Time and Energy Optimal Control for a Single Track Modeled Vehicle.

Adil Anton Pozharskiy Mario

Albert-Ludwigs-Universität Freiburg Albert-Ludwigs-Universität Freiburg Albert-Ludwigs-Universität Freiburg

Freiburg, Germany Freiburg, Germany
email anton@pozhar.ski email

Abstract—
Index Terms—Optimal control

I. INTRODUCTION

II. DEFINITIONS

III. NUMERICAL SOLUTION

IV. RESULTS

V. CONCLUSIONS

VI. FURTHER EXPLORATION

ACKNOWLEDGMENT

REFERENCES