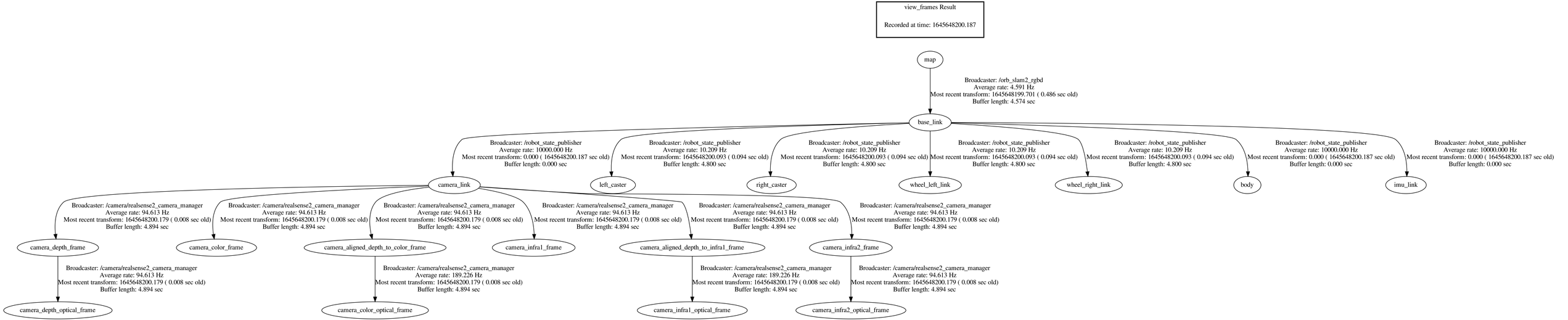
view_frames Result
Recorded at time: 1645648200.187
map
Broadcaster: /orb_slam2_rgbd
Average rate: 4.591 Hz
Most recent transform: 1645648199.701 (0.486 sec old)
Buffer length: 4.574 sec
base_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1645648200.187 sec old)
Buffer length: 0.000 sec
camera_link
Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1645648200.093 (0.094 sec old)
Buffer length: 4.800 sec
left_caster
right_caster
wheel_left_link
wheel_right_link
body
imu_link
Broadcaster: /camera/realsense2_camera_manager
Average rate: 94.613 Hz
Most recent transform: 1645648200.179 (0.008 sec old)
Buffer length: 4.894 sec
camera_depth_frame
camera_color_frame
camera_aligned_depth_to_color_frame
camera_infra1_frame
camera_aligned_depth_to_infra1_frame
camera_infra2_frame
Broadcaster: /camera/realsense2_camera_manager
Average rate: 189.226 Hz
Most recent transform: 1645648200.179 (0.008 sec old)
Buffer length: 4.894 sec
camera_depth_optical_frame
camera_color_optical_frame
camera_infra1_optical_frame
camera_infra2_optical_frame