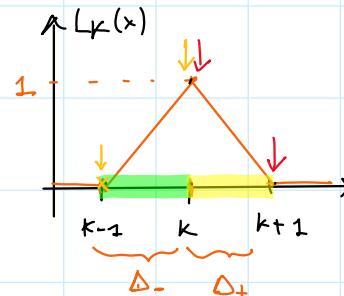


L 16 an element $\tilde{f}(x)$ depends on only TWO DATA points and
 " " that functions

$$\text{if } x \in W_{k,k+1} \rightarrow \tilde{f}(x) = f_k L_k(x) + f_{k+1} L_{k+1}(x)$$

Definition
of $L_k(x)$

$$L_k(x) = \begin{cases} 1 + \frac{x - x_k}{\Delta_-}, & x \in W_{k-1,k} \\ 1 - \frac{x - x_k}{\Delta_+}, & x \in W_{k,k+1} \\ 0, & x \notin \underbrace{W_{k-1,k} \cup W_{k,k+1}}_{S_k} \end{cases}$$



$$\text{if } x = x_{k-1} \quad L_k(x) = 1 + \frac{(x_{k-1} - x_k)}{\Delta_-} = 1 - 1 = 0$$

$x = x_{k-1}$ $x_k - x_{k-1}$

$$\text{if } x = x_k \quad L_k(x) = 1 + \frac{x_k - x_k}{\Delta_-} = 1$$

$x = x_k$

$$\text{if } x = x_k \quad L_k(x) = 1 - \frac{x_k - x_k}{\Delta_+} = 1$$

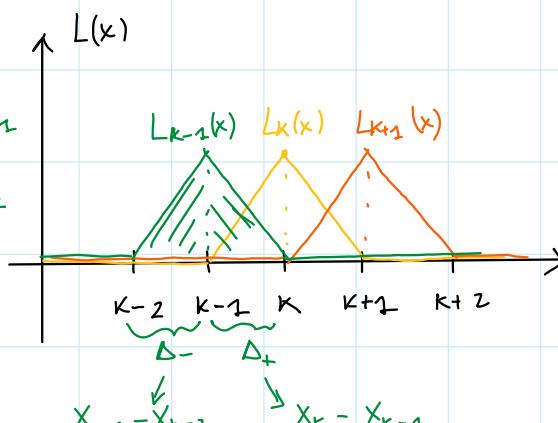
$x = x_k$

$$\text{if } x = x_{k+1} \quad L_k(x) = 1 - \frac{x_{k+1} - x_k}{\Delta_+} = 0$$

$x = x_{k+1}$

Example:

$$L_{k-1}(x) = \begin{cases} 1 + \frac{x - x_{k-1}}{\Delta_-}, & x \in W_{k-2,k-1} \\ 1 - \frac{x - x_{k-1}}{\Delta_+}, & x \in W_{k-1,k} \\ 0, & x \notin S_{k-1} \end{cases}$$



Boundary nodes

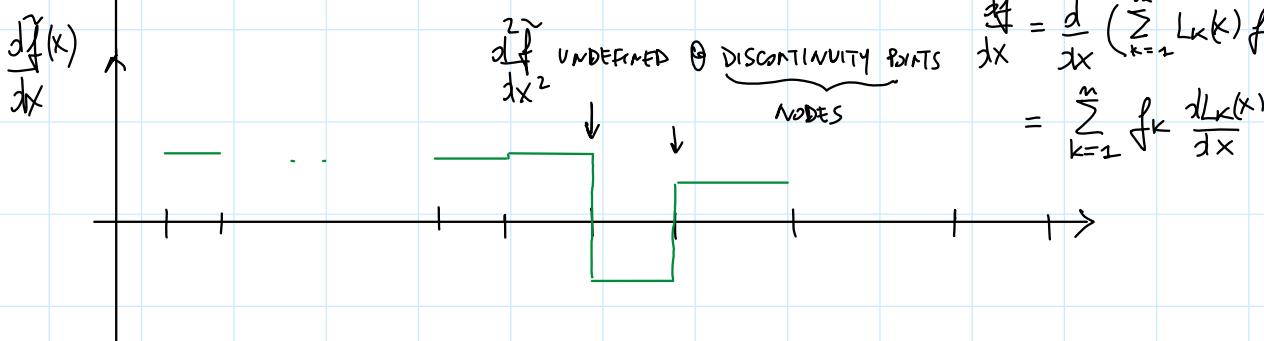
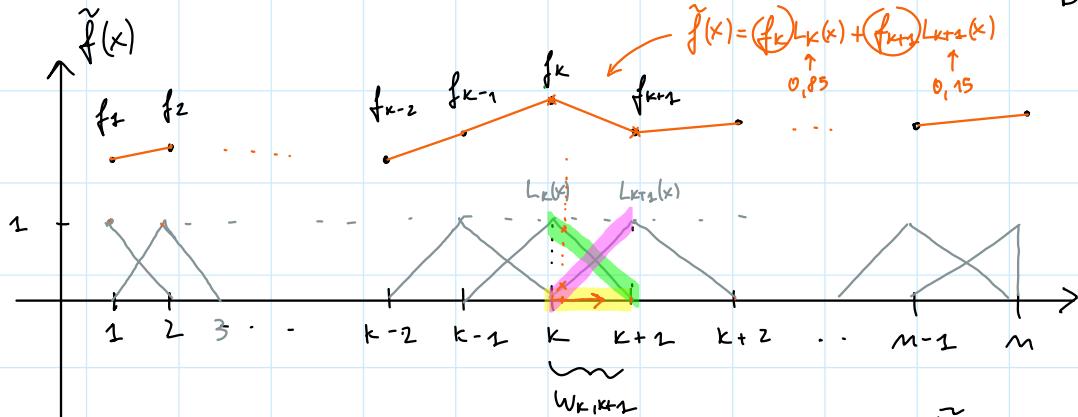
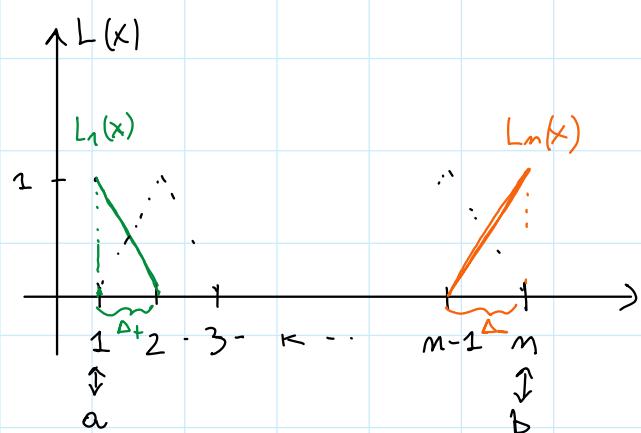
$$r_1 = x - x_1, x \in W_{1,2}$$



Boundary nodes

$$L_1(x) = \begin{cases} 1 - \frac{x-x_1}{\Delta t}, & x \in W_{1,2} \\ 0, & x \notin \Omega_1 \equiv W_{1,2} \end{cases}$$

$$L_m(x) = \begin{cases} 1 + \frac{x-x_m}{\Delta t}, & x \in W_{m-1,m} \\ 0, & x \notin \Omega_m \equiv W_{m-1,m} \end{cases}$$



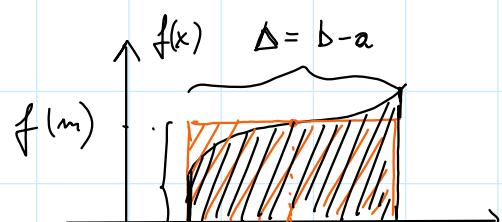
EXAMPLE: $L_k(x) \begin{cases} 1 + \frac{x-x_k}{\Delta t}, & x \in W_{k-1,k} \\ 1 - \frac{x-x_k}{\Delta t}, & x \in W_{k,k+1} \\ 0, & \text{otherwise} \end{cases} \Rightarrow \frac{dL_k}{dx} = \begin{cases} 1/\Delta t, & x \in W_{k-1,k} \\ -1/\Delta t, & x \in W_{k,k+1} \\ 0, & \text{otherwise} \end{cases}$

Numerical integration (1D)

goal: $\int_a^b f(x) dx$ numerically

RECTANGLES METHOD (midpoint)

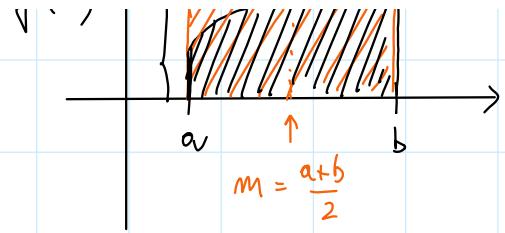
$$\int_a^b f(x) dx = f(m) \Delta + O(\Delta^3)$$



$$\int_a^b f(x) dx = f(m) \Delta + O(\Delta^3)$$

$$\approx f(m) \Delta$$

third-order accuracy



⚠ For FINITE differences formulas

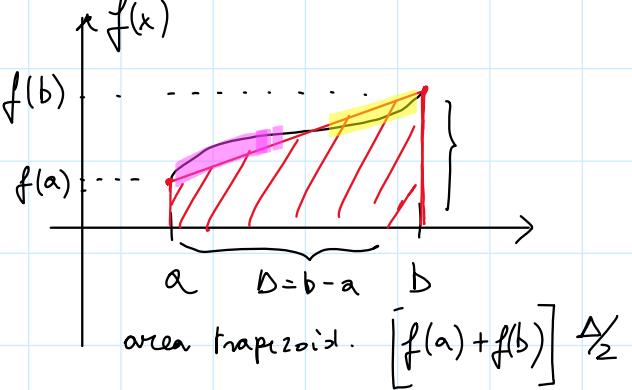
$O(\Delta x^h)$ → when Δx is halved, error is divided by $2^h \Rightarrow$ true for integration

→ able to solve without error a problem whose solution is a polynomial of order $h \Rightarrow$ NOT true for integration
no Taylor series

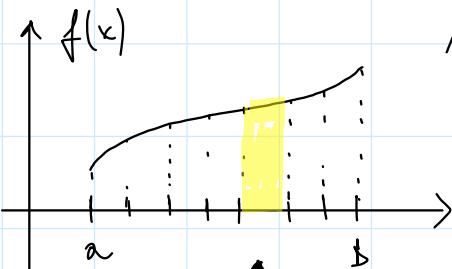
TRAPEZOIDAL RULE

$$\int_a^b f(x) dx = \frac{1}{2} [f(a) + f(b)] \Delta + O(\Delta^3)$$

$$\approx \frac{1}{2} [f(a) + f(b)] \Delta$$



on multiple sub-domains



$m-1$ elements

$$\Delta = \frac{b-a}{m-1} \Rightarrow \Delta \text{ is smaller}$$

+ sub-interval: apply rectangles trapezoidal

[sum of m -elements of LOCAL error GLOBAL ERROR $O(\Delta^3)$]

RECT: $\int_a^b f(x) dx = \sum_{k=1}^{m-1} f(m_k) \Delta + O(\Delta^2)$

midpoint of element k

GLOBAL error has increased but SMALLER Δ

if $m_{\text{ints}} = 1 \quad \Delta = b - a$

$m_{\text{ints}} = m \quad \Delta = \frac{b-a}{m-1}$

TRAPEZ: $\int_a^b f(x) dx = \sum_{k=1}^{m-1} \frac{1}{2} [f(x_k) + f(x_{k+1})] \Delta + O(\Delta^2)$

GAUSS integration (GAUSS QUADRATURE)

IDEA: Compute a numerical integral as a WEIGHTED sum of $f(x)$ evaluated at a given number of points

$$\int_{-1}^1 f(x) \approx \sum_{k=1}^m w_k f(x_k)$$

WEIGHTS GAUSS POINTS

order of accuracy: $2m - 1$

example: if $m = 2 \Rightarrow m = 2^{m-1} = 3 \Rightarrow$ if $m=2 \rightarrow$ integrate a polynomial of order 3 without $\text{ERR} > R$

Derivation of QUADRATURE RULES (values of w_k and x_k to obtain a certain degree of accuracy)

$$m = 1$$

$$\begin{aligned} &\downarrow \\ m &= 2m-1 \\ &= 1 \end{aligned}$$

Gauss formula
integrate with no error \rightarrow polynomial order 0

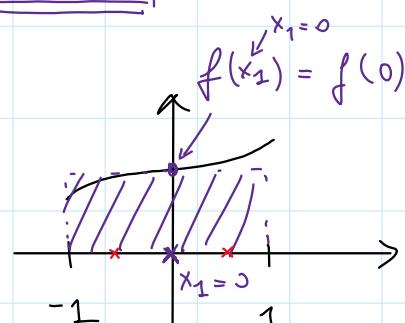
Order 0: $f_1(x) = 1$ example $\int_{-1}^1 f_1(x) dx = [x]_{-1}^1 = 1 - (-1) = 2$

$$\Rightarrow w_1 \cdot f_1(x_1) = w_1 \cdot 1 = 2 \quad \rightarrow \text{FULFILLED to integrate exactly polynomial functions order 0}$$

Order 1: $f_2(x) = x$ $\int_{-1}^1 f_2(x) dx = \left[\frac{x^2}{2} \right]_{-1}^1 = 0$

$$\Rightarrow w_1 \cdot f_2(x_1) = w_1 \cdot x_1 = 0$$

$$\left. \begin{array}{l} \text{order 0 poly} \\ w_1 \cdot 1 = 2 \Rightarrow w_1 = 2 \end{array} \right. \quad \left. \begin{array}{l} \text{order 1 poly} \\ w_1 \cdot x_1 = 0 \Rightarrow x_1 = 0 \end{array} \right.$$



order 1
poly m

$$w_1 \cdot x_1 = 0 \Rightarrow (x_1 = 0)$$

$$\int_{-1}^1 f(x) dx = 2 f(0)$$

weight = 2 gours point

QUADRATURE RULE for n=1 = rectangles method



$M = 2$. $m = h - 1 = 3 \rightarrow$ REQUIRE no error
for polynomials order

$$\int_{-1}^1 f(x) dx = w_1 f(x_1) + w_2 f(x_2)$$

h degrees of freedom



order 0 $f_0(x) = 1 \rightarrow \int_{-1}^1 f_0(x) dx = 2 \Rightarrow w_1 \underbrace{f_0(x_1)}_1 + w_2 \underbrace{f_0(x_2)}_1 = 2$

$$\Rightarrow \boxed{w_1 + w_2 = 2}$$

order 1. $f_1(x) = x \rightarrow \int_{-1}^1 f_1(x) dx = 0 \Rightarrow w_1 \underbrace{f_1(x_1)}_{=x_1} + w_2 \underbrace{f_1(x_2)}_{=x_2} = 0$

$$\Rightarrow \boxed{w_1 x_1 + w_2 x_2 = 0}$$

order 2. $f_2(x) = x^2 \rightarrow \int_{-1}^1 f_2(x) dx = \frac{2}{3} \Rightarrow \boxed{w_1 x_1^2 + w_2 x_2^2 = \frac{2}{3}}$

$$\uparrow \left[\frac{x^3}{3} \right]_{-1}^1 = \frac{1}{3} - \left(-\frac{1}{3} \right) = \frac{2}{3}$$

order 3 : $f_3(x) = x^3 \rightarrow \int_{-1}^1 f_3(x) dx = 0 \Rightarrow \boxed{w_1 x_1^3 + w_2 x_2^3 = 0}$

Find w_1, x_1, w_2, x_2

$$\boxed{w_1 + w_2 = 2 \Rightarrow w_1 = w_2 = 1}$$

nonlinear $w_1 x_1 + w_2 x_2 = 0 \Rightarrow 1 \cdot x_1 + 1 \cdot x_2 = 0 \Rightarrow x_1 = -x_2$

nonlinear system

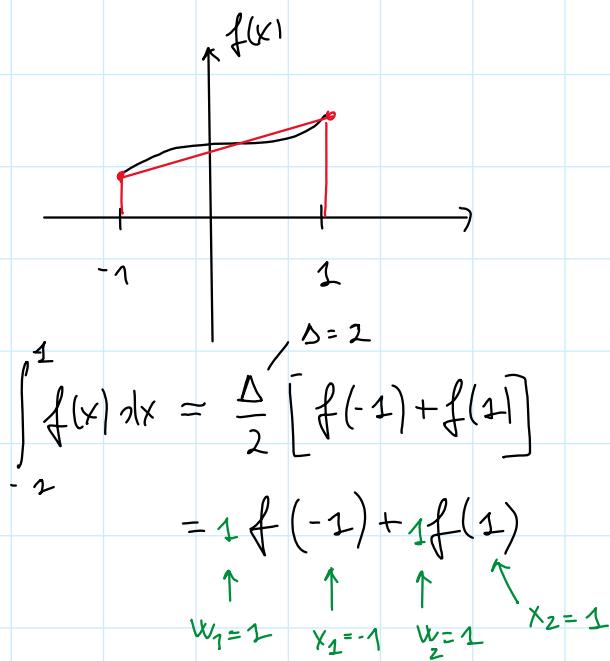
$$\left. \begin{array}{l} w_1 + w_2 = 2 \Rightarrow w_1 = w_2 = 1 \\ w_1 x_1 + w_2 x_2 = 0 \Rightarrow x_1 + x_2 = 0 \Rightarrow x_1 = -x_2 \\ w_1 x_1^2 + w_2 x_2^2 = y_3 \\ w_1 x_1^3 + w_2 x_2^3 = 0 \end{array} \right\}$$

$1 \cdot x_1^3 + 1 \cdot (-x_1)^3 = 0 \Rightarrow$ SATISFIED by every value of x_1

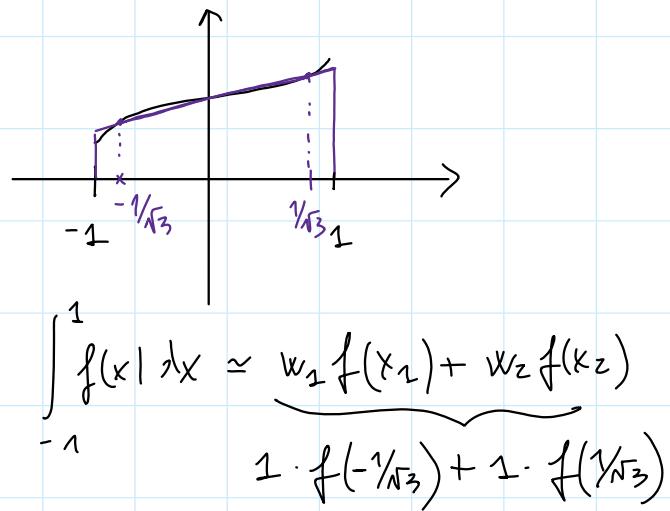
$$x_1^2 + x_2^2 = y_3 \Rightarrow 2x_1^2 = y_3 \Rightarrow \boxed{x_1 = \pm \frac{1}{\sqrt{3}}, x_2 = \pm \frac{1}{\sqrt{3}}, w_1 = w_2 = 1}$$

QUADRATURE RULE
for $m=2$

TRAP. RULE



GAUSS ($m=2$)



$$m = 3 \quad m = 2m - 1 = 5$$

$$\int_{-2}^1 f(x) dx = w_1 f(x_1) + w_2 f(x_2) + w_3 f(x_3)$$

$$\left\{ \begin{array}{l} w_1 = 5/9 \\ w_2 = 8/9 \end{array} \right. \quad \left\{ \begin{array}{l} x_1 = -\sqrt{3/5} \\ x_2 = 0 \end{array} \right.$$

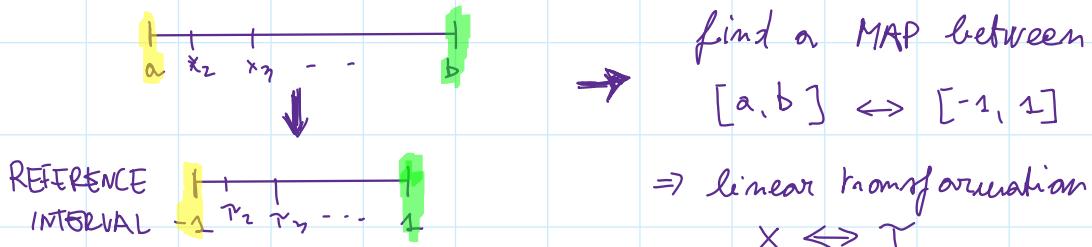
$$\left\{ \begin{array}{l} w_2 = 8/9 \\ w_3 = 5/9 \end{array} \right. \quad \left\{ \begin{array}{l} x_2 = 0 \\ x_3 = \sqrt{3/5} \end{array} \right.$$

GAUSS QUADRATURE for arbitrary intervals

$$\int_a^b f(x) dx = \int_{-1}^1 f(\tau) d\tau \approx \sum_{k=1}^m w_k f(\tau_k)$$

$\downarrow \qquad \qquad \downarrow$

$x \in [a, b] \qquad \qquad \tau \in [-1, 1]$



requirements f and m and q

$$\left\{ \begin{array}{l} x = m\tau + q \\ a = m(-1) + q \\ b = m(1) + q \end{array} \right. \quad \begin{array}{l} \text{(linearity)} \\ \Rightarrow b - a = m + q - (-m + q) \\ \Rightarrow b - a = 2m \\ \Rightarrow m = \boxed{\frac{b-a}{2}} \end{array}$$

to find q :

$$a = -\frac{b-a}{2} + q \Rightarrow q = a + \frac{b-a}{2} = \frac{2a+b-a}{2} = \boxed{\frac{a+b}{2} = q}$$

Linear transformation:

$$x = m\tau + q = \frac{b-a}{2}\tau + \frac{a+b}{2}$$

\uparrow
 $[a, b]$

differential . $\frac{dx}{d\tau} = m \Rightarrow \boxed{dx = m d\tau = \frac{b-a}{2} d\tau}$

$$\text{differential} \quad . \quad \frac{dx}{dt} = m \Rightarrow \boxed{dx = m dt = \frac{b-a}{2} dt}$$

$$\int_a^b f(x) dx = \int_{-1}^1 f(m\tau + q) \underbrace{\frac{b-a}{2}}_{m} d\tau = \frac{b-a}{2} \int_{-1}^1 f\left(\frac{b-a}{2}\tau + \frac{a+b}{2}\right) d\tau$$

↓

$$\approx \sum_{k=1}^n w_k \frac{b-a}{2} f\left(\frac{b-a}{2}\tau_k + \frac{a+b}{2}\right)$$

if $m = 1 \quad w_1 = 2, \quad x_k \rightarrow \tau_k = 0$

$$\int_a^b f(x) dx \approx 2 \cdot \frac{b-a}{2} f\left(\frac{b-a}{2} \cdot 0 + \frac{a+b}{2}\right)$$