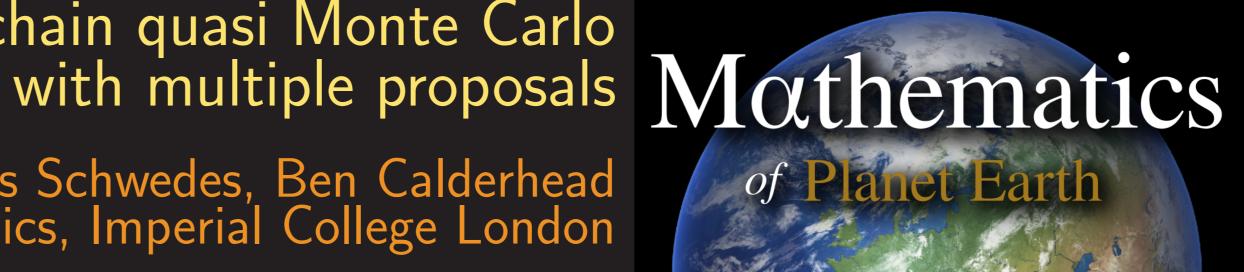
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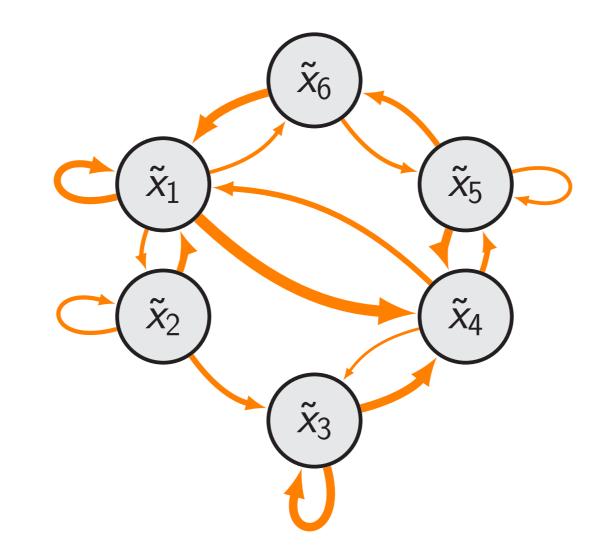
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Abstract

Markov chain Monte Carlo (MCMC) is a preferred sampling method due its wide applicability. However, it suffers from a slow scaling of $n^{-\frac{1}{2}}$, analogously to standard Monte Carlo. For the latter, scaling close to n^{-1} can be achieved by using more homogeneously distributed points in space than the usual pseudo-random numbers. With the same philosophy in mind we apply quasi-Monte Carlo to an MCMC method that uses multiple proposals. We show consistency and achieve an improved scaling of close to n^{-1} numerically.

Using multiple proposals in MCMC

Metropolis-Hastings (M-H) was generalised in (Cal14) such that it allows for parallelising a single chain by proposing multiple points via a kernel κ in parallel. In every MCMC iteration, a finite state Markov chain on the proposed points, i.e. $\tilde{x}_1, ..., \tilde{x}_{N+1}$, is constructed, as displayed in the figure on the right, from which samples are drawn.



In practice, generating proposals $x_{\setminus I} = x_{[1:N+1]\setminus\{I\}}$ from $\kappa(x_I,\cdot)$ is typically performed via applying its generalised inverse Ψ_{x_l} to a set of pseudo-random numbers $u_1, ..., u_{Nd} \in [0,1]$ such that $x_{\setminus I} = \Psi_{x_I}(u_1, ..., u_{Nd})$. The overall procedure is described in Algorithm 1.

Algorithm 1: Multiple proposal Metropolis-Hastings

Input: Initialise starting point $\tilde{x}_1 \in \Omega \subset \mathbb{R}^d$, number of proposals N, auxiliary variable I=1 and counter n=0, generate an pseudo-random sequence $u_1,u_2,...\in(0,1]$;

1 for each MCMC iteration i = 1, 2, ... do

- 2 | Set $u^i = (u_{(i-1)Nd+1}, ..., u_{iNd}) \in (0,1]^{Nd}$, and sample $\tilde{x}_{\setminus I}$ conditioned on I, i.e., draw Nnew points from $\kappa(\tilde{x}_I,\cdot) = p(\tilde{x}_{\setminus I}|\tilde{x}_I)$ by the inverse $\Psi_{\tilde{x}_I}(u^i)$;
- 3 Compute the stationary distribution of $I|\tilde{x}_{1:N+1}$, i.e. $p(I=j|\tilde{x}_{1:N+1})=$ $\pi(\tilde{x}_j)\kappa(\tilde{x}_j,\tilde{x}_{\setminus j})/\sum_k \pi(\tilde{x}_k)\kappa(\tilde{x}_k,\tilde{x}_{\setminus k})$, which can be done in parallel;
- 4 | for m = 1, ..., N do
- Sample new I via $p(\cdot|\tilde{x}_{1:N+1})$;
- Set new sample $x_{n+m} = \tilde{x}_I$;
- end
- 8 Update counter n = n + N
- 9 end

Properties of multiple proposal M-H

- Satisfies detailed balance, thus updates leave the stationary distribution invariant
- The proposal kernel κ can be chosen freely, including formulations based on Langevin diffusion and Hamiltonian dynamics
- ▶ The likelihoods of the proposed states can be computed in parallel
- Due to the multiple alternatives to accept the next state, the acceptance rate is increased

Completely uniformly distributed numbers

The star discrepancy D_n^{*d} for a set of points $P = \{x_1, ..., x_n\} \subset (0, 1]^d$ is defined by

$$D_n^*(P) = \sup_{b \in (0,1]^d} \left| \frac{\#\{x_i \in (0,b]\}}{n} - \text{vol}((0,b]) \right|.$$

A sequence $(u_i)_{i\geq 1}\subset (0,1]$ is called c.u.d. if for any $d\geq 1$ the points $x_i^{(d)}=(u_i,\ldots,u_{i+d-1})\in (0,1]^d$ fulfill $D_n^{*d}(x_1^{(d)},\ldots,x_n^{(d)})\to 0$ as $n\to\infty$.

References

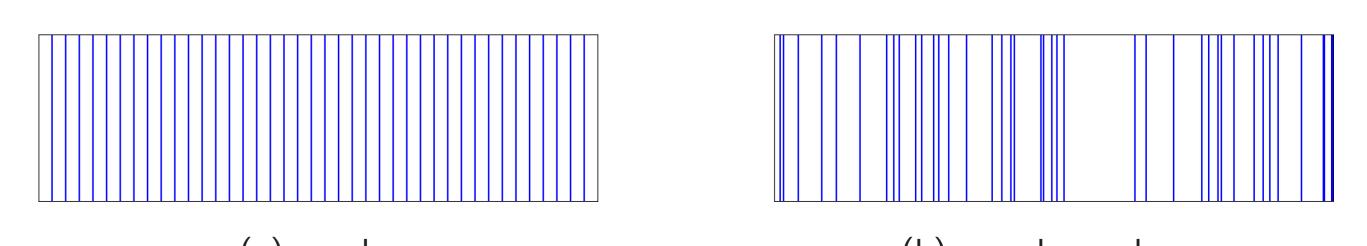
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C.u.d. numbers in practice

The c.u.d. construction used in our simulations was introduced in (CMNO12) and relies on a linear-feedback shift register with a transition mechanism based on primitive polynomials over the Galois field GF(2). Referring to Fig. 1, the resulting sequence is more homogeneously distributed than pseudo-random numbers.



(a) c.u.d. (b) pseudo-random Figure : Segments of c.u.d. and pseudo-random finite sequences in (0,1].

Regularity conditions

Coupling: For any MCMC iteration in Algorithm 1, let $\phi(x_I, (u_1, ..., u_{Nd})) =$ $(x_1,...,x_N)$ denote the innovation operator that produces the N new samples. Let $\mathcal{C} \subset (0,1]^{Nd}$ have positive Jordan measure. If for any $u \in \mathcal{C}$ it holds $\phi(x,u) =$ $\phi(x',u) \ \forall \ x,x' \in \Omega$, then \mathcal{C} is called a *coupling region*.

Integrability: Let x_n be a sample from the *i*th iteration. Any $g:[0,1]^{iNd}\to\mathbb{R}$, defined by $g(u^1, \ldots, u^i) = f(x_n(u^1, \ldots, u^i))$, where $f: \mathbb{R}^d \to \mathbb{R}$ is bounded and continuous, is Riemann integrable.

Consistency theorem

Let us assume the above regularity and that the Markov chain defined by Algorithm 1 is irreducible and Harris recurrent with stationary distribution π . If the sequence of pseudo-random numbers is replaced by c.u.d. numbers, then $(x_n)_{n\geq 1}$ still consistently samples π .

Numerical results

Example problem: Estimate mean and distribution of a one-dimensional Gaussian

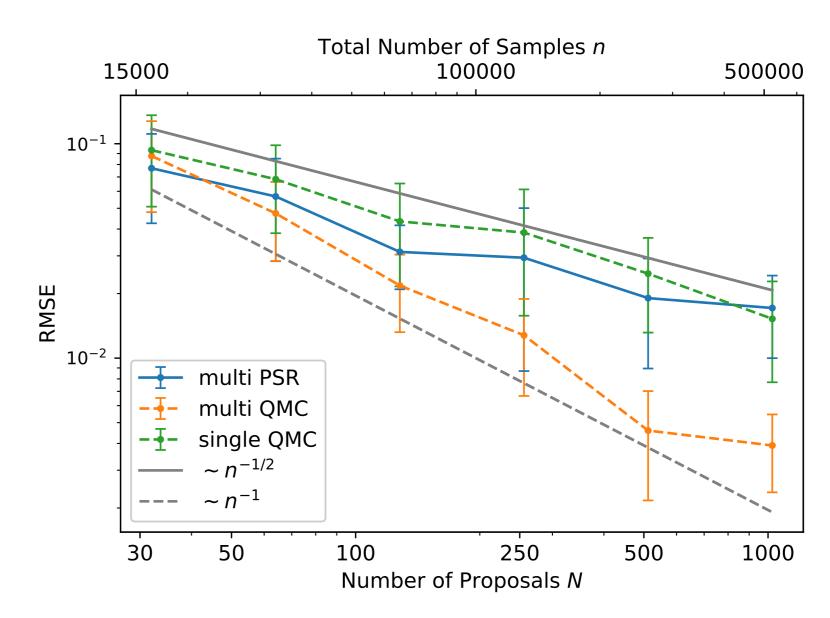


Figure: RMSE of the sample mean based on M-H with independent proposals using pseudo-random (PSR) vs. c.u.d. (QMC) numbers as driving sequences, resp., for increasing proposal numbers and sample sizes. The results are based on 25 MCMC simulations

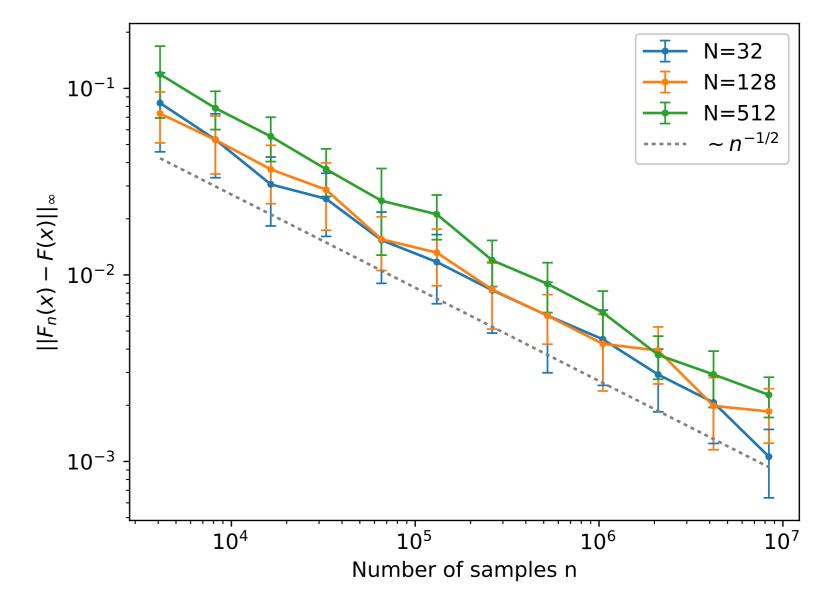


Figure : Maximum-norm error for the empirical distribution function of samples from the Nproposal M-H with random walk proposals, using c.u.d. numbers as driving sequence, for increasing sample sizes. The results are based on 25 MCMC simulations

Future research

- Performance in higher dimensions
- Consistency proof for larger classes of proposal kernels