

ANMOL POPLI

M.S. IN COMPUTER SCIENCE · PG

University of California, San Diego

☎ (+91) 94-1264-8425 | ✉ apopli@eng.ucsd.edu

Fields of Interest

COMPUTER VISION, ROBOTICS, ARTIFICIAL INTELLIGENCE

Academic Details

2020 (Expected) **M.S. in Computer Science**

University of California, San Diego

2018

B.Tech. in Electrical Engineering

Indian Institute of Technology Roorkee

CGPA: 8.7/10

Research Projects and Internships

Human-Computer Interaction Robot (Mitacs GRI 2017)

University of Alberta, Edmonton

PROF. ANUP BASU, DEPARTMENT OF COMPUTING SCIENCE

May-July 2017

- The Mecanum robot's NVIDIA Jetson TX2 processor obtains visual feedback of its environment through web camera and transmits it to the server over WiFi via User Datagram Protocol.
- Face Detection using Viola Jones algorithm and Face Recognition using Local Binary Patterns Histograms algorithm are performed on the input video feed on the server. The server transmits User Interaction data to robot and the robot communicates with the user through audio interface employing Festival API for Text-to-Speech Synthesis and CMU Sphinx API for Speech Recognition.
- The motor control data is transmitted from server to the robot, which then transmits it to its Arduino microcontroller via USB, thereby enabling wireless motion control of the robot. [\[Certificate\]](#)

Diabetic Retinopathy Diagnosis using Deep Learning

EE Department, IIT Roorkee

PROF. G N PILLAI, DEPARTMENT OF ELECTRICAL ENGINEERING

January-April 2018

- Developed a data-driven method for automatic segmentation of retinal lesions based on their characteristics in fundus images to treat Diabetic Retinopathy. The trained model is based on U-Net architecture with weighted cross entropy loss. [\[Short Paper\]](#)
- Trained a 50 layer deep ResNet as classifier for Diabetic Retinopathy disease grading. [\[Short Paper\]](#)
- Trained a concatenation of a standard CNN and a U-Net model for localization of fovea and optic disc. [\[Short Paper\]](#)
- Submitted short papers to ISBI IEEE as a member of Team MedLabs. Won the 1st place in Fovea Localization with overall 3rd place in Localization sub-challenge of IDRiD Grand Challenge. Secured 5th rank in Segmentation of Hard Exudates. [\[Git Repo\]](#)
- Developed a Django webserver with basic UI to run demo of the trained models. [\[Git Repo\]](#) [\[Video\]](#)

Brain Tumor Segmentation using Deep Learning

EE Department, IIT Roorkee

PROF. G N PILLAI, DEPARTMENT OF ELECTRICAL ENGINEERING

May 2018 -

- Working on a U-Net inspired 3D ConvNet architecture for segmentation of tumor subregions from multimodal MRI images of the brain.

ABU ROBOCON Problem Statement (Member, Team Robocon IITR)

Models and Robotics Section, IIT Roorkee

FACULTY ADVISOR: PROF. ABINASH KUMAR SWAIN, IIT ROORKEE

2015-17

- Programmed Raspberry Pi for Frisbee trajectory tracking and pole detection, wherein the Pi's GPU acquires video input through Pi Camera. The video input is then processed parallelly on the CPU's 4 cores. [\[Git Repo\]](#) [\[Video\]](#)
- Developed a Computer Vision application on Android platform employing phone camera for Vision based navigation of a Robot on a track with varying configurations. Comprises algorithms to segment and follow white line, intelligently implement motion control based on the region of track, and to keep track of the white line in presence of background noise. [\[Report\]](#)
- Worked on Magnetometer based Navigation Algorithm for a four-wheel Omni drive using concepts of Machine Learning. [\[Report\]](#)
- Participated in ABU-ROBOCON INDIA - 2016. Secured 5th rank among 105 teams.

Analysis and Implementation of Fast Bilateral Filter (SRFP 2016)

Indian Institute of Science, Bangalore

DR. KUNAL NARAYAN CHAUDHURY, DEPARTMENT OF ELECTRICAL ENGINEERING

May-June 2016

- Analyzed and implemented fast algorithms of the Gaussian filter in MATLAB and C. Studied existing papers on the fast approximation of the edge-preserving Bilateral filter, focusing on a series of papers that approximate the Range kernel using trigonometric polynomials.
- Quantified the effect of certain parameters on approximation, and introduced several optimizations to develop an algorithm which performs fast filtering for a wide range of Spatial and Range kernels. Developed a parallelized C library of the algorithm, which can perform bilateral filtering in almost real time on images as large as 1 MP.
- The C library and an article has been published on IPOL Research Journal. [\[Publication & Code\]](#) [\[Report\]](#)

Satellite Image Classification

Techfest 2016-17 IIT Bombay

COMPETITION: RESEMBLANCE

October 2016

- Classification of four-channel Satellite imagery into 7 land cover classes employing Support Vector Machines. RBF kernel was used to linearize data in infinite dimensional space. Parameters gamma and C were tuned by performing 5-fold cross-validation on training data. Performance measures were computed. [\[Git Repo\]](#) [\[Report\]](#)

Swarm Robotics

Models and Robotics Section, IIT Roorkee

SRISHTI 2017

2016-17

- The server receives continuous video feed of the arena through webcam and applies Vision algorithms to detect configurations of the 4 robots, which it then transmits to all robots over WiFi so that each robot is aware of all robots' positions and orientations.
- The desired configuration of robots is transmitted from an Android app to the server, which further transmits it to each of the robots.
- Without the intervention of the server, the robots process all information - comprising current and desired configuration - and optimize their motion in such a way that the desired configuration is finally achieved. [\[Git Repo\]](#)

Quadcopter

Models and Robotics Section, IIT Roorkee

SRISHTI 2015

February-March 2015

- Propellers were actuated using BLDC motors, the speed of which was controlled by Electronic Speed Controllers. PID control algorithm was implemented on Arduino Mega microcontroller to control the orientation of quadcopter using feedback from IMU sensor.

Academic Achievements

2018	Ranked 3rd on Leaderboard	IDRiD Grand Challenge
2017	Selected as intern	Mitacs Globalink Research Internship
2016	Selected as Intern	Science Academies' Summer Research Fellowship Programme
2014	All India Rank 1672	JEE-Advanced
2013	All India Rank 1111	Kishore Vaigyanik Protsahan Yojana (KVPY)
2013	All India Rank 30	Technothon - International School Championship

Technical Skills

Languages C, C++, Python, Java, PHP, Javascript, Unix Shell

Tools TensorFlow, Theano, MATLAB, Simulink, OpenMP, OpenCV, Android Studio, CMU Sphinx, Git, CMake, Eagle CAD, \LaTeX

Courses Taken

At IIT Roorkee

Programming in C++ (including OOP), Mathematics-I (Matrix Algebra, Calculus), Network Theory, Mathematical Methods (ODEs, PDEs, Transform Techniques), Digital Electronics and Circuits, Control Systems, Microprocessors and Peripheral Devices, Advanced Control Systems, Single Chip Microcontroller and its Applications, Robotics and Control, Optimization Techniques, Data Mining for Business Intelligence, Graph Theory, Intelligent Control Techniques, Advanced Numerical Analysis, Data Structures, Machine Learning.

Others

Convolutional Neural Networks for Visual Recognition, Machine Learning - Online Courses from Stanford University

Fundamentals of Digital Image and Video Processing - Online Course from Northwestern University

Signals & Systems, Circuits & Electronics - Online Courses from Massachusetts Institute of Technology

Extracurricular Activities

Srishti | Annual Techno-Hobby Exhibition of IIT Roorkee

March 2017, March 2016, March 2015

- Mentored Freshman Students for the projects 'Light Painting Robot' and 'Virtual Air Hockey' in 2016 and 2017 respectively.
- Won First Prize for Quadcopter in 2015.

Cognizance | Annual Technical Festival of IIT Roorkee

March 2018, March 2017, March 2015

- 2018 - Served as Secretary of Departmental Organizing Team.
- 2017 - Worked as Coordinator at the Paper Presentation event IDEAZ.
- 2015 - Won First Prize in Breach Wars (robotics competition).

IIT HEARTBEAT | Inter-IIT Magazine

2014-16

- Worked as Web Developer for the magazine.

National Cadet Corps (NCC) | Cadet during Session 2014-15

2014-15

- Participated in the Guard of Honour on Republic Day 2015.

Research Publications

- PRAVIN NAIR, ANMOL POPLI, AND KUNAL N. CHAUDHURY, *A Fast Approximation of the Bilateral Filter using the Discrete Fourier Transform*, Image Processing On Line, 7 (2017), pp. 115–130. <https://doi.org/10.5201/ipol.2017.184>