$$a_3x + b_3y + c_3z = k_3$$

$$Let_{1}A = \begin{bmatrix} a_{1} & b_{1} & c_{1} \\ a_{2} & b_{2} & c_{2} \\ a_{3} & b_{3} & c_{3} \end{bmatrix}; X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}; B = \begin{bmatrix} k_{1} \\ k_{2} \\ k_{3} \end{bmatrix}$$

Then the system of equations can be written as  $AX = B_i i.e.$ 

$$\begin{bmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix}$$

## Important Conditions: -

Case I:- (When  $|A| \neq 0$ )

Then the solution will be  $X = A^{-1}B$ .

Case II:- (When |A| = 0 & (adj. A)B = 0)

Then the system may have infinite solution (consistent) or no solution (inconsistent).

Case II:- (When  $|A| = 0 \& (adj.A)B \neq 0$ )

Then solution doesn't exist (inconsistent).

## **Probability**

- (1) In a random experiment, if S be a sample space & E be an event, then
  - (i)  $P(E) \ge 0$
  - (ii)  $P(\emptyset) = 0$
  - (iii) P(S) = 1.
- (2)  $0 \le P(E) \le 1$ .
- $(3) P(E) + P(\overline{E}) = 1$
- $(4) P(E-F) = P(E) P(E \cap F)$
- (5)  $P(E \cup F) = P(E) + P(F) P(E \cap F)$
- $(6) P(E \cup F \cup G) = P(E) + P(F) + P(G) P(E \cap F) P(F \cap G) P(E \cap G) + P(E \cap F \cap G)$
- (7) If  $E_1 \& E_2$  be two events such that  $E_1 \subseteq E_2$ , then  $P(E_1) \le P(E_2)$
- (8) If E & F are mutually exclusive events, then
  - (i)  $P(E \cap F) = 0$
  - (ii)  $P(E \cup F) = P(E) + P(F)$
- (9) If E & F are two mutually exclusive exhaustive events, then P(E) + P(F) = 1.
- (10) Independent Event:-

$$P(E \cap F) = P(E).P(F)$$

(11) Conditional Probability:-

If E & F be two events associated with the same random experiment, then

$$P(E \cap F) = P(E).P\left(\frac{F}{E}\right)$$
 [where  $P(E) \neq 0$ ]