

Dilation theory for right LCM semigroup dynamical systems

Boyu Li

University of Victoria

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Background and Motivation

Theorem (Sz. Nagy 1953)

For a contraction $T \in \mathcal{B}(\mathcal{H})$ (that is $TT^* \leq I$), there exists an isometry $V \in \mathcal{B}(\mathcal{K})$ on $\mathcal{K} \supset \mathcal{H}$ such that $T^n = P_{\mathcal{H}}V^n|_{\mathcal{H}}$ for all $n \geq 1$.

Theorem (Brehmer 1961)

For commuting contractions $T_1, \dots, T_n \in \mathcal{B}(\mathcal{H})$, if for each $F \subset \{1, \dots, n\}$, we have

$$\sum_{U \subset F} (-1)^{|U|} T_U T_U^* \geq 0.$$

Then T_i can be dilated to commuting isometries V_i .

Note: V_i can be chosen to be doubly commuting (that is, Nica-covariant).

Background and Motivation

Theorem (Frazho-Bunce-Popescu 1980's)

For non-commuting contractions T_1, \dots, T_n , if $\sum_{i=1}^n T_i T_i^* \leq I$, then T_i dilate to isometries V_i with orthogonal ranges.

Moreover, if $\sum_{i=1}^n T_i T_i^* = I$, the minimal dilations V_i also satisfy $\sum_{i=1}^n V_i V_i^* = I$.

Theorem (L. 2019)

Let P be a right LCM semigroup. Then a contractive representation $T : P \rightarrow \mathcal{B}(\mathcal{H})$ has an isometric Nica-covariant dilation if and only if for any $F \subset P$,

$$\sum_{U \subset F} (-1)^{|U|} T_U T_U^* \geq 0.$$

Right LCM Semigroup Dynamical Systems

Recall a semigroup P is called right LCM if for any $p, q \in P$,

$$pP \cap qP = \begin{cases} rP, & \text{if } pP \cap qP \neq \emptyset; \\ \emptyset, & \text{otherwise.} \end{cases}$$

An isometric representation V of P is called Nica-covariant if for any $p, q \in P$,

$$V_p V_p^* V_q V_q^* = \begin{cases} V_r V_r^*, & \text{if } pP \cap qP = rP; \\ 0, & \text{otherwise.} \end{cases}$$

The universal C*-algebra for isometric Nica-covariant representations is called the semigroup C*-algebra of P .

Right LCM Semigroup Dynamical Systems

A semigroup dynamical system is a triple (\mathcal{A}, P, α) where \mathcal{A} is a unital C^* -algebra, P is a semigroup, and α is a P -action on \mathcal{A} by injective $*$ -endomorphisms. One may notice that α only encodes the multiplicative structure on P but not the right LCM structure.

Definition

Let P be a right LCM semigroup. A semigroup dynamical system (\mathcal{A}, P, α) is called a right LCM semigroup dynamical system if each $\alpha_p(\mathcal{A})$ is an ideal in \mathcal{A} and for any $p, q \in P$,

$$\alpha_p(1)\alpha_q(1) = \begin{cases} \alpha_r(1), & \text{if } pP \cap qP = rP; \\ 0, & \text{if } pP \cap qP = \emptyset. \end{cases}$$

Right LCM Semigroup Dynamical Systems

Example

The semigroup C^* -algebra for a right LCM semigroup P has a natural right LCM semigroup dynamical system. Let $\mathcal{D}_P = \overline{\text{span}}\{V_p V_p^*\}$. Let $\alpha_p(x) = V_p x V_p^*$. Then $(\mathcal{D}_P, P, \alpha)$ is a right LCM semigroup dynamical system.

By the Nica-covariance condition, $\mathcal{D}_P = C(\Omega_P)$ is a commutative C^* -algebra. If $K \subset \Omega_P$ is a compact subset such that K and K^c are invariant under α , then we get a right LCM semigroup dynamical system $(C(K), \alpha, P)$.

One such K gives the boundary quotient $(C(\partial\Omega_P), P, \alpha)$. The boundary quotient is generated by isometric representations V such that for all foundation set $F \subset P$, $\prod_{i \in F} (I - V_i V_i^*) = 0$.

Right LCM Semigroup Dynamical Systems

Fix a right LCM semigroup dynamical system (\mathcal{A}, P, α)

Definition

An isometric covariant representation is a pair (π, V) where:

- ① π is a unital $*$ -homomorphism of \mathcal{A} ;
- ② V is an isometric representation of P ;
- ③ For all $p \in P$ and $a \in \mathcal{A}$, $V_p \pi(a) V_p^* = \pi(\alpha_p(a))$.

Note: from the right LCM condition, V is Nica-covariant.

Right LCM Semigroup Dynamical Systems

Definition

A contractive covariant representation is a pair (ϕ, T) where:

- ① ϕ is a $*$ -preserving linear map on \mathcal{A} ;
- ② T is a contractive representation of P ;
- ③ For all $p \in P$ and $a \in \mathcal{A}$, $T_p \phi(a) T_p^* = \phi(\alpha_p(a))$.

Question: when does a contractive covariant representation (ϕ, T) dilate to an isometric covariant representation (π, V) ?

Right LCM Semigroup Dynamical Systems

Example

On $(\mathcal{D}_P, P, \alpha)$, a contractive representation T of P also defines a $*$ -preserving linear map ϕ on \mathcal{D}_P by $\phi(V_p V_p^*) = T_p T_p^*$. The pair (ϕ, T) defines a contractive covariant representation.

The pair (ϕ, T) dilates to an isometric covariant pair if and only if for any $F \subset P$,

$$\phi \left(\prod_{i \in F} (I - V_i V_i^*) \right) = \sum_{U \subset F} (-1)^{|U|} T_U T_U^* \geq 0.$$

Main Result

Theorem (Laca-L.)

A contractive covariant representation (ϕ, T) dilates to an isometric covariant representation (π, V) if and only if ϕ is unital completely positive. Moreover, the dilation (π, V) can be chosen to be minimal and this minimal dilation is unique.

Examples and Applications

We first obtain a dilation result for the boundary quotient.

Theorem

Suppose T is a contractive representation of a right LCM semigroup P such that for any $F \subset P$,

$$\sum_{U \subset F} (-1)^{|U|} T_U T_U^* \geq 0,$$

and for any foundation set F ,

$$\sum_{U \subset F} (-1)^{|U|} T_U T_U^* = 0.$$

Then T can be dilated to an isometric representation V of the boundary quotient.

Examples and Applications

Corollary

If contractions T_1, \dots, T_n satisfy $\sum_{i=1}^n T_i T_i^* = I$, then they can be dilated to isometries V_1, \dots, V_n that $\sum_{i=1}^n V_i V_i^* = I$.

Corollary

If T_1, \dots, T_n are commuting co-isometries, then they dilate to commuting unitaries.

Examples and Applications

Let (\mathcal{A}, P, β) be an automorphic semigroup dynamical system. We can build a right LCM semigroup dynamical system $(\mathcal{D}_P \otimes \mathcal{A}, P, \tilde{\alpha})$ by

$$\tilde{\alpha}_p(f \otimes a) = \alpha_p(f) \otimes \beta_p(a).$$

A *-preserving linear map ϕ on \mathcal{A} and a contractive representation T of P can define a contractive covariant representation $(\tilde{\phi}, T)$ by

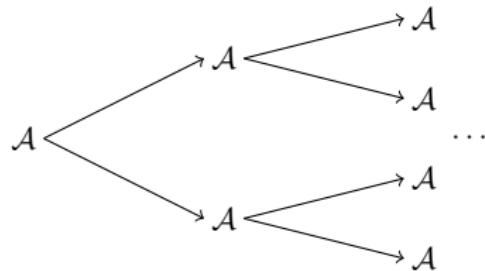
$$\tilde{\phi}(V_p V_p^* \otimes a) = T(p)\phi(\beta_p^{-1}(a))T(p)^*.$$

Proposition

The map $\tilde{\phi}$ is unital completely positive if and only if for each finite $F \subset P$, the map $\phi_F(a) := \sum_{U \subset F} (-1)^{|U|} T(s_U) \phi(\beta_{s_U}^{-1}(a)) T(s_U)^*$ is completely positive.

Examples and Applications

Let \mathcal{A} be a C^* -algebra. Consider the direct limit $\tilde{\mathcal{A}} = C(X) \otimes \mathcal{A}$.



We have a right LCM semigroup dynamical systems $(\tilde{\mathcal{A}}, \mathbb{F}_2^+, \alpha)$ where $\alpha_{e_1}(a) = a \oplus 0$ and $\alpha_{e_2}(a) = 0 \oplus a$.

Proposition

If $\phi : \mathcal{A} \rightarrow \mathcal{B}(\mathcal{H})$ is unital completely positive and if there exist contractions T_1, \dots, T_n such that $\phi(a) = \sum_{i=1}^n T_i \phi(a) T_i^*$. Then we can dilate ϕ to a unital $*$ -representation π of \mathcal{A} and T_i to isometries V_i with orthogonal ranges, such that $\pi(a) = \sum_{i=1}^n V_i \pi(a) V_i^*$

Thank you