PARTIAL 3D OBJECT RETRIEVAL

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Outline

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- 2. Problem Statement
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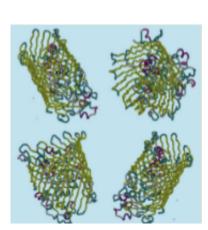
Motivation and Scope

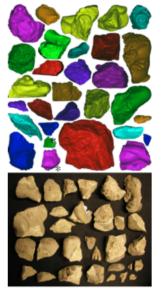
Increasing amount of 3D data.

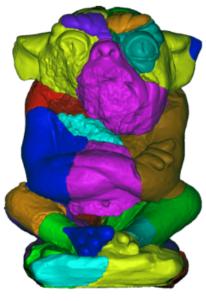
Ability of capture devices to produce low-cost multimedia data.

Applications:

- 1. Cultural Heritage
- 2. Archaeology
- 3. 3D protein retrieval and classification
- 4. 3D retrieval for museums



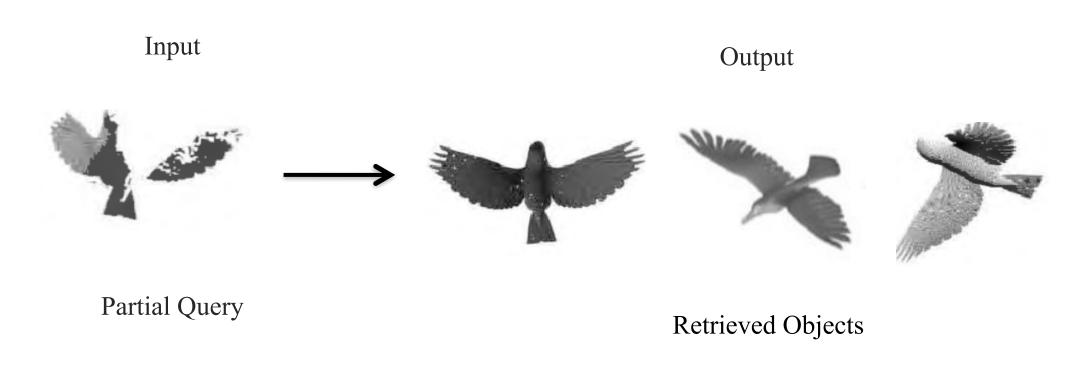






Problem Statement

To develop a technique to retrieve the similar objects given a partial query.



Objectives

- 1. To extract the features from the given 3D objects.
- 2. To perform encoding of the extracted features.
- 3. To match the input query with the dataset.
- 4. To evaluate the performance of the proposed technique.

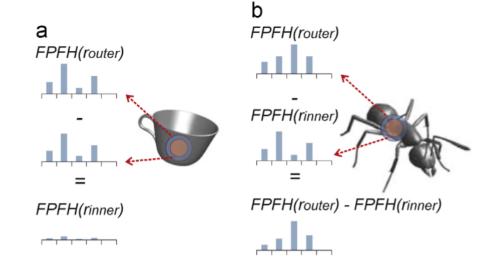
Related Works

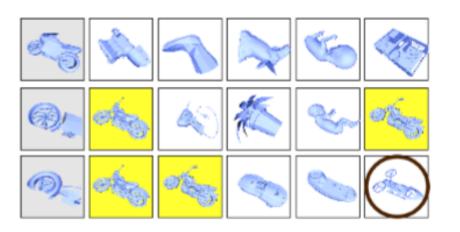
Fisher encoding of Differential Fast Point Feature histograms for Partial 3D Object Retrieval, 2016 [1] The proposed system is based on hybrid shape matching scheme so as to account for both global and local shape similarities.

- Differential fast point feature histogram
- Fisher vector.

A Query-by-Example Concept and User Interface for Global and Partial 3D Object Retrieval,2009. [2] It is based on the idea to apply an existing global 3D descriptor on both whole models and model segments.

- Partial similarity Local to local correspondences
- Model segmentation





System Model Dataset **EVALUATION FEATURE FEATURE MATCHING SAMPLING EXTRACTION ENCODING IWKS** FV BoF Partial Query Retrieved Objects

1. Feature Extraction

Improved Wave Kernel Signature (IWKS)

- Characterize a point by the average probabilities of quantum particles of different energy levels.
- Energies correspond to frequency.
- Eigen values of the LBO.
- Cube root scaling.
- Curvature aggregation.

2. Feature Encoding

- Bag-of-features (BOF)
 - Convert the descriptors to codewords.
 - K-means clustering
- Fisher Vector (FV)
 - Gaussian Mixture Model used as visual code book.
 - Captures the average first and second order differences between descriptors and the centers of GMM.

• For Kth GMM, we define,

$$u_k = rac{1}{N\sqrt{\pi_k}} \sum_{i=1}^N q_{ik} \sum_k^{-1/2} (x_i - \mu_k)$$

$$v_k = rac{1}{N\sqrt{2\pi_k}} \sum_{i=1}^N q_{ik} [(x_i - \mu_k) \sum_k^{-1} (x_i - \mu_k) - 1]$$

• Fisher encoding of feature vector is given by,

$$f = [u_1^T, v_1^T, ..., u_k^T, u_k^T]$$

3. Matching

Manhattan Distance (L1- norm)

$$d = \sum_{i=1}^N |a_i - b_i|$$

• Euclidean Distance (L2-norm)

$$d = \sqrt{\sum_{i=1}^N (a_i - b_i)^2}$$

Cosine Distance

$$d = rac{\sum_{i=1}^{N}(x_iy_i)}{\sqrt{\sum_{i=1}^{N}x_i^2}\sqrt{\sum_{i=1}^{N}y_i^2}}$$

• Earth Mover Distance

$$d = rac{\sum_{i=1}^{M} \sum_{j=1}^{N} f_{i,j} d_{i,j}}{\sum_{i=1}^{M} x_i^2 \sum_{j=1}^{N} f_{i,j}}$$

4. Performance Evaluation

Nearest Neighbor (NN)

- Ratio of objects in the query's class that are present in the top N matches. N=1 is considered.
- First Tier (FT)
- Given a query, it is the precision when C objects have been retrieved, where C is the number of relevant objects. K=|C|-1 is considered for first tier.

Second Tier (ST)

- Given a query, it is the precision when 2*C objects have been retrieved, where C is the number of relevant objects in the 3D dataset. K = 2*(|C|-1) for the second tier.
- E-measure
- F-measure, which is the weighted harmonic mean of precision and recall. F-measure is defined as:

$$F = \frac{(1+\alpha) \times precision \times recall}{\alpha \times precision + recall}$$

Where α is the weight. Let $\alpha = 1$ then,

$$F = \frac{2 \times precision \times recall}{\alpha \times precision + recall}$$

E-measure is defined as,

$$E = 1 - F$$

Discount cumulat
$$E = 1 - \frac{1}{\frac{1}{precision} + \frac{1}{recall}}$$

DCG penalizes the objects which are relevant and appear lower in the result list.

$$DCG_r = relevant_1 + \sum_{i=2}^{r} \frac{relevent_i}{log_2(i+1)}$$

Dataset

SHREC 2011 Range Scan

Classes: 50

Objects per class: 20



Encoding	K	NN	FT	ST	E	DCG
	10	0.0000	0.0180	0.0350	0.0223	0.3085
	20	0.0067	0.0107	0.0303	0.0149	0.3037
	25	0.0067	0.0107	0.0310	0.0162	0.3068
FV	50	0.0000	0.0097	0.0310	0.0162	0.3037
r v	100	0.0000	0.0093	0.0293	0.0151	0.3064
	125	0.0133	0.0133	0.0347	0.0200	0.3081
	150	0.0133	0.0117	0.0303	0.0164	0.3079
	200	0.0133	0.0160	0.0317	0.0179	0.3102
	10	0.0000	0.0143	0.0243	0.0164	0.3056
	50	0.0200	0.0217	0.0417	0.0246	0.3170
	100	0.0000	0.0140	0.0317	0.0182	0.3104
D _o E	150	0.0200	0.0177	0.0327	0.0205	0.3128
BoF	200	0.0267	0.0257	0.0430	0.0285	0.3209
	300	0.0400	0.0257	0.0437	0.0282	0.3218
	500	0.0533	0.0240	0.0443	0.0290	0.3219
	1000	0.0600	0.0527	0.0527	0.0333	0.3222

Performance metrics obtained using L1-Norm for matching

Encoding	K	NN	FT	ST	E	DCG
	10	0.0067	0.0177	0.0337	0.0221	0.3086
	20	0.0000	0.0180	0.0350	0.0223	0.3085
	25	0.0000	0.0183	0.0357	0.0218	0.3078
FV	50	0.0000	0.0157	0.0310	0.0195	0.3068
r v	100	0.0000	0.0140	0.0310	0.0187	0.3079
	125	0.0000	0.0140	0.0283	0.0182	0.3077
	150	0.0067	0.0160	0.0287	0.0190	0.3098
	200	0.0000	0.0153	0.0287	0.0192	0.3088
	10	0.0067	0.0403	0.0690	0.0446	0.3362
	50	0.0200	0.0200	0.0387	0.0226	0.3171
	100	0.0000	0.0160	0.0407	0.0218	0.3119
BoF	150	0.0067	0.0203	0.0383	0.0231	0.3114
	200	0.0333	0.0247	0.0460	0.0285	0.3187
	300	0.0400	0.0190	0.0450	0.0295	0.3198
	500	0.0333	0.0267	0.0503	0.0313	0.3212
	1000	0.0533	0.0267	0.0527	0.0333	0.3222

Performance metrics obtained using L2-Norm for matching

Encoding	K	NN	FT	ST	E	DCG
	10	0.0133	0.0140	0.0267	0.0167	0.3064
	20	0.0133	0.0137	0.0257	0.0149	0.3073
	25	0.0133	0.0177	0.0307	0.0187	0.3103
FV	50	0.0133	0.0180	0.0323	0.0218	0.3108
r v	100	0.0133	0.0153	0.0333	0.0195	0.3065
	125	0.0133	0.0167	0.0320	0.0197	0.3086
	150	0.0133	0.0140	0.0300	0.0190	0.3090
	200	0.0000	0.0150	0.0320	0.0179	0.3086
	10	0.0067	0.0493	0.0907	0.0569	0.3436
	50	0.0200	0.0243	0.0467	0.0277	0.3243
	100	0.0000	0.0217	0.0397	0.0249	0.3177
BoF	150	0.0000	0.0140	0.0287	0.0172	0.3073
	200	0.0133	0.0273	0.0520	0.0338	0.3239
	300	0.0400	0.0247	0.0447	0.0292	0.3247
	500	0.0267	0.0247	0.0440	0.0277	0.3262
	1000	0.0400	0.0290	0.0497	0.0292	0.0292

Performance metrics obtained using Cosine Distance for matching

Encoding	K	NN	$_{ m FT}$	ST	Е	DCG
	10	0.0067	0.0157	0.0350	0.0218	0.3096
	20	0.0000	0.0173	0.0427	0.0254	0.3126
	25	0.0000	0.0167	0.0437	0.0269	0.3119
FV	50	0.0000	0.0167	0.0417	0.0228	0.3117
r v	100	0.0067	0.0170	0.0403	0.0236	0.3139
	125	0.0000	0.0160	0.0413	0.0231	0.3134
	150	0.0067	0.0187	0.0407	0.0251	0.3163
	200	0.0000	0.0160	0.0423	0.0241	0.3142
	10	0.0067	0.0167	0.0417	0.0246	0.3136
	50	0.0000	0.0197	0.0397	0.0244	0.3187
	100	0.0667	0.0317	0.0633	0.0418	0.3354
BoF	150	0.0600	0.0323	0.0630	0.0390	0.3338
	200	0.0200	0.0153	0.0370	0.0226	0.3134
	300	0.0067	0.0180	0.0347	0.0218	0.3102
	500	0.0067	0.0157	0.0370	0.0215	0.3160
	1000	0.0000	0.0187	0.0420	0.02625	0.3144

Performance metrics obtained using EMD for matching

Comparison with state-of-the art technique

Feature	NN	FT	ST
RSI	0.0892	0.0734	0.0713
PSI	0.0933	0.0812	0.0770
SC	0.0861	0.0825	0.0771
FPFH	0.1167	0.0799	0.074

Performance metrics of state-of-the art technique on SHREC'09

Encoding	Distance	K	NN	FT	ST
	l_1 -norm	200	0.0133	0.016	0.0317
FV	l_2 -norm	10	0.0067	0.0177	0.0337
l r v	Cosine	50	0.0133	0.0180	0.0323
	EMD	150	0.0067	0.0187	0.0407
BoF	l_1 -norm	1000	0.0600	0.0527	0.0527
	l_2 -norm	1000	0.0533	0.0267	0.0527
	Cosine	1000	0.0400	0.0290	0.0497
	EMD	100	0.0667	0.0317	0.0633

Performance metrics of proposed partial 3D object retrieval technique on SHREC'11

- We observed that the proposed technique using BoFs encoding outperformed FV encoding techniques.
- L1-norm distance out performed other distance measures.

Conclusions And Future Scope

We proposed a partial 3D object retrieval technique comprising five modules, namely, sampling, feature extraction, feature encoding, matching and performance evaluation.

- We demonstrated the performance of the proposed technique on SHREC'11 dataset.
- We observed that the proposed technique using BoFs encoding outperformed other encoding techniques. Also, for matching L1-norm distance performed better.
- As future work the proposed technique can be extended by using other feature extraction methods and matching techniques.
- Also weighting of codewords can be done in BoF.

THANK-YOU

REFERENCES:

- [1] Michalis A. Savelonas, Ioannis Pratikakis, Konstantinos Sfikas. Fisher encoding of Differential Fast Point Feature histograms for Partial 3D Object Retrieval, 2016.
- [2] I.Pratikakis, M.Spagnuolo, T. Theoharis, and R.Veltkamp. A Query-by-Example Concept and User Interface for Global and Partial 3D Object Retrieval, 2009.
- [3] Mathieu Aubry, Ulrich Schlickewei, Daniel Cremers. The Wave Kernel Signature: A Quantum Mechanical Approach to Shape Analysis.

Implementation

```
46622 90161 0
0.345632 -0.989338 -0.226566
-0.063311 0.753159 -0.400532
1.0083 -0.183685 -0.54204
-0.725983 -0.052494 -0.085058
                                                      10.050280 0.051050 0.051972 0.053143 0.054726 0.056962 0.060149 0.064598 0.070571 0.078203 0.087451 0.098063 0.109598 0.121453 0.132929 0.143311 0.151967 0.158453 0.162594 0.164515 0.164631 0.163583
-0.386981 0.021914 0.190186
                                                       0.162155 0.161166 0.161363 0.163312 0.167302 0.173294 0.180938 0.189663 0.198832 0.207903 0.216550 0.224720 0.232612 0.240599 0.249110 0.258491 0.268878 0.280108 0.291690 0.302850 0.312642 0.320110
-0.401598 0.049609 0.176745
                                                       0.324443 0.325113 0.321956 0.315195 0.305407 0.293443 0.280317 0.267066 0.254630 0.243741 0.234870 0.228215 0.223730 0.221194 0.220282 0.220641 0.221963 0.224026 0.226730 0.230098 0.234247 0.239350
                                                       0.245562 0.252953 0.261442 0.270754 0.280422 0.289827 0.298280 0.305132 0.309868 0.312186 0.312024 0.309545 0.305080 0.299066 0.291974 0.284248 0.276260 0.268288 0.260501 0.252976 0.245722 0.238733
-0.411009 0.038168 0.181225
                                                       0.232030 0.225708 0.219944 0.214995 0.211151 0.208685 0.207803 0.208604 0.211071 0.215077 0.220413 0.102731
-0.377571 0.033354 0.185706
-0.41137 0.040663 0.183257
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-0.410374 0.044023 0.184144
                                                      30.022735 0.024567 0.027117 0.030519 0.034885 0.040241 0.046473 0.053298 0.060292 0.066970 0.072905 0.077811 0.081584 0.084289 0.086113 0.087315 0.088171 0.088941 0.089852 0.091088 0.092804 0.095145
-0.386346 0.027768 0.193105
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-0.405669 0.049743 0.181904
-0.381641 0.033489 0.190865 Feature
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                                                       0.066582 0.087255 0.113168 0.144151 0.179360 0.217162 0.255171 0.290474 0.320019 0.341093 0.351752 0.351113 0.339440 0.318049 0.289049 0.255009 0.218606 0.182311 0.148170 0.117684 0.091801 0.070987
-0.403221 0.050571 0.179377
-0.379193 0.034317 0.188338 Extraction
                                                       0.055357 0.044801 0.039092 0.037936 0.040964 0.047673 0.057353 0.069033 0.081486 0.093321 0.103139 0.109741 0.112310 0.110544 0.104680 0.095428 0.083815 0.071003 0.058102 0.046026 0.035414 0.026606
-0.367505 0.00965 0.199779
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-0.382122 0.037345 0.186338
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-0.391533 0.025905 0.190818
-0.358095 0.021091 0.195299
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                                                                                                                     IWKS features
-0.367866 0.012146 0.201811
-0.390898 0.03176 0.193737
-0.36687 0.015505 0.202698
-0.388811 0.035083 0.193242
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-0.386193 0.03748 0.191497
-0.362165 0.021225 0.200458
```

Input 3D Point

-0.383745 0.038308 0.18897 -0.359717 0.022054 0.197931 -0.348029 -0.002613 0.209372 -0.362646 0.025082 0.195931 -0.372056 0.013641 0.200411

Implementation

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15.071215 16.113056 17.701663 17.698095 19.596749 18.429274 15.756585 17.207922 21.874132
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20.312392 19.041746 18.668388 14.708485 16.568877 15.873677 17.730311 14.506933 18.414865
14.962078 16.252771 17.590681 17.230871 17.457804 16.730490 14.307772 16.261599 16.794094
16.544997 20.560552 16.894241 17.453510 15.222383 14.936353 14.814873 16.918622 18.439448
16.610459 23.714509 15.940356 16.719464 15.783190 17.510626 16.825642 15.937560 17.043565
16.521372 18.035684 19.569748 15.667983 13.821432 15.243081 20.219066 20.681037 15.389233
```

Feature

Matching

Encoding and

Distance Matrix

```
R00001
D00325 13.729901000000002
D00263 13.808893
D00665 13.821432000000001
D00568 13.936519
D00915 14.029943
D00478 14.08895
D00156 14.139003
D00468 14.160554999999999
D00873 14.166057
D00051 14.167767999999999
D00921 14.185222
D00953 14.201017000000002
D00198 14.203201000000002
D00173 14.222005
D00504 14.226023999999999
D00676 14.245052
D00577 14.260414
D00889 14.263792
D00310 14.278835
D00631 14.303379000000001
D00607 14.307772
D00781 14.312448000000002
D00946 14.314570999999999
D00860 14.318677
D00654 14.333682000000001
D00044 14.346034
D00836 14.359932
D00933 14.371594
D00045 14.372935
D00789 14.38384
D00359 14.393061999999999
D00458 14.399866000000001
D00053 14.39999299999998
D00881 14.406676999999998
D00747 14.420335000000001
D00951 14.429309
D00901 14.455884
D00323 14.459999
D00978 14.46285
D00837 14.47649
D00158 14.481909
```

Generating

Ranked List

Ranked List