### Lecture 7

# **Line Integrals**

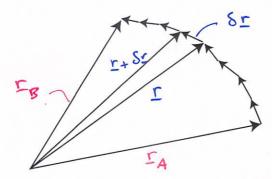
### 7.1 Line integration

In Lecture 2, we looked at integrals of scalar functions between limits specified by the independent variables, e.g  $\int_{x_1}^{x_2} \phi(x) dx$ . We now extend this to integration in 3-D along a *specified line in space*.

When we perform the familiar integral,

$$\int \phi(x) \, dx \quad , \tag{7.1}$$

we sum up the contributions of the product of  $\delta x$  elements (along the x-axis) multiplied by the 'weighting function' (the integrand),  $\phi$ , evaluated at the same x.



In a line integral, the element is part of a specified line in 3-D space. The line element can be a scalar,  $\delta s$  measured a long the curve, or a vector  $\delta \mathbf{r}$ . The integrand can also be a scalar or a vector. For example,

$$\int \rho(s) ds$$

$$\int c ds$$

$$\int e(s) ds$$

$$\int e(s)$$

In general, the result of the line integral depends on the path taken between the start and end of the line.

## 7.2 Line integrals of the form $\int \mathbf{F} \cdot d\mathbf{r}$

Integrals of the form  $\int \mathbf{F} \cdot d\mathbf{r}$  are the most important type of line integral. For example, the work required to move a particle along a path from A to B in a force field  $\mathbf{F}$  is,

$$W = \int_{A}^{g} E \cdot dc$$

In Cartesian coordinates,

$$E = f_{x} i + f_{y} j + f_{z} k$$

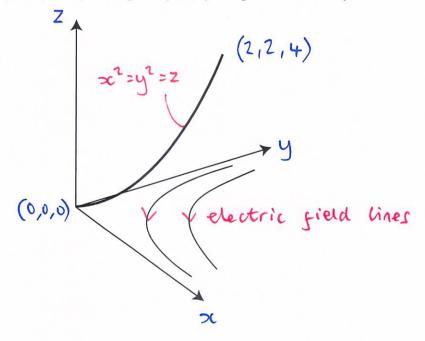
$$dc = dx i + dy j + dz k$$

$$W = \int_{A}^{B} f_{x} dx + f_{y} dy + f_{z} dz$$

It is often convenient to express the equation for the line, and the integrand, in parametric form. e.g. x = x(s), y = y(s),  $F_x = F_x(s)$ , etc.

#### Example

An electric field is determined by the equation  $\mathbf{E} = x\mathbf{i} - y\mathbf{j} + z\mathbf{k}$ . Find the work required to move a charge q from the point (0,0,0) to the point (2,2,4) along the curve  $x^2 = y^2 = z$ .



Force on charge = 
$$qE$$

$$W = \int_{A}^{B} E \cdot dr = \int_{A}^{B} qE \cdot dr$$

Parametric eq<sup>1</sup> for curve:
$$x = t \quad y = t \quad z = t^{2}$$
Hence  $dx = dt \quad dy = dt \quad dz = 2t dt$ 

$$dr = dx = i \quad dy = i \quad dz = 2t dt$$

$$dr = dx = i \quad dy = i \quad dz =$$

### Example

Although it is often simpler to use a parametric approach (requiring one integration), as in the previous example, it is also possible to retain the coordinate system independent variables e.g. (x, y, z), (requiring 3 integrations).

For example, evaluate,

$$I = \int_{(0,0,0)}^{(1,1,1)} \mathbf{F} \cdot d\mathbf{r} \quad \text{where} \quad \mathbf{F} = (y-z)\mathbf{i} + (z-x)\mathbf{j} + (x-y)\mathbf{k}$$
 (7.2)

and the integral is along the path  $y = x^2$ ,  $z = x^3$ .

$$I = \int (y-z) dx + (z-x) dy + (x-y) dz$$
(0,0,0)

$$I = \int_{z=0}^{1} (y-z) dx + \int_{z=0}^{1} (z-x) dy + \int_{z=0}^{1} (x-y) dz$$

Using the specified curve, we can make substitutions:
$$I = \int_{3}^{1} (3^{2} - x^{3}) dx + \int_{3}^{1} (y^{3}h_{-}y^{1/2}) dy + \int_{3}^{1} (z^{1/3} - z^{2/3}) dz$$

$$= \left[\frac{z^{3}}{3} - x^{4}\right]_{0}^{1} + \left[\frac{z}{3}y^{5/2} - \frac{z}{3}y^{3/2}\right]_{0}^{1} + \left[\frac{3}{4}z^{4/3} - \frac{3}{5}z^{5/3}\right]_{0}^{1}$$

$$= -\frac{1}{30}$$

#### 7.3 Conservative fields

If a vector field V is 'conservative' then the integral  $\int V d\mathbf{r}$  between any two points A and B is independent of the path of integration. We now investigate the conditions which ensure that a field V is conservative.

In Cartesian coordinates,

$$\int_{A}^{B} \mathbf{V} \cdot d\mathbf{r} = \int_{A}^{B} \mathbf{V}_{x} \, dx + \mathbf{V}_{y} \, dy + \mathbf{V}_{z} \, dz \tag{7.3}$$

If we can obtain V by taking the gradient of the scalar  $\phi$ ,  $V = \nabla \phi$ , then,

$$\mathbf{V} \cdot d\mathbf{r} = \nabla \phi \cdot d\mathbf{r} = \left(\frac{\partial \phi}{\partial x}\mathbf{i} + \frac{\partial \phi}{\partial y}\mathbf{j} + \frac{\partial \phi}{\partial z}\mathbf{k}\right) \cdot (dx\mathbf{i} + dy\mathbf{j} + dz\mathbf{k})$$

$$= \frac{\partial \phi}{\partial x} \quad \partial x \quad + \quad \frac{\partial \phi}{\partial y} \quad dy \quad + \quad \frac{\partial \phi}{\partial z} \quad dz$$

$$= \partial \phi$$

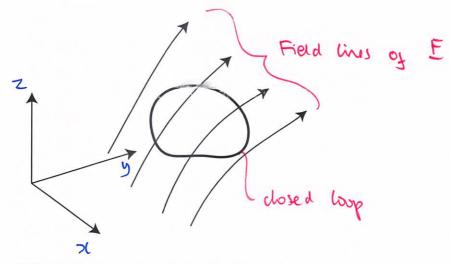
$$= \partial \phi$$

Hence, if  $\mathbf{V} = \nabla \phi$ , then  $\mathbf{V} \cdot d\mathbf{r}$  is a *perfect differential* and the integral becomes,

$$\int_{A}^{B} \mathbf{V} \cdot d\mathbf{r} = \int_{A}^{B} d\phi = \phi_{B} - \phi_{A} \quad , \tag{7.5}$$

and does not depend on the integration path; V, therefore, is a conservative field.

We have previously found that, if  $\mathbf{V} = \nabla \phi$ , then  $\nabla \times \mathbf{V} = 0$  and the field is irrotational. The condition  $\nabla \times \mathbf{V} = 0$ , therefore, means that the field  $\mathbf{V}$  is irrotational and also conservative - the two terms mean the same thing and are retained by convention. Traditionally, "irrotational" is used to describe a fluid velocity field  $\mathbf{V}$  where  $\nabla \times \mathbf{V} = 0$ , and "conservative" is used to describe a force field  $\mathbf{F}$  (such as the gravitational or electrostatic field) where  $\nabla \times \mathbf{F} = 0$ .



For a conservative field, the line integral around a closed loop in space,

$$\oint \mathbf{F} \cdot d\mathbf{r} = 0 \quad , \tag{7.6}$$

because the final and initial values of  $\phi$  are the same. The symbol  $\phi$  is used to indicate integration around a closed loop because it does not matter at which point the integration starts.

For non-conservative fields,

$$\oint \mathbf{F} \cdot d\mathbf{r} = \Gamma \quad , \tag{7.7}$$

and  $\Gamma$  is generally non-zero.  $\Gamma$  is referred to as the *circulation*.

If  $\nabla \times \mathbf{V} = 0$  everywhere, then the field is conservative or irrotational, and the circulation around any closed loop in the field is zero.

#### Example

The electrostatic field  $\mathbf{E}$  at position  $\mathbf{r}$  due to a point charge q at the origin is given by,

$$\mathbf{E} = \frac{q}{4\pi\varepsilon_0 r^3} \mathbf{r} \quad . \tag{7.8}$$

Show that **E** is conservative and find its scalar potential.

Central force field 
$$\Rightarrow$$
 spherical polar coordinates 
$$\frac{E}{4\pi\epsilon_0 r^2} = \frac{2}{4\pi\epsilon_0 r^2}$$
 components in  $\epsilon_0$  and  $\epsilon_\phi$  are zero

$$\nabla \times \vec{E} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} er & re\theta & r \sin \theta & e\varphi \\ \frac{2}{4\pi \epsilon_0 r^2} & 0 & 0 \end{vmatrix}$$

$$= 0er + 0e\theta + 0e\theta & : \vec{E} \text{ is conservative}$$

$$Scalar potential such that  $\vec{E} = \nabla y$ 

$$\frac{\partial y}{\partial r} = \frac{2}{4\pi \epsilon_0 r^2} \quad \frac{\partial y}{\partial \theta} = 0$$

$$\vdots \quad y = \frac{-2}{4\pi \epsilon_0 r} + \cos y$$

$$i.e. equipotential surfaces  $(y = \cos y)$  are spheres centred at the origin, saryhere normal to field lines of  $\vec{E}$$$$$

You can now do Examples Paper 2: Q8, 9, 10, 11 and 12