FEM Poisson's equation 1D

Monday, December 2, 2024 1:42 PM



$$\nabla \cdot (P \nabla Y) = t \xrightarrow{y_1 = 0} \frac{1}{y_2} \left[P(k) \frac{1}{2k} \right] = t(k)$$

4 t(x)=- 8/20.

P(x)= En ELECTROSIATIC

Formulation [STRONG FORMULATION]

"Find y(x) much that Hin=> in true for cremy

XE[a,b]"

$$\varphi(a) = \varphi a$$

Diriclet BC . X = a prescribing volve of 4 in a

 $\frac{d\phi}{dx}|_{x} = \varphi_{b}$ Neumann BC, $x = \frac{d\phi}{dx}$ in b

K - - M-1 M

DISCRETIZATION

· introduce n- points between a and b m-NODES > m-1 intervols

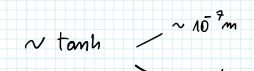
ELEMENTS

X1 X2 --- XK -- XM-1 XM

Shouthand

if und is uniform :
$$\Delta = \frac{L}{M-1} = \frac{b-a}{M-1}$$

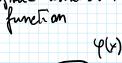
$$\Delta = \frac{L}{M-1} = \frac{b-a}{M-1}$$

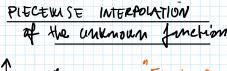


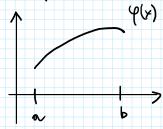
INTERPOLATION

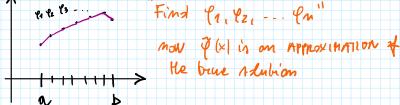
$$\varphi(x) \longrightarrow \tilde{\varphi}(x)$$

original unknown

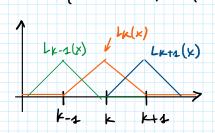








Q(x)= 91 L1(x) + 92 L2(x) + -... + 9x Lx(x) + -..., 9m-2 Lm-2(x) + 9m Lm(x) HAT FUNCTIONS as interpolant functions [SHAPE FUNCTIONS]



WELLHTED PEPIDUALS APPROACH

if exact solution
$$\rightarrow \left[\frac{d}{dx}\left[p(x)\right]dy/_{x}\right]-t(x)=0$$

we have mitched from $f(x) \Rightarrow \widetilde{\varphi}(x)$

x(x) RESIDUAL ⇒ CAMPOT SE O YX

W. R. opprach: PEQUIRE that the WEIGHTED RESIDUAL is ZERO over

$$\int_{\mathbb{R}} w(x) \mathcal{H}(x) \, dx = 0$$

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$$(ACESTANDRO'S CHOICE)$$

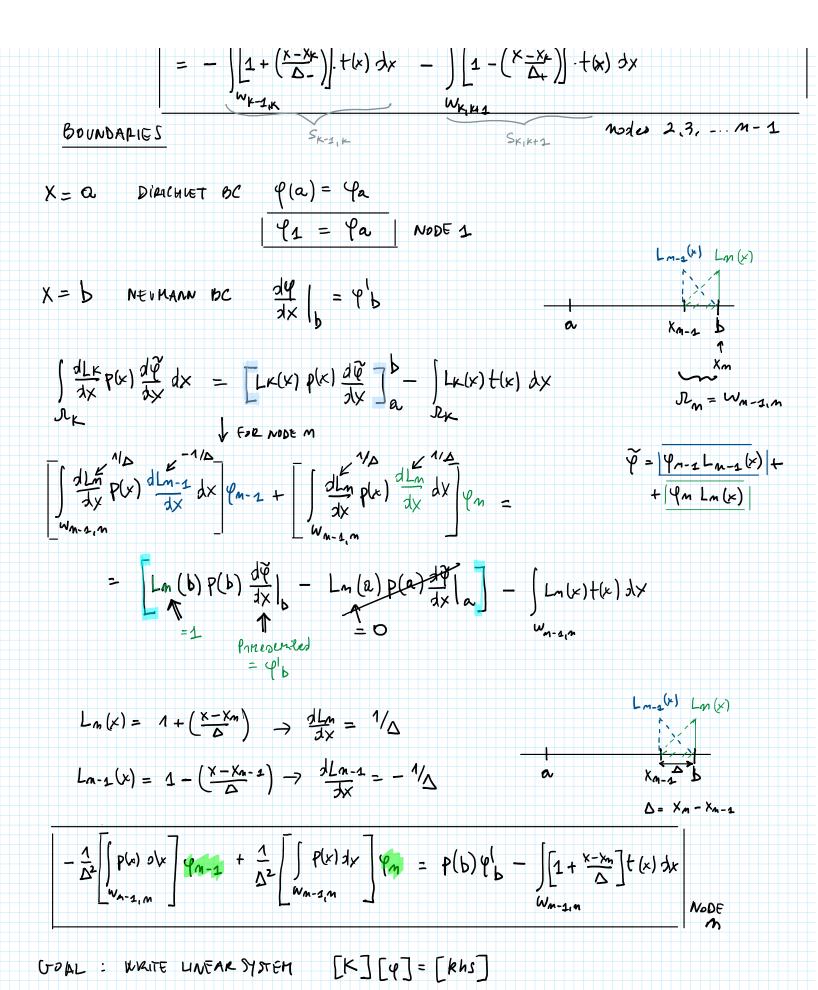
$$(X) \Rightarrow \{(X-X_{k})$$

 $\int_{0}^{b} w(x) \frac{dx}{dx} \left[p(x) \frac{d\tilde{y}}{dx} \right] dx = \int_{0}^{b} w(x) t(x) dx$ $\int f(x)g'(x) dx = \left[f(x)g(x) \right]^b - \int f'(x)g(x) dx \qquad \text{integration by}$

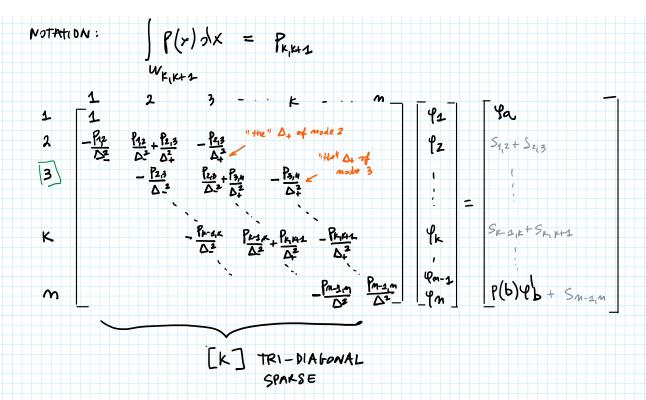
$$\left[w(x) p(x) \frac{d\tilde{y}}{dx}\right]_{a}^{b} - \left(\frac{dw}{dx} p(x) \frac{d\tilde{y}}{dx} dx\right) = \int w(x) t(x) dx$$

No SECOND DEPINATIVES

$$\frac{d \ln p(x)}{d x} \frac{d x}{d x} \frac{d x}{d x} = \frac{d \ln p(x)}{d x} \frac{d \ln p(x)}{d x} \frac{d \ln p(x)}{d x} = \frac{d \ln p(x)}{d x} \frac{d \ln p(x)}{d x} = \frac{d \ln p(x)}{d x} \frac{d \ln p(x)}{d x} = \frac{d \ln p(x)}{d x} \frac{d \ln p(x)}{d x} = \frac{d \ln p(x)}{d x} \frac{d \ln p(x)}{d x} \frac{d \ln p(x)}{d x} = \frac{d \ln p(x)}{d x} \frac{d \ln p(x)}{d x} \frac{d \ln p(x)}{d x} = \frac{d \ln p(x)}{d x} \frac{d \ln p(x)}{d x} \frac{d \ln p(x)}{d x} \frac{d \ln p(x)}{d x} = \frac{d \ln p(x)}{d x} \frac{d \ln p(x)}{d$$

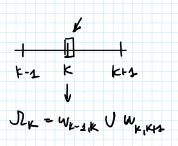


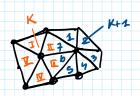
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FEM. (Piccurise Linear Shape functions) $\Rightarrow \theta(\Delta^2)$

S. for ... ASSEMBLY reduce [K] from the point of view of NODES
6000 for 1D, less practical for 2D, 3D
TRIANGLULAR GRIDS





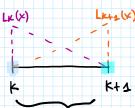
HOW mainy ELEMENTS in

Ik: 5 elements = # of man-2000

Ikus: 7 elements in [k]
in nows k kers is alforent

ELEMENT POINT of VIEW

ishate contributions of each element to [K] and assemble by cycling over elements



WKIKHS

Expresion NODE K.

$$\left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k-1}}{dx} dx\right] \varphi_{k-1} + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k}}{dx} dx\right] \varphi_{k} + \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k+1}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p(x) \frac{d l_{k}}{dx} dx\right] \varphi_{k+1} = \dots + \left[\int \frac{d l_{k}}{dx} p($$

Expression made K+1 (Kel [h,1])

$$\begin{bmatrix}
\int \frac{dl_{k+1}}{dx} p(x) \frac{dl_{k}}{dx} dx \\
V_{k} + \begin{bmatrix}
\int \frac{dl_{k+1}}{dx} p(x) \frac{dl_{k+1}}{dx} dx \\
W_{k,k+1} \end{bmatrix} q_{k} + \frac{dl_{k+1}}{dx} p(x) \frac{dl_{k+1}}{dx} dx
\end{bmatrix} q_{k+1} + \dots \\
+ \dots \begin{bmatrix}
\int \frac{dl_{k+1}}{dx} p(x) \frac{dl_{k+1}}{dx} dx \\
W_{k+1,k+2} \end{bmatrix} q_{k+1} + \frac{dl_{k+1}}{dx} p(x) \frac{dl_{k+2}}{dx} dx
\end{bmatrix} q_{k+2} = \dots \\
- \int l_{k+1}(x) l(x) dx - \int l_{k+1}(x) l(x) dx \\
W_{k+1,k+2} - \dots \\
W_{k+2,k+2} - \dots \\
W_$$

$$K_{l} = \begin{bmatrix} \frac{1}{3x} & \frac{1}{3x} &$$

