Learning priors, likelihoods, or posteriors

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"Within the field of approximate Bayesian inference, variational and Monte Carlo methods are currently the mainstay techniques."

— http://approximateinference.org/

The Statistician (1987) 36, pp. 247-249

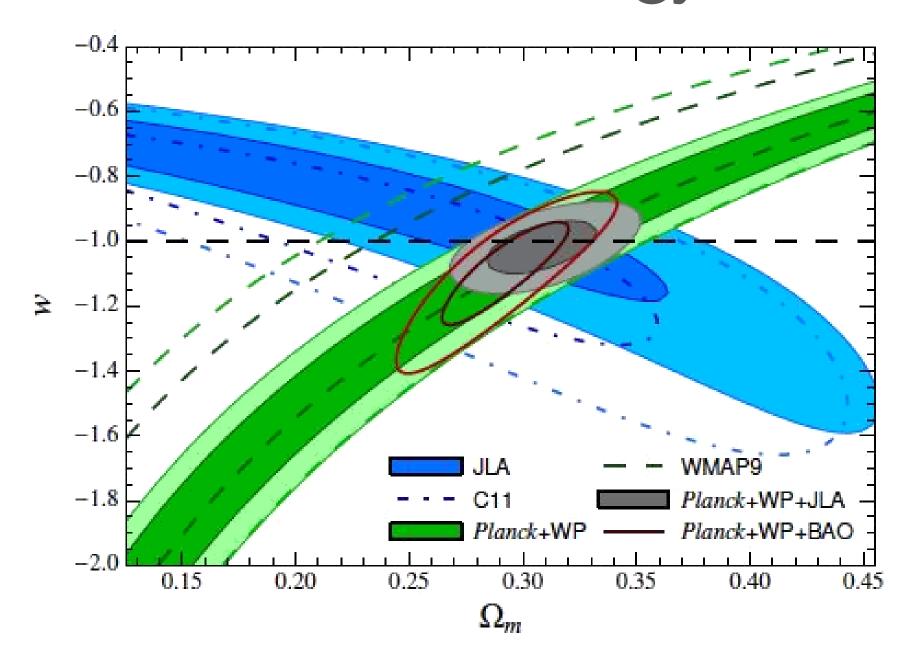
Monte Carlo is fundamentally unsound

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Abstract. We present some fundamental objections to the Monte Carlo method of numerical integration.

Posteriors in Cosmology



Recognition networks

$$\theta^{(s)} \sim p(\theta)$$
 $\mathbf{x}^{(s)} \sim p(\mathbf{x} \mid \theta^{(s)})$

Training set:
$$\left\{\theta^{(s)}, \mathbf{x}^{(s)}\right\}_{s=1}^{S}$$

Some of the relevant work

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Hinton et al. (1995, Science) — Wake Sleep, Helmholtz machine Morris (2001, UAI) — Recognition Networks

Blum & Francois (2010, S&C) — Conditional Gaussian, neural nets

Fan, Nott, Sisson (2012, Stat) — Mixture of experts

Mitrović, Dino Sejdinović, Teh (2016, ICML) — Kernel regression
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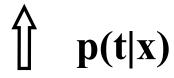
Fast *ϵ*-free Inference of Simulation Models with Bayesian Conditional Density Estimation

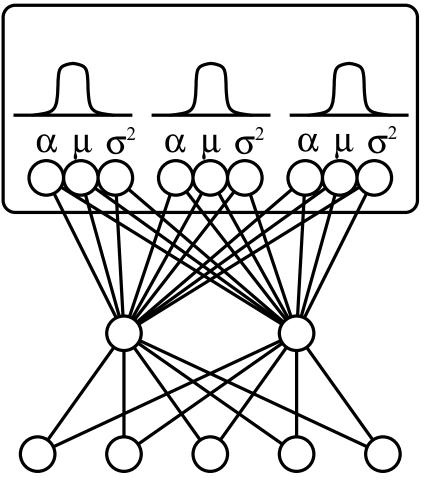
Papamakarios and Murray (NIPS, 2016) Lueckmann et al. (NIPS, 2017)

— Fit $\hat{p}(\theta \mid \mathbf{x})$ maximize $\sum_{s} \log \hat{p}(\theta^{(s)} \mid \mathbf{x}^{(s)})$

Mixture Density Networks (Bishop, 1994)

conditional probability density





mixture model

neural network

input vector



Fast *∈*-free Inference of Simulation Models with Bayesian Conditional Density Estimation

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- $\hat{p}(\theta \mid \mathbf{x}_{\mathsf{observed}}) \rightarrow \mathsf{approx} \; \mathsf{posterior}$

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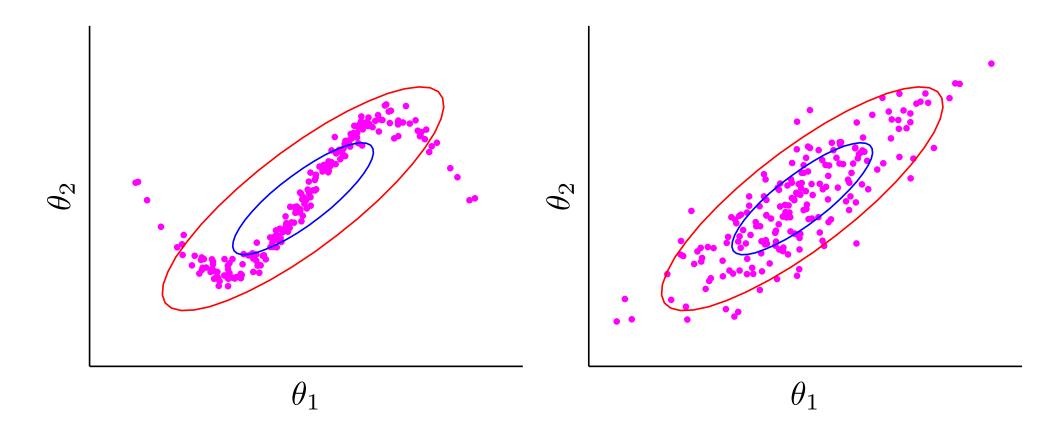
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— Refine fit: more simulations

Underfitting



True posterior samples

samples from Gaussian fit

— Modeling posteriors

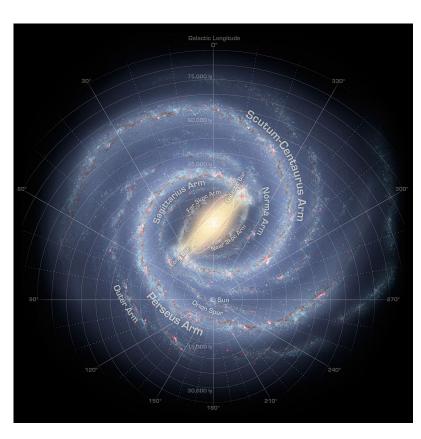
— Modeling priors

— Modeling likelihoods

Weighing the Milky Way

Busha, Marshall, Wechsler, Klypin and Primack (2011)

APJ 743:40



Milky Way diagram, NASA



Magellanic Clouds, ESO/S. Brunier

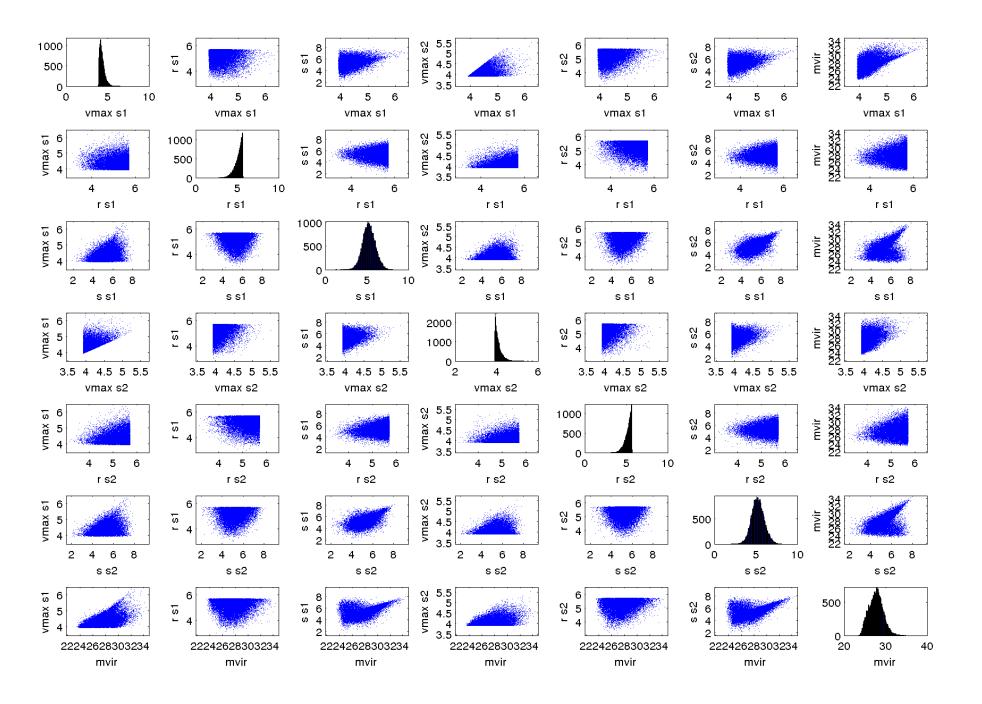
http://en.wikipedia.org/wiki/File:236084main_MilkyWay-full-annotated.jpg http://www.eso.org/public/images/b01/

Bayesian Inference

$$p(\mathbf{x} \mid \mathbf{y}) \propto p(\mathbf{y} \mid \mathbf{x}) p(\mathbf{x})$$

 $\mathbf{x} = [r, v, m]$, vector of galaxy properties $\mathbf{y} = [\hat{r}, \hat{v}]$, noisily observe part of \mathbf{x}

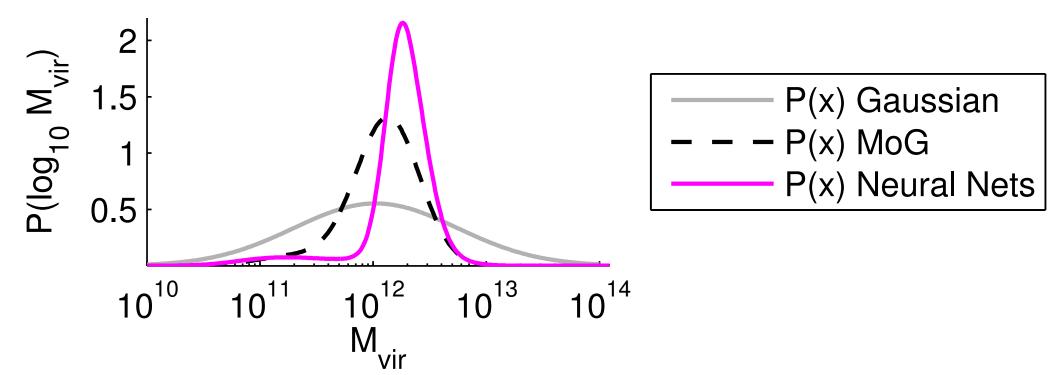
The prior: simulation samples



Milky Way mass

 $p(\mathbf{x})$ theory: simulated galaxy properties $p(\mathbf{y} \mid \mathbf{x})$ observations of Milky Way

 $p(\mathbf{x} \mid \mathbf{y}) \to p(x_1 \mid \mathbf{y})$, posterior of mass

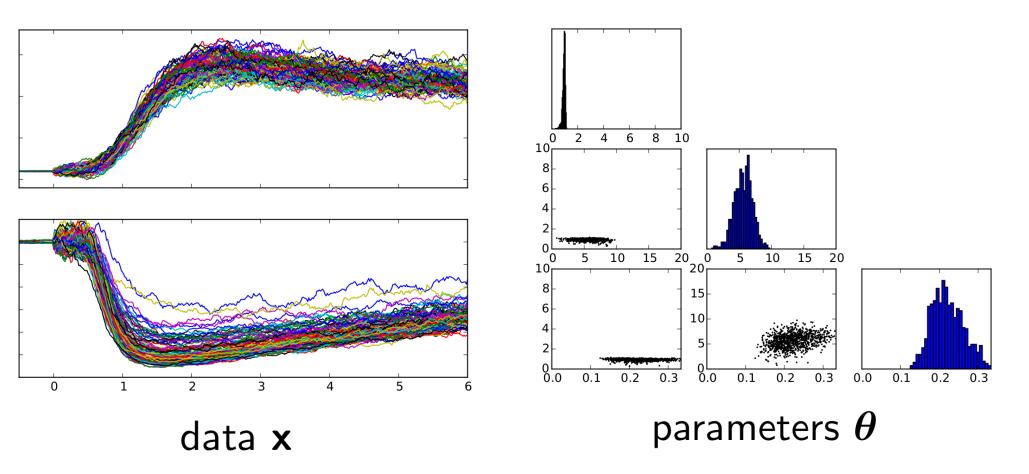


— Modeling posteriors

— Modeling priors

— Modeling likelihoods

Surrogate modeling / emulation



$$p(\theta \mid \mathcal{D}) \propto p(\theta) \prod_{n} p(\mathbf{x}^{(n)} \mid \theta)$$

Cf Cranmer, Pavez, Louppe (2016) arXiv:1506.02169

Thanks!

http://iainmurray.net

NADE variants, MADE, and MAF ϵ -free ABC, pseudo-marginal slice sampling