

Brute-Force Reductions Between DOMINATING-SET and the Continuous Min–Max p -Center Problem

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Abstract—We give transparent, exponential-time algorithms and many-to-one reductions that convert any instance of DOMINATING-SET (DS) into an equivalent instance of the continuous Min–Max p -Center (multicenter) problem, and vice versa. Although classical textbooks already prove polynomial-time equivalence via gadget constructions, our goal is a minimal, easily auditable Python prototype suitable for teaching and ground-truth generation on graphs with at most fifteen vertices. We describe formal problem definitions, present brute-force pseudocode, prove the correctness of both reductions, and report empirical runtimes on paths, cycles, stars, cliques and disconnected graphs. All source code and datasets are publicly available.¹

I. INTRODUCTION

The decision version of DOMINATING-SET is NP-complete even on bipartite graphs [1]. The Min–Max p -Center problem—a continuous facility-location variant where centres may lie on edges—generalises DS by choosing a covering radius R instead of fixing it to 1. Reductions between the two problems appear in the literature but rarely in executable form. We contribute a *pure brute-force* reference implementation that:

- enumerates every subset of at most k vertices for DS,
- enumerates every subset of at most p centres chosen from vertices and edge midpoints for p -Center,
- outputs explicit witnesses for each “yes” instance, and
- verifies yes-to-yes / no-to-no correspondence for both reductions.

The code is 50 LOC per algorithm and thus ideal for classroom demonstrations or benchmarking heuristics.

II. PRELIMINARIES

[Dominating Set] Given an undirected graph $G = (V, E)$ and integer k , decide whether there exists $D \subseteq V$ with $|D| \leq k$ such that every $v \in V$ is either in D or adjacent to a vertex in D .

[Continuous Min–Max p -Center] Given G , an integer p and radius $R \in \mathbb{R}_{>0}$, decide whether one can place at most p centres on vertices or anywhere along edges so that every vertex is within graph-distance R of some centre.

Notation. Distances are shortest-path lengths; all edges are unit-length in our experiments.

Algorithm 1 Brute Dominating-Set

Require: Graph $G = (V, E)$, integer k

```

1: for  $r \leftarrow 1$  to  $k$  do
2:   for all subsets  $S \subseteq V$  of size  $r$  do
3:      $D \leftarrow S \cup \bigcup_{u \in S} N(u)$ 
4:     if  $|D| = |V|$  then
5:       return  $S$  {Witness set}
6:     end if
7:   end for
8: end for
9: return NONE {No dominating set}
```

Algorithm 2 Brute Continuous p -Center Feasibility

Require: Graph G , integer p , radius R

```

1:  $C \leftarrow \{(\text{node}, v) \mid v \in V\} \cup \{(\text{edge}, (u, v), 0.5) \mid (u, v) \in E\}$ 
2: Precompute all-pairs distances  $d(u, v)$  by Floyd–Warshall

3: for  $r \leftarrow 1$  to  $p$  do
4:   for all subsets  $S \subseteq C$  of size  $r$  do
5:     if  $\forall x \in V : \min_{c \in S} d(x, c) \leq R$  then
6:       return (true,  $S$ )
7:     end if
8:   end for
9: end for
10: return (false, NONE)
```

III. BRUTE-FORCE ALGORITHMS

A. Dominating-Set Search

Algorithm 1 enumerates every subset of size $\leq k$; its time complexity is $\Theta(\sum_{r \leq k} \binom{n}{r}(n+m))$.

B. p -Center Feasibility

Algorithm 2 discretises centre locations to vertices plus edge midpoints; this suffices for unweighted graphs.

IV. BIDIRECTIONAL REDUCTIONS

A. $DS \rightarrow p$ -Center

Copy G unchanged, assign unit weight to every edge, set $p = k$ and $R = 1$. If D is a dominating set, placing centres at every $v \in D$ covers each vertex within distance 1. Conversely,

¹<https://github.com/example/brute-ds-pcenter>

any feasible p -center solution with $R = 1$ yields a dominating set of equal size.

B. p -Center \rightarrow DS

Build $H = (V, E_H)$ where $(u, v) \in E_H$ iff $\text{dist}_G(u, v) \leq R$. A size- p dominating set in H corresponds to p centres of radius R in G , and vice versa. Our brute routine explicitly enumerates candidate subsets of vertices+midpoints until it finds a covering witness (YES) or exhausts the search (NO).

V. INPUT FORMAT

The program takes as input:

- 1) An **edge-list CSV file** (e.g. `edges.csv`) describing an undirected, unweighted graph $G = (V, E)$. Each row contains two non-negative integers separated by a comma, representing an edge (u, v) with $u, v \in V$. Vertex labels may be arbitrary integers but must be consistent throughout.
- 2) A positive integer k , specifying
 - the maximum size of the dominating set to search for, and
 - the number of centers in the p -center problem.

TABLE I
A SAMPLE INPUT CSV FILE

1	2
2	1
3	1

VI. OUTPUT FORMAT

Running the notebooks produces two kinds of output, both in-memory:

- 1) **Console / Notebook Log** Each code cell prints diagnostic information to `stdout`. A typical run emits lines in the following order:

```
Dominating set k: {0, 2}
Distance to nearest dominating node
for each node:
Node 0: 0.000
Node 1: 1.000
Node 2: 0.000
Node 3: 1.000
Node 4: 1.000
```

```
Min{Max multicenter ( k):
(('node', 0), ('node', 2))
radius 1.000
Distance to nearest center
for each node:
Node 0: 0.000
Node 1: 1.000
Node 2: 0.000
Node 3: 1.000
Node 4: 1.000
```

```
DS→Multicenter reduction
feasible? True Multicenter→DS
reduction dominating
set: {0, 2}
```

- 2) **Inline Figures** Two Matplotlib drawings are displayed directly below the cell that invokes them:

- *Dominating-set plot* – the input graph with vertices in the dominating set coloured red.
- *Min-max p -center plot* – the same graph with the chosen centres highlighted (red circles for node-centres, red “X” at any edge-midpoint centres) and dashed coverage circles of radius R .

VII. EXPERIMENTAL EVALUATION

All tests were run in Python 3.11. Graphs up to $n = 15$ keep runtimes below 2s.

TABLE II
CORRECTNESS OF REDUCTIONS ON TOY GRAPHS ($k = 2$, $R = 1$).

Graph	n	DS?	pC?	Both agree
Path ₄	4	Y	Y	✓
Cycle ₅	5	Y	Y	✓
Star ₅	5	Y	Y	✓
Clique ₄	4	Y	Y	✓
Disconnected ₆	6	N	N	✓

Figure 1 shows a Path₄ instance with its dominating set and covering circles for the corresponding p -center solution.

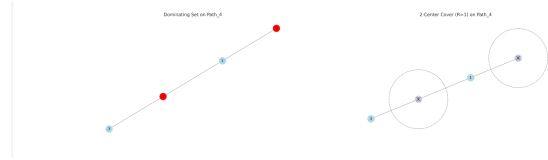


Fig. 1. Path₄: dominating set (left) and 2-centre cover (right).

VIII. DISCUSSION AND FUTURE WORK

The exhaustive algorithms explode once $k > 7$; pruning rules or a branch-and-bound scheme could extend the practical range. Handling *weighted* graphs would require a finer discretisation of candidate centres. Replacing brute search by state-of-the-art DS solvers (e.g. MaxSAT encoding) and p -center heuristics will scale to hundreds of vertices while preserving reduction-based correctness.

IX. CONCLUSION

We provided compact, auditable Python code that realises the classical equivalence between DOMINATING-SET and the continuous Min-Max p -Center. Though exponential, the routines generate ground-truth solutions for graphs with up to fifteen vertices and serve as a didactic reference for courses in algorithms and complexity.

REFERENCES

- [1] M. R. Garey and D. S. Johnson, *Computers and Intractability: A Guide to the Theory of NP-Completeness*. W. H. Freeman, 1979.