

Exam 2 Notes

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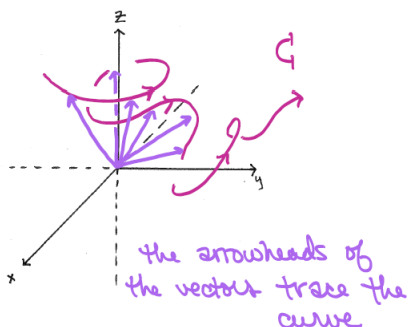
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Chapter 13 - Vector-Valued Functions

13.1 - Space Curves

Space curves vs Vector functions

- A space curve is a curve in \mathbb{R}^3 . If $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$, then the set of points (x, y, z) where $x = f(t)$, $y = g(t)$, $z = h(t)$ is a space curve, C .



$\vec{r}(t)$ is the position vector of the point $P = (f(t), g(t), h(t))$ on C .

Any continuous vector function defines a space curve.

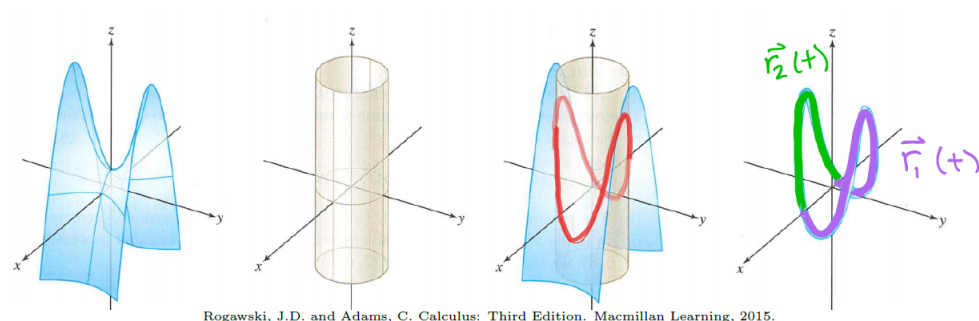
Note: $x = f(t)$, $y = g(t)$, $z = h(t)$ are again called parametric equations.

Identify/sketch a curve from its vector equation

Show a curve lies on a given surface. Use this to sketch the curve.

Parameterize a curve given Cartesian equations
(solve/eliminate variable; use trig: $x = r\cos$, $y = r\sin$)

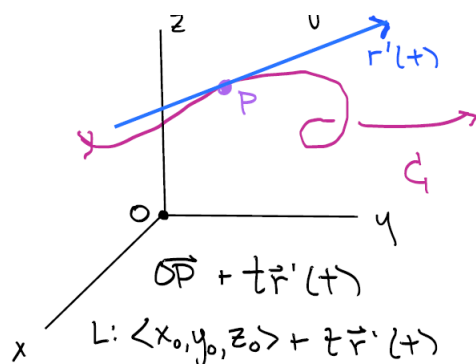
example Parametrize the curve C obtained as the intersections of the surfaces $x^2 - y^2 = z - 1$ and $x^2 + y^2 = 4$.



Rogawski, J.D. and Adams, C. Calculus: Third Edition. Macmillan Learning, 2015.

13.2-13.3 - Arc Length & Speed

Derivatives, Tangent Vector, Tangent Line, Integrals



$\mathbf{r}'(t)$ is the tangent vector to the curve defined by \mathbf{r} at the point P .
 $P = (x_0, y_0, z_0)$
 $(\mathbf{r}'(t) \text{ exists and } \mathbf{r}'(t) \neq 0)$

The tangent line to C at P is defined to be the line through P parallel to the tangent vector $\mathbf{r}'(t)$.

The unit tangent vector: $\hat{\mathbf{T}}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|}$

Find the tangent vector of $\mathbf{r}(t)$ at a given point.

Find the line tangent to a curve at a given point.

DERIVATIVE RULES

Let \mathbf{u} and \mathbf{v} be differentiable vector functions, c a scalar, and f a real-valued function.

$$\bullet \frac{d}{dt}(\mathbf{u}(t) + \mathbf{v}(t)) = \mathbf{u}'(t) + \mathbf{v}'(t)$$

$$\bullet \frac{d}{dt}(c\mathbf{u}) = c\mathbf{u}'(t)$$

$$\bullet \frac{d}{dt}(f(t)\mathbf{u}(t)) = f'(t)\mathbf{u} + f(t)\mathbf{u}'(t)$$

$$\bullet \frac{d}{dt}(\mathbf{u}(f(t))) = f'(t)\mathbf{u}'(f(t))$$

chain rule

similar to the product rule

$$\bullet \frac{d}{dt}(\mathbf{u}(t) \cdot \mathbf{v}(t)) = \mathbf{u}'(t) \cdot \mathbf{v}(t) + \mathbf{u}(t) \cdot \mathbf{v}'(t)$$

$$\bullet \frac{d}{dt}(\mathbf{u}(t) \times \mathbf{v}(t)) = \mathbf{u}'(t) \times \mathbf{v}(t) + \mathbf{u}(t) \times \mathbf{v}'(t)$$

INTEGRALS

$$\int_a^b \mathbf{r}(t) dt = \left(\int_a^b f(t) dt \right) \vec{i} + \left(\int_a^b g(t) dt \right) \vec{j} + \left(\int_a^b h(t) dt \right) \vec{k}$$

FUNDAMENTAL THEOREM OF CALCULUS...VECTOR FUNCTION EDITION

If $\mathbf{r}(t)$ is continuous on $[a, b]$, and $\mathbf{R}(t)$ is an antiderivative of $\mathbf{r}(t)$, then

$$\int_a^b \mathbf{r}(t) dt = \mathbf{R}(b) - \mathbf{R}(a)$$

Arc Length: $L = \int_a^b \|\mathbf{r}'(t)\| dt = \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt$

Parametric: $s(t) = \int_a^t \|\mathbf{r}'(u)\| du$

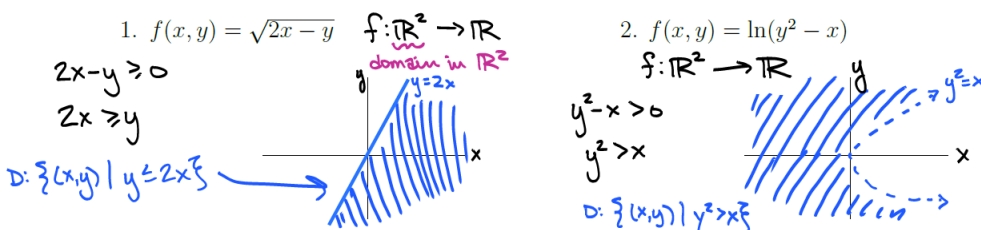
(u is "placeholder")

Speed: $\frac{ds}{dt} = \|\mathbf{r}'(t)\|$
 (at time t)

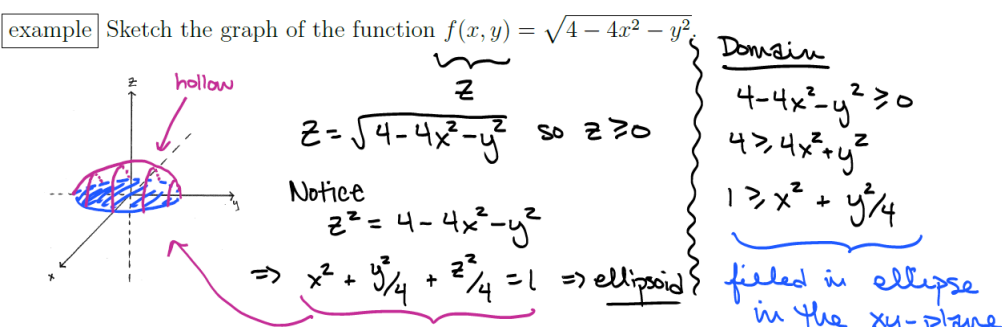
Chapter 14 - Differentiation in Several Variables

14.1 - Functions of 2+ Variables

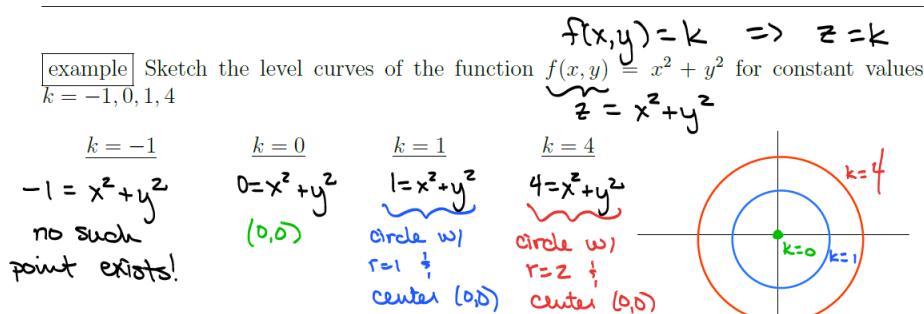
Find and sketch the domain of the function



Sketch graph of function



Sketch level curves and contour maps of a function



Sketch *sections* (vertical traces) of a graph

14.2 - Limits and Continuity in Several Variables

$$\lim_{x \rightarrow b} f(x) = L \iff \left(\forall \epsilon > 0, \exists \delta > 0 \text{ s.t. } \sqrt{(x_1 - b_1)^2 + (x_2 - b_2)^2 + \dots + (x_n - b_n)^2} < \delta \implies |f(x) - L| < \epsilon \right)$$

$$x = (x_1, x_2, \dots, x_n) \in D(f) \subset \mathbb{R}^n$$

Continuity: $\lim_{(x, y) \rightarrow (a, b)} f(x, y) = f(a, b)$

Limit Existence:

If $f(x, y) \rightarrow L_1$ as $(x, y) \rightarrow (a, b)$ along a path C_1 and
if $f(x, y) \rightarrow L_2$ as $(x, y) \rightarrow (a, b)$ along a path C_2 and

$$L_1 \neq L_2, \text{ then } \lim_{(x,y) \rightarrow (a,b)} f(x, y) \text{ DNE}$$

Disclaimer:

C_1, C_2 might be difficult to pick.

Potential Options

$$x=0, y=0, y=kx^2 \\ x=ky^2, y=mx, \text{ etc}$$

14.3 - Partial Derivatives

* PARTIAL DERIVATIVES : the rates of change with respect to each variable separately.

The partial derivative of f with respect to x at (a, b) is

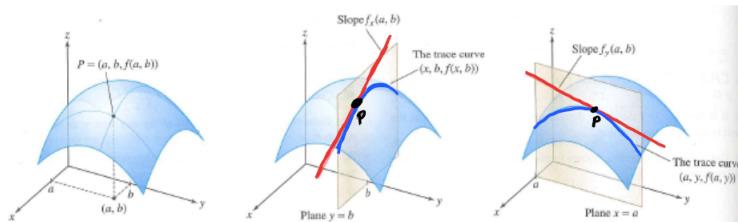
$$f_x(a, b) = \lim_{h \rightarrow 0} \frac{f(a+h, b) - f(a, b)}{h}$$

similarly for y

$$f_y(a, b) = \lim_{h \rightarrow 0} \frac{f(a, b+h) - f(a, b)}{h}$$

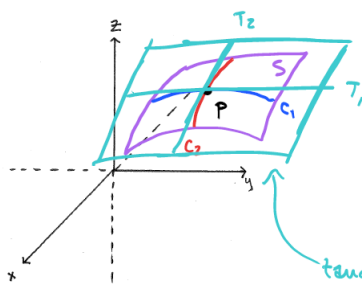
Graphically, we have the following:

Let $P = (a, b)$. Then the partial derivatives at P are slopes of tangent lines to the vertical traces curves through the point $(a, b, f(a, b))$.



Rogawski, J.D. and Adams, C. Calculus: Third Edition. Macmillan Learning, 2015.

14.4 - Differentiability and Tangent Planes



TANGENT PLANES

Let C_1 and C_2 be curves on the surface obtained by obtaining the intersection with the surface and vertical planes.

T_1 and T_2 be tangents to C_1 and C_2 at the point P .

$$z - z_0 = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

- Compare: $y - y_0 = f'(x_0)(x - x_0)$

Linear Approximation: The linearization of f at (a, b) — $L(x, y) = f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b)$

Differentials and Increments

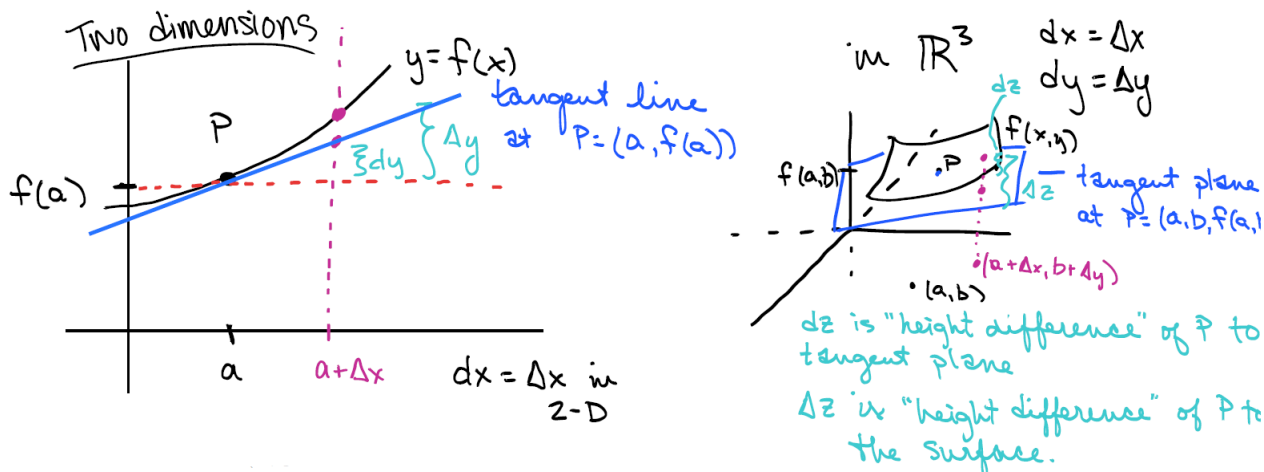
Increments: $\Delta z = f(a + \Delta x, b + \Delta y) - f(a, b)$

Differentiability: If $z = f(x, y)$, f is differentiable at (a, b) if

$$\Delta z = f_x(a, b)\Delta x + f_y(a, b)\Delta y + \varepsilon_1\Delta x + \varepsilon_2\Delta y \quad \text{and} \quad \varepsilon_1, \varepsilon_2 \rightarrow 0 \text{ as } (a, b) \rightarrow (0, 0)$$

Theorem — if f_x, f_y exist “near” (a, b) and are continuous at (a, b) , then f is differentiable at (a, b)

Differentials: $dz = f_x dx + f_y dy$, $dz \approx \Delta z$



14.5 - Directional Derivatives and the Gradient of a Vector-Valued Function

The **directional derivative** of f at (x_0, y_0, z_0) in the direction of a unit vector $\vec{u} = \langle a, b, c \rangle$:

$$D_{\vec{u}}f(x, y, z) = \lim_{h \rightarrow 0} \frac{f(x_0 + ha, y_0 + hb, z_0 + hc) - f(x_0, y_0, z_0)}{h}$$

Theorem — $f(x, y, z)$ differentiable $\implies \forall \vec{u} = \langle a, b, c \rangle$, f has a directional derivative:

$$D_{\vec{u}}f(x, y, z) = f_x(x, y, z)a + f_y(x, y, z)b + f_z(x, y, z)c$$

Gradient: $\nabla f(x, y, z) = \langle f_x, f_y, f_z \rangle = \frac{\partial f}{\partial x} \vec{i} + \frac{\partial f}{\partial y} \vec{j} + \frac{\partial f}{\partial z} \vec{k}$
(similar for function of two variables, $\nabla f(x, y) = \langle f_x, f_y \rangle$)

$$\text{Re: Directional Derivative: } D_{\vec{u}}f(x, y, z) = \nabla f(x, y, z) \cdot \vec{u}$$

Assume $\nabla f(p) \neq 0$:

- $\pm \nabla f(p)$ points in the direction of max rate of increase/decrease of f at p
- $\nabla f(p)$ is normal to the level curve (or surface) of f at p
— tangent plane of $f(x, y, z) = k$ at $p = (x_0, y_0, z_0)$: $\nabla f(x_0, y_0, z_0) \cdot \langle x - x_0, y - y_0, z - z_0 \rangle = 0$
- $\|\nabla f(p)\|$ gives max slope of a tangent line (max rate of change) to the surface $z = f(x, y)$ at $(p, f(p))$

14.6 - The Chain Rule

1.) z is a differentiable function of two single-parameter differentiable functions

$$z = f(x(t), y(t)) \longrightarrow \frac{dz}{dt} = \left(\frac{\partial f}{\partial x}\right)\left(\frac{dx}{dt}\right) + \left(\frac{\partial f}{\partial y}\right)\left(\frac{dy}{dt}\right)$$

2.) z is a differentiable function of two “double”-parameter differentiable functions

$$\frac{\partial z}{\partial s} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial s}$$

$$\frac{\partial z}{\partial t} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial t}$$

3.) Implicit Differentiation

For instance, consider the implicit function $x^2y - xy^3 = 3$. We learned to use the following steps to find $\frac{dy}{dx}$:

$$\begin{aligned} \frac{d}{dx} (x^2y - xy^3) &= \frac{d}{dx} (3) \\ 2xy + x^2 \frac{dy}{dx} - y^3 - 3xy^2 \frac{dy}{dx} &= 0 \\ \frac{dy}{dx} &= -\frac{2xy - y^3}{x^2 - 3xy^2}. \end{aligned} \tag{13.5.1}$$

Instead of using this method, consider $z = x^2y - xy^3$. The implicit function above describes the level curve $z = 3$. Considering x and y as functions of x , the Multivariable Chain Rule states that

$$\frac{dz}{dx} = \frac{\partial z}{\partial x} \frac{dx}{dx} + \frac{\partial z}{\partial y} \frac{dy}{dx}. \tag{13.5.2}$$

$$\frac{dx}{dx} = 1 \text{ and, if } z \text{ is constant, } \frac{dz}{dx} = 0. \text{ Hence } \frac{\partial z}{\partial y} \neq 0 \implies \frac{dy}{dx} = -\frac{\partial z}{\partial x} / \frac{\partial z}{\partial y} = \frac{f_x}{f_y}$$

Note that

Types of Questions

13.1

Identify/sketch a curve from its vector equation

Show a curve lies on a given surface. Use this to sketch the curve.

Parameterize a curve given Cartesian equations

(solve/eliminate variable; use trig: $x = r\cos, y = r\sin$)

13.2-13.3

Find the tangent vector of $\mathbf{r}(t)$ at a given point.

Find the line tangent to a curve at a given point.

14.1

Find and sketch the domain of the multi-valued function

14.2

Where is the function continuous?

Determine if the limit exists and compute the limit if possible