

Mathematisch-Naturwissenschaftliche Fakultät

Computergrafik

Masters Thesis

Investigations on Backbone Computation

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Bearbeitungszeitraum: April 1st-October 30th

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Jonas Bollgrün (Matrikelnummer 3353424), 5. August 2019

Abstract

Template

Acknowledgments

If you have someone to Acknowledge;)

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1 Introduction

introduction wofür brauche ich backbones wer hat sich damit beschäftigt welche paper waren relevant

2 Disambiguation

This thesis is an investigation on the calculation of backbones for boolean formulas in conjunctive normal form (or CNF in short). A CNF formula F is a conjunction of a set of clauses C(F), meaning that all of these clauses have to be satisfied (or fulfilled) to satisfy the formula. A clause c in turn is a disjunction of a set of literals, meaning at least one of said literals must be fulfilled. A literal l can be defined as the occurence of a boolean variable v which may or not be negated and to fulfill such a literal, it's variable must be assigned \bot for negated literals and \top for those literals without negation. The same variable can occur in multiple clauses of the same formula but must have the same assignment in all occurences, either false (\bot) or true (\top). A complete assignment of all variables of F (written as Var(F)) that leads to the formula being fulfilled is called a model. A formula for which no model can be found is called unsatisfiable.

The exact terminology can differ depending on the paper and project that you read. A formula can be called a problem and the assignment of a variable can be called it's phase. Clauses can also be called constraints and sometimes sentences. A synonym for a formula, clause or literal being fulfilled is it being satisfied. Models can also be called solutions of formulas

The backbone is a problem specific set of literals that contains all literals that occur in every model of that problem. We can also say that a variable is not part of the backbone, if neither it's positive or it's negative assignment is in the backbone. If we have an unsatisfiable formula, it's backbone can be considered undefinable, which is why this thesis concerns itself only with satisfiable CNF formulas. (TODO ref unsat backbone, aber keine einigkeit drüber)

Implikante/Primimplikante notwendig?

3 Base Algorithms

The algorithms that I investigated for this thesis can be grouped very broadly into two approaches, which I will describe in the following two sections.

3.1 Enumeration algorithms

A simple definition of the backbone is that it is the intersection of all models of it's formula. If a literal is not part of the backbone, there must exist a model that contains the negation of that literal. Therefore if we had a way to iterate over every single model of the formula and, starting with the set of both literals for every variable and removing every literal from that set that was missing in one of these models, that set would end up being the backbone of the formula. [MSJL10] as well as [JLMS15] list an algorithm that does exactly this.

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Algorithm 1: Enumeration-based backbone computation
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Input: Satisfiable formula F

Output: Backbone of F, v_r

v_r \leftarrow \{x | x \in Var(F)\} \cup \{\neg x | x \in Var(F)\}

while v_r \neq \emptyset do

(outc, v) \leftarrow SAT(F)

if outc = \bot then
\_ return v_r

v_r \leftarrow v_r \cap v

\omega_B \leftarrow \bigvee_{l \in v} \neg l
F \leftarrow F \cup \omega_B

assert(v_r = \emptyset)

return v_r
```

Here, found models are prevented from being found again by adding a blocking clause of said model and the algorithm terminates once all models are prohibited and the formula became unsatisfiable through this.

Clearly, calculating every single model of a formula leaves room for optimization. Most models of a common boolean formula differ by small, independent differences that can just as well occur in other models. Therefore the intersection of only a

Kapitel 3. Base Algorithms

handful of models can suffice to result in the backbone, as long as these models are chosen to be as different as possible. This was achieved in [JLMS15] as is described in algorithm 2.

Algorithm 2: Iterative algorithm with complement of backbone estimate

```
Input: Satisfiable formula F

Output: Backbone of F, v_r

(outc, v_r) \leftarrow SAT(F)

while v_r \neq \emptyset do

bc \leftarrow \bigvee_{l \in v_r} \neg l

(outc, v) \leftarrow SAT(F \cup \{bc\})

if outc = \bot then

return v_r

v_r \leftarrow v_r \cap v
```

It generates an upper bound v_r of the backbone by intersecting found models and inhibits this upper bound instead of individual models. This blocking clause is much more powerful, because it enforces not only that a new model is found, but also that this new model will reduce the upper bound estimation of the backbone in each iteration.

This is because what remains after the intersection of a handful of models, are the assignments that were the same in all these models and from that we make a blocking clause that prohibits the next model to contain that particular combination of assignments, eliminating

Eventually v_r will be reduced to the backbone. This can be easily recognized, because the blocking clause of the backbone or any of it's subsets makes the formula unsatisfiable, except in the case that the formulas backbone would be empty.

Note that it is not particularly important whether the blocking clauses remain in F or get replaced by the next blocking clause, because the new blocking clause bc_{i+1} always subsumes the previous one bc_i , meaning that every solution that is prohibited by bc_{i+1} is also prohibited by bc_i and $F \cup \{bc_i, bc_{i+1}\}$ is equivalent to $F \cup \{bc_{i+1}\}$ concerning the set of models.

This algorithm is implemented in the Sat4J library under the designation IBB.

TODO hier noch iwie prefbones0 einordnen

3.2 Iterative algorithms

Alternatively, you can define the backbone as all literals that occur with the same assignment in all models of it's problem, which implies that enforcing that variable to it's negation should make the formula unsatisfiable. This definition already leads to a simple algorithm that can calculate the backbone, by checking both assignments of every literal for whether it would make the formula unsatisfiable, see Algorithm 1. This algorithm is referenced in [MSJL10]

Algorithm 3: Iterative algorithm (two tests per variable)

As is commonly written in literature about boolean satisfiability, the two calls to the *SAT* function return a pair which consists first of whether the given function was satisfiable at all and, secondly, the found model, which in this case is discarded. There is no good algorithm that can tell whether a boolean formula is satisfiable or not without trying to find a model for said formula, but we can use it to greatly improve the algorithm above by combining this approach with that of the enumeration algorithms.

First observe that any model of *F* would already reduce the set of literals to test by half, because every literal in it obviously does not make the formula unsatisfiable. For every assignment missing in the model, we know that it cannot be part of the backbone, so there is no need to test it.

This can be repeated with every further model that we find. The following algorithm is another one that is listed in both [MSJL10] and [JLMS15] and is implemented in the Sat4J library as *BB*

Algorithm 4: Iterative algorithm (one test per variable)

im unsat fall gibt es kein model, kann also nicht geschnitten werden drei zeilen im unsat fall erklären 1. zur rückgabemenge hinzufügen 2. literal nicht mehr prüfen 3. backbone literal in formel aufnehmen (lernen)

Literaturverzeichnis

- [JLMS15] Mikoláš Janota, Inês Lynce, and Joao Marques-Silva. Algorithms for computing backbones of propositional formulae. *AI Commun.*, 28(2):161–177, April 2015.
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