

Percentage

■ Failure ■ Success

100%

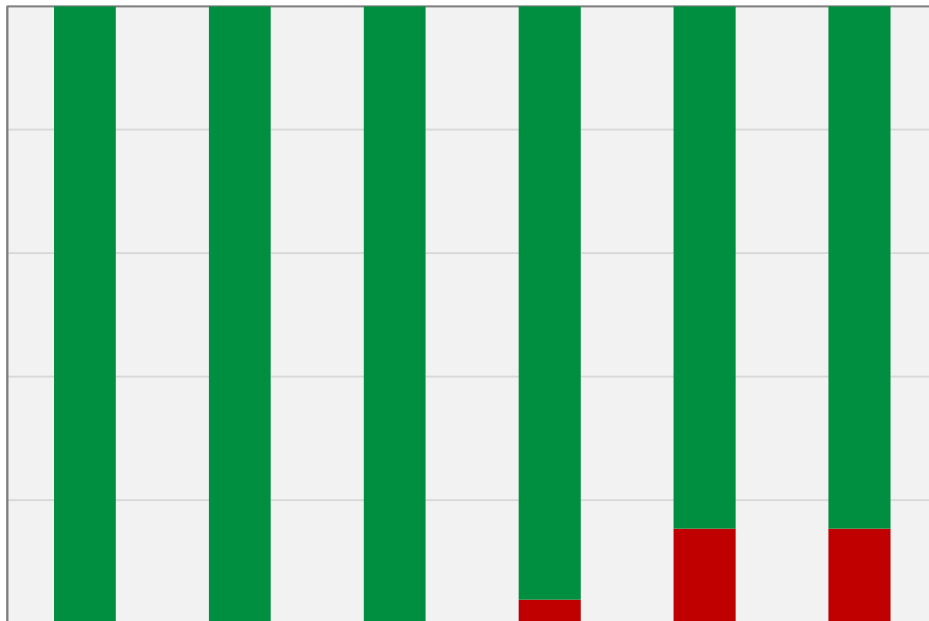
80%

60%

40%

20%

0%



Pick Spacer

Place Spacer

Pick Gear

Place Gear

Pick Propeller

Place Propeller

Tasks