

nanort::IntersectRayAABB
< double >

nanort::IntersectRayAABB
< float >

nanort::safemax

```
graph LR; A["nanort::IntersectRayAABB< double >"] --> C["nanort::safemax"]; B["nanort::IntersectRayAABB< float >"] --> C;
```

The diagram illustrates a common variable, `nanort::safemax`, which is referenced by two different function templates. The first template, `nanort::IntersectRayAABB< double >`, is shown in a white box with a black border. The second template, `nanort::IntersectRayAABB< float >`, is also in a white box with a black border. Both templates have a blue arrow pointing to the `nanort::safemax` variable, which is contained within a gray box with a black border. This suggests that `safemax` is a shared resource or a constant value used by both intersection functions.