



Google

**DReGs**

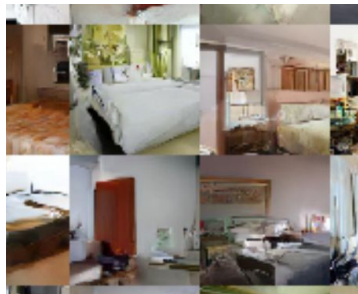
# Doubly Reparameterized Gradient Estimators for latent variable models

George Tucker ([gjt@google.com](mailto:gjt@google.com))

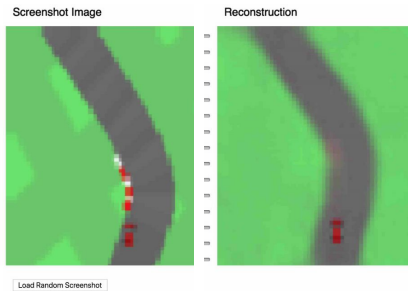
Dieterich Lawson, Shixiang Gu, Chris J. Maddison



# Generative Latent Variable Models



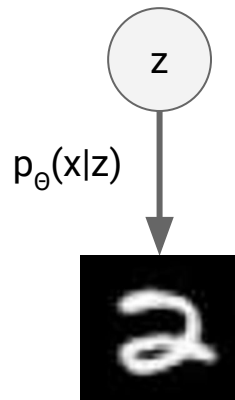
Samples from PixelVAE  
(Gulrajani et al. 2016)



Model based RL  
(Ha and Schmidhuber 2018)



Samples from SVG  
(Denton & Fergus 2018)



$z$  are latent factors  
(e.g., number, stroke  
width)

Model data  $x$  with a generative model

$$p_{\theta}(x) = \int p_{\theta}(x, z) dz$$

Would like to maximize log likelihood,  $\log p_{\theta}(x)$ ,  
with stochastic gradient descent.

# DReGs

Introduce an **unbiased, low variance gradient estimator** for training latent variable models.

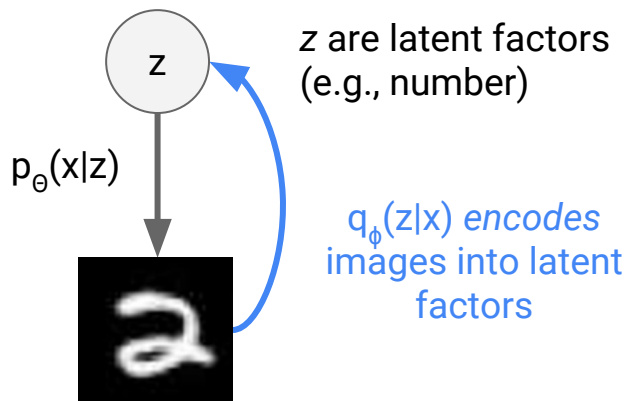
Show its applicability to three recent training techniques for latent variable models:

- **IWAE** (Burda et al. 2015)
- **Reweighted Wake-Sleep (RWS)**  
(Bornschein & Bengio, 2014)
- **Jackknife Variational Inference (JVI)** (Nowozin, 2018)

1. Background on IWAE
2. DReG estimators
3. Experiments
  - a. Gaussian system
  - b. Omniglot and MNIST

# Latent Variable Models

We optimize a *variational* lower bound (**ELBO**) on the log likelihood



$$\log p_{\theta}(x) = \log \int_z p_{\theta}(x, z) dz$$

# Importance weighted bounds (**IWAE**)

We can improve the bound using  $K$  samples instead of 1

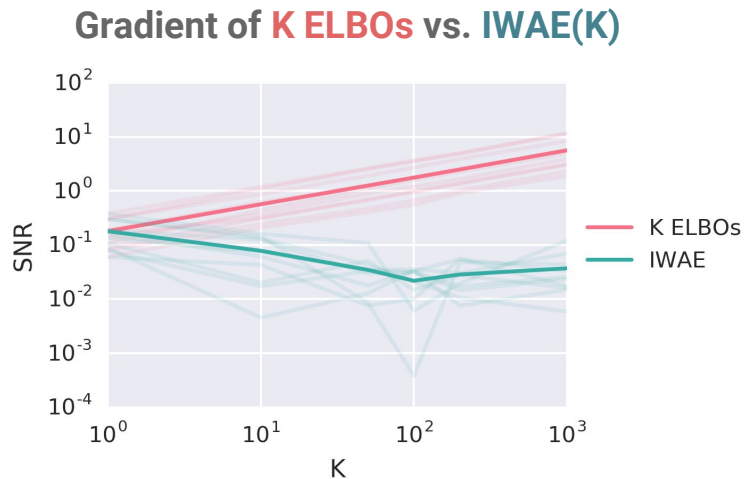
$$\text{IWAE}(K) = \mathbb{E}_{z_{1:K}} \left[ \log \left( \frac{1}{K} \sum_{i=1}^K w_i \right) \right] \leq \log p_{\theta}(x) \quad w_i = w(z_i) = \frac{p_{\theta}(x, z_i)}{q_{\phi}(z_i | x)}$$

$$\text{ELBO} = \text{IWAE}(1) \leq \text{IWAE}(2) \leq \dots \leq \text{IWAE}(K) \leq \log p_{\theta}(x)$$

An increasingly tight bound, **so as  $K \rightarrow \infty$ , the effect of an overly simplistic  $q_{\phi}$  family diminishes.**

# Importance weighted bounds (**IWAE**)

But the gradient wrt to  $\phi$  gets worse as  $K$  increases ...



As  $K$  increases:

- IWAE( $K$ ) becomes tighter.
- $\phi$  gradient estimator for IWAE( $K$ ) degrades.

**Can we resolve this tension?**

# Double Reparameterized Gradient Estimator

$$\nabla_{\phi} \mathbb{E}_{z_{1:K}} \left[ \log \left( \frac{1}{K} \sum_{i=1}^K w_i \right) \right] = \mathbb{E}_{\epsilon_{1:K}} \left[ \sum_{i=1}^K \frac{w_i}{\sum_j w_j} \nabla_{\theta, \phi} \log w_i \right]$$

The single sample estimator is typically used.

$$= \mathbb{E}_{\epsilon_{1:K}} \left[ \sum_{i=1}^K \frac{w_i}{\sum_{j=1}^K w_j} \left( -\frac{\partial}{\partial \phi} \log q_{\phi}(z_i|x) + \frac{\partial \log w_i}{\partial z_i} \frac{dz_i}{d\phi} \right) \right]$$

When  $K = 1$ ,  $t = 1$   
 (Apply reparameterization trick)  $= \mathbb{E}_{\epsilon_{1:K}} \left[ \sum_{i=1}^K \left( \frac{w_i}{\sum_j w_j} \right)^2 \frac{\partial \log w_i}{\partial z_i} \frac{\partial z_i}{\partial \phi} \right]$  al. 2017)  
 So drop it when  $K > 1$

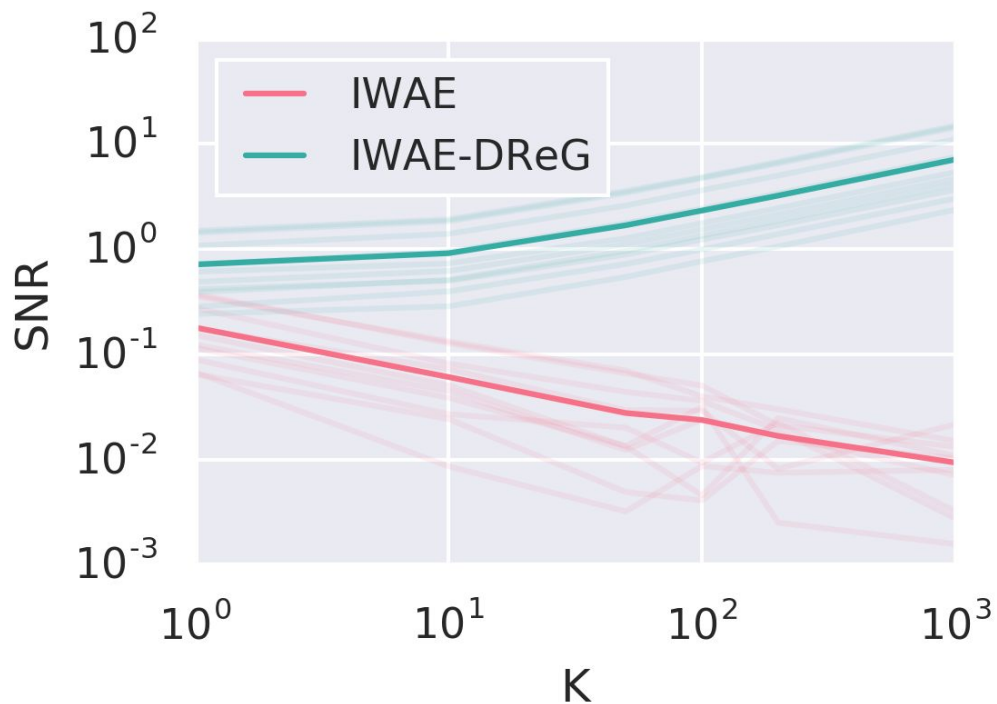
The IWAE-DReG estimator is the single sample Monte Carlo estimator.

# Double Reparameterized Gradient Estimator

$$\begin{aligned}\mathbb{E}_{\epsilon_{1:K}} \left[ \sum_{i=1}^K \frac{w_i}{\sum_{j=1}^K w_j} \frac{\partial}{\partial \phi} \log q(z_i|x) \right] &= \sum_{i=1}^K \mathbb{E}_{\epsilon_{1:K}} \left[ \frac{w_i}{\sum_{j=1}^K w_j} \frac{\partial}{\partial \phi} \log q(z_i|x) \right] \\ \mathbb{E}_{z_{1:K}} \left[ \frac{w_i}{\sum_j w_j} \frac{\partial}{\partial \phi} \log q_\phi(z_i|x) \right] &= \mathbb{E}_{z_{-i}} \mathbb{E}_{z_i} \left[ \frac{w_i}{\sum_j w_j} \frac{\partial}{\partial \phi} \log q_\phi(z_i|x) \right] \\ \mathbb{E}_{z_i} \left[ \frac{w_i}{\sum_j w_j} \frac{\partial}{\partial \phi} \log q_\phi(z_i|x) \right] &= \mathbb{E}_{\epsilon_i} \left[ \frac{\partial}{\partial z_i} \left( \frac{w_i}{\sum_j w_j} \right) \frac{\partial z_i}{\partial \phi} \right] \\ &= \mathbb{E}_{\epsilon_i} \left[ \left( \frac{1}{\sum_j w_j} - \frac{w_i}{(\sum_j w_j)^2} \right) \frac{\partial w_i}{\partial z_i} \frac{\partial z_i}{\partial \phi} \right] = \mathbb{E}_{\epsilon_i} \left[ \left( \frac{w_i}{\sum_j w_j} - \frac{w_i^2}{(\sum_j w_j)^2} \right) \frac{\partial \log w_i}{\partial z_i} \frac{\partial z_i}{\partial \phi} \right]\end{aligned}$$



# Simple Gaussian System

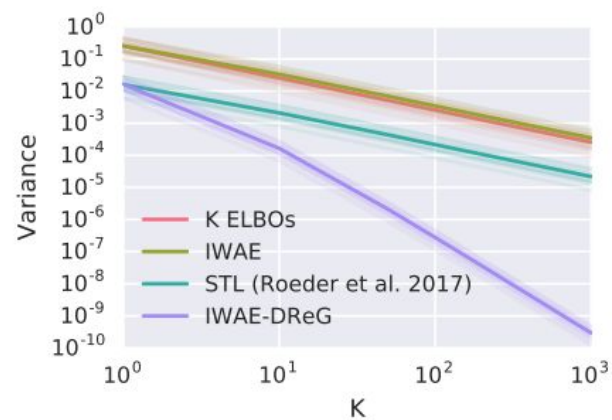
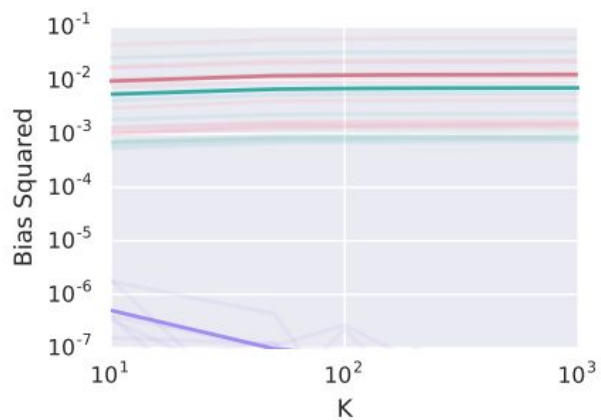
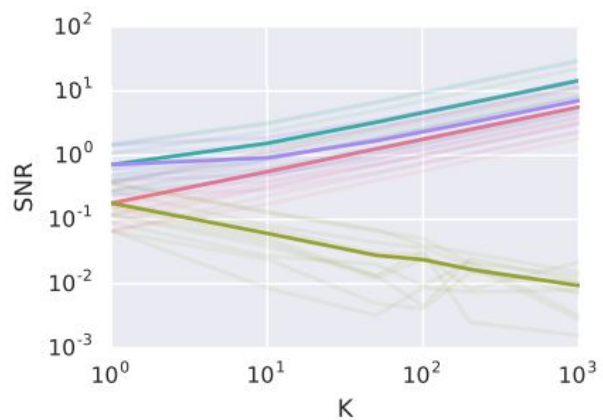


**Delta method implies**

IWAE SNR:  $O(1/K^{0.5})$

IWAE-DreG SNR:  $O(K^{0.5})$

# Simple Gaussian System



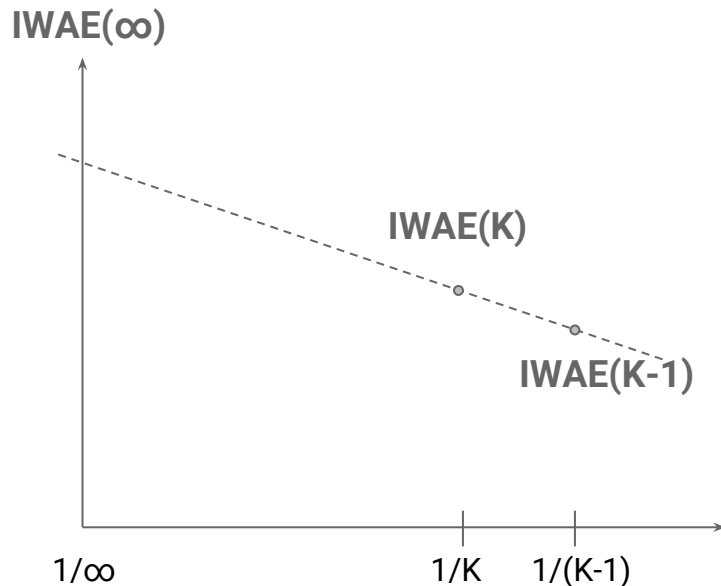
# Reweighted Wake-Sleep (RWS)

Instead, optimize  $\phi$  by minimizing  $\text{KL}(p(z|x) \parallel q(z|x))$

$$\begin{aligned}\nabla_{\phi} \mathbb{E}_{p_{\theta}(z|x)} [\log p_{\theta}(z|x) - \log q_{\phi}(z|x)] &= -\mathbb{E}_{p_{\theta}(z|x)} \left[ \frac{\partial}{\partial \phi} \log q_{\phi}(z|x) \right] \\ &- \mathbb{E}_{p_{\theta}(z|x)} \left[ \frac{\partial}{\partial \phi} \log q_{\phi}(z|x) \right] \approx -\mathbb{E}_{z_{1:K}} \left[ \underbrace{\sum_i \frac{w_i}{\sum_j w_j} \frac{\partial}{\partial \phi} \log q_{\phi}(z_i|x)}_{\text{(Apply reparameterization trick)}} \right]\end{aligned}$$

(Apply reparameterization trick)

# Jackknife Variational Inference (JVI)



Use a linear combination of  $\text{IWAE}(K)$  and  $\text{IWAE}(K-1)$  to cancel the first order bias term.

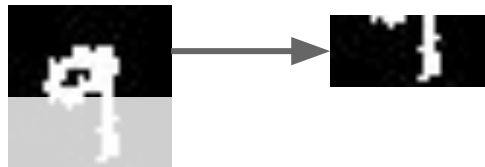
$$\text{JVI}(1) = \underbrace{K \times \mathbb{E}_{z_1:K} \left[ \log \left( \frac{1}{K} \sum_{i=1}^K w_i \right) \right]}_{\text{IWAE}(K)} - \frac{K-1}{K} \sum_{i=1}^K \underbrace{\mathbb{E}_{z_{-i}} \left[ \log \left( \frac{1}{K-1} \sum_{j \neq i} w_j \right) \right]}_{\text{IWAE}(K-1)}$$

# Experiments

## MNIST & Omniglot Generative Modeling



## MNIST Structured Prediction



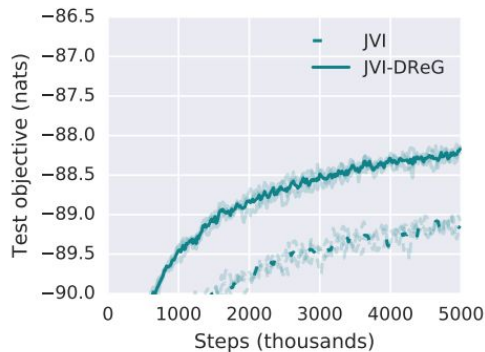
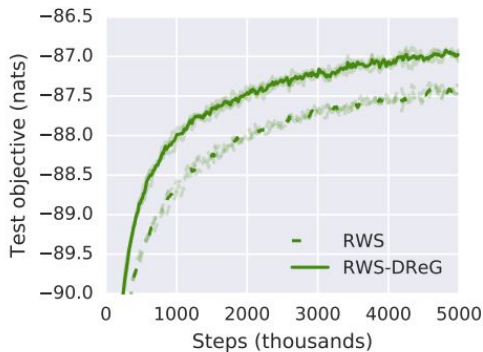
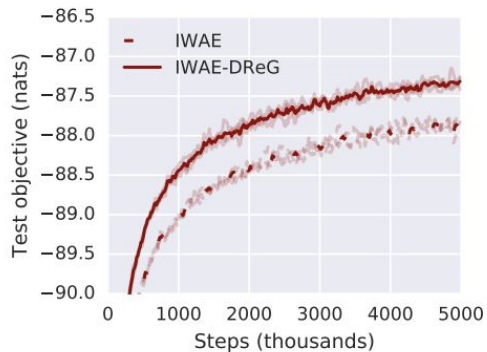
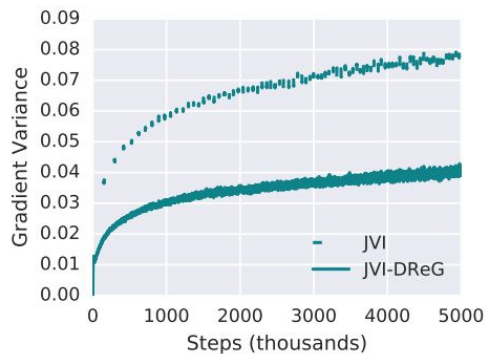
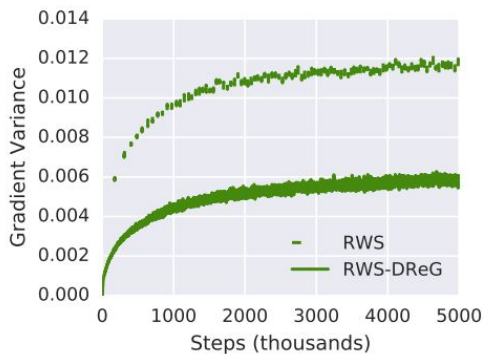
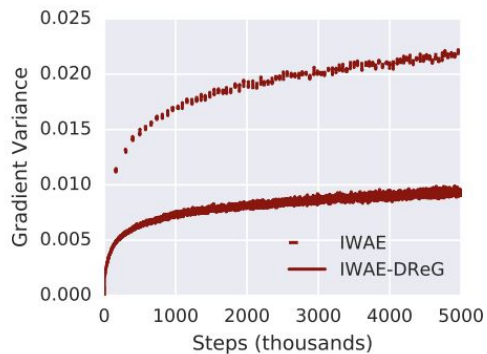
### Network details

50 dimensional latent variable ( $z$ )

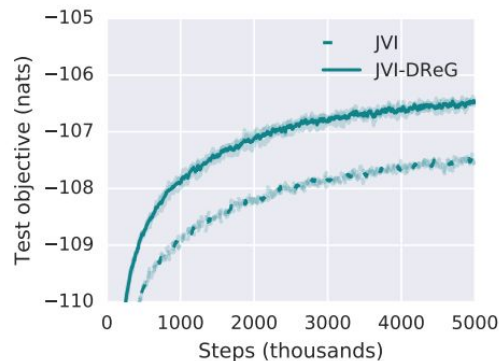
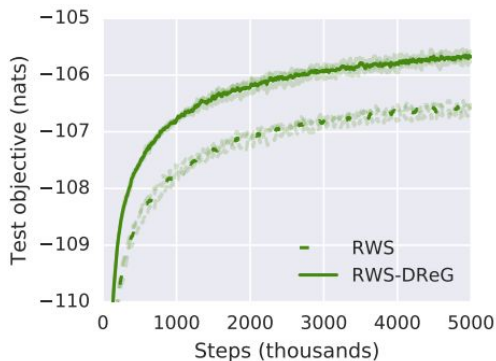
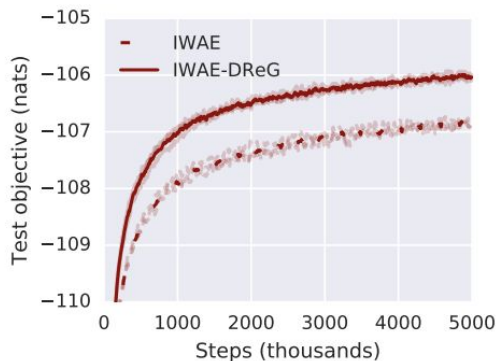
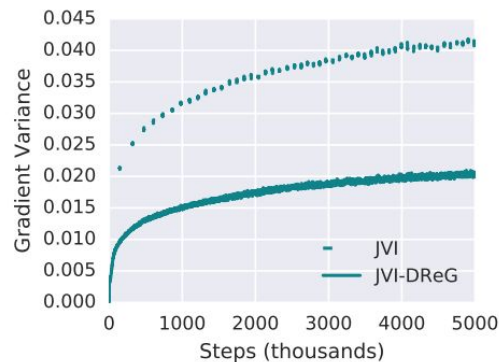
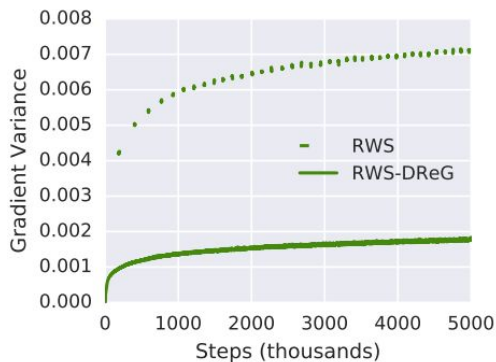
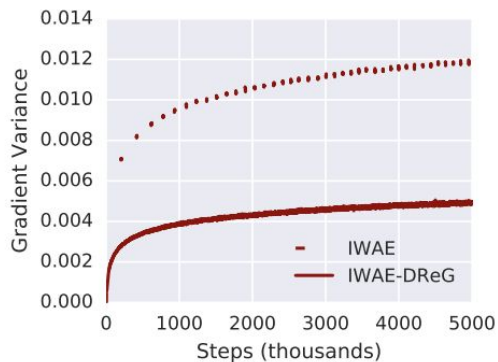
2 hidden layers 200 tanh units

Factorized Bernoulli and Gaussian distributions

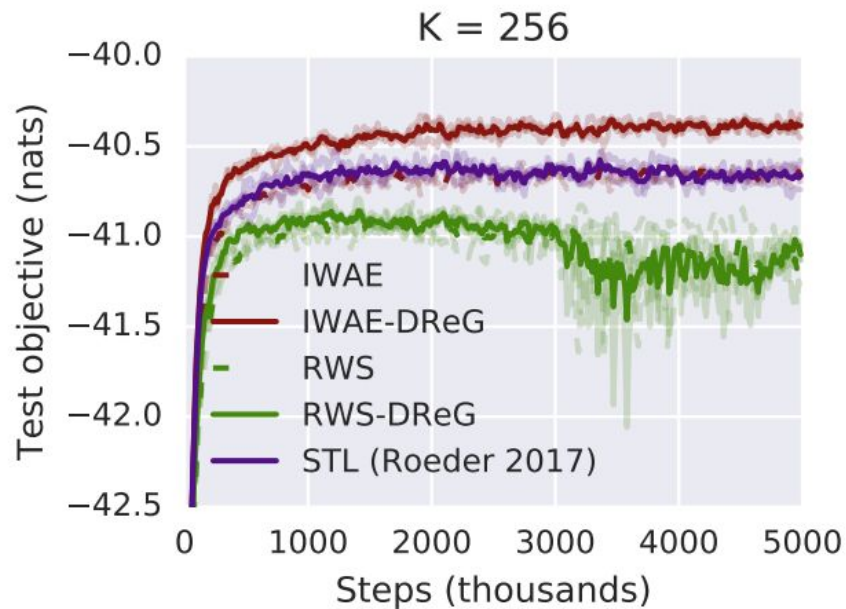
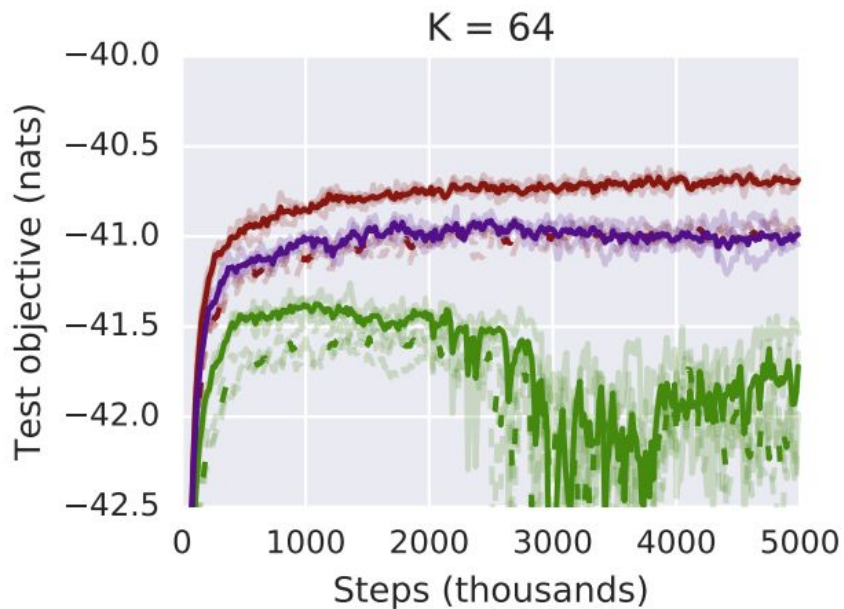
# MNIST Generative Modeling



# Omniglot Generative Modeling



# MNIST Structured Prediction





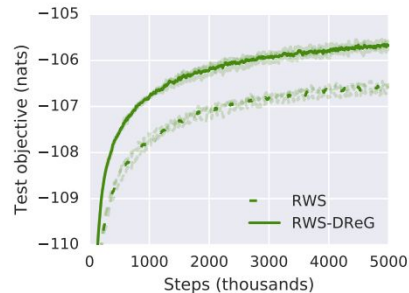
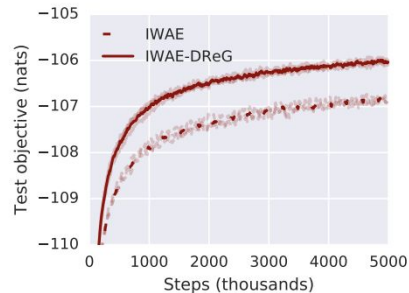
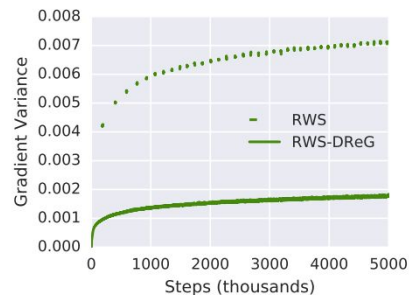
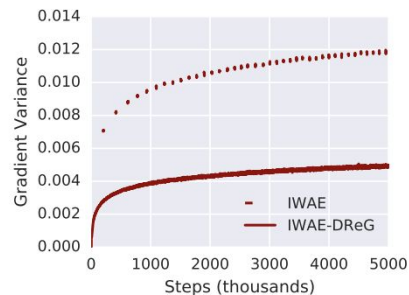
# Summary & Future Work

**DReG estimators** are computationally efficient, unbiased, drop-in replacements for standard gradient estimators.

They rectify practical and asymptotic issues raised in Rainforth et al. 2018.

We plan to explore extensions to sequential models (e.g., Maddison et al. 2017, Naesseth et al. 2018, Le et al. 2018).

**Paper, Slides, Code:** [sites.google.com/view/dregs](https://sites.google.com/view/dregs)



# Appendix

