

nanort::BVHAccel< vertex  
\_t >::ListNodeIntersections

nanort::BVHAccel< vertex  
\_t >::Traverse

nanort::vsafe\_inverse

```
graph LR; A[nanort::BVHAccel< vertex_t >::ListNodeIntersections] --> C[nanort::vsafe_inverse]; B[nanort::BVHAccel< vertex_t >::Traverse] --> C;
```

The diagram illustrates a mapping or reduction of two different BVH acceleration structure methods to a single, unified inverse safety check. On the left, two separate boxes represent the `ListNodeIntersections` and `Traverse` methods of the `nanort::BVHAccel` template class, parameterized with `vertex_t`. Blue arrows from both boxes point towards a single, shaded box on the right labeled `nanort::vsafe_inverse`, indicating that both methods rely on or utilize this common function.