



Model Optimization and Tuning Phase

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Project Title	Crystal Clear Vision: Revolutionizing Cataract Prediction through Transfer Learning Mastery
Maximum Marks	10 Marks

Model Optimization and Tuning Phase:

The Model Optimization and Tuning Phase involves refining neural network models for peak performance. It includes optimized model code, fine-tuning hyperparameters, comparing performance metrics, and justifying the final model selection for enhanced predictive accuracy and efficiency.

Hyperparameter Tuning Documentation:

Model	Tuned Hyperparameters
date me trai the Tra wei Resnet 50 ove its justified the trai con Ear	aining with 5 Epochs - The model starts to learn basic patterns in the ta with just 5 epochs, it's highly likely that the model will underfit, caning it hasn't had enough time to learn the underlying patterns in the ining data. The accuracy and loss metrics might show improvement, but a model's performance will likely be suboptimal. The model has more time to learn and adjust its eights, leading to better performance. With more epochs, there's a risk of erfitting, where the model learns the noise in the training data, reducing performance on unseen data. Using techniques like early stopping helps tigate overfitting by stopping training once the model performance on a validation set stops improving. More epochs usually result in higher ining accuracy and potentially higher validation accuracy if overfitting is introlled. The stopping: raining when the validation accuracy stops improving for a ecified patience





Data Augmentation: Applying data augmentation as a layer (x=data_augmentation(inputs)) is a technique to artificially expand the size of a training dataset by creating modified versions of images in the dataset.

```
#adding in data augmentation as a layer itself
x=data_augmentation(inputs)
#pass inputs to base model
x=base_model(x, training=False)
print(x.shape)
#We will use average pooling to reduce the size of the feature map.
x=tf.keras.layers.GlobalAveragePooling2D(name='global average pooling layer')(x)
print(x.shape)
outputs=tf.keras.layers.Dense(1,activation='sigmoid',name='output_layer')(x)
model_0= tf.keras.Model(inputs,outputs)
#define early stopping callback.
early\_stopping=EarlyStopping(monitor='val\_accuracy',patience=3,restore\_best\_weights=True)
checkpoint = ModelCheckpoint('best_resnet_model.h5', monitor='val_accuracy', save_best_only=True)
model_0.compile(loss='binary_crossentropy',
                optimizer=tf.keras.optimizers.Adam().
                metrics=['accuracy'])
#Using 50 epochs instead of 5
history model 0= model 0.fit(train data,
                             epochs=50,
                             validation data=val data,
                             callbacks=[early_stopping,checkpoint])
```

Accuracy -

Epochs = 5

Epochs = 50





Vgg16	Training with 5 Epochs - The model starts to learn basic patterns in the data With just 5 epochs, it's highly likely that the model will underfit, meaning it hasn't had enough time to learn the underlying patterns in the training data. The accuracy and loss metrics might show improvement, but the model's performance will likely be suboptimal. Training with 50 Epochs - The model has more time to learn and adjust its weights, leading to better performance. With more epochs, there's a risk of overfitting, where the model learns the noise in the training data, reducing its performance on unseen data. Using techniques like early stopping helps mitigate overfitting by stopping training once the model performance on the validation set stops improving. More epochs usually result in higher training accuracy and potentially higher validation accuracy if overfitting is controlled. ModelCheckpoint('best_inception_model.h5', monitor='val_accuracy', save_best_only=True): Saves the best model during training based on validation accuracy. fit(train_gen, validation_data=val_gen, epochs=50, callbacks=[early_stopping, checkpoint]): Trains the model with the training data, validates it with validation data, and uses callbacks for early stopping and checkpointing. Epochs = 5	
	Epoch 1/5 19/19	





Learning Rate: Controls step size at each iteration. **Batch Size**: Number of training samples per iteration.

Epochs: Number of complete passes through the training dataset. **Optimizer**: Algorithm used to minimize the loss function (e.g.,

Adam, RMSprop).

GlobalAveragePooling2D: Reduces the spatial dimensions of the feature map by averaging, which helps in reducing the number of parameters and computational load.

Training with 5 Epochs - The model starts to learn basic patterns in the data With just 5 epochs, it's highly likely that the model will underfit, meaning it hasn't had enough time to learn the underlying patterns in the training data. The accuracy and loss metrics might show improvement, but the model's performance will likely be suboptimal.

Training with 50 Epochs - The model has more time to learn and adjust its weights, leading to better performance. With more epochs, there's a risk of overfitting, where the model learns the noise in the training data, reducing its performance on unseen data. Using techniques like early stopping helps mitigate overfitting by stopping training once the model performance on the validation set stops improving. More epochs usually result in higher training accuracy and potentially higher validation accuracy if overfitting is controlled.

Efficientnet B1

```
#input layer
inputs=tf.keras.layers.Input(shape=(240,240,3),name='input layer')
#adding in data augmentation as a layer itself
x=data augmentation(inputs)
#pass inputs to base model
x=base_model(x, training=False)
print(x.shape)
#We will use average pooling to reduce the size of the feature map.
x=tf.keras.layers.GlobalAveragePooling2D(name='global_average_pooling_layer')(x)
print(x.shape)
outputs=tf.keras.layers.Dense(1,activation='sigmoid',name='output_layer')(x)
model_0= tf.keras.Model(inputs,outputs)
#define early stopping callback.
early_stopping=EarlyStopping(monitor='val_accuracy',patience=3,restore_best_weights=True)
checkpoint = ModelCheckpoint('best_efficientnet_model.h5', monitor='val_accuracy', save_best_only=True)
model_0.compile(loss='binary_crossentropy',
                optimizer=tf.keras.optimizers.Adam(),
                metrics=['accuracy'])
history_model_0= model_0.fit(train_data,
                             epochs=50.
                             validation data=val data.
                             callbacks=[early stopping,checkpoint])
```





Accuracy –

Epochs = 5

Epochs = 50

```
========] - ETA: 0s - loss: 0.5833 - accuracy: 0.7031/usr/local/lib/python3.10/dist-packages/keras/src/e
saving api.save model(
Epoch 3/50
10/10 [====
Epoch 4/50
     10/10 [====
Epoch 5/50
       10/10 [====
Epoch 6/50
10/10 [====
Epoch 7/50
     10/10 [====
          ======] - 26s 1s/step - loss: 0.2921 - accuracy: 0.8906 - val_loss: 0.3606 - val_accuracy: 0.8250
10/10 [=
     ==========] - 26s 1s/step - loss: 0.2749 - accuracy: 0.8875 - val_loss: 0.3477 - val_accuracy: 0.8250
```

Inception V3

rescale=1./255: Normalizes the image pixel values to the range [0,1]

flow_from_directory: Generates batches of data with real-time data augmentation.

target_size: Resizes the input images.

class_mode='categorical': Specifies that the target labels are one-hot encoded.

Flatten: Converts the 3D output of the base model to 1D.

Dense(2, activation='softmax'): Adds a fully connected layer with 2 output units and a softmax activation function for binary classification.

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Training with 50 Epochs - The model has more time to learn and adjust its weights, leading to better performance. With more epochs, there's a risk of





overfitting, where the model learns the noise in the training data, reducing its performance on unseen data. Using techniques like early stopping helps mitigate overfitting by stopping training once the model performance on the validation set stops improving. More epochs usually result in higher training accuracy and potentially higher validation accuracy if overfitting is controlled.

```
# Define Early Stopping and Model Checkpoint callbacks
early_stopping = EarlyStopping(monitor='val_accuracy', patience=3, restore_best weights=True)
checkpoint = ModelCheckpoint('best_inception_model.h5', monitor='val_accuracy', save_best_only=True)
# Train the model with early stopping and model checkpoint callbacks
\label{linear_model} history = inception\_model.fit(train\_gen, validation\_data=val\_gen, epochs=epochs, callbacks=[early\_stopping, checkpoint])
model_save_path = '/content/best_inception_model.h5'
inception_model.save(model_save_path)
print(f"Model saved at: {model_save path}")
# Evaluate the model on the test set
test_loss, test_accuracy = inception_model.evaluate(test_gen)
print(f"Test accuracy: {test_accuracy}")
predictions = inception_model.predict(test_gen)
y_pred = np.argmax(predictions, axis=1)
y_true = test_gen.classes
# Print the classification report
print("Classification Report:")
print(classification_report(y_true, y_pred, target_names=test_gen.class_indices.keys()))
# Print the confusion matrix
print("Confusion Matrix:"
print(confusion_matrix(y_true, y_pred))
```

Accuracy –

Epochs = 5

Epochs = 50





Final Model Selection Justification:

Final Model	Reasoning
Resnet 50	As, Resnet50 and Vgg16 have a comparable train accuracy of 90%. But Resnet50 Validation accuracy is 87.5% and Vgg16 Validation accuracy is 85%