

## Experiments in Matlab with numerical integration

$$\int_a^b f(x) dx = \int_{-1}^1 f(m\tau + q) \frac{b-a}{2} d\tau$$

$$\approx \sum_{k=1}^m w_k \frac{b-a}{2} f\left(\frac{b-a}{2}\tau_k + \frac{a+b}{2}\right)$$

↑                      ↑                      ↑  
 $m$                      $m$                      $q$

$$m = 1 \rightarrow m = 2m - 1 = \textcircled{1}$$

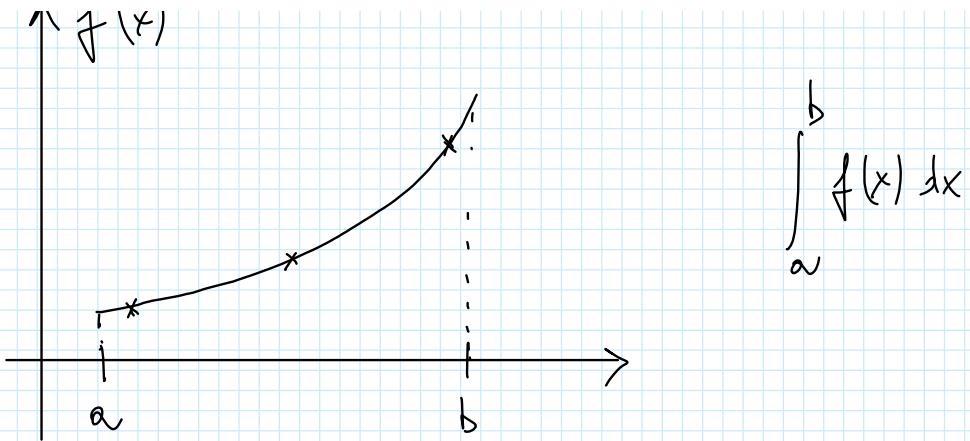
Quadrature Rule for  $m=2$

$$\begin{cases} x_1 = \pm \sqrt{1/3} \\ x_2 = 0 \\ w_1 = w_2 = 1 \end{cases}$$

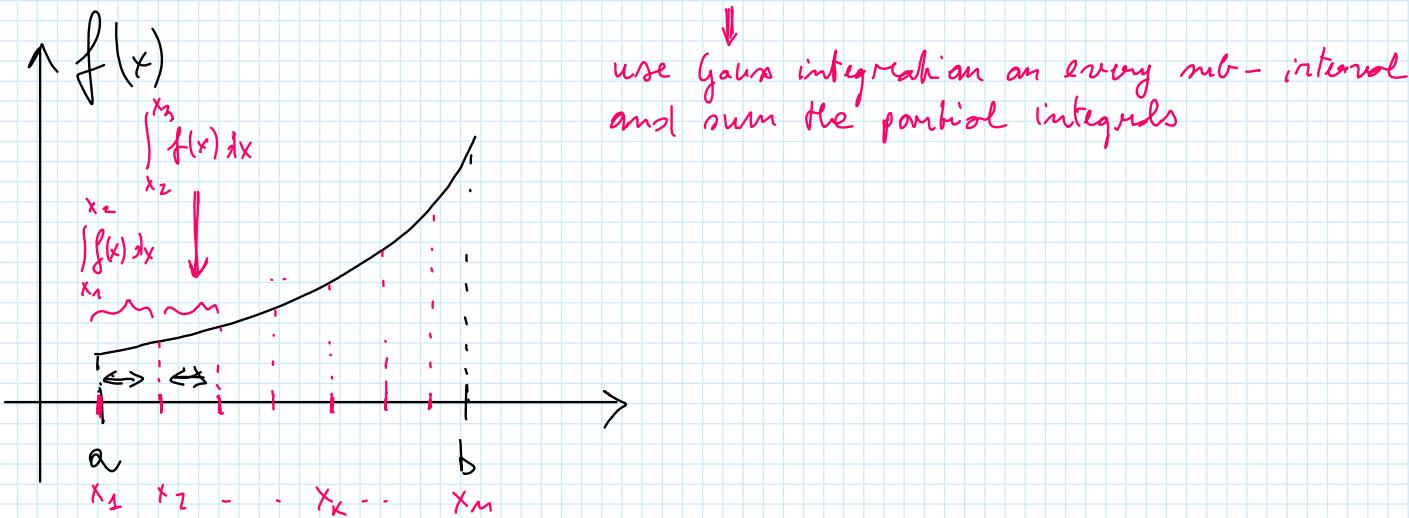
 $n = 3$ 

$$\begin{cases} w_1 = 5/9 \\ w_2 = 8/9 \\ w_3 = 5/9 \end{cases} \quad \begin{cases} x_1 = -\sqrt{3/5} \\ x_2 = 0 \\ x_3 = \sqrt{3/5} \end{cases}$$

$$\uparrow f(x)$$



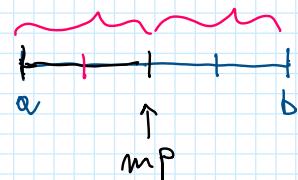
ADAPTIVE INTEGRATION: subdivide interval  $[a, b]$  into multiple sub-intervals



PSEUDO CODE

integrand    # of gauss points    tolerance for integration  
 $\downarrow$                                   ↓                                      ↓  
 $[int] = INT\_ADT (f, a, b, m, tol)$

$$I_1 = \int_a^b f(x) dx$$



$$I_2 = \int_a^{mp} f(x) dx + \int_{mp}^b f(x) dx$$

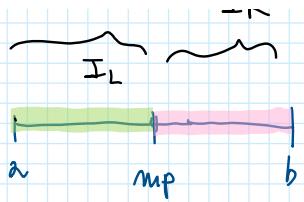
error =  $| I_1 - I_2 |$  ← if just one interval is enough,  
 I<sub>1</sub> very close to I<sub>2</sub>

if error < tolerance  $< 10^{-6}$

int = I<sub>2</sub> ← routine is over



$$\text{int} = I_2 \quad \leftarrow \text{routine is over}$$



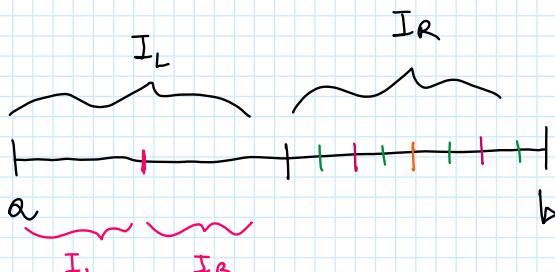
else

$$\rightarrow \rightarrow I_L = \text{INT\_ADT}(f, a, mp, m, tol)$$

$$\rightarrow \rightarrow I_R = \text{INT\_ADT}(f, mp, b, m, tol)$$

$$\text{int} = I_L + I_R$$

end



$$I_L = \int_a^{mp} f(x) dx$$

$$I_R = \int_{mp}^b f(x) dx$$

$$I_2 = \int_0^1 f(x) dx$$

$$L = \pi \quad R = 2\sqrt{3}\pi$$

$$x = 0, 0.25, 0.5, 1$$

$$I_2 = \int_0^1 f(x) dx = \int_0^{0.5} f(x) dx + \int_{0.5}^1 f(x) dx$$

$$\text{error} > tol$$

$$I_L' = \int_0^{0.25} f(x) dx = I_2'$$

$$I_2' = \int_0^{0.25} f(x) dx + \int_{0.25}^{0.5} f(x) dx$$

$$\text{error} > tol ?$$

$$I_2'' = \int_0^{0.25} f(x) dx = I_2''' = \int_0^{0.125} f(x) dx + \int_{0.125}^{0.25} f(x) dx$$

$$\text{error} < tol \Rightarrow OK$$

$$\text{int}^2 = I_2 = \pi$$