Algo dec_21

Introduction

Suppose we are given a problem

$$\exists_X \phi(X, \overline{X}) \land \alpha(\overline{X}) = [\exists_X \phi(X, \overline{X})] \land \alpha(\overline{X})$$

Where ϕ and α are in CNF, and X and \overline{X} are disjoint sets of variables.

Since α does not depend on X, it can actually be removed from the problem. We might still decide to use it while running the factor graph algorithm, since adding more factors can only give tighter results, but it's not necessary, so let's ignore it for now.

Suppose running the factor graph algorithm gives us $\phi'(\overline{X})$

The solution is strictly an over-approximation if there are solutions to:

$$\phi'(\overline{X}) \land \neg \exists_X \phi(X, \overline{X}) = \phi'(\overline{X}) \land \forall_X \neg \phi(X, \overline{X})$$

i.e., there exists an \overline{X} , say \overline{a} , such that \overline{a} satisfies the factor graph solution $\phi'(\overline{X})$, and makes the original problem ϕ unsat. This algorithm is based around the hunt for such \overline{a} assignments, and using them to make our solution tighter.

Using \bar{a} to get better solutions

One way to ensure that the factor graph solution $\phi'(\overline{X})$ is not satisfied by \overline{a} is simply to introduce $\neg \overline{a}$ as a factor before running the algorithm. Also note that $\neg \overline{a}$ is a disjunction of literals, and therefore, can be added as a CNF clause to the original formula. And because it does not contain any variables from \overline{X} , it should be included into $\alpha(\overline{X})$ instead of $\phi(X, \overline{X})$.

Searching for \bar{a}

Let's look at $\phi(X,\overline{a})$. This is the same as $\phi(X,\overline{X})$, but with some clauses removed, and some clauses shorter (without the \overline{X} variables). Also look at another formula $\psi(X)$, which was created by removing all the non quantified variables \overline{X} from $\phi(X,\overline{X})$. (Note that each clause in ϕ has at least one variable from X). $\psi(X)$ is the same as $\phi(X,\overline{a})$, but it might also have a few extra clauses which were removed by \overline{a} . Therefore,

$$\psi(X) \Rightarrow \phi(X, \overline{a})$$

And therefore, in order for $\phi(X, \bar{a})$ to be unsat, $\psi(X)$ must also be unsat, and therefore, $\psi(X)$ must have some minimal unsat cores (MUC) $\mu_1, \mu_2 \dots \mu_m$.

Furthermore, because the clauses in of $\phi(X, \overline{a})$ are a subset of the clauses of $\psi(X)$, the set of MUCs of $\phi(X, \overline{a})$ must be a subset of the MUCs of $\psi(X)$.

Therefore, the following problem:

Find \bar{a} such that $\phi(X,\bar{a})$ is unsat, and $\phi'(\bar{a})$ is not \perp .

is now reduced to a simpler problem:

Assignment driven search: Find \overline{a} such that applying it to \overline{X} in $\phi(X, \overline{X})$ generates/preserves one or more MUCs of $\psi(X)$ and $\phi'(\overline{a}) = \top$.

or equivalently:

MUC driven search: For each MUC μ of $\psi(X)$, check whether it is possible to find an assignment \overline{a} of \overline{X} in $\phi(X, \overline{X})$ such that the clauses in μ are preserved, and $\phi'(\overline{a}) = \top$.

The following two sections explore these two techniques.

Assignment driven search

Find \overline{a} such that applying it to \overline{X} in $\phi(X, \overline{X})$ generates/preserves one or more MUCs of $\psi(X)$ and $\phi'(\overline{a}) = \top$.

Let us look at how an assignment $\overline{a} = l_1 \wedge l_2 \wedge ... \wedge l_N$ affects $\phi(X, \overline{X}) = D_1 \wedge D_2 \wedge ... \wedge D_M$. Each disjunctive clause D_i either:

• Disappears, if it contains *any* of the l_i literals.

or:

• Otherwise (if it does not have any l_i literals), it loses all the $\neg l_i$ literals it might have.

Furthermore, each clause C_k in $\psi(X) = C_1 \wedge C_2 \wedge ... \wedge C_M$ comes from a corresponding D_k in $\phi(X, \overline{X})$ that has all the literals from C_k , plus some literals on the variables in \overline{X} , and C_k would be preserved as a clause in $\phi(X, \overline{a})$ if and only if C_k does not have the negation of any literals from \overline{a} .

Therefore, if two clauses C_j and C_k in $\psi(X)$ have opposite signs of some literal l, then at most one of the clauses can be preserved in any given assignment \overline{a} . (Suppose C_j contains l and suppresses l and l

Therefore, if we create an undirected graph G:

- whose nodes are the clauses D_i in $\phi(X, \overline{X})$,
- and two nodes D_j and D_k are connected by an edge if and only if they have opposite literals on some variable in \overline{X} , then each

then each assignment \bar{a} will preserve a set of clauses C_i whose corresponding set of clauses D_i will create an independent subset of this graph.

Furthermore, since our objective is to look for assignments that preserve MUCs, we can make sure we do not miss any MUCs by looking at all maximal independent subsets. Therefore, the algorithm now becomes:

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1. Create the graph \,G\, as described above.
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- 2. For every maximal independent set I:
- 3. Find the corresponding subset S_I of clauses from $\psi(X)$
- 4. Check if S_I is un-satisfiable

MUC driven search

The disadvantage with an assignment driven search from the previous section is that there might be intersecting independent subsets generated by the algorithm, causing the algorithm to redundantly look for MUCs in those intersecting sets multiple times. Another approach would be to instead generate MUCs and then check if they form an independent subset.

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1. For every MUC \,\mu\, of \,\psi(X) :
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- 2. Find the corresponding set σ_u of nodes in G
- 3. Check if σ_u forms an independent set in G

This algorithm would not work well if $\psi(X)$ has many MUCs, and none of whose corresponding subset of nodes in G forms an independent subset.

Perhaps a better approach would be to look for a hybrid approach of the above two sections, which is MUC based, but avoids generating/exploring an MUC unless the corresponding set of nodes forms an independent subset.