

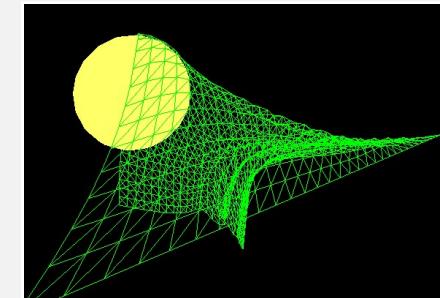
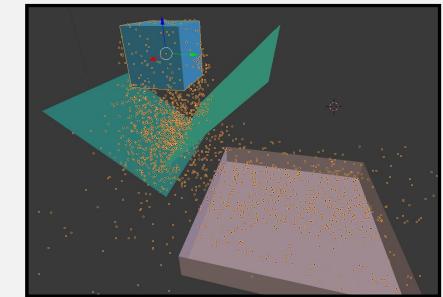
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## Animation



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Animation.pptx

mjb – August 10, 2020

## Animation

Rendering is the process of giving motion to your geometric modes. Before animating, there are questions you need to ask first:

- Why am I doing this?
- Do I want the animation to obey the real laws of physics?
- Am I willing to “fake” the physics to get the objects to *want* to move in a way that I tell it?
- Do I have specific key positions I want the objects to pass through no matter what?
- Do I want to simply record the motion of a real person, animal, etc., and then play it back?



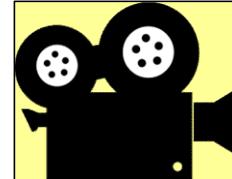
# Keyframe Animation

The image displays a 3D animation software interface, likely Blender, illustrating keyframe animation. On the left, the Dope Sheet and Outliner panels are visible. The Dope Sheet shows keyframes for various channels like LocRot, Location, and Euler Rotation across frames 0 to 250. A red circle highlights a specific keyframe at frame 66 for the LocRot channel. The 3D Viewport on the right shows a 3D scene with a character and a cube. Below the interface, a smaller window shows a camera icon with the text "anim2.mp4". A large black arrow points from the explanatory text box to this video thumbnail.

These icons refer to explanatory videos on the class web site

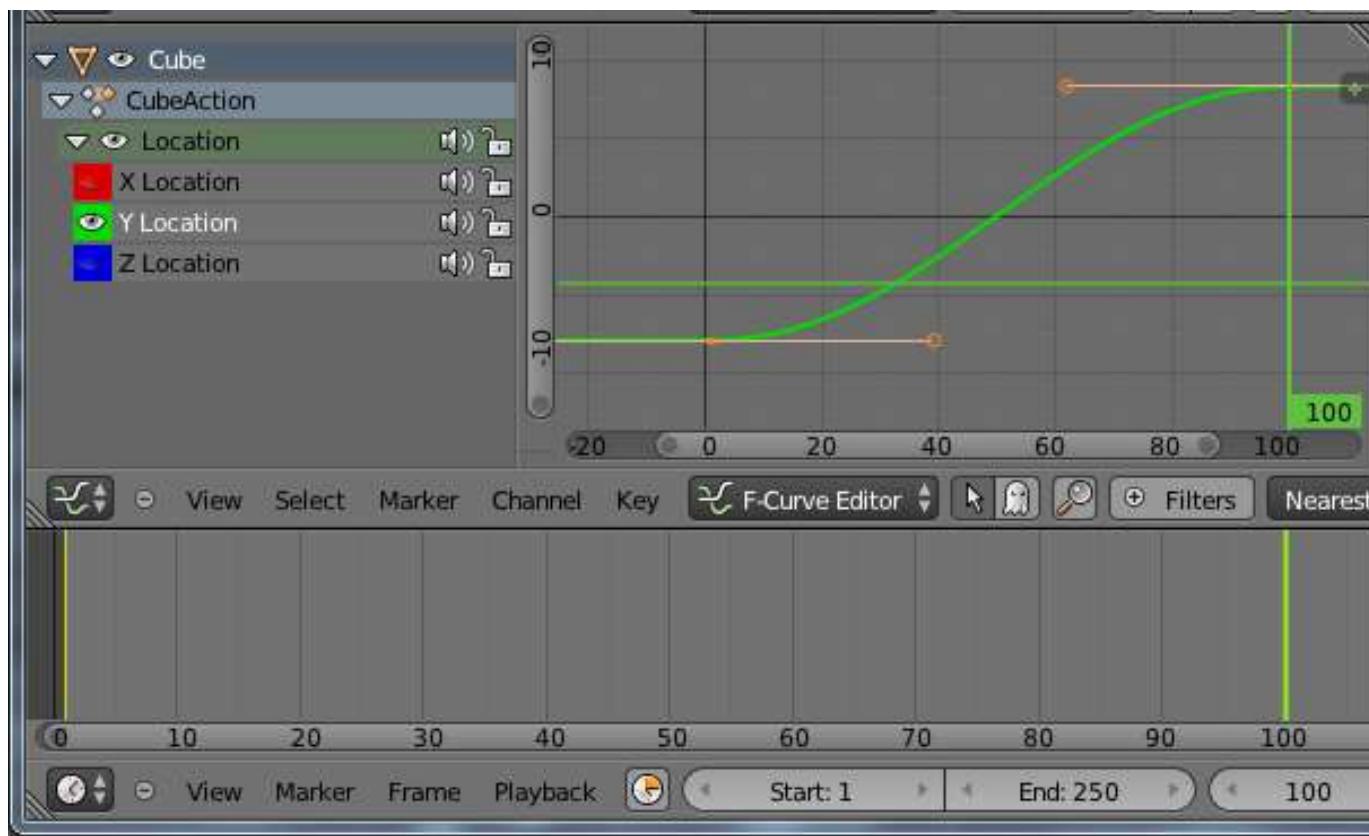
**anim2.mp4**

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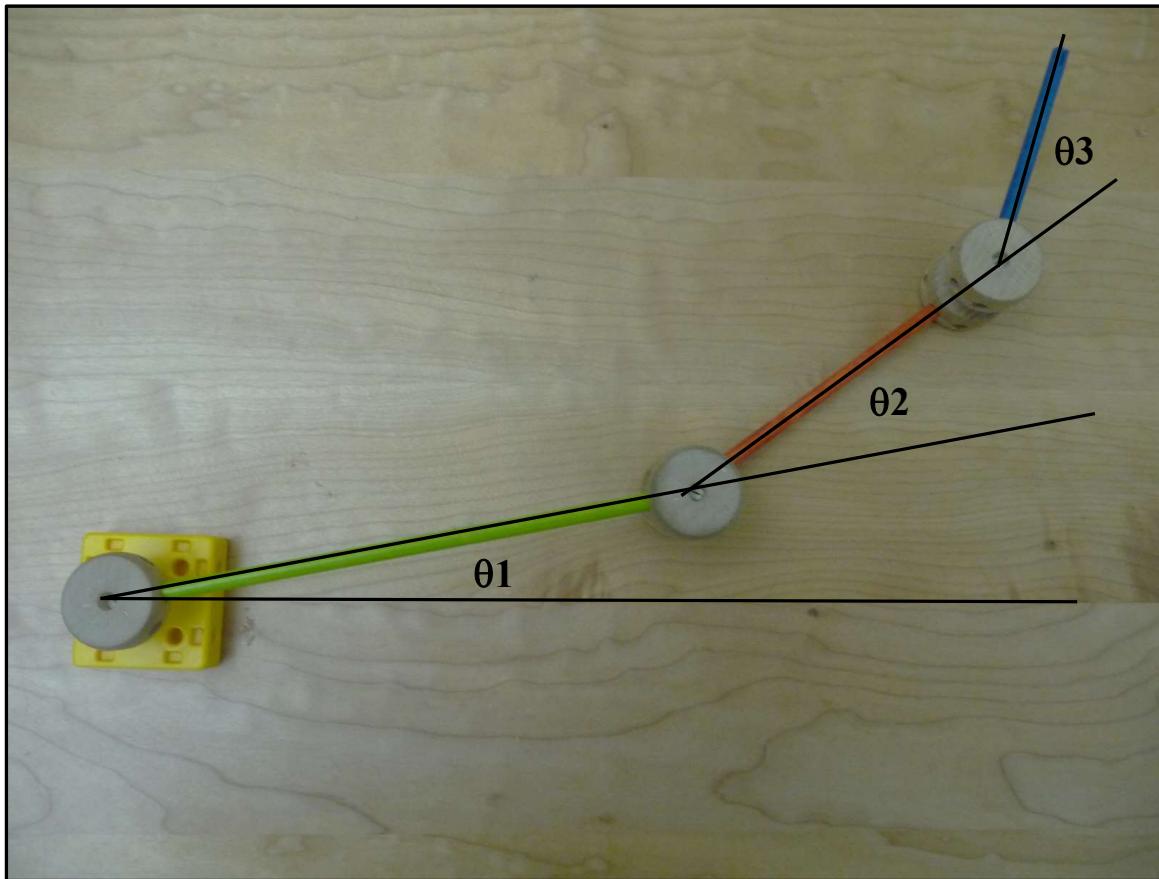


# Keyframe Animation

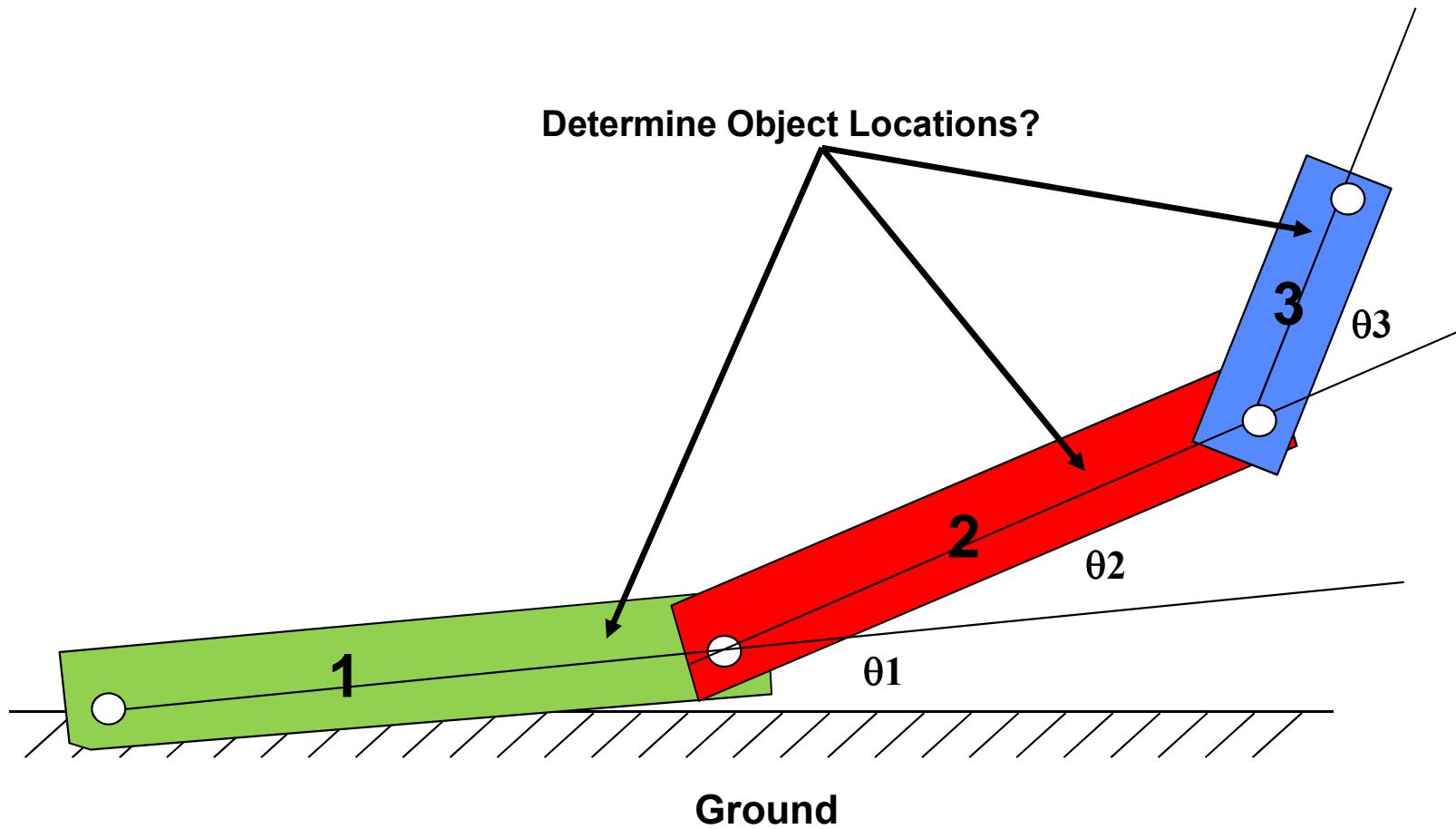
Blender:



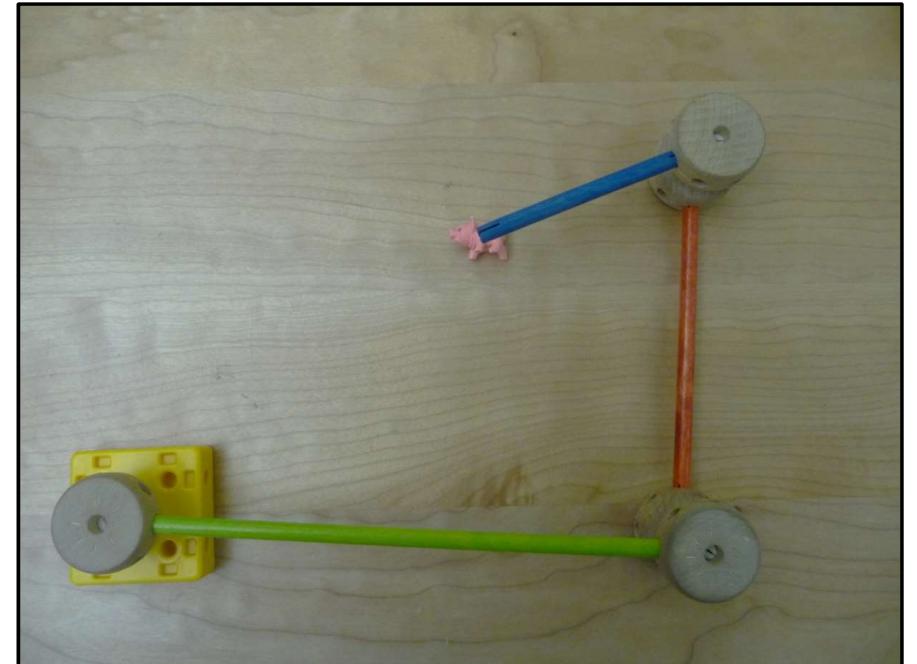
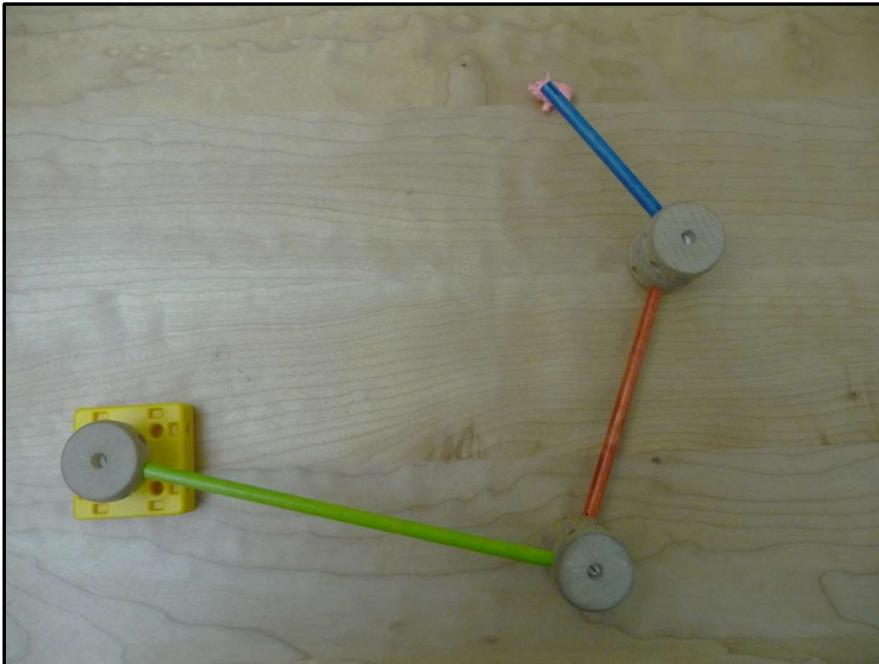
## Forward Kinematics: Change Parameters – Connected Things Move (All Tinker Toy users understand this)



## Forward Kinematics: Transformation Hierarchies



## Inverse Kinematics (IK): Things Need to Move to a Particular Location – What Parameters Will Make Them Do That?



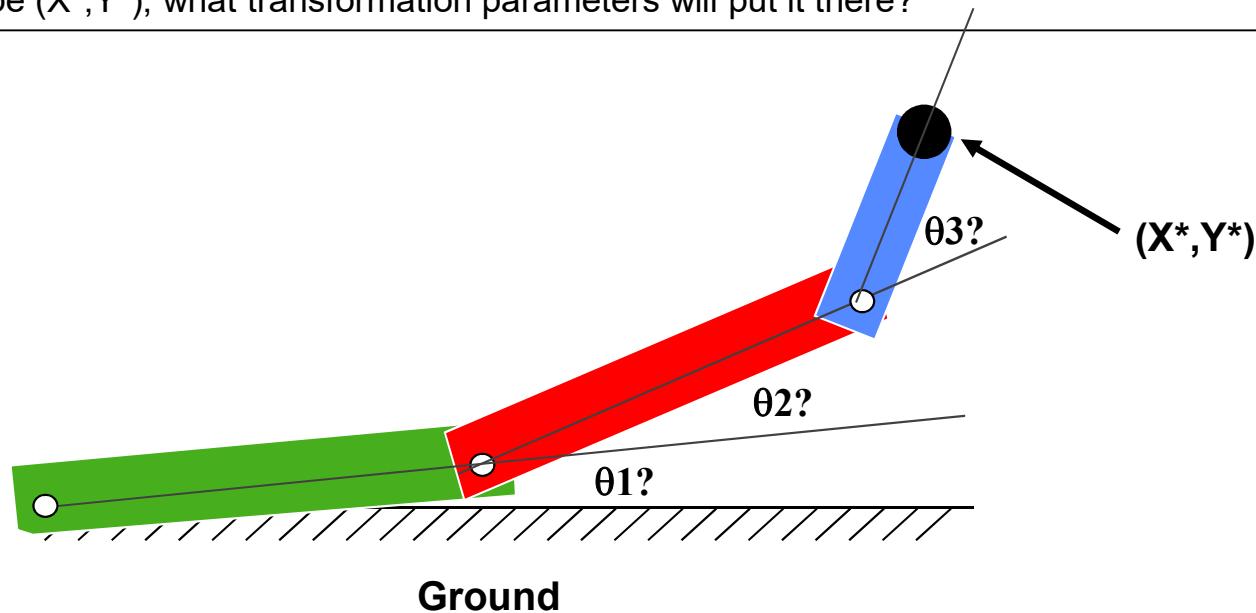
Of course, there will always be target locations that can *never* be reached.  
Think about that spot in the middle of your back that you can never scratch! ☺



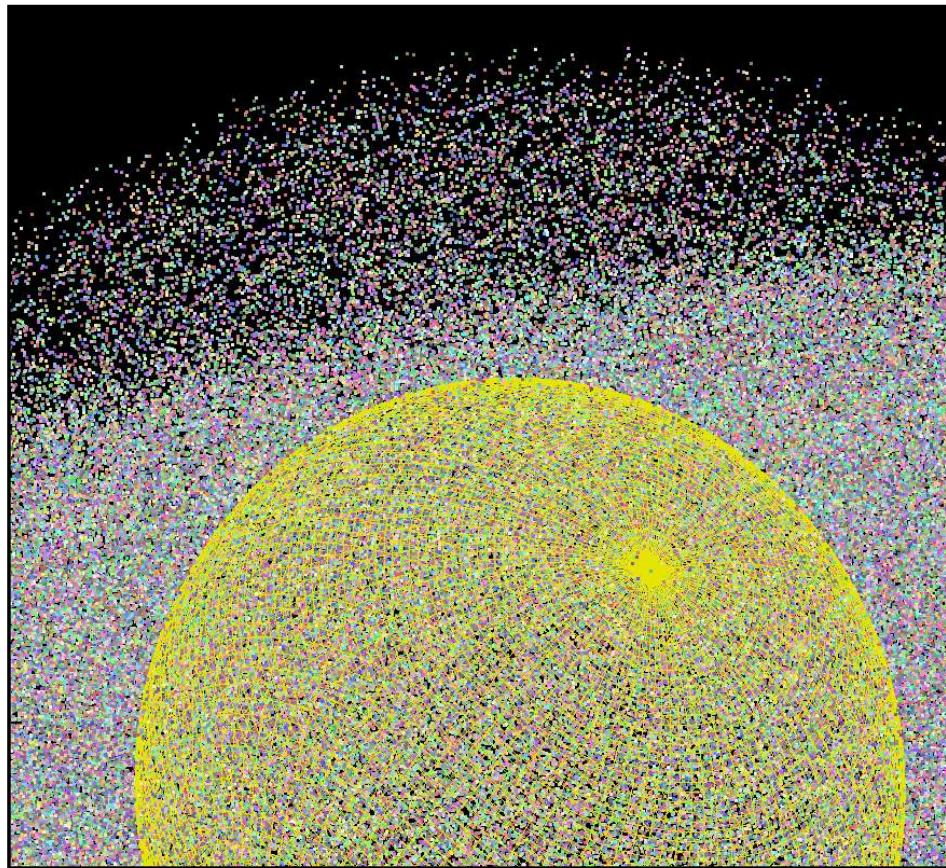
## Inverse Kinematics (IK)

**Forward Kinematics** solves the problem “if I know the link transformation parameters, where are the links?”.

**Inverse Kinematics (IK)** solves the problem “If I know where I want the end of the chain to be  $(X^*, Y^*)$ , what transformation parameters will put it there?”

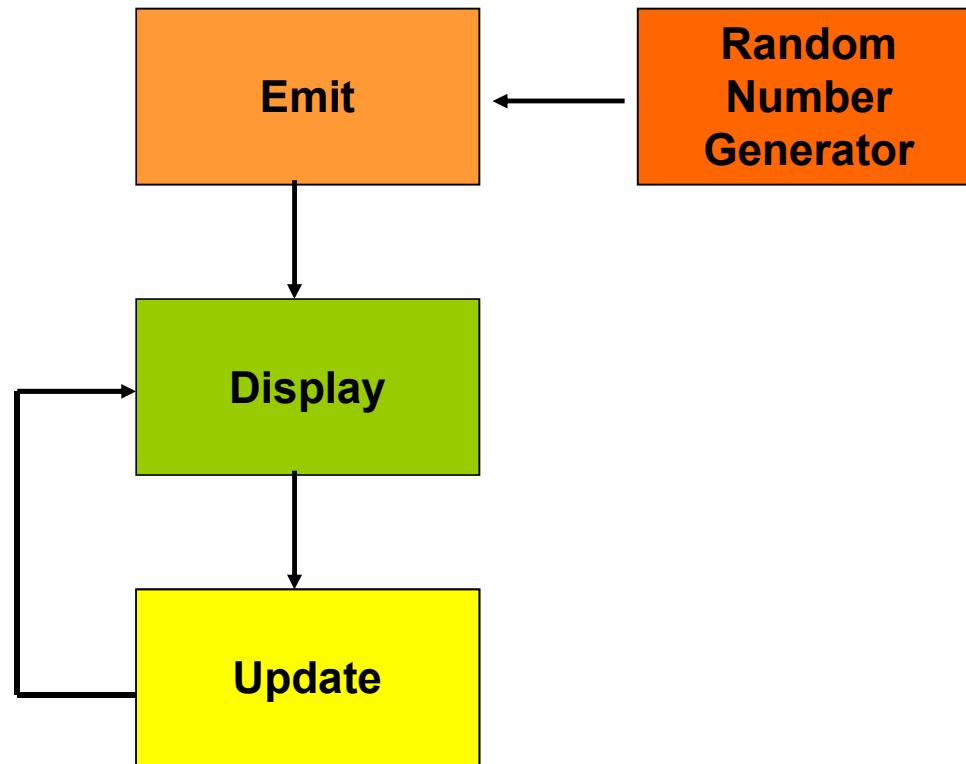


# Particle Systems: A Cross Between Modeling and Animation?

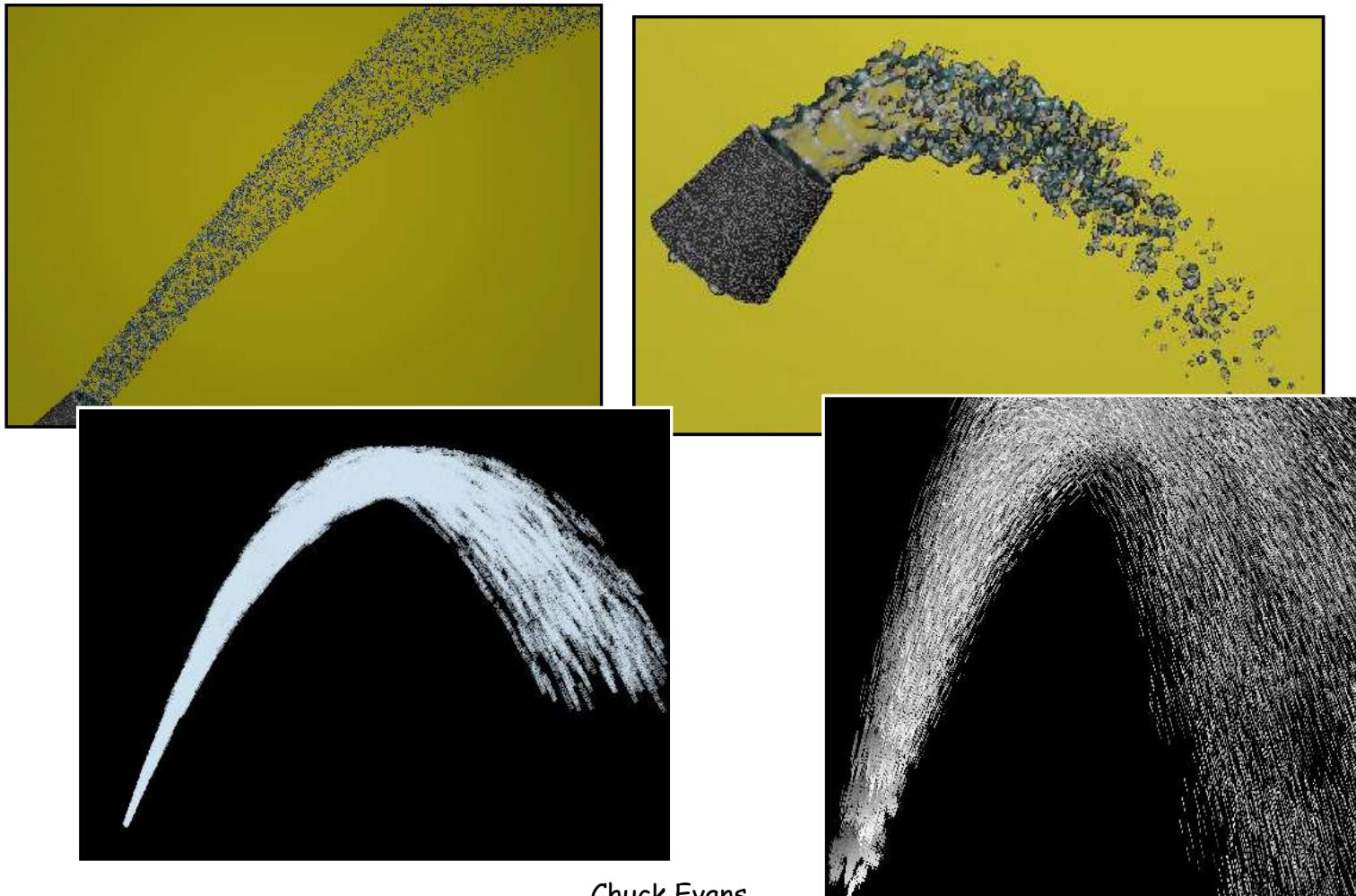


## Particle Systems: A Cross Between Modeling and Animation?

The basic process is:

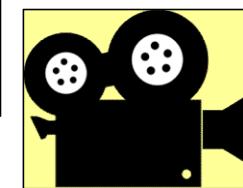
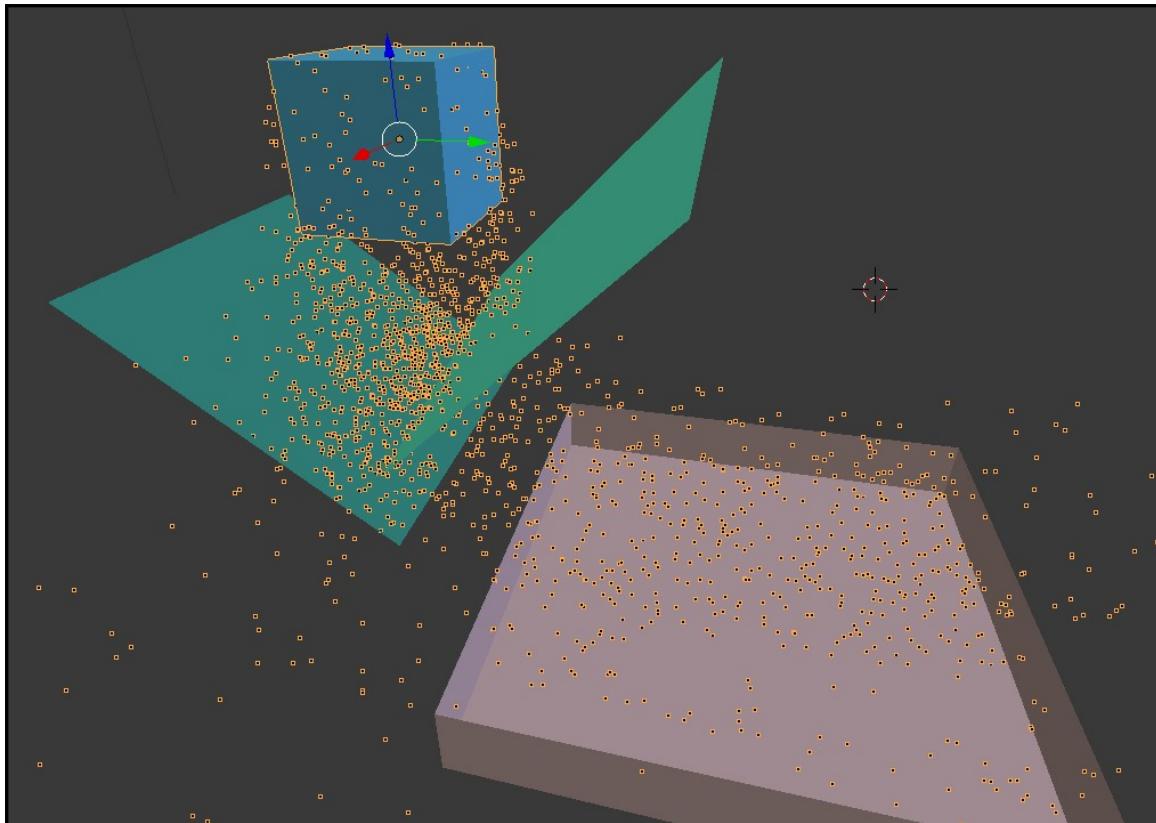


## Particle Systems Examples



Chuck Evans

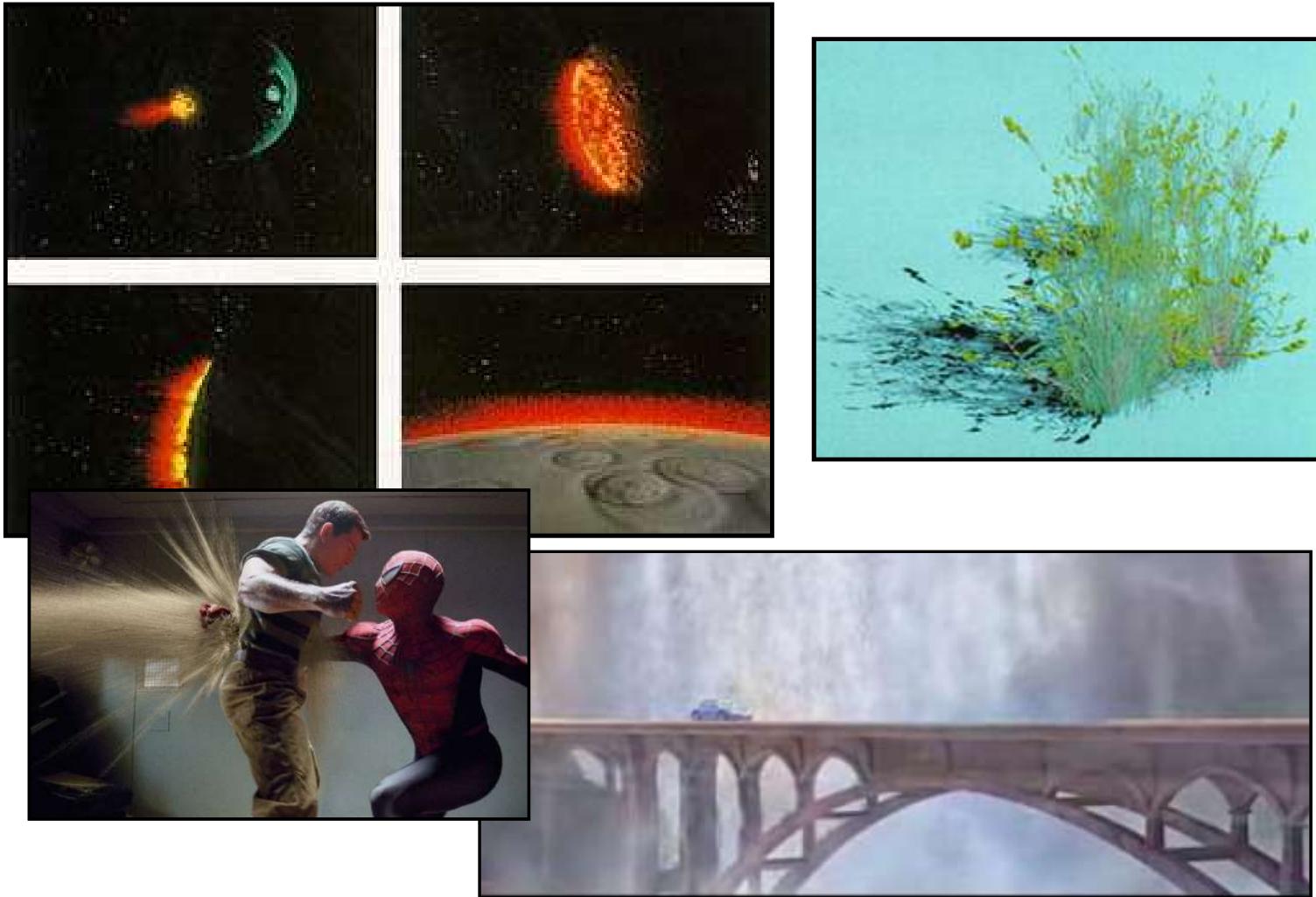
## Particle Systems Examples



particles.mp4



## Particle Systems Examples



## Particle Systems Examples



The Lion King (2019) -- Disney



## A Particle System to Simulate Colliding Galaxies in *Cosmic Voyage*

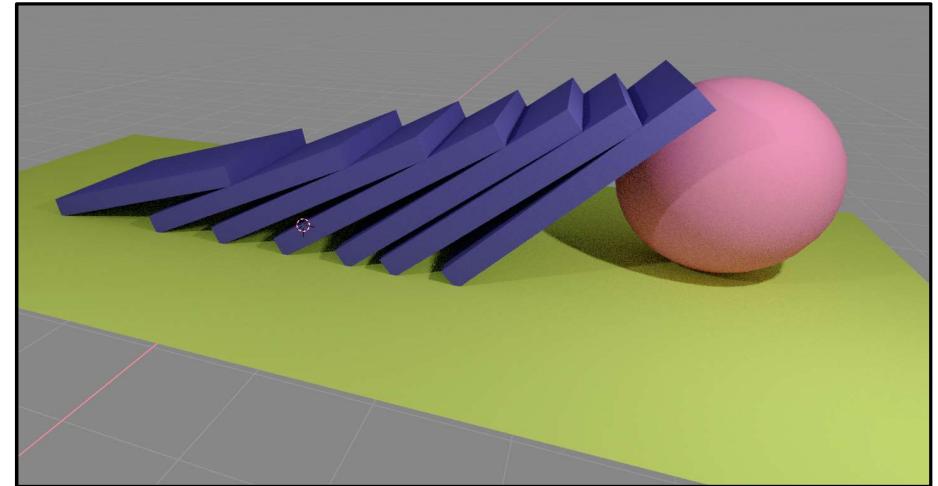
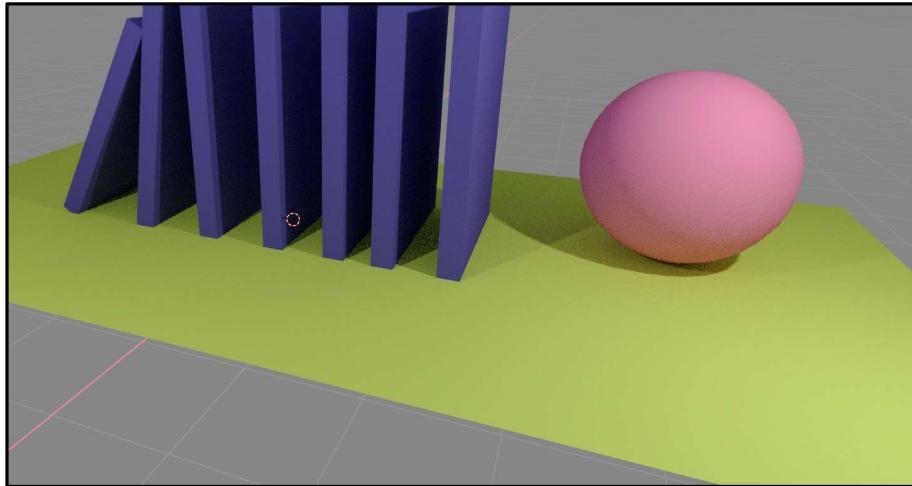


## Particles Don't Actually Have to Be "Particles"



## Animating using Rigid-body Physics

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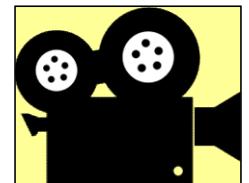


Newton's second law:

$$\text{force} = \text{mass} * \text{acceleration}$$

or

$$\text{acceleration} = \text{force} / \text{mass}$$



dominos.mp4

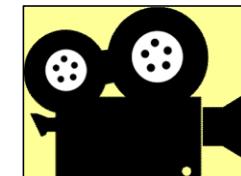
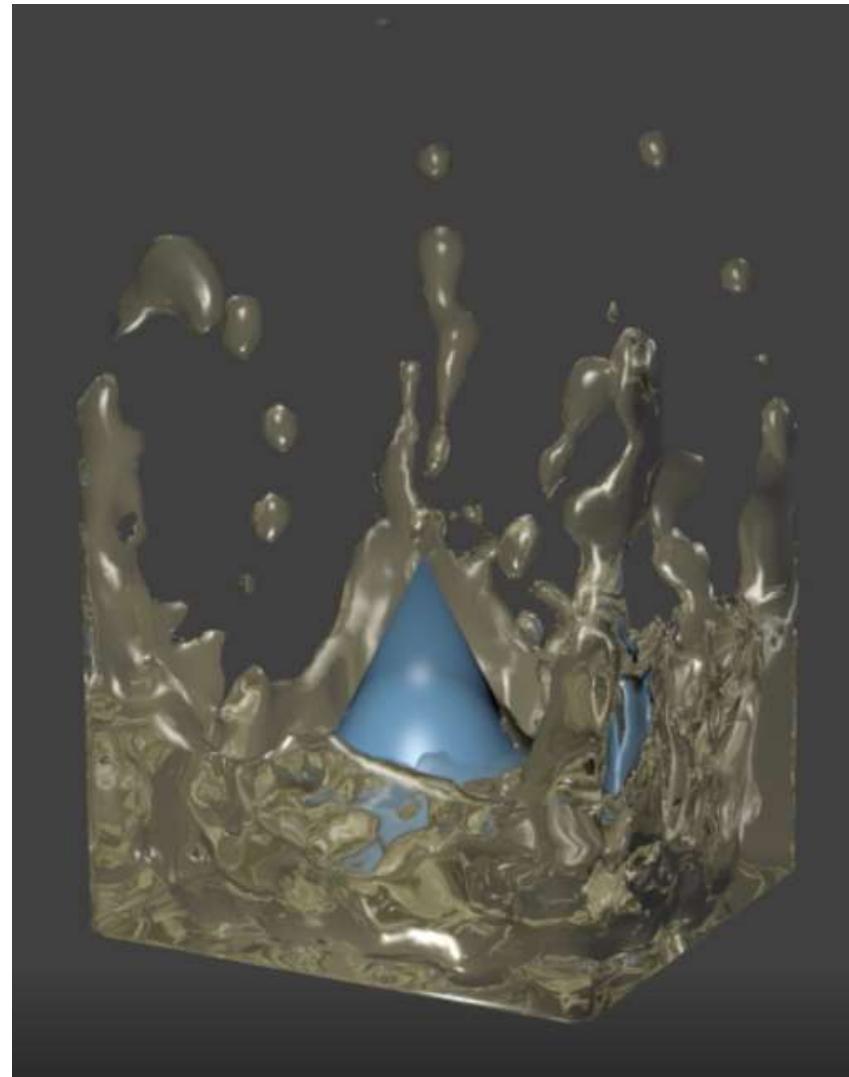
In order to make this work, you need to supply physical properties such as mass, center of mass, moment of inertia, coefficients of friction, coefficients of restitution, etc.



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## Animating using Fluid Physics

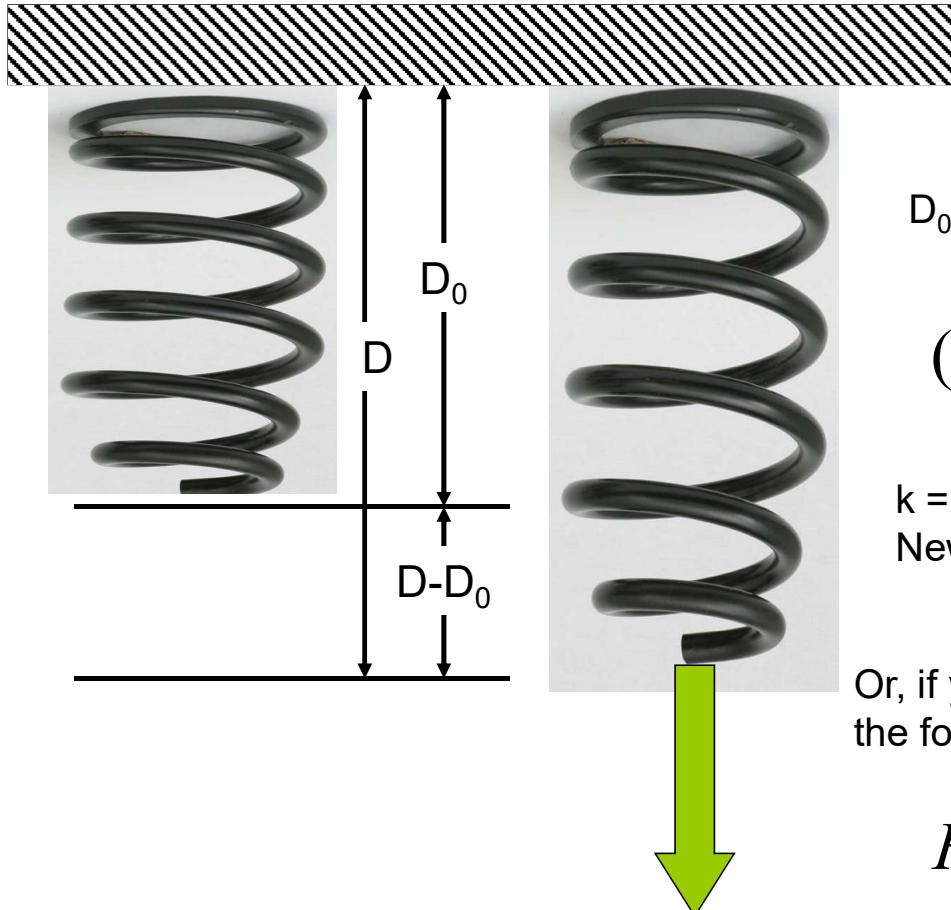


fluid.avi



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## Animating using Physics



$D_0$  = unloaded spring length

$$(D - D_0) = \frac{F}{k}$$

$k$  = **spring stiffness** in  
Newtons/meter or pounds/inch

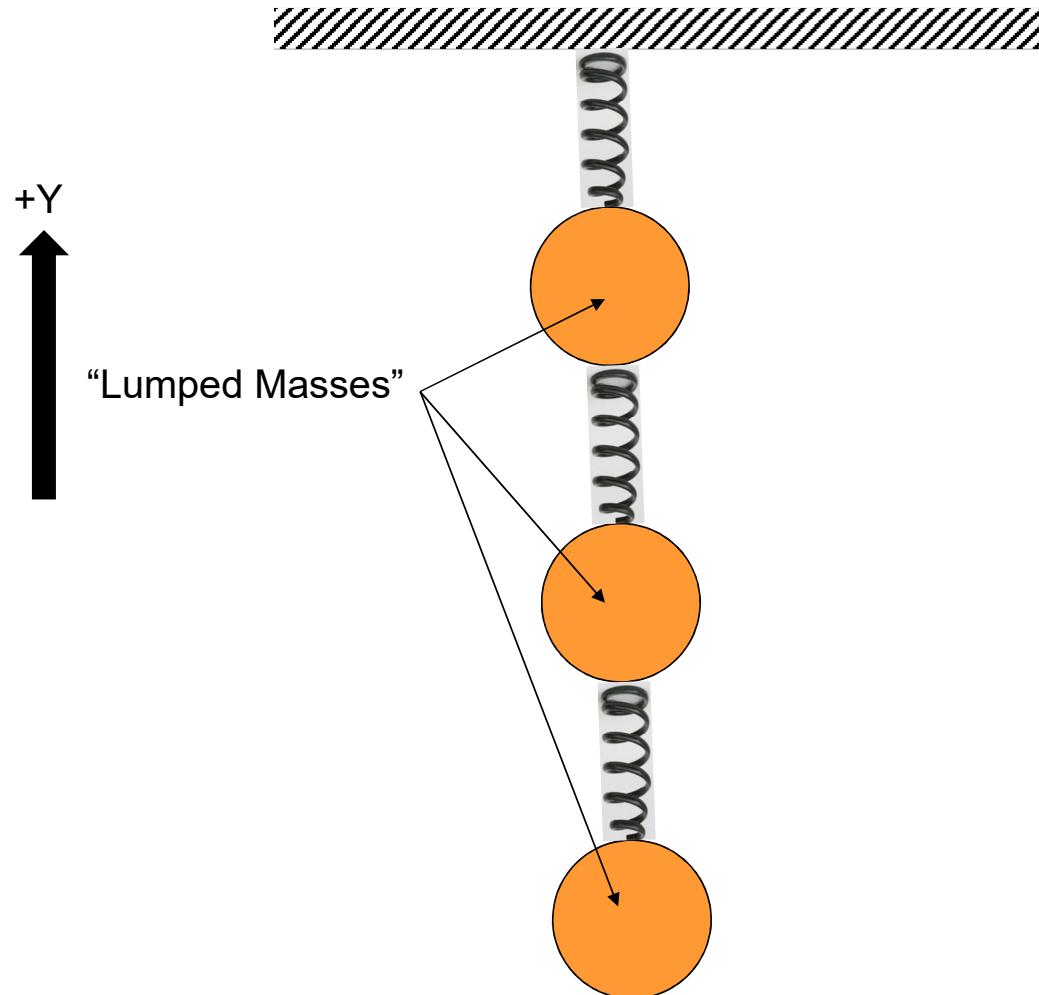
Or, if you know the displacement,  
the force exerted by the spring is:

$$F = k(D - D_0)$$

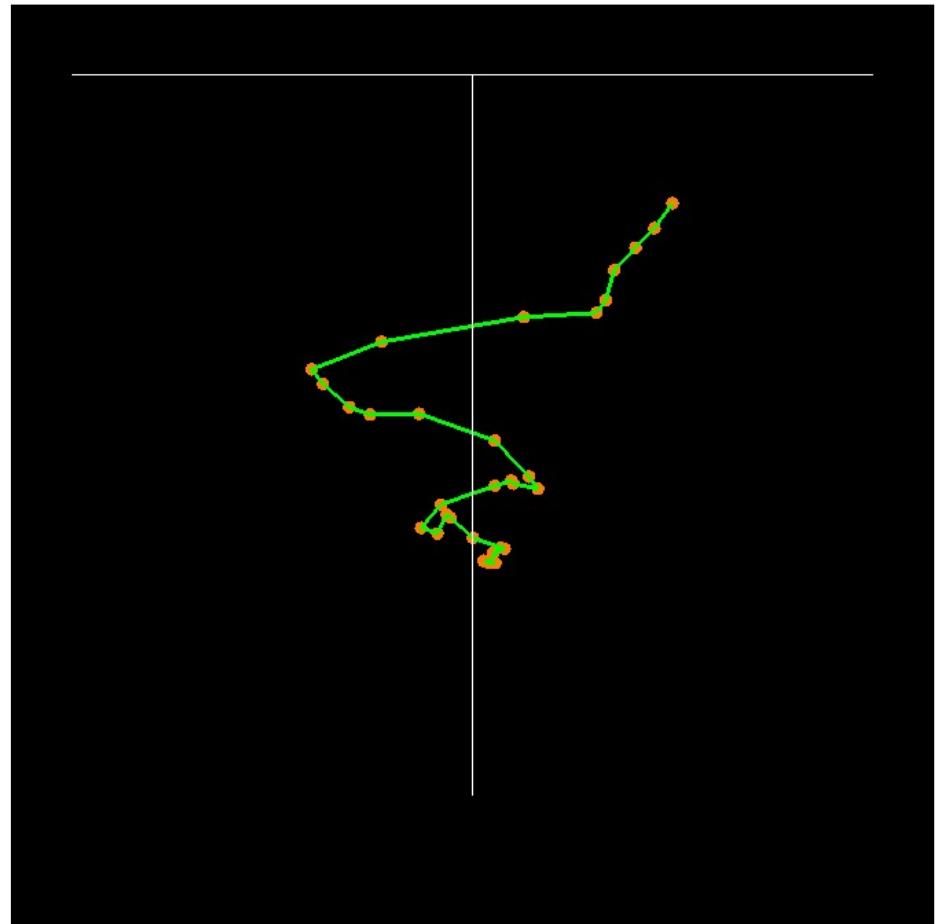
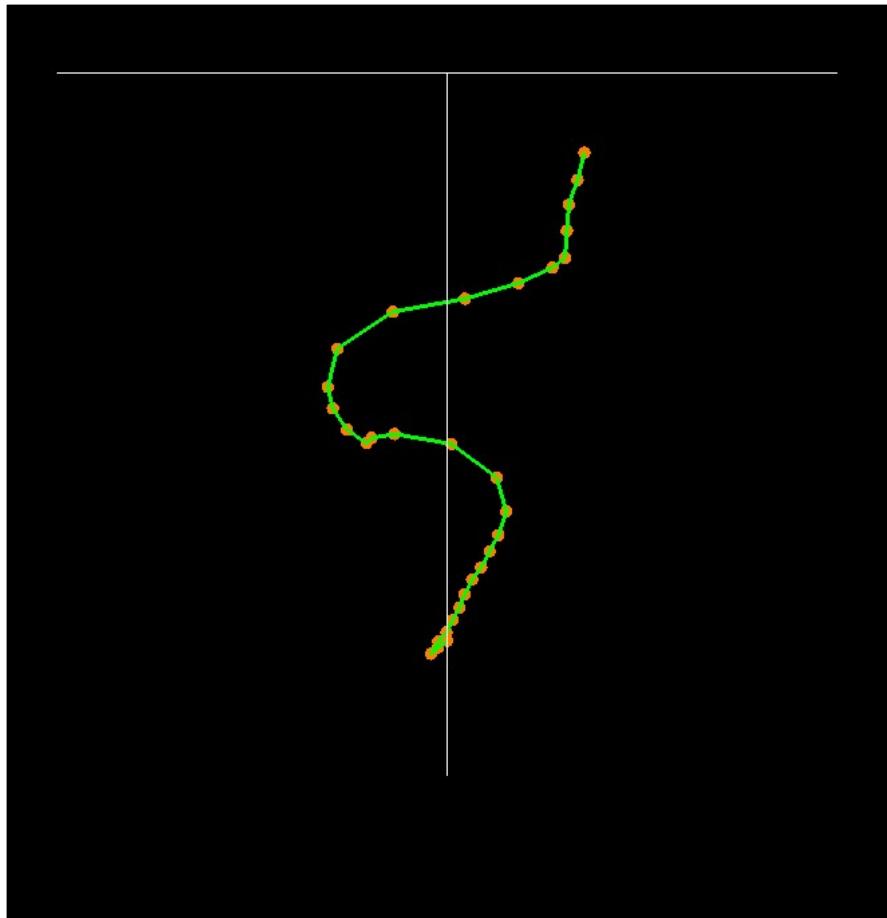
This is known as **Hooke's Law**

## Animating using the Physics of a Mesh of Springs

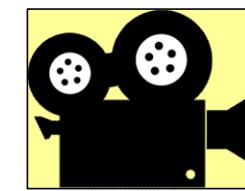
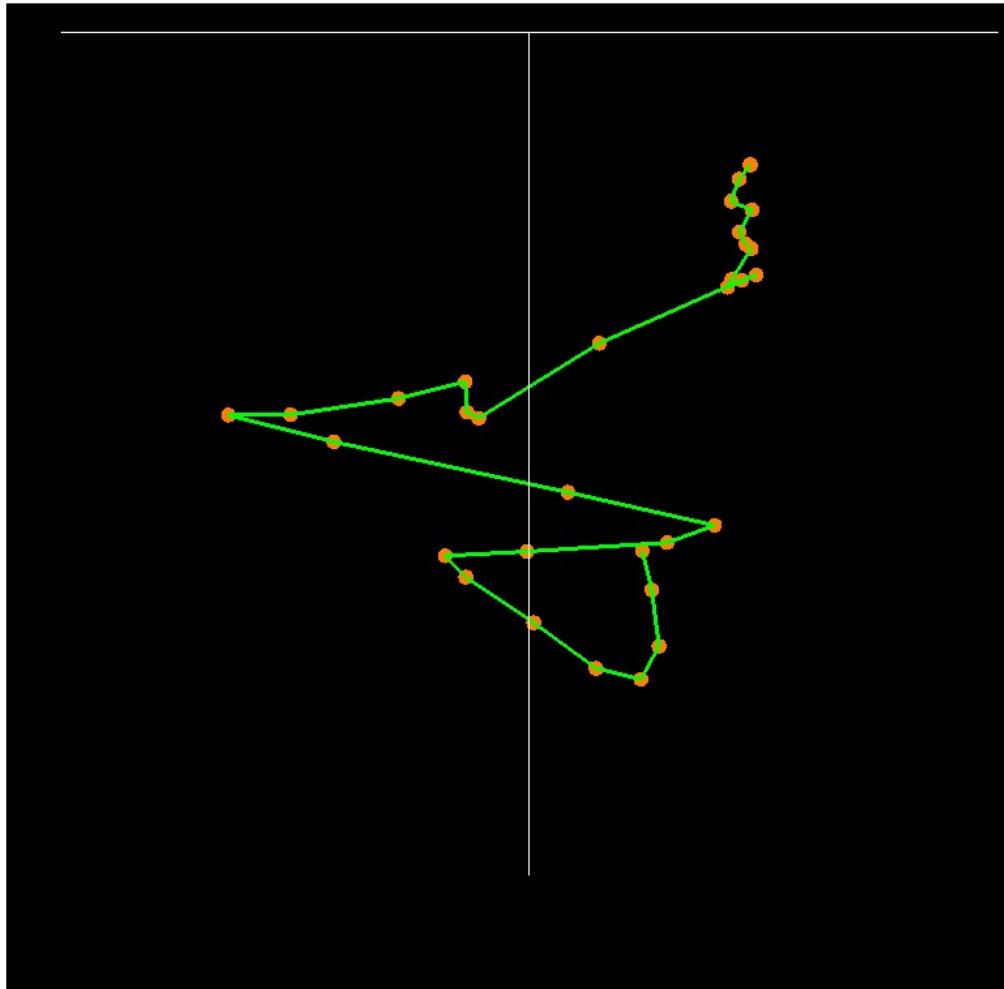
20



## Simulating a Bouncy String

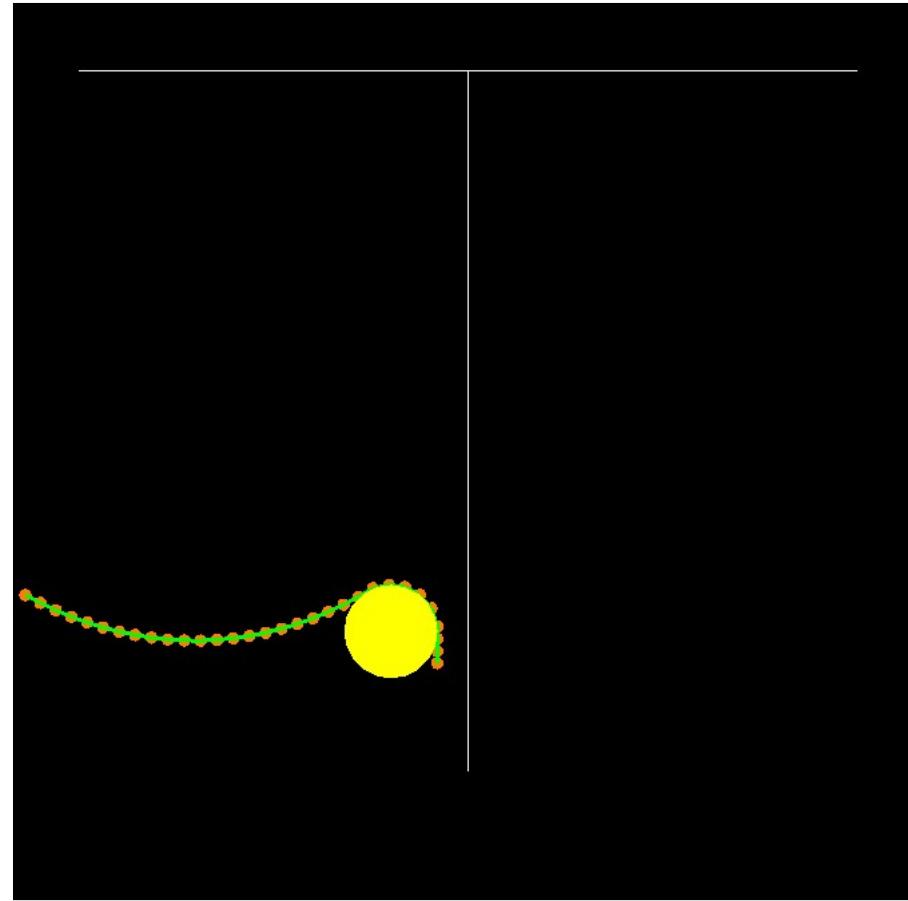
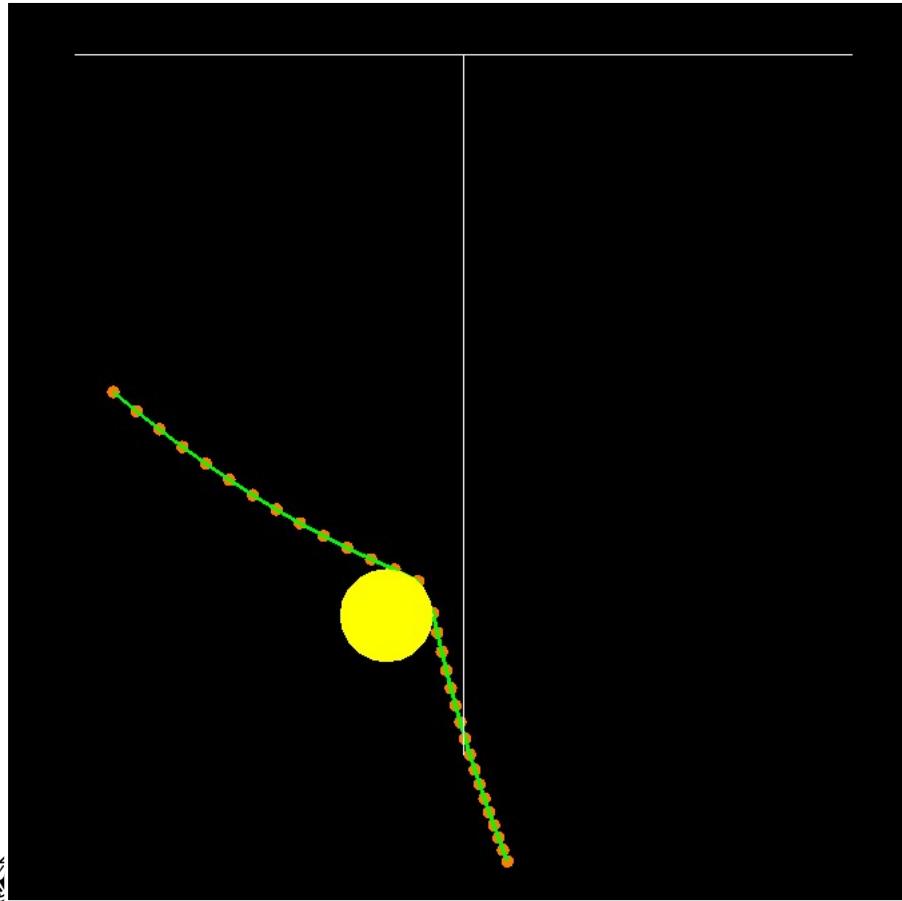


## Simulating a Bouncy String

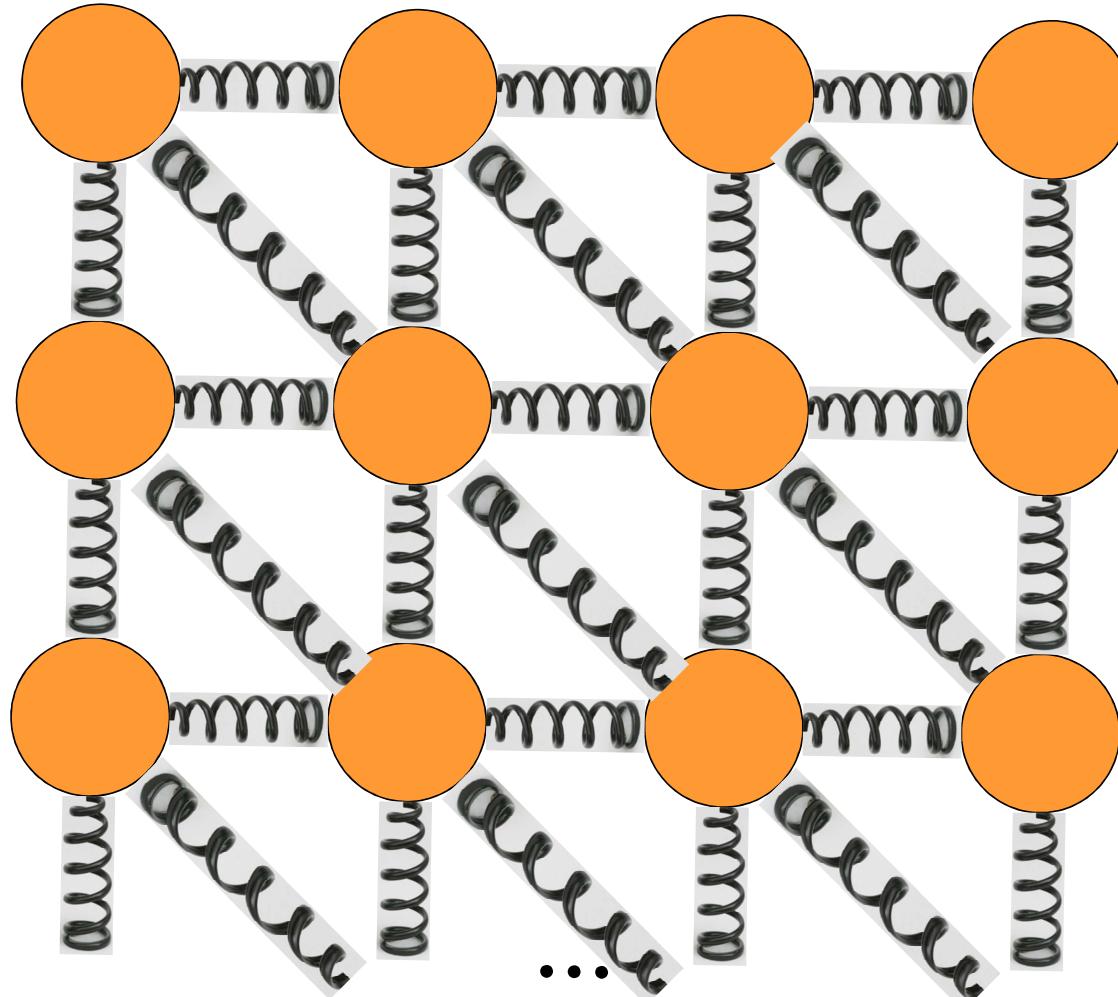


string.mp4

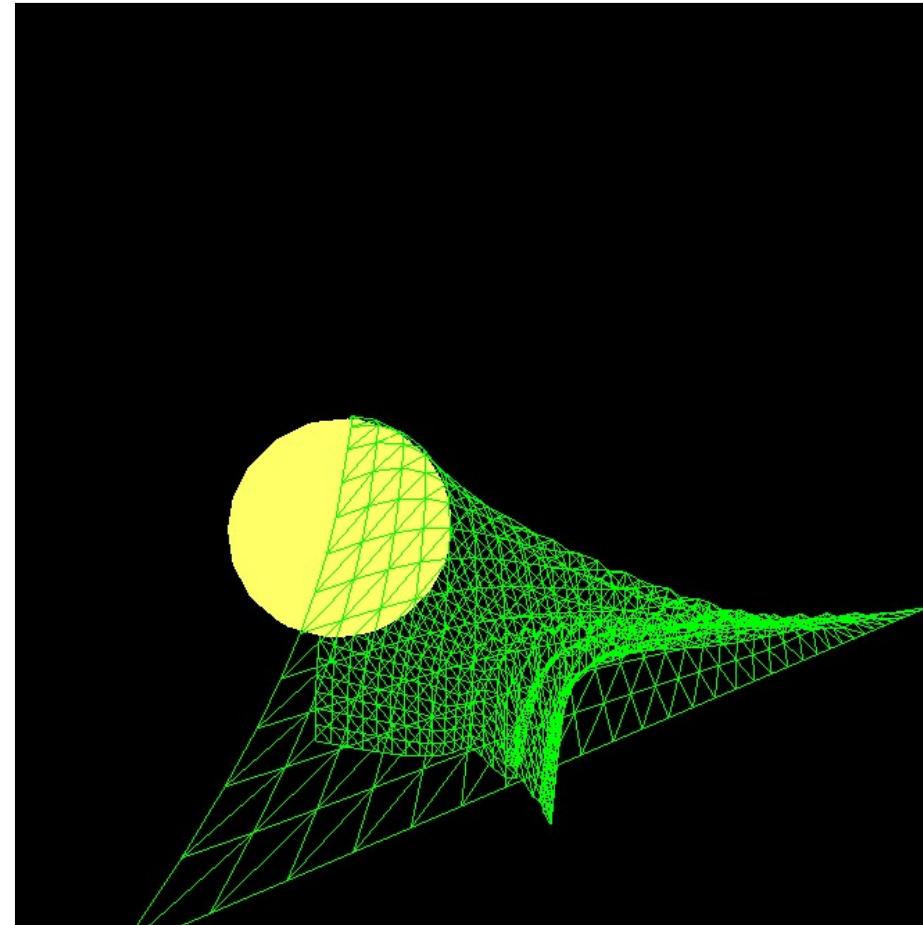
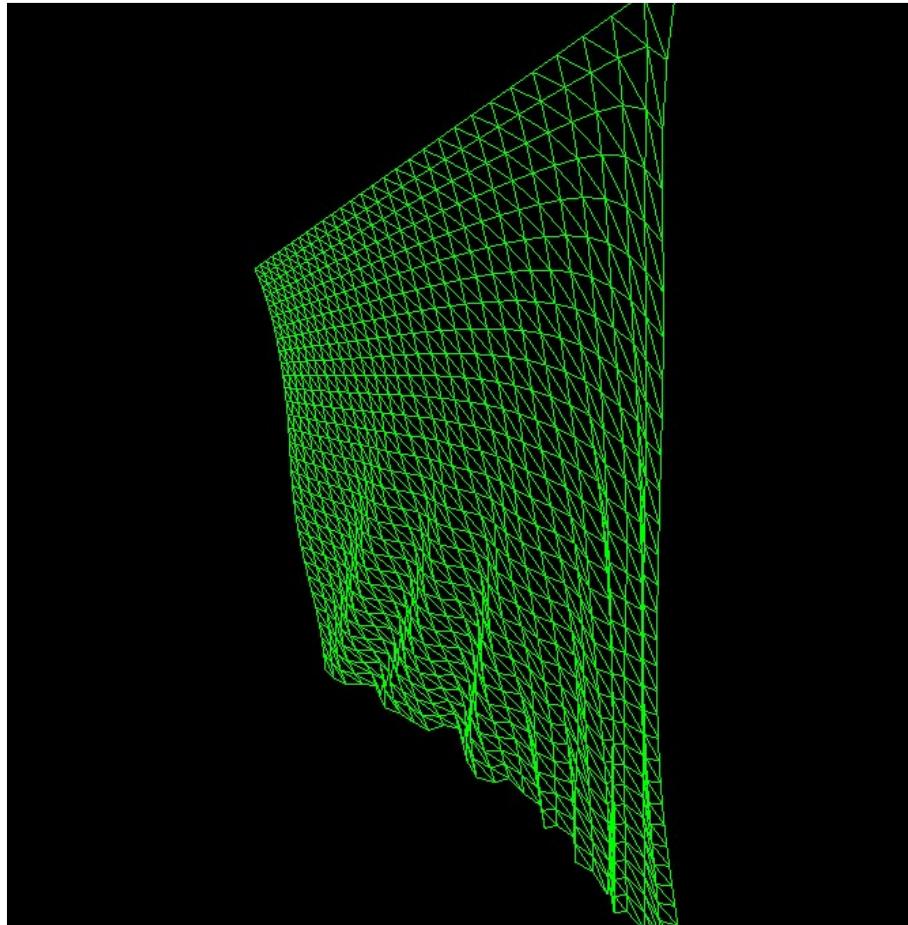
## Placing a Physical Barrier in the Scene



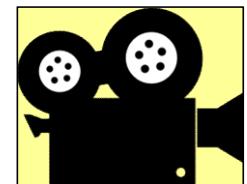
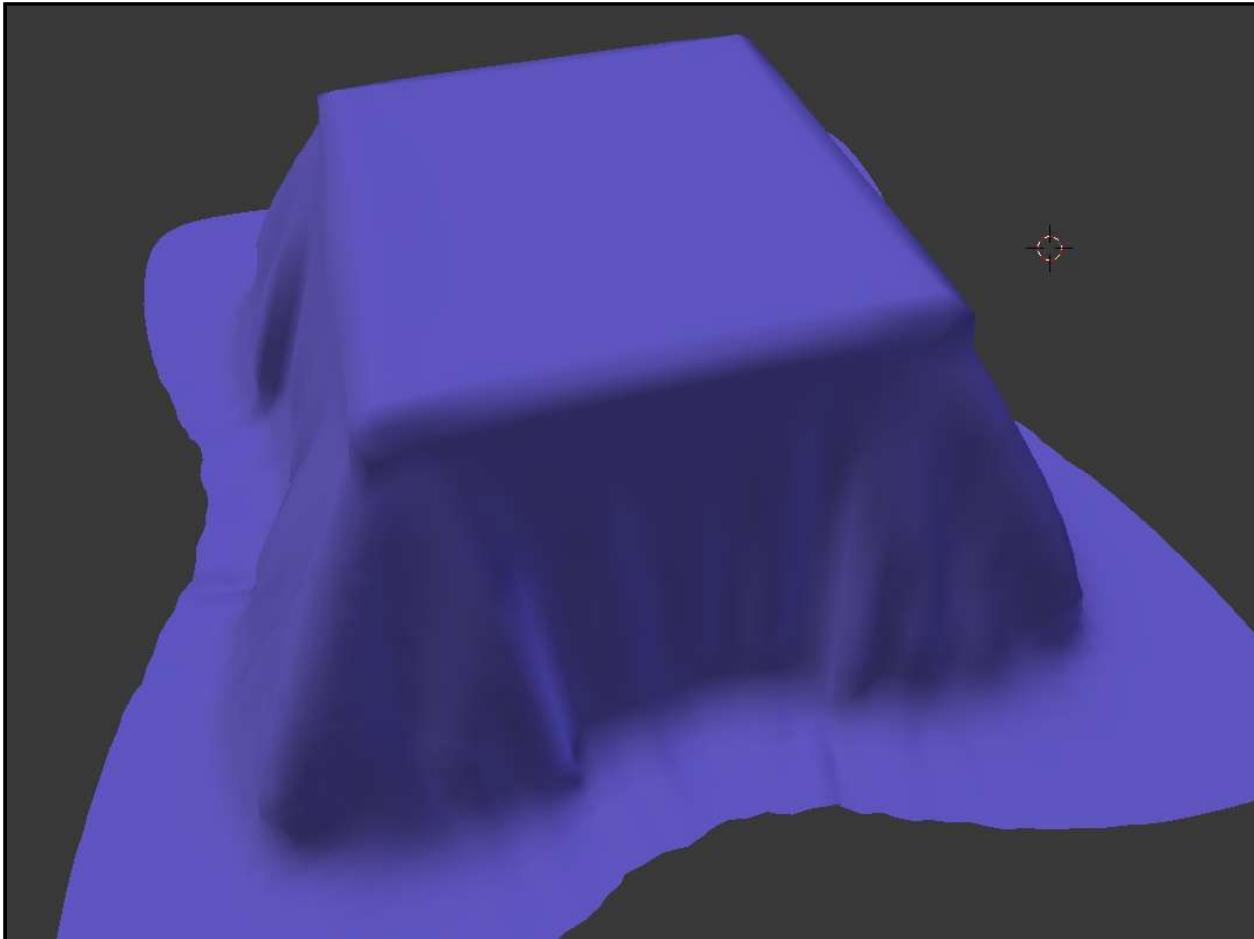
## Animating Cloth



## Cloth Examples



## Cloth Example

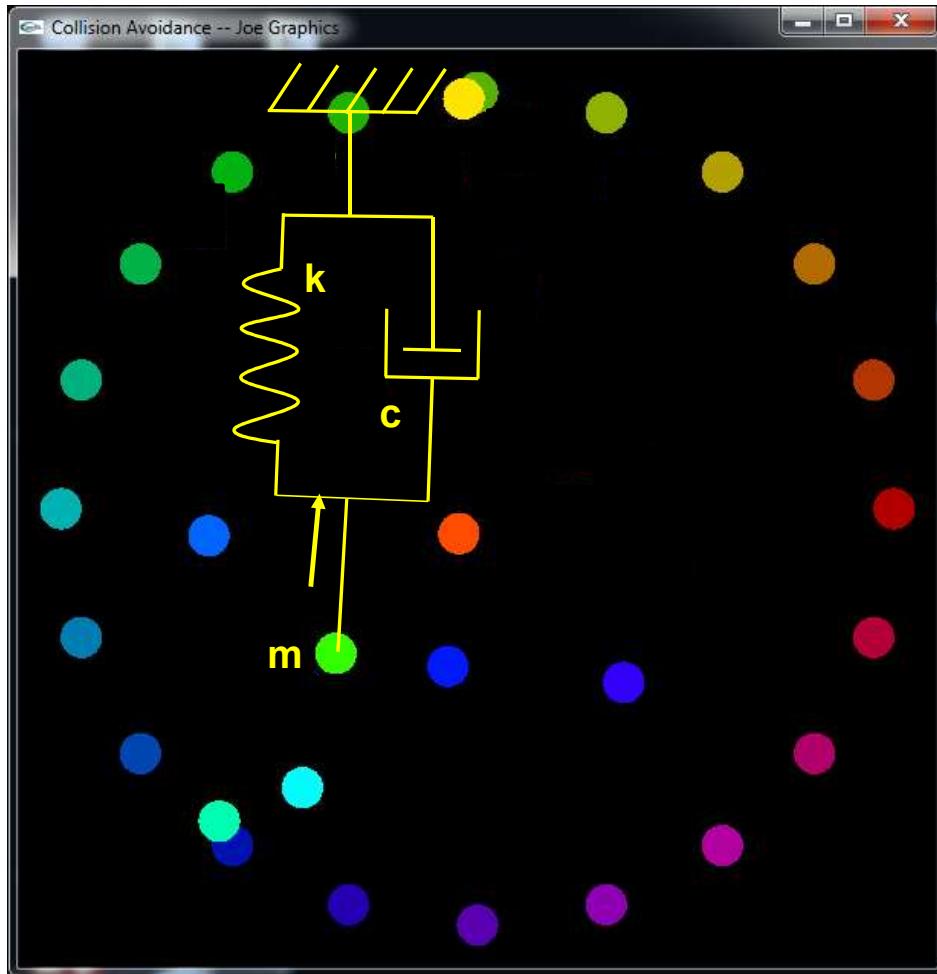


cloth.mp4

## Cloth Example



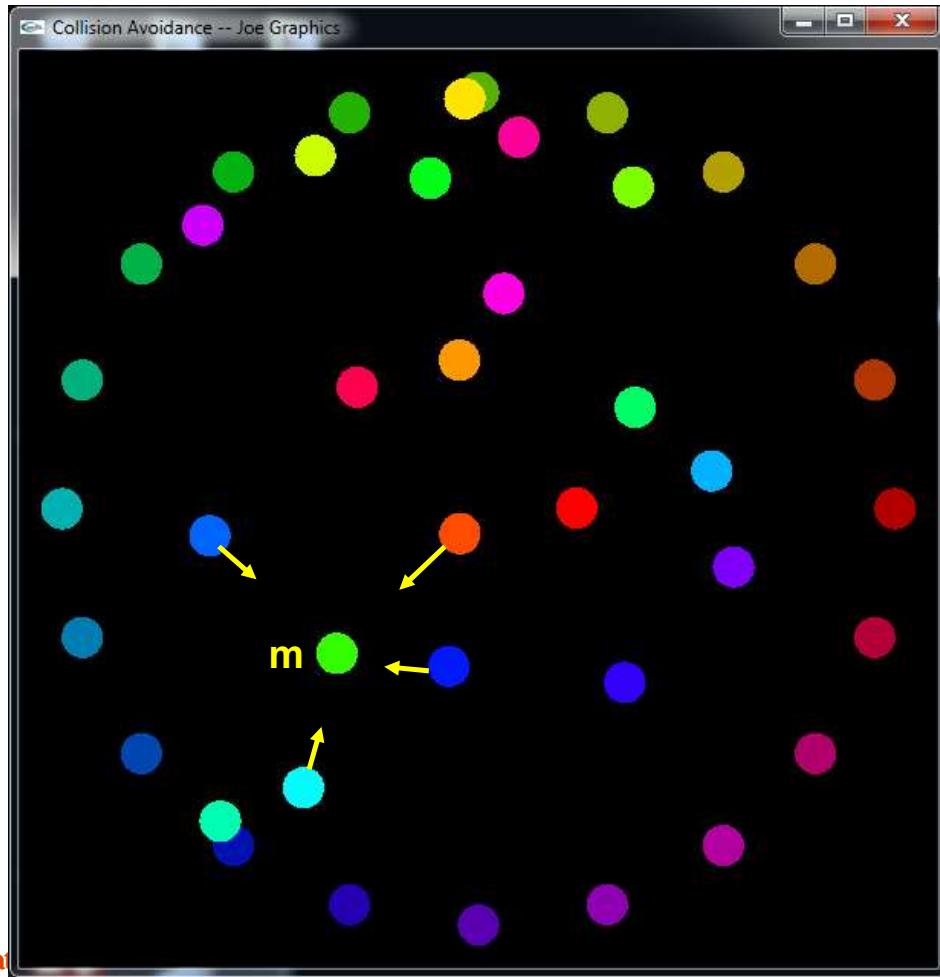
## Functional Animation: Make the Object Want to Move Towards a Goal Position



$$m\ddot{x} + c\dot{x} + kx = 0$$



## Functional Animation: While Making it Want to Move Away from all other Objects



$$m\ddot{x} = \sum F_{repulsive}$$

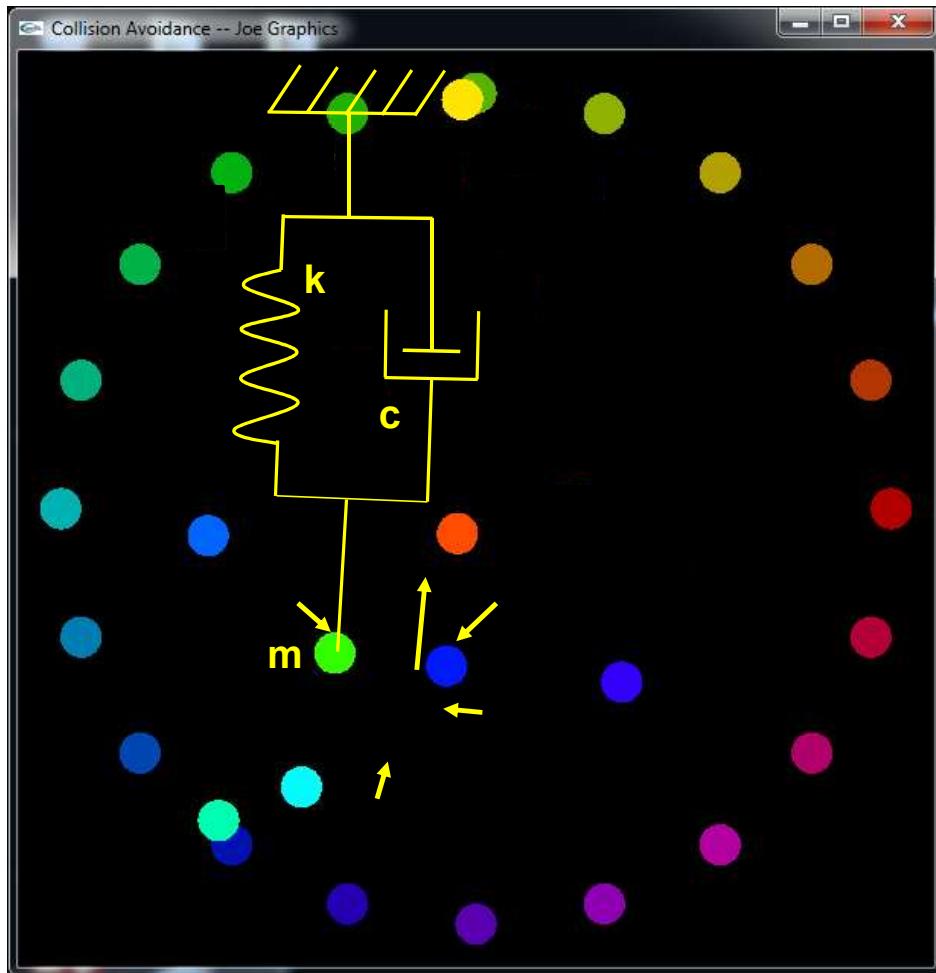
Repulsion Coefficient

$$F_{repulsive} = \frac{C_{repulse}}{d^{Power}}$$

Distance between the boundaries of the 2 bodies

Repulsion Exponent

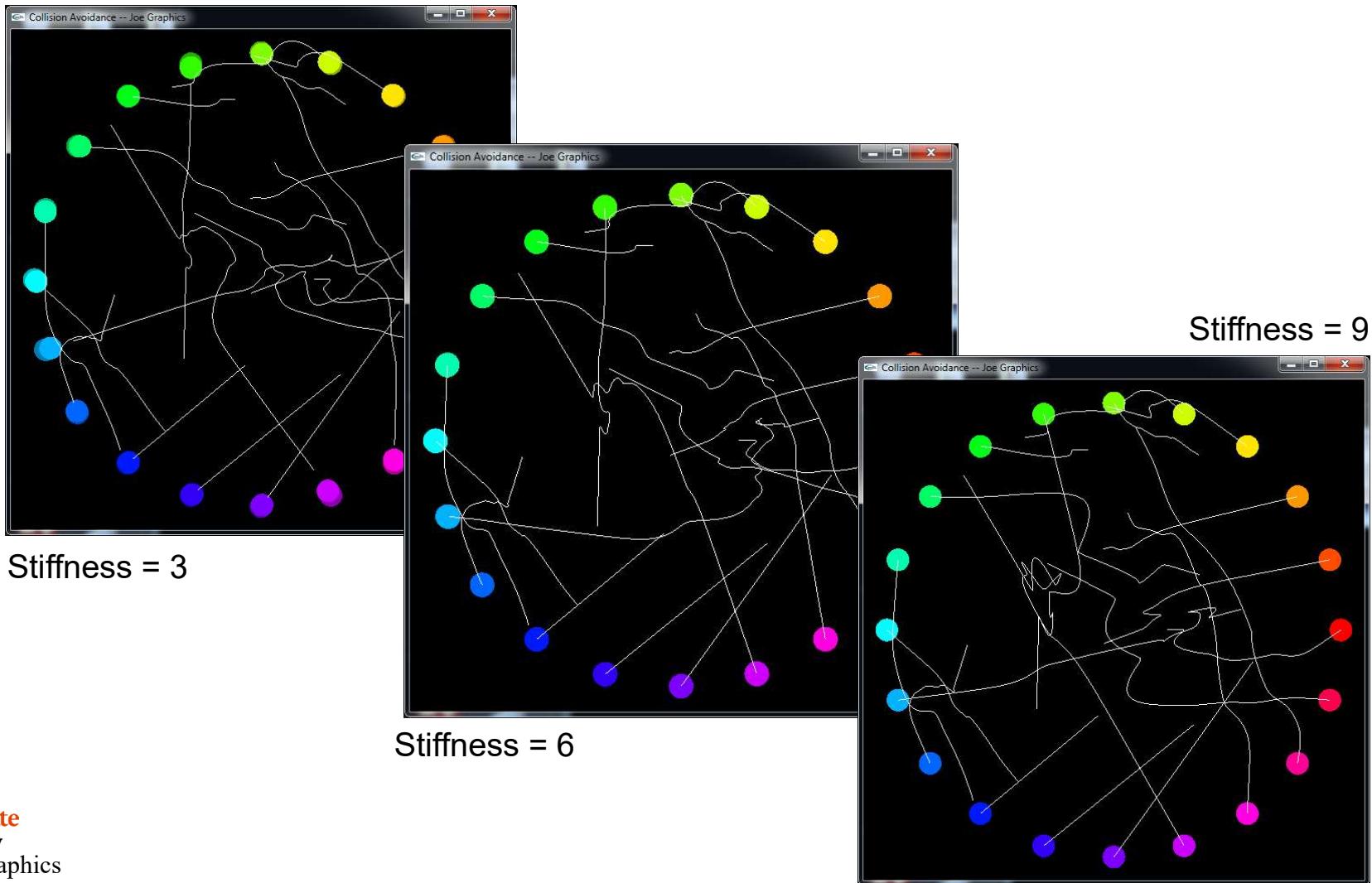
Total Goal – Make the Free Body Move Towards its Final Position  
While Being Repelled by the Other Bodies



$$m\ddot{x} + c\dot{x} + kx = \sum F$$

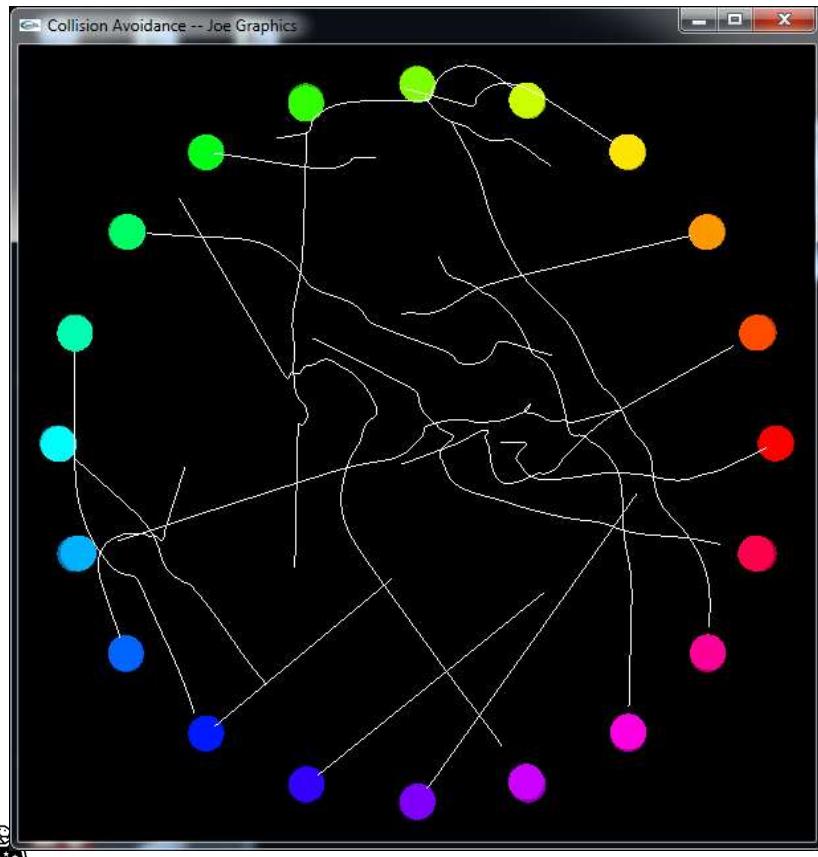


## Increasing the Stiffness

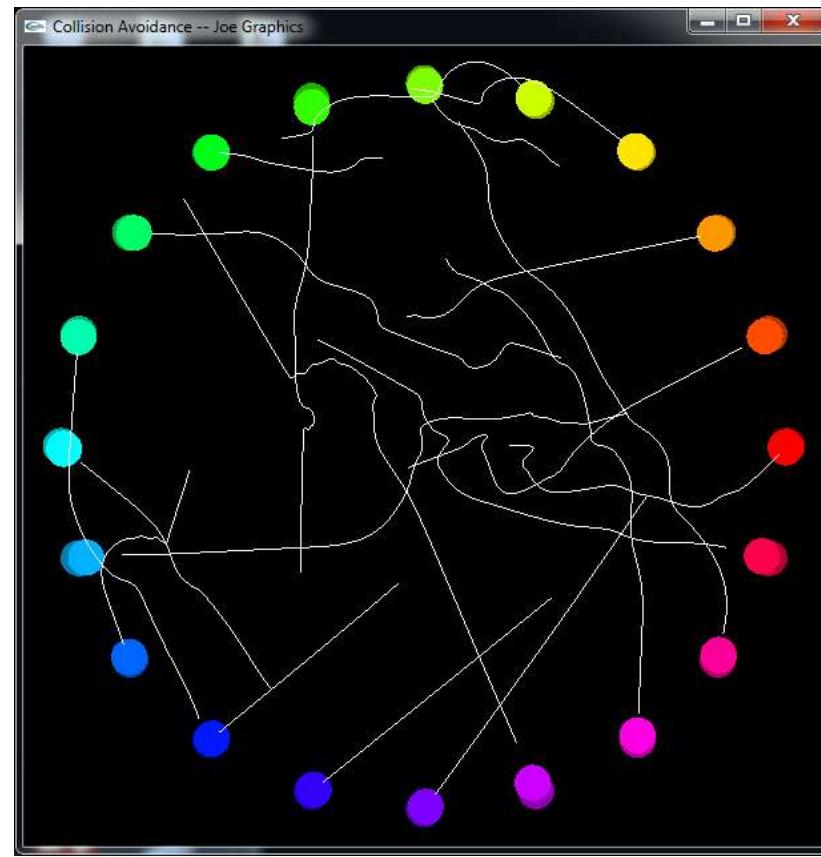


## Increasing the Repulsion Coefficient

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Repulse = 10



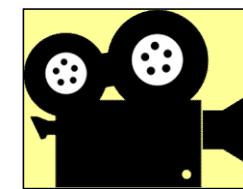
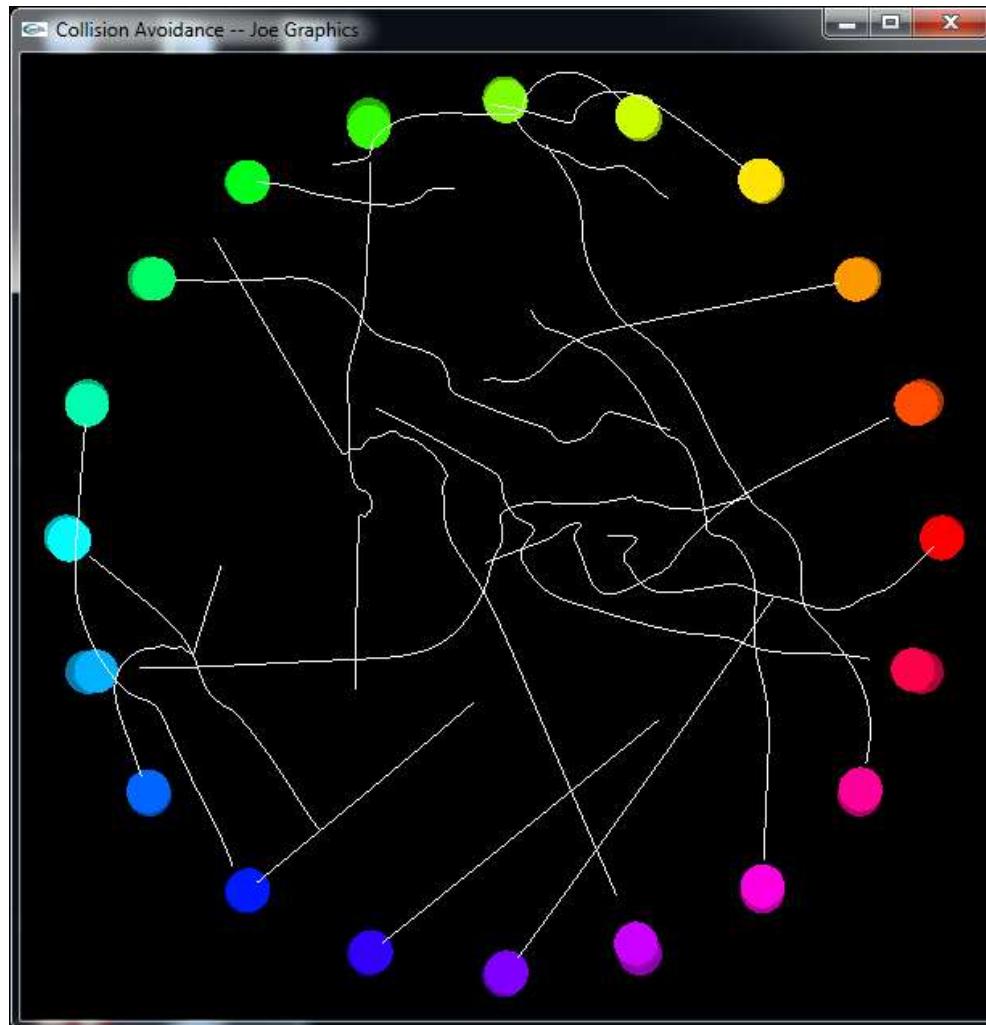
Repulse = 30



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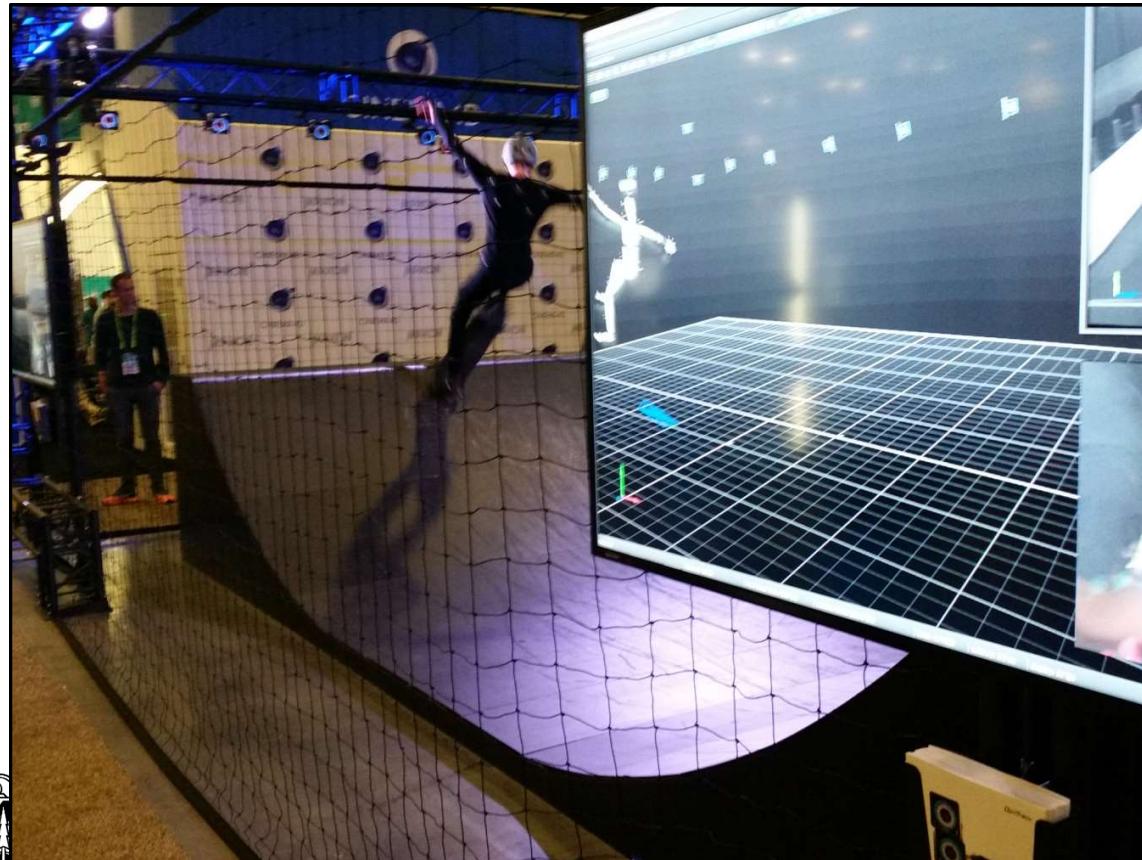
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## Functional Animation



avoid.mp4

## Motion Capture as an Input for Animation



Natural Point

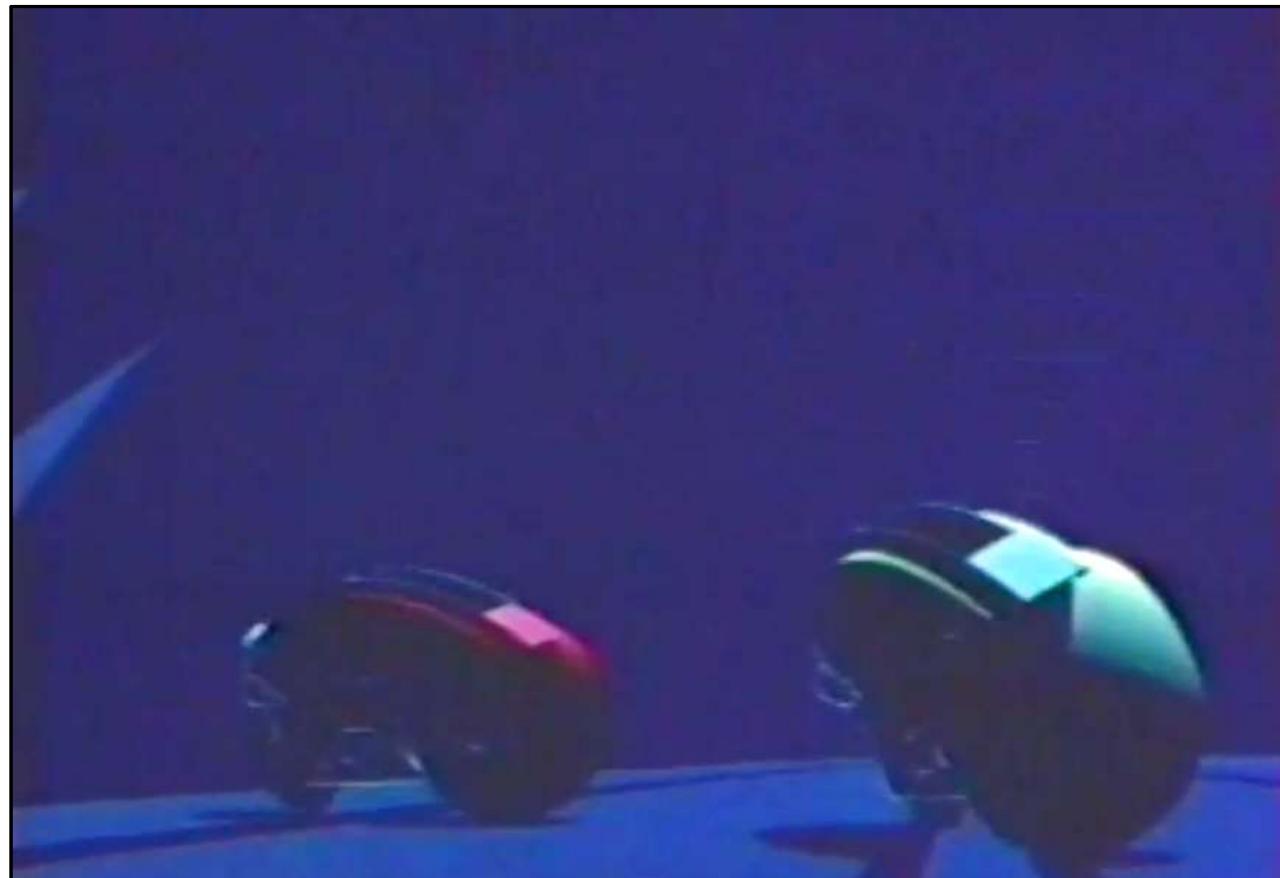


## Motion Capture is for Faces Too



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Tron I –  
They probably should have used physics, but didn't



MAGI

## Card Trick



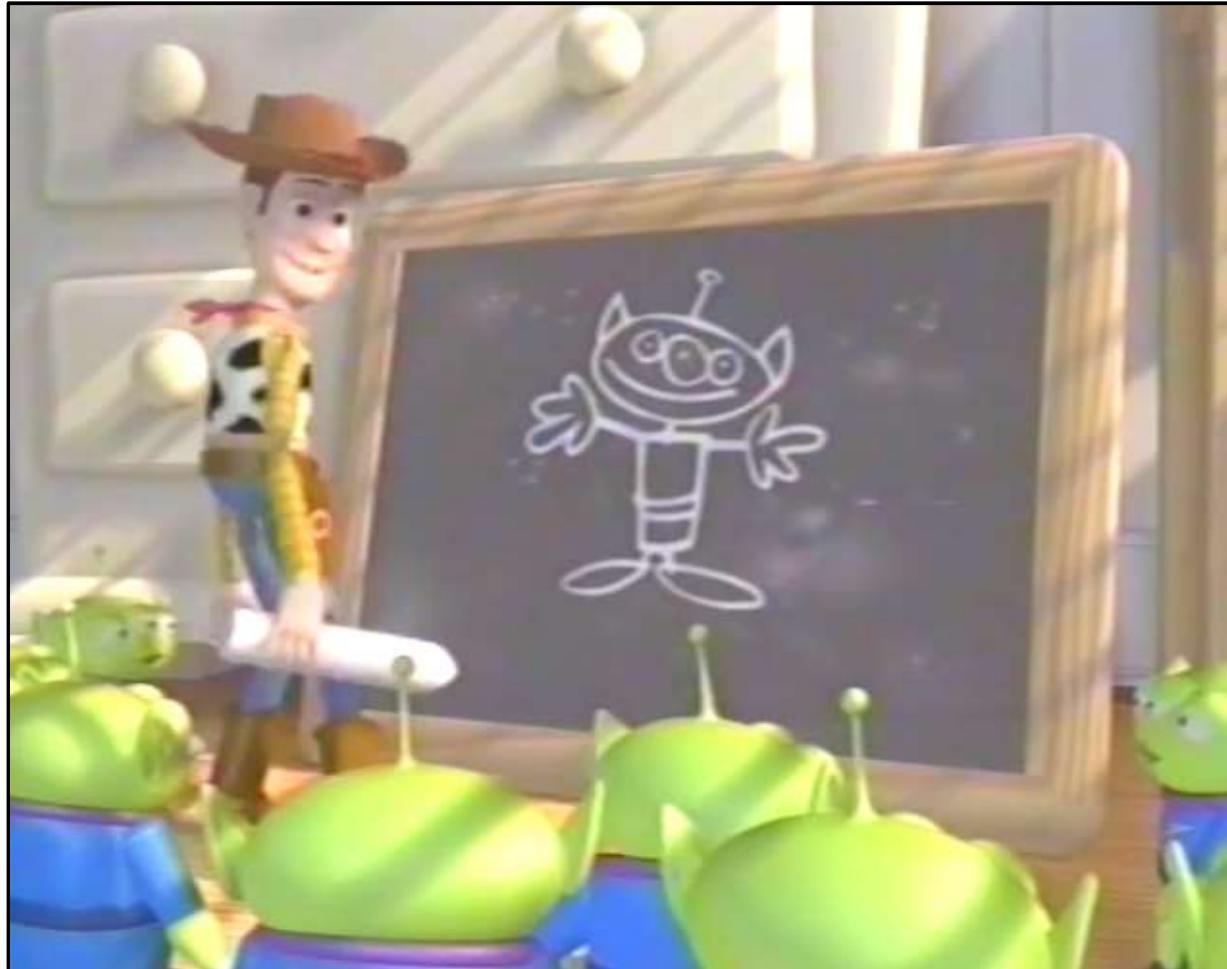
Rob Russ

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## Pixar Animated Shorts



Pixar

## Sidebar: DIY KeyTime Animation

A C++ class can do it all for you

```
class Keytimes:
```

```
    void AddTimeValue( float time, float value );
    float GetFirstTime( );
    float GetLastTime( );
    int GetNumKeytimes( );
    float GetValue( float time );
    void PrintTimeValues( );
```



## DIY KeyTime Animation

```
Keytimes Xpos;

int
main( int argc, char *argv[ ] )
{
    Xpos.AddTimeValue( 0.0, 0.000 );
    Xpos.AddTimeValue( 2.0, 0.333 );
    Xpos.AddTimeValue( 1.0, 3.142 );
    Xpos.AddTimeValue( 0.5, 2.718 );
    fprintf( stderr, "%d time-value pairs:\n", Xpos.GetNumKeytimes( ) );
    Xpos.PrintTimeValues( );

    fprintf( stderr, "Time runs from %8.3f to %8.3f\n", Xpos.GetFirstTime( ), Xpos.GetLastTime( ) );

    for( float t = 0.; t <= 2.01; t += 0.1 )
    {
        float v = Xpos.GetValue( t );
        fprintf( stderr, "%8.3f%8.3f\n", t, v );
    }
}
```



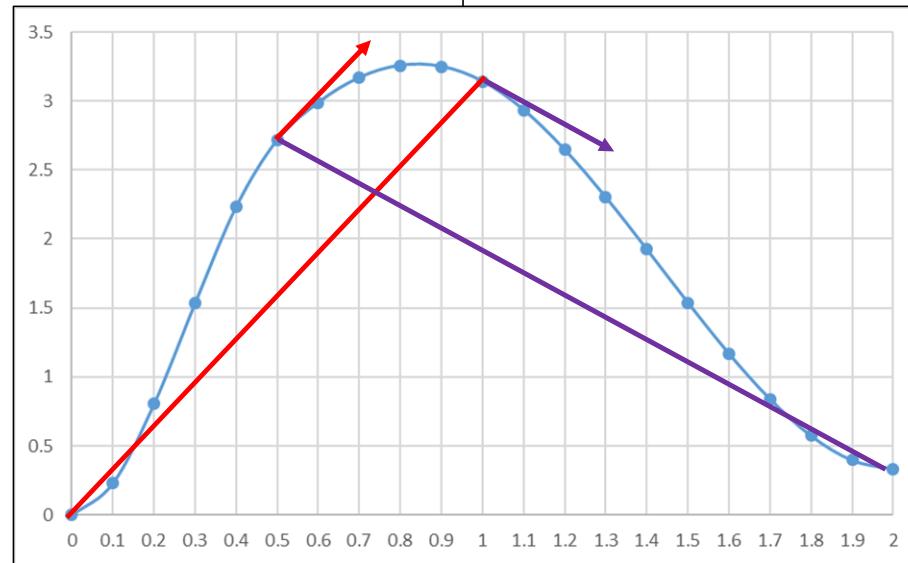
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## DIY KeyTime Animation

```
( 0.00,  0.000)
( 0.00,  0.000) ( 2.00,  0.333)
( 0.00,  0.000) ( 1.00,  3.142) ( 2.00,  0.333)
( 0.00,  0.000) ( 0.50,  2.718) ( 1.00,  3.142) ( 2.00,  0.333)
4 time-value pairs
Time runs from  0.000 to  2.000
 0.000      0.000
 0.100      0.232
 0.200      0.806
 0.300      1.535
 0.400      2.234
 0.500      2.718
 0.600      2.989
 0.700      3.170
 0.800      3.258
 0.900      3.250
 1.000      3.142
 1.100      2.935
 1.200      2.646
 1.300      2.302
 1.400      1.924
 1.500      1.539
 1.600      1.169
 1.700      0.840
 1.800      0.574
 1.900      0.397
 2.000      0.333
```



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## Using the System Clock for Timing in Display( )

```

#define MSEC      10000 // i.e., 10 seconds
Keytimes Xpos, Ypos, Zpos;
Keytimes ThetaX, ThetaY, ThetaZ;
...
if( AnimationIsOn )
{
    // # msec into the cycle ( 0 - MSEC-1 ):
    int msec = glutGet( GLUT_ELAPSED_TIME ) % MSEC;

    // turn that into a time in seconds:
    float nowTime = (float)msec / 1000.;
    glPushMatrix();
    glTranslatef( Xpos.GetValue( nowTime ), Ypos.GetValue( nowTime ), Zpos.GetValue( nowTime ) );
    glRotatef( ThetaX.GetValue( nowTime ), 1., 0., 0. );
    glRotatef( ThetaY.GetValue( nowTime ), 0., 1., 0. );
    glRotatef( ThetaZ.GetValue( nowTime ), 0., 0., 1. );
    << draw the object >>
    glPopMatrix();
}

```

Number of msec in the animation cycle

