







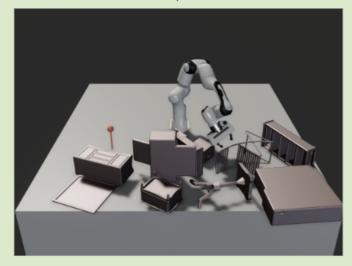
Datasets of feasible joint states

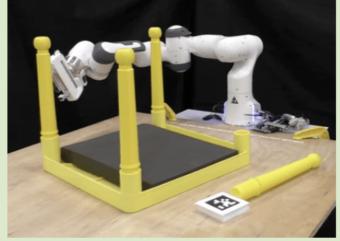
Synthetic point cloud data of diverse scenes

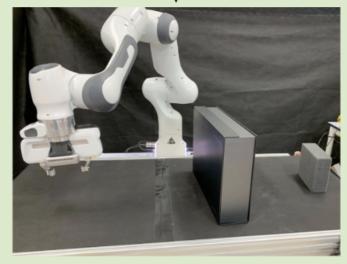
## **AMP-LS**

Test

Deploy to unseen scenes for planning







(a) Simulated static env

(b) Real-world static env

(c) Moving conveyor belt env