

nanort::BVHAccel< vertex  
\_t >::ListNodeIntersections

nanort::BVHAccel< vertex  
\_t >::Traverse

nanort::vsafe\_inverse

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graph LR; A[nanort::BVHAccel< vertex_t >::ListNodeIntersections] --> C[nanort::vsafe_inverse]; B[nanort::BVHAccel< vertex_t >::Traverse] --> C;
```

The diagram illustrates a mapping or reduction of two different BVH acceleration structure methods to a single, unified inverse safety check. On the left, two separate boxes represent the 'ListNodeIntersections' and 'Traverse' methods of the 'nanort::BVHAccel' template. Arrows from both boxes point towards a single box on the right labeled 'nanort::vsafe\_inverse', indicating that both methods utilize or are handled by this common function.