

MECHANISM AND SENSOR DESIGN FOR SUPERBALL, A
CABLE-DRIVEN TENSEGRITY ROBOT

By

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A report submitted in partial satisfaction of the

requirements for the degree of

Masters of Science, Plan II

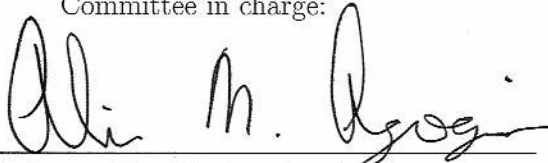
in

Mechanical Engineering

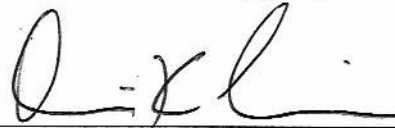
at the

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Fall Semester 2014