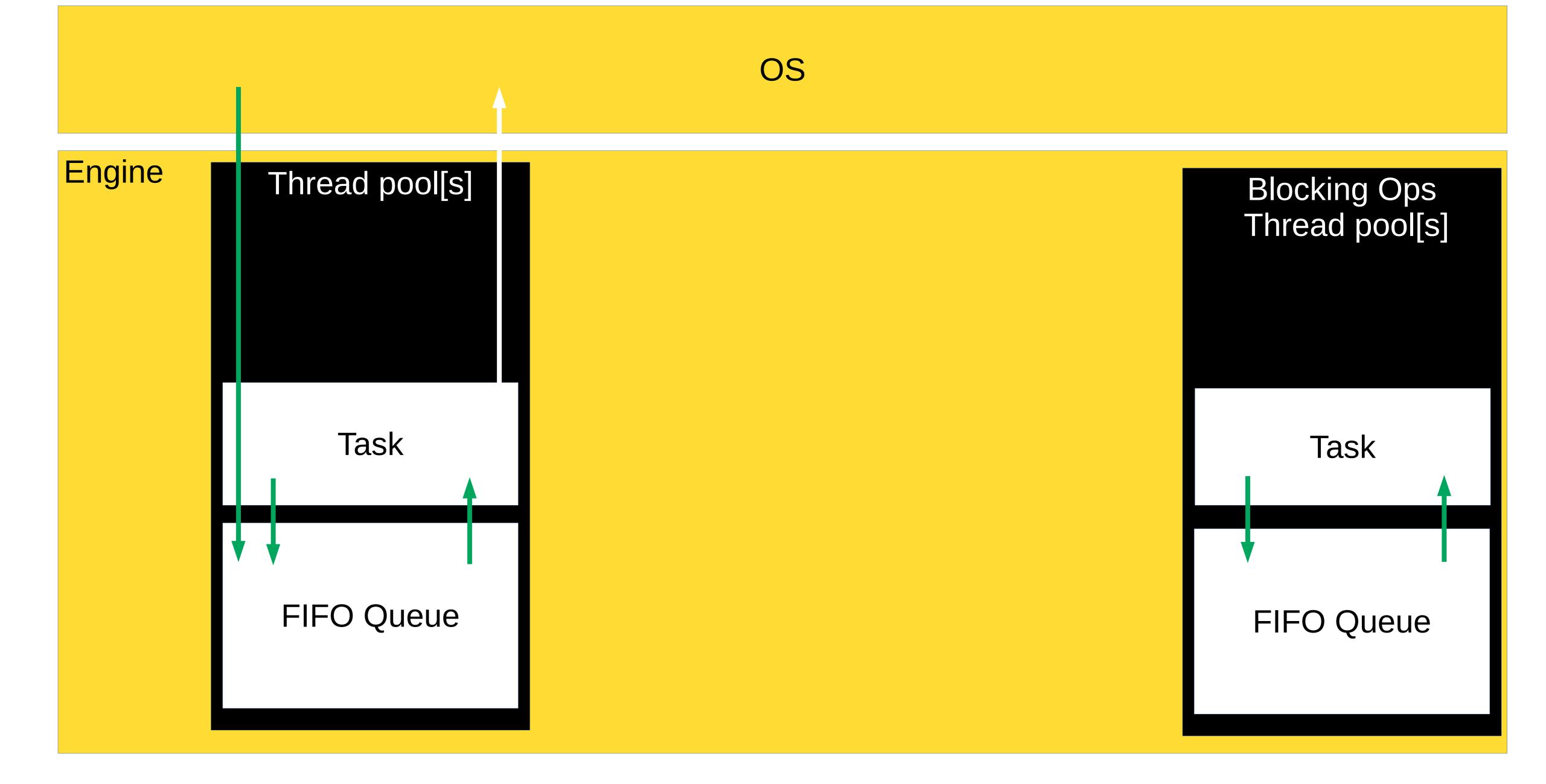


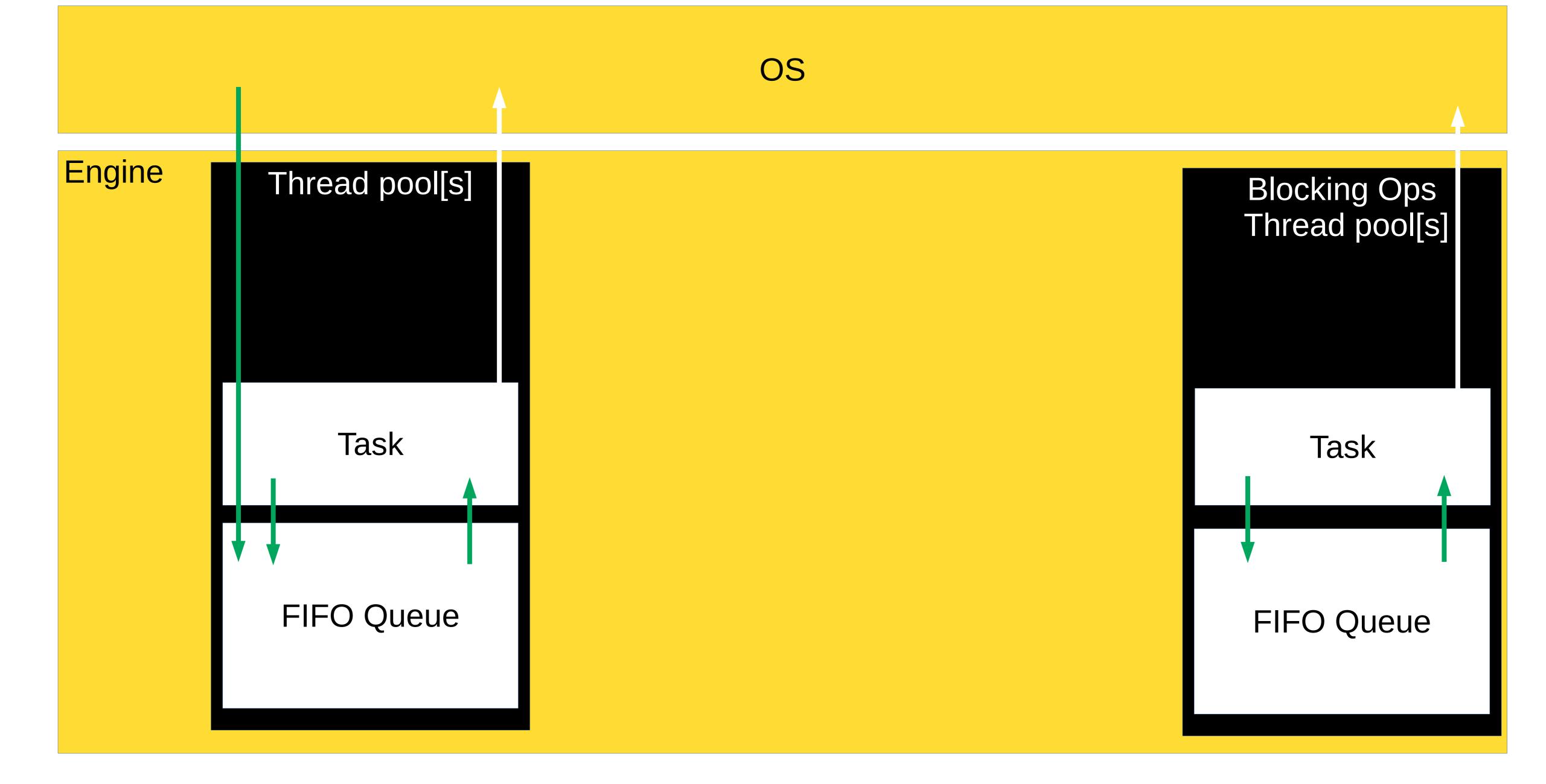


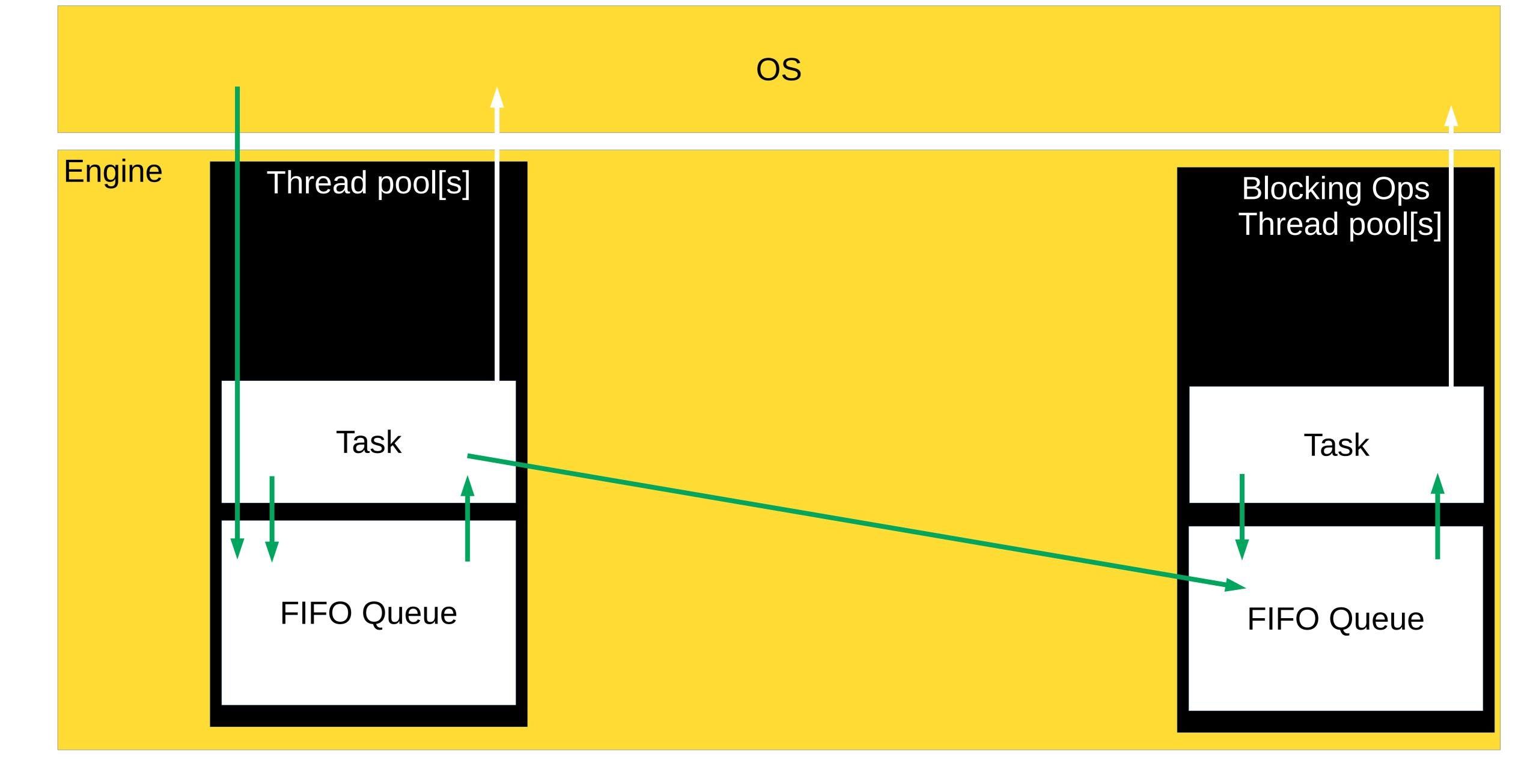


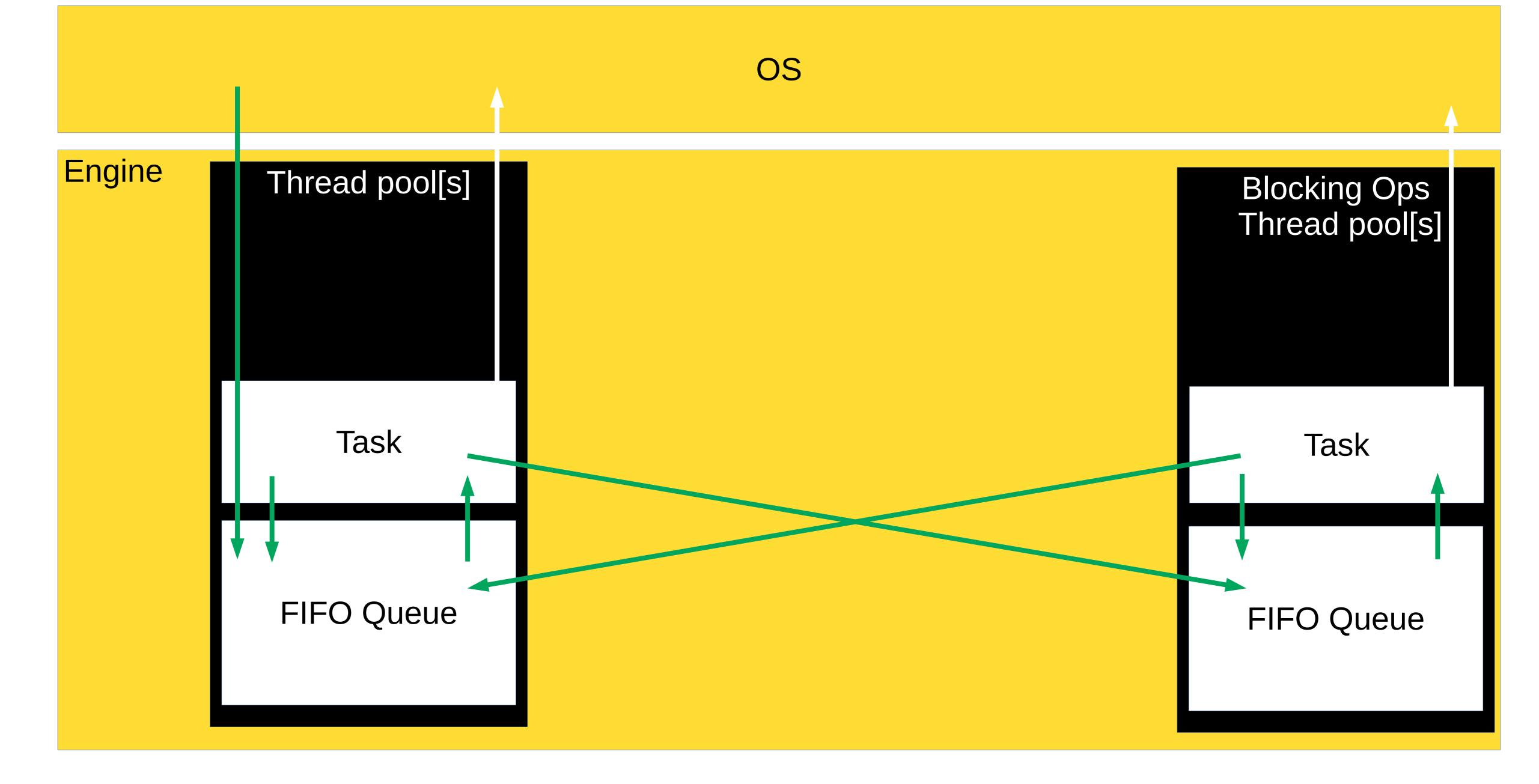






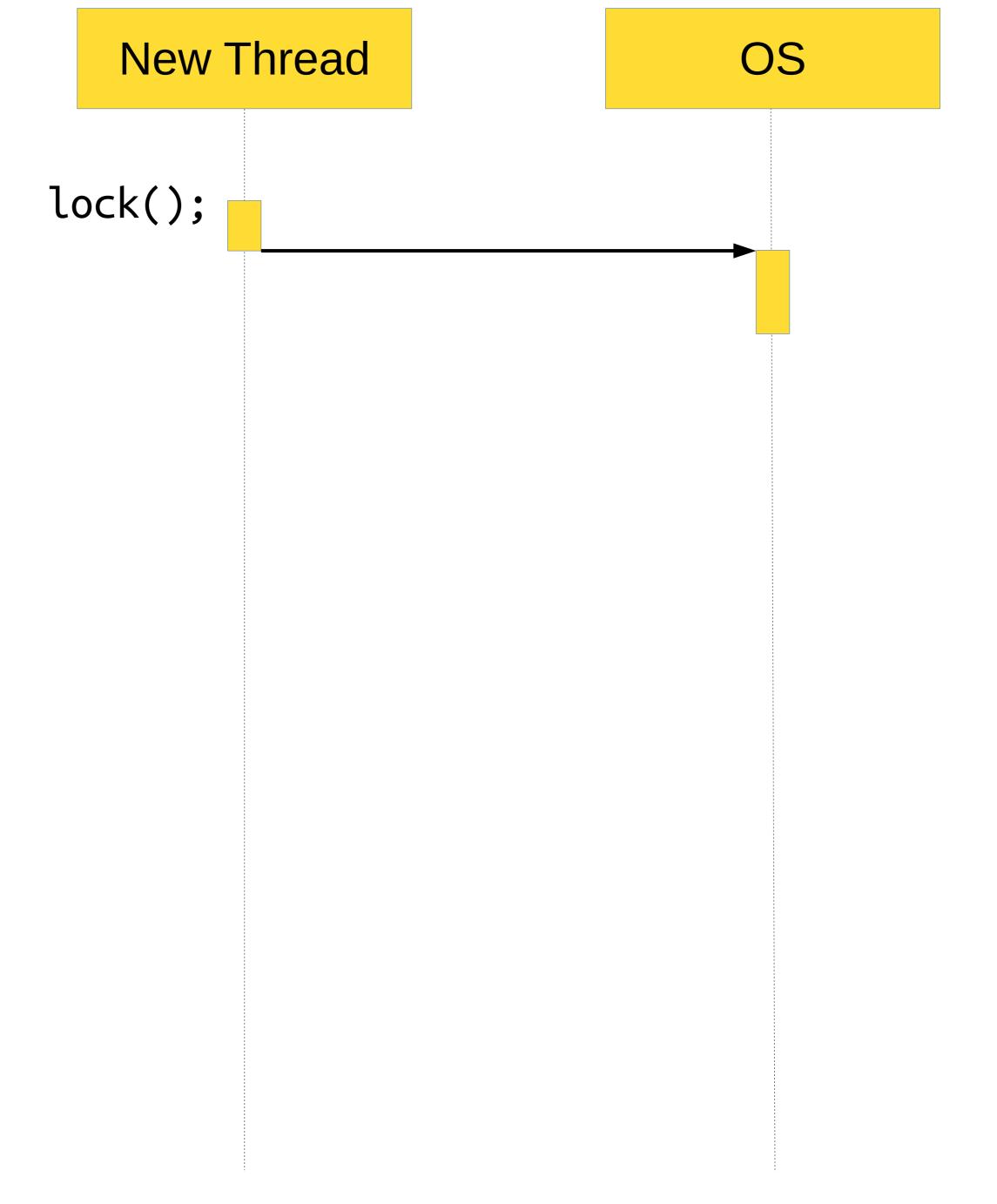


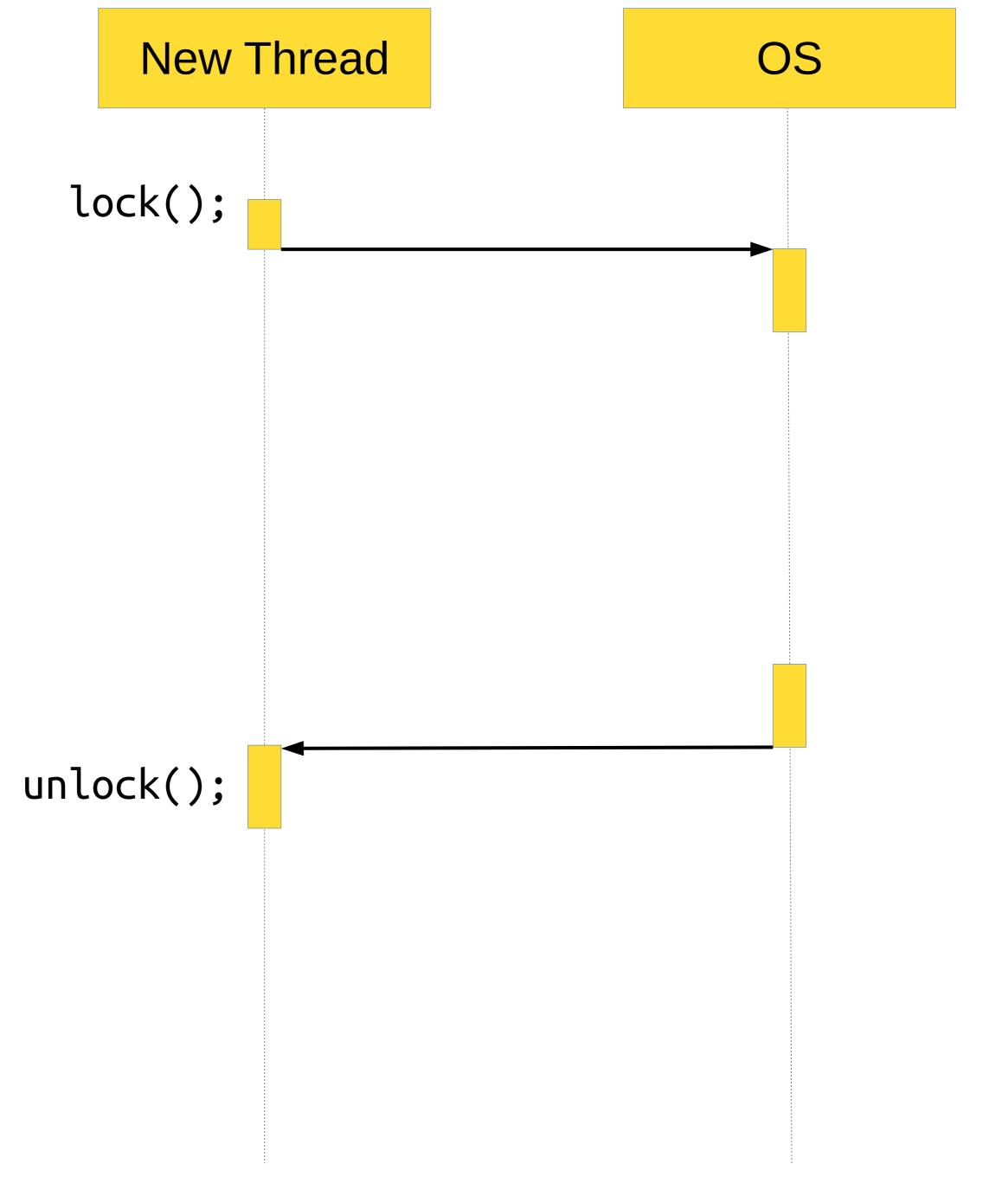




А что с синхронизацией?

New Thread	OS	





Мьютекс

```
void async_accept_lock() {
  accept(listener, [](socket_t socket) {
    async_accept_lock();
    socket.receive(
        [socket](std::vector<unsigned char> data) mutable {
          mutex.lock([data = std::move(data), socket = std::move(socket)]() {
            process2(shared_resource, data);
            socket.send(data, kNoCallback);
          });
        });
  });
```

Мьютекс

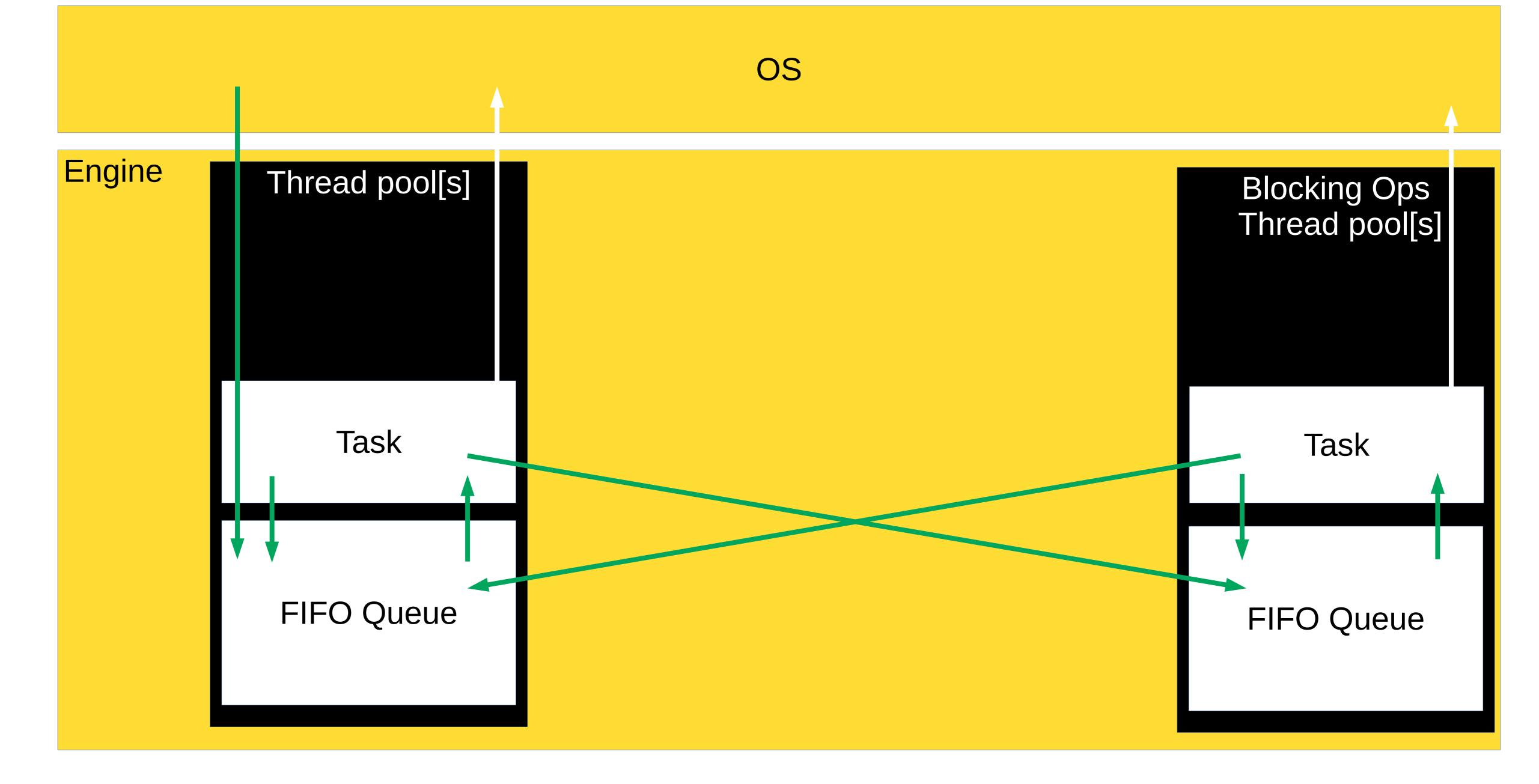
```
void async_accept_lock() {
  accept(listener, [](socket_t socket) {
    async_accept_lock();
    socket.receive(
        [socket](std::vector<unsigned char> data) mutable {
          mutex.lock([data = std::move(data), socket = std::move(socket)]() {
            process2(shared_resource, data);
            socket.send(data, kNoCallback);
         });
        });
```

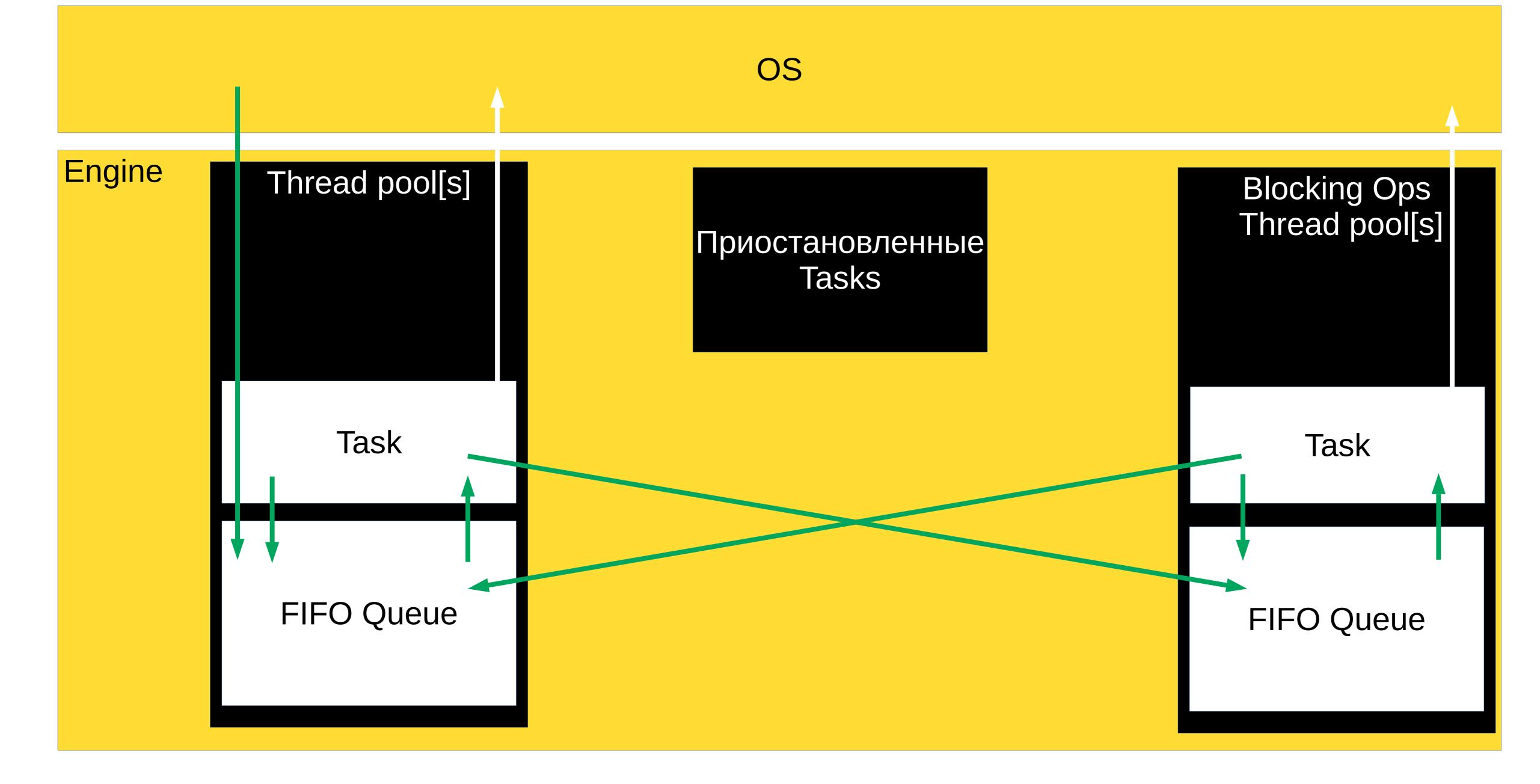
```
template <class Functor>
void lock(Functor f) {
  auto lock = this->try_lock();
  if (lock) {
    f();
  } else {
    wait_for_unlock(std::move(f));
  }
}
```

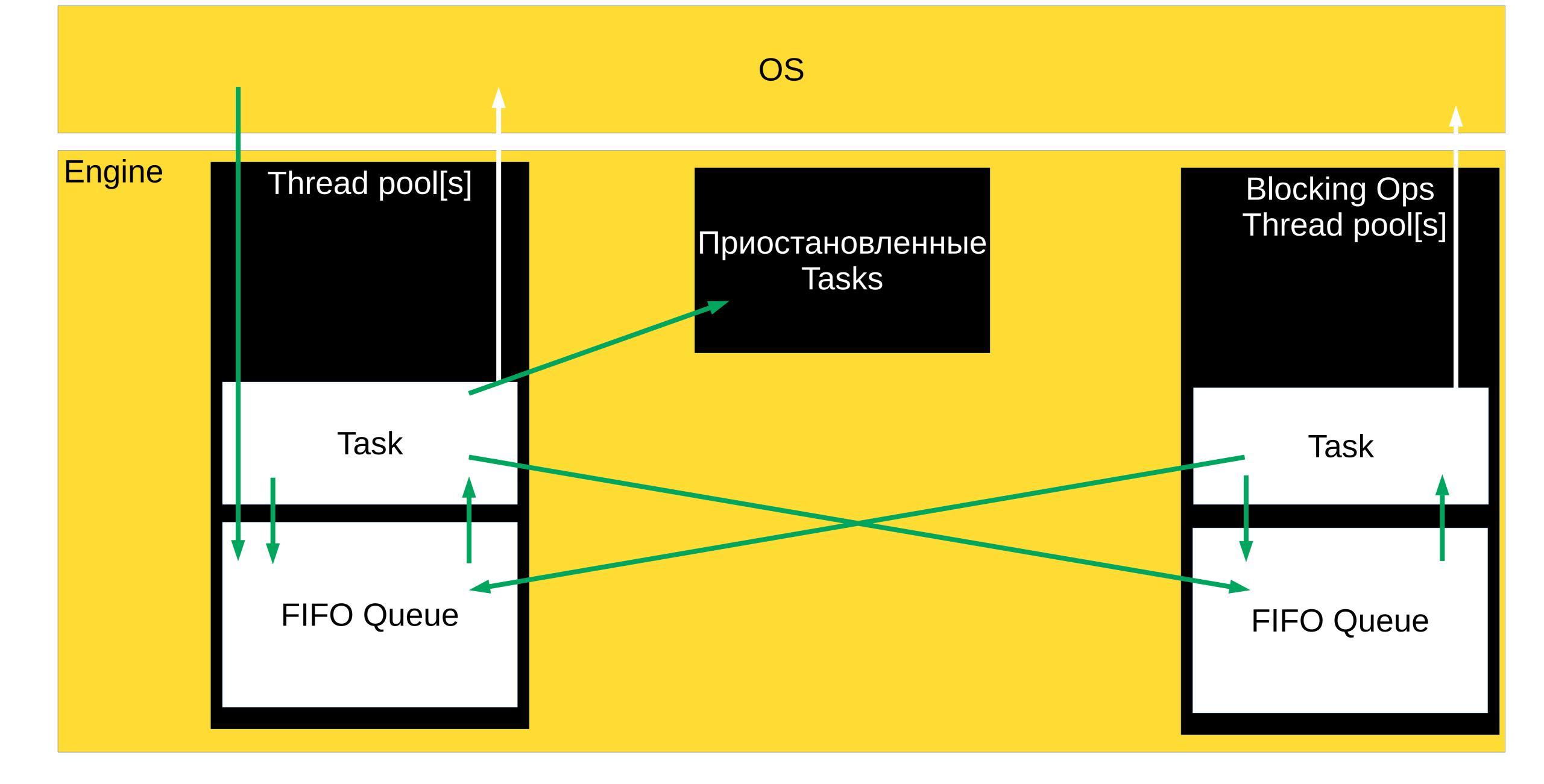
```
template <class Functor>
void lock(Functor f) {
   auto lock = this->try_lock();
   if (lock) {
      f();
   } else {
      wait_for_unlock(std::move(f));
   }
}
```

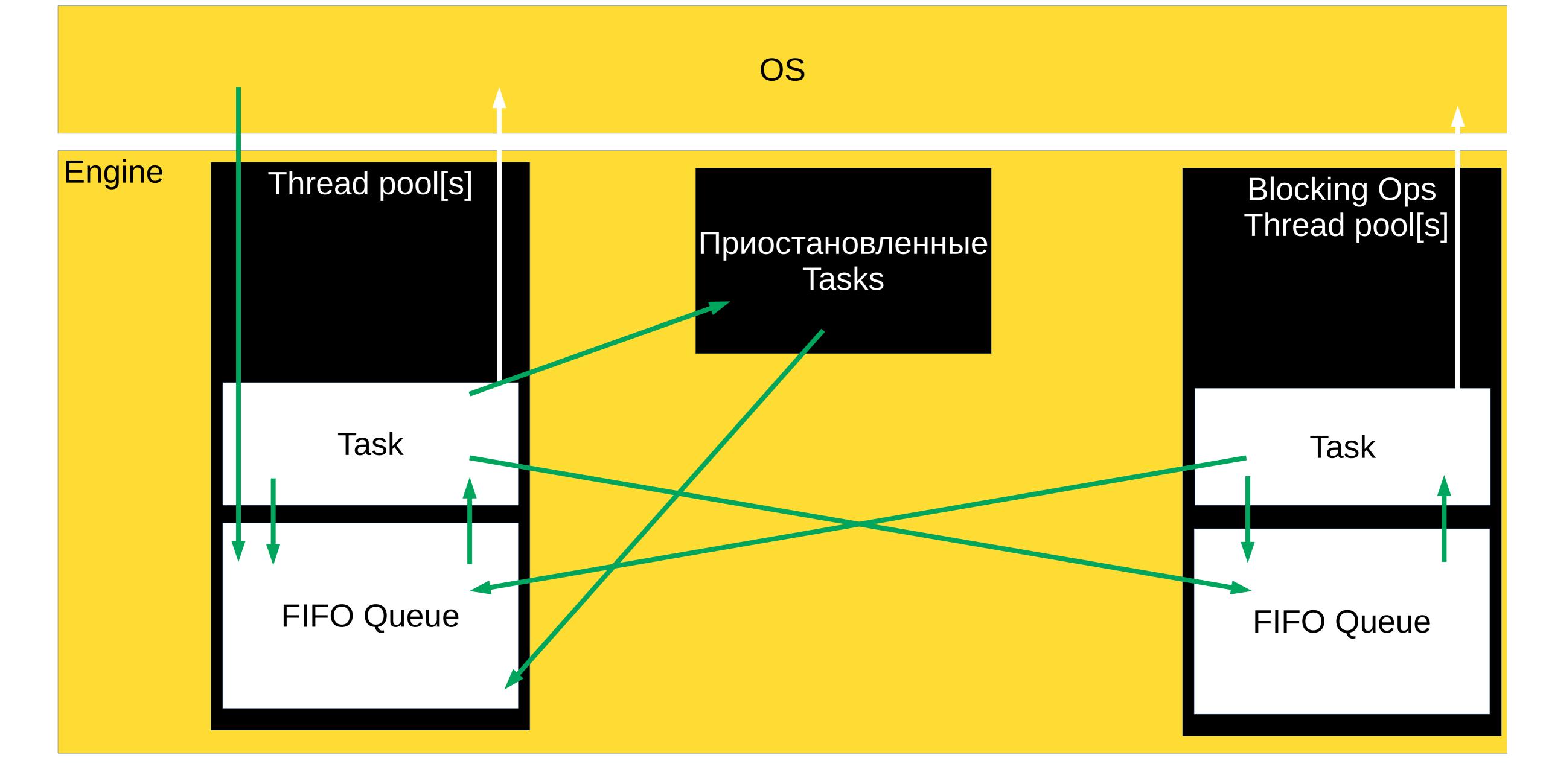
```
template <class Functor>
void lock(Functor f) {
  auto lock = this->try_lock();
  if (lock) {
    f();
  } else {
    wait_for_unlock(std::move(f));
  }
}
```

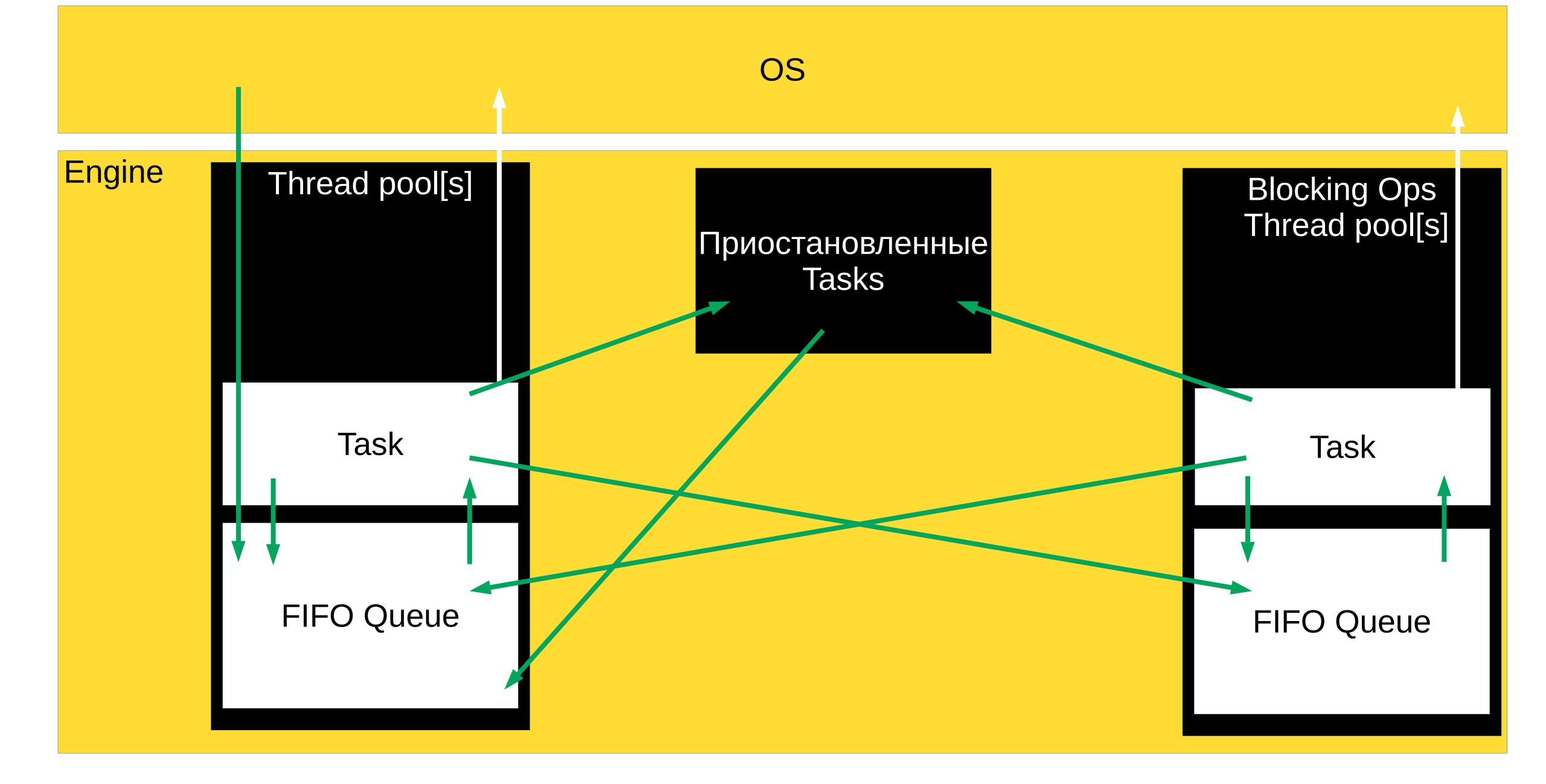
```
template <class Functor>
void lock(Functor f) {
   auto lock = this->try_lock();
   if (lock) {
     f();
   } else {
     wait_for_unlock(std::move(f));
   }
}
```

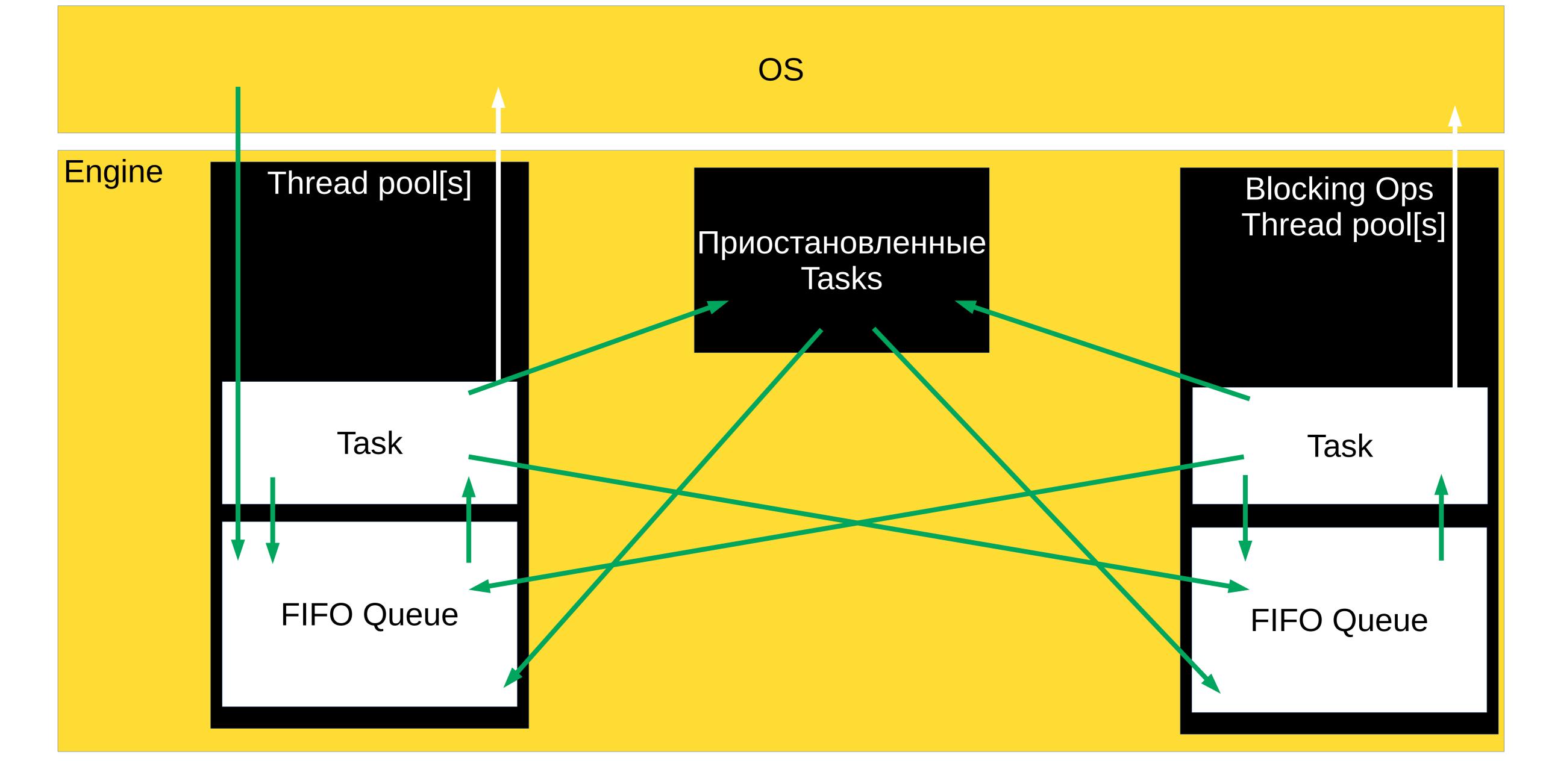












Плюсы:

Плюсы:

• Всё очень эффективно

Плюсы:

• Всё очень эффективно

Минусы:

Ну давай, прочти меня!

```
void async_accept() {
    accept(listener, [](socket t socket) {
      async accept();
      auto something = Async(process1, {42});
      auto& socket_ref = *socket; socket_ref.receive(
           [socket = std::move(socket), something = std::move(something)]
  (std::vector<unsigned char> data) mutable {
             auto task = Async(process1, data);
             process(data);
             task.wait();
             auto& socket_ref = *socket; socket_ref.send(data, [data, socket =
  std::move(socket), something = std::move(something)]() mutable {
                mutex.lock([data = std::move(data), socket = std::move(socket), something =
  std::move(something)]() mutable {
                   process2(shared_resource, data);
                   socket->send(data, kNoCallback);
                 });
             });
Анатомия асинхронных движков
                                                                                            102 / 223
```

Плюсы:

• Всё очень эффективно

Минусы:

• Нечитаемо...

Корутины спешат на помощь

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

Асинхронный сервер с корутинами vs синхронный

```
coro_future coro_accept_stackles() {
                                                    void naive_accept() {
  for (;;) {
                                                      for (;;) {
                                                        auto new_socket = accept(listener);
    auto new_socket = co_await accept(listener);
    auto task = Async(/*...*/ {
                                                        std::thread thrd(/*...*/ {
                                                          auto data = socket.receive();
      auto data = co_await socket.receive();
      process(data);
                                                          process(data);
      co_await socket.send(data);
                                                          socket.send(data);
      co_return;
                                                        });
    });
                                                        thrd.detach();
    task.Detach();
```

Асинхронный сервер с корутинами vs синхронный

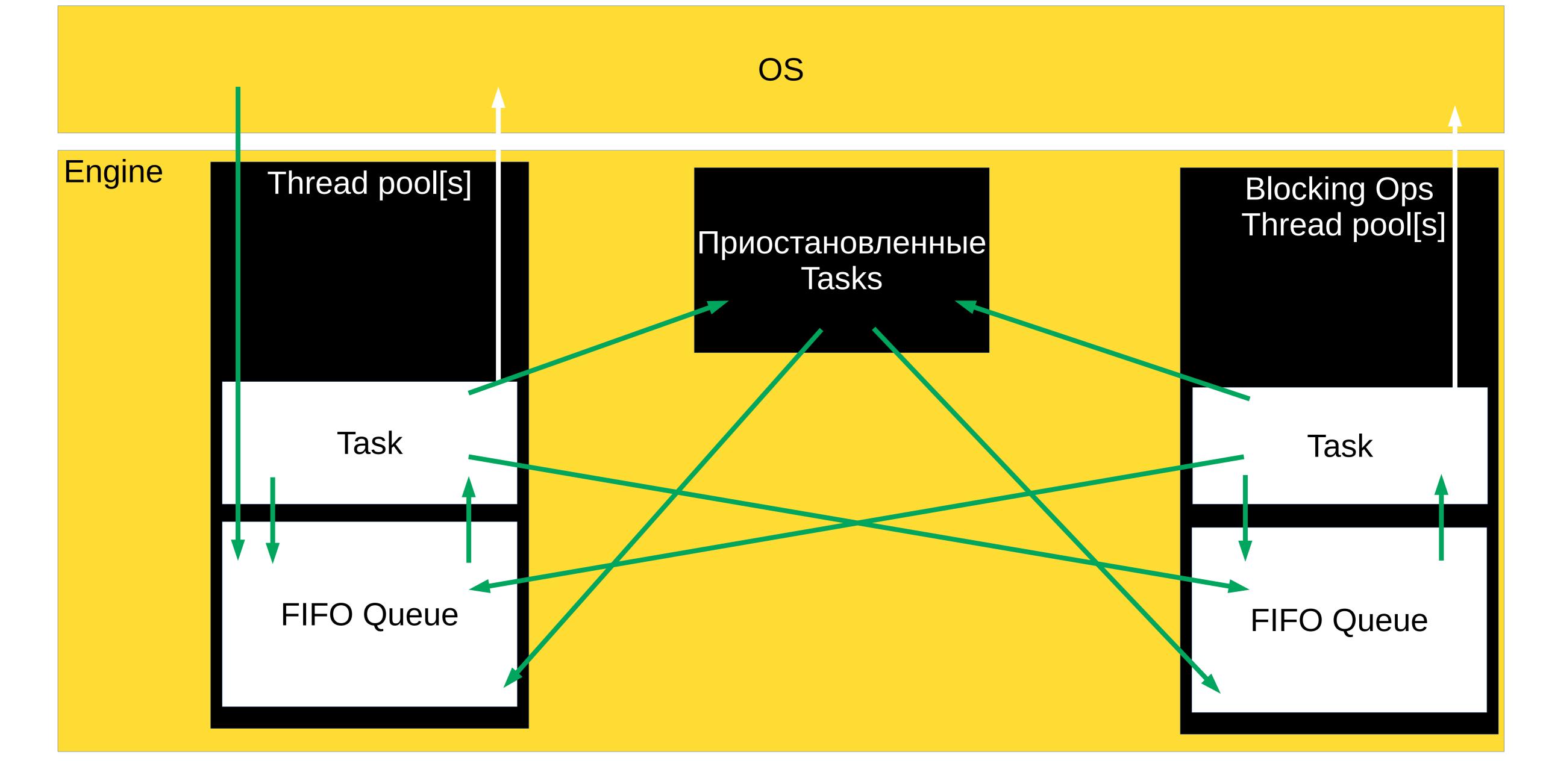
```
coro_future coro_accept_stackles() {
                                                    void naive_accept() {
  for (;;) {
                                                      for (;;) {
    auto new_socket = co_await accept(listener);
                                                        auto new_socket = accept(listener);
    auto task = Async(/*...*/ {
                                                        std::thread thrd(/*...*/ {
      auto data = co_await socket.receive();
                                                          auto data = socket.receive();
      process(data);
                                                          process(data);
      co_await socket.send(data);
                                                          socket.send(data);
      co_return;
                                                        });
    });
                                                        thrd.detach();
    task.Detach();
```

Асинхронный сервер с корутинами vs синхронный

```
void coro_accept_stackfull() {
  for (;;) {
    auto new_socket = accept(listener);
    auto task = Async(/*...*/ {
      auto data = socket.receive();
      process(data);
      socket.send(data);
    });
    task.Detach();
```

```
void naive_accept() {
  for (;;) {
    auto new_socket = accept(listener);
    std::thread thrd(/*...*/ {
      auto data = socket.receive();
      process(data);
      socket.send(data);
    });
    thrd.detach();
```

Устройство корутинового движка



```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
     process(data);
     co_await socket.send(data);
     co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
     process(data);
     co_await socket.send(data);
     co_return;
    });
    task.Detach();
```

```
coro_future coro_accept_stackles() {
  for (;;) {
    auto new_socket = co_await accept(listener);
    auto task = Async([socket = std::move(new_socket)]() -> coro_future {
      auto data = co_await socket.receive();
      process(data);
      co_await socket.send(data);
      co_return;
    });
    task.Detach();
```

Плюсы:

Плюсы:

• Всё очень эффективно

Плюсы:

- Всё очень эффективно
- Просто и читаемо

Плюсы:

- Всё очень эффективно
- Просто и читаемо

Минусы:

• Под капотом жесть!..

Плюсы:

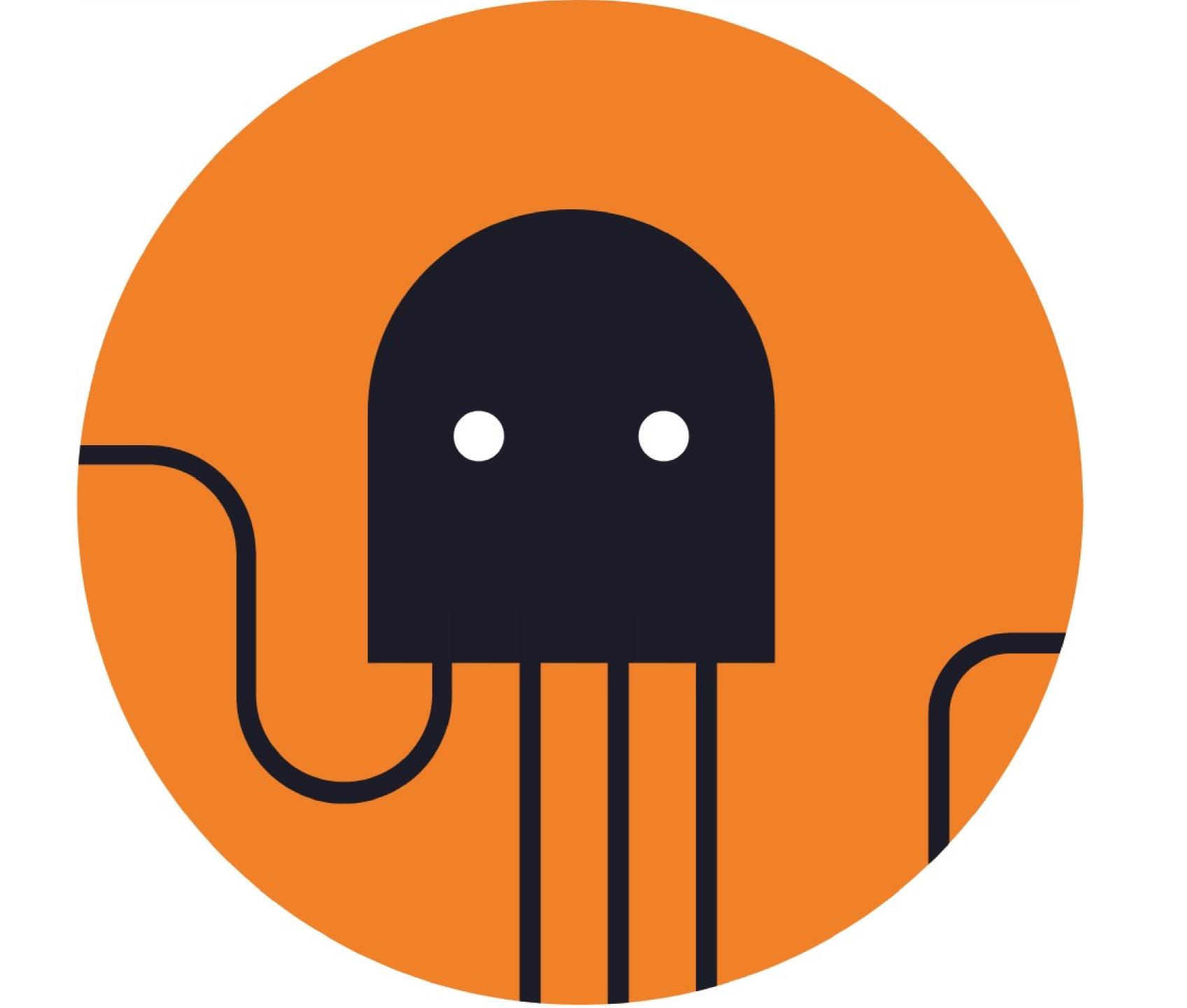
- Всё очень эффективно
- Просто и читаемо

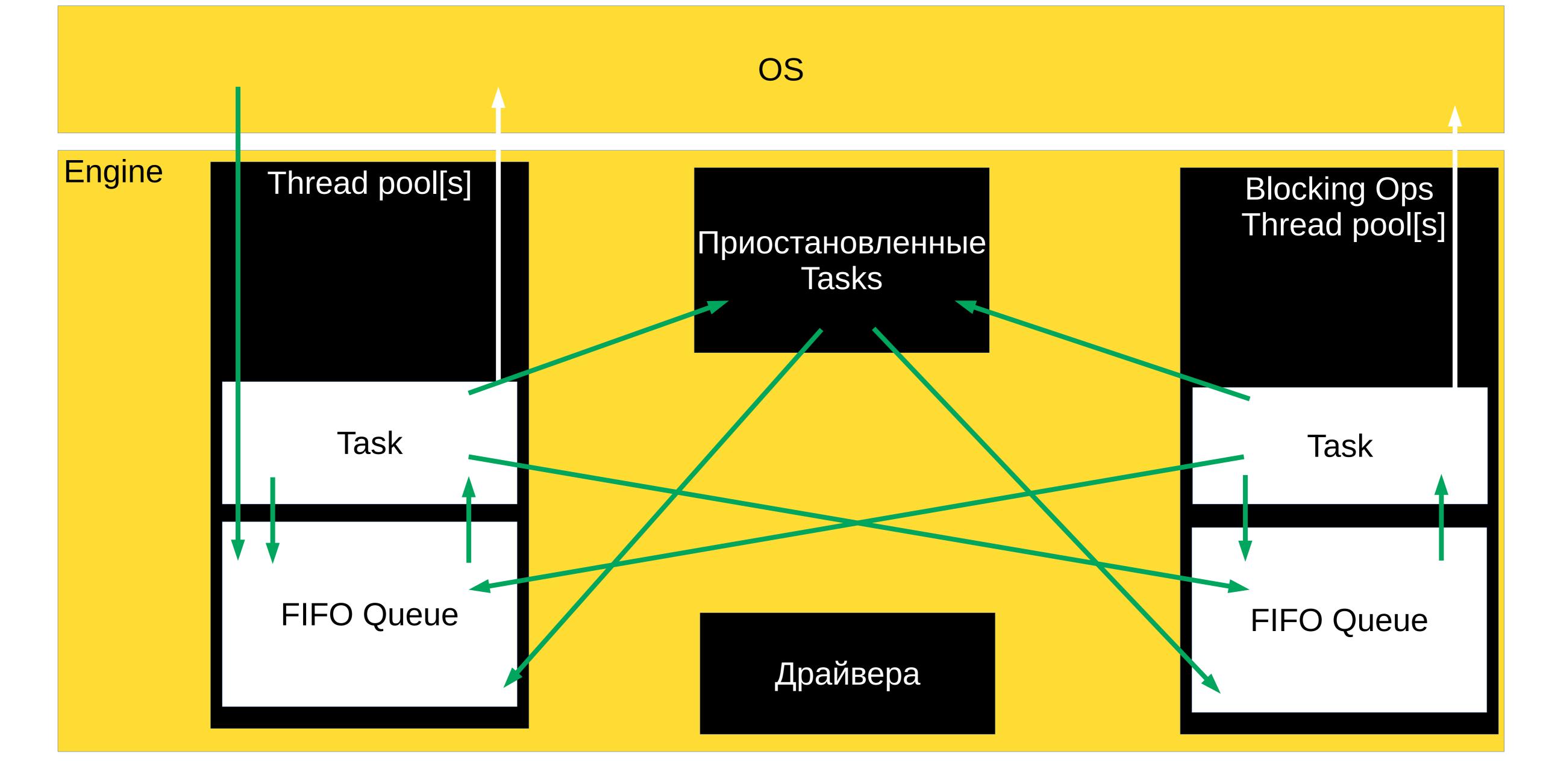
Минусы:

• Под капотом жесть!.. Впрочем, такая же жесть при любой асинхронности

Плюсы:

- Всё очень эффективно
- Просто и читаемо
- Под капотом жесть!..





С++ хардкорище!

```
struct Mutex {
  void lock();
  void unlock();

private:
  std::atomic<Coroutine*> owner_{nullptr};
};
```

```
struct Mutex {
  void lock();
  void unlock();

private:
  std::atomic<Coroutine*> owner_{nullptr};
};
```

```
struct Mutex {
  void lock();
  void unlock();

private:
  std::atomic<Coroutine*> owner_{nullptr};
};
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
 if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
 if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
class Coroutine {
  public:
    // ...
    void Sleep(WaitStrategy& strategy);
    // ...
};
```

```
class Coroutine {
  public:
    // ...
    void Sleep(WaitStrategy& strategy);
    // ...
};
```

```
class Coroutine {
  public:
    // ...
    void Sleep(WaitStrategy& strategy);
    // ...
};
```

```
class Coroutine {
 public:
 // ...
  void Sleep(WaitStrategy& strategy);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
  virtual void BeforeAwake() = 0;
 protected:
  ~WaitStrategy() = default;
};
```

```
class Coroutine {
 public:
 // ...
 void Sleep(WaitStrategy& strategy);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
  virtual void BeforeAwake() = 0;
 protected:
  ~WaitStrategy() = default;
};
```

```
class Coroutine {
 public:
 // ...
  void Sleep(WaitStrategy& strategy);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
  virtual void BeforeAwake() = 0;
 protected:
  ~WaitStrategy() = default;
};
```

```
class Coroutine {
 public:
 // ...
 void Sleep(WaitStrategy& strategy);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
  virtual void BeforeAwake() = 0;
 protected:
  ~WaitStrategy() = default;
};
```

```
class Coroutine {
 public:
 // ...
  void Sleep(WaitStrategy& strategy);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
  virtual void BeforeAwake() = 0;
 protected:
  ~WaitStrategy() = default;
};
```

```
struct Mutex {
  void lock();
  void unlock();

private:
  std::atomic<Coroutine*> owner_{nullptr};
};
```

```
struct Mutex {
  void lock();
  void unlock();

private:
  std::atomic<Coroutine*> owner_{nullptr};
  WaitList lock_waiters_;
};
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::ListNode<Coroutine*> node{current};
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
class MutexWaitStrategy final : public WaitStrategy {
   public:
    MutexWaitStrategy(WaitList& waiters, Coroutine* current)
         : WaitStrategy(), waiters_(waiters), current_(current), lock_(waiters) {}
    void AfterAsleep() override {
      waiters_.Append(lock_, current_);
      lock .unlock();
    void BeforeAwake() override {
      lock .lock();
      waiters_.Remove(lock_, current_);
   private:
    WaitList& waiters_;
    Coroutine* const current_;
    WaitList::Lock lock_;
Анатомия асинхронных движков
```

170 / 223

```
class MutexWaitStrategy final : public WaitStrategy {
public:
 MutexWaitStrategy(WaitList& waiters, Coroutine* current)
      : WaitStrategy(), waiters_(waiters), current_(current), lock_(waiters) {}
 void AfterAsleep() override {
   waiters_.Append(lock_, current_);
    lock .unlock();
 void BeforeAwake() override {
    lock .lock();
    waiters_.Remove(lock_, current_);
 private:
 WaitList& waiters_;
 Coroutine* const current_;
 WaitList::Lock lock_;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

Анатомия асинхронных движков

```
class MutexWaitStrategy final : public WaitStrategy {
public:
 MutexWaitStrategy(WaitList& waiters, Coroutine* current)
      : WaitStrategy(), waiters_(waiters), current_(current), lock_(waiters) {}
 void AfterAsleep() override {
   waiters_.Append(lock_, current_);
    lock_.unlock();
 void BeforeAwake() override {
    lock .lock();
    waiters_.Remove(lock_, current_);
 private:
 WaitList& waiters_;
 Coroutine* const current_;
 WaitList::Lock lock_;
```

177 / 223

```
void Mutex::unlock() {
    [[maybe_unused]] const auto old_owner = owner_.exchange(nullptr);
    assert(old_owner == GetCurrentCoro());
    WaitList::Lock lock(lock_waiters_);
    lock_waiters_.WakeupOne(lock);
}
```

```
void Mutex::unlock() {
    [[maybe_unused]] const auto old_owner = owner_.exchange(nullptr);
    assert(old_owner == GetCurrentCoro());
    WaitList::Lock lock(lock_waiters_);
    lock_waiters_.WakeupOne(lock);
}
```

```
void Mutex::unlock() {
    [[maybe_unused]] const auto old_owner = owner_.exchange(nullptr);
    assert(old_owner == GetCurrentCoro());
    WaitList::Lock lock(lock_waiters_);
    lock_waiters_.WakeupOne(lock);
}
```

```
void Mutex::unlock() {
    [[maybe_unused]] const auto old_owner = owner_.exchange(nullptr);
    assert(old_owner == GetCurrentCoro());
    WaitList::Lock lock(lock_waiters_);
    lock_waiters_.WakeupOne(lock);
}
```

```
void Mutex::unlock() {
    [[maybe_unused]] const auto old_owner = owner_.exchange(nullptr);
    assert(old_owner == GetCurrentCoro());
    WaitList::Lock lock(lock_waiters_);
    lock_waiters_.WakeupOne(lock);
}
```

```
void Mutex::unlock() {
    [[maybe_unused]] const auto old_owner = owner_.exchange(nullptr);
    assert(old_owner == GetCurrentCoro());
    WaitList::Lock lock(lock_waiters_);
    lock_waiters_.WakeupOne(lock);
}
```

```
void Mutex::unlock() {
    [[maybe_unused]] const auto old_owner = owner_.exchange(nullptr);
    assert(old_owner == GetCurrentCoro());
    WaitList::Lock lock(lock_waiters_);
    lock_waiters_.WakeupOne(lock);
}
```

Анатомия асинхронных движков

```
class MutexWaitStrategy final : public WaitStrategy {
public:
 MutexWaitStrategy(WaitList& waiters, Coroutine* current)
      : WaitStrategy(), waiters_(waiters), current_(current), lock_(waiters) {}
 void AfterAsleep() override {
   waiters_.Append(lock_, current_);
    lock .unlock();
 void BeforeAwake() override {
    lock_.lock();
   waiters_.Remove(lock_, current_);
 private:
 WaitList& waiters_;
 Coroutine* const current_;
 WaitList::Lock lock_;
```

185 / 223

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

```
void Mutex::lock() {
  Coroutine* current = GetCurrentCoro();
  Coroutine* expected = nullptr;
  if (owner_.compare_exchange_strong(expected, current)) return;
  Coroutine* expected = nullptr;
  impl::MutexWaitStrategy wait_manager(lock_waiters_, current);
 while (!owner_.compare_exchange_strong(expected, current)) {
    assert(expected != current && "Mutex is locked twice from the same task");
    current->Sleep(wait_manager);
    expected = nullptr;
```

• Не блокирует поток

- Не блокирует поток
- Не переключает контекст

- Не блокирует поток
- Не переключает контекст
- Не аллоцирует

А если с таймаутами?

```
struct Mutex {
  void lock();
  bool try_lock_untill(Deadline deadline);
  void unlock();

private:
  std::atomic<Coroutine*> owner_{nullptr};
  WaitList lock_waiters_;
};
```

```
struct Mutex {
  void lock();
  bool try_lock_untill(Deadline deadline);
  void unlock();

private:
  std::atomic<Coroutine*> owner_{nullptr};
  WaitList lock_waiters_;
};
```

```
struct Mutex {
  void lock();
  bool try_lock_untill(Deadline deadline);
  void unlock();

private:
  std::atomic<Coroutine*> owner_{nullptr};
  WaitList lock_waiters_;
};
```

```
class Coroutine {
 public:
 // ...
 void Sleep(WaitStrategy& strategy);
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
 protected:
 ~WaitStrategy() = default;
```

```
class Coroutine {
 public:
 // ...
 void Sleep(WaitStrategy& strategy);
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
 protected:
 ~WaitStrategy() = default;
```

```
class Coroutine {
 public:
 // ...
 void Sleep(WaitStrategy& strategy);
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
 protected:
 ~WaitStrategy() = default;
```

```
class Coroutine {
public:
 // ...
 void Sleep(WaitStrategy& strategy);
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
 protected:
 ~WaitStrategy() = default;
```

```
class Coroutine {
 public:
 // ...
 void Sleep(WaitStrategy& strategy);
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
 protected:
 ~WaitStrategy() = default;
```

```
class Coroutine {
public:
 // ...
 void Sleep(WaitStrategy& strategy);
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
 protected:
 ~WaitStrategy() = default;
```

```
class Coroutine {
public:
 // ...
 void Sleep(WaitStrategy& strategy);
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
 protected:
 ~WaitStrategy() = default;
```

```
class Coroutine {
 public:
  // ...
 void Sleep(WaitStrategy& strategy);
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
  const Deadline deadline;
protected:
 ~WaitStrategy() = default;
};
```

```
class Coroutine {
 public:
  // ...
 void Sleep(WaitStrategy& strategy);
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
  const Deadline deadline;
protected:
 ~WaitStrategy() = default;
};
```

```
class Coroutine {
 public:
  // ...
 void Sleep(WaitStrategy& strategy);
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
  const Deadline deadline;
protected:
 ~WaitStrategy() = default;
};
```

```
class Coroutine {
public:
  // ...
 WakeupReason Sleep(WaitStrategy& strategy);
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
  const Deadline deadline;
protected:
 ~WaitStrategy() = default;
```

```
class Coroutine {
public:
 // ...
 WakeupReason Sleep(WaitStrategy& strategy);
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
  const Deadline deadline;
protected:
 ~WaitStrategy() = default;
```

```
class Coroutine {
public:
  // ...
 WakeupReason Sleep(WaitStrategy& strategy);
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
  const Deadline deadline;
protected:
 ~WaitStrategy() = default;
```

Аесли с отменами?

А отмены?

```
class Coroutine {
 public:
  // ...
 WakeupReason Sleep(WaitStrategy& strategy);
  bool IsCancelled() const;
 void Cancel();
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
protected:
 ~WaitStrategy() = default;
};
```

А отмены?

```
class Coroutine {
 public:
  // ...
 WakeupReason Sleep(WaitStrategy& strategy);
  bool IsCancelled() const;
 void Cancel();
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
protected:
 ~WaitStrategy() = default;
};
```

А отмены?

```
class Coroutine {
 public:
  // ...
 WakeupReason Sleep(WaitStrategy& strategy);
 bool IsCancelled() const;
 void Cancel();
  Epoch GetEpoch();
 void Wakeup(Epoch epoch);
  // ...
class WaitStrategy {
 public:
 virtual void AfterAsleep() = 0;
 virtual void BeforeAwake() = 0;
protected:
 ~WaitStrategy() = default;
};
```

Итог

• Kopyтины ≈ callbacks

- Kopyтины ≈ callbacks
- Асинхронность позволяет экономить потоки и CPU

- Kopyтины ≈ callbacks
- Асинхронность позволяет экономить потоки и CPU
- Под капотом жесть

- Kopyтины ≈ callbacks
- Асинхронность позволяет экономить потоки и CPU
- Под капотом жесть, прикольная жесть!

- Kopyтины ≈ callbacks
- Асинхронность позволяет экономить потоки и CPU
- Под капотом жесть, прикольная жесть!
- Снаружи всё просто и понятно

- Корутины ≈ callbacks
- Асинхронность позволяет экономить потоки и CPU
- Под капотом жесть, прикольная жесть!
- Снаружи всё просто и понятно
- Во всех движках очередь готовых к выполнению задач

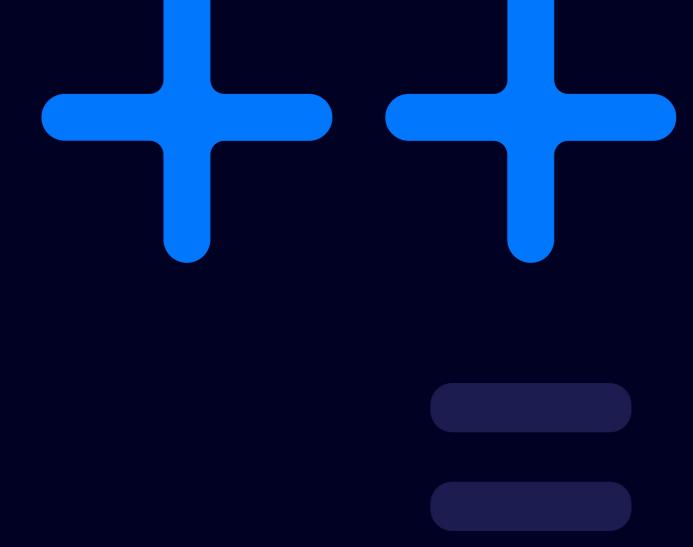
Спасибо

C++Zero Cost Conf

Спасибо за внимание

Полухин Антон Эксперт разработчик C++

antoshkka@yandex-team.ru antoshkka@gmail.com



Yandex for developers *//>