

# Orthogonality and Gateaux derivative of $C^*$ -norm

Sushil Singla

Department of Mathematics  
School of Natural Sciences  
Shiv Nadar University

June 18, 2021

# Table of Contents

- 1 States and orthogonality in  $C^*$ -algebra
- 2 Proofs and applications

# Table of Contents

1 States and orthogonality in  $C^*$ -algebra

2 Proofs and applications

# Existence of states on a $C^*$ -algebra

**Let  $\mathcal{A}$  be a  $C^*$  algebra over field  $\mathbb{C}$  or  $\mathbb{R}$ .  $\mathcal{S}_{\mathcal{A}}$  will stand for the set of all states on  $\mathcal{A}$ .**

# Existence of states on a $C^*$ -algebra

**Let  $\mathcal{A}$  be a  $C^*$  algebra over field  $\mathbb{C}$  or  $\mathbb{R}$ .  $\mathcal{S}_{\mathcal{A}}$  will stand for the set of all states on  $\mathcal{A}$ .**

**Theorem (Gelfand-Naimark-Segal)**

*Let  $a \in \mathcal{A}$ . Then there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$ .*

# Existence of states on a $C^*$ -algebra

Let  $\mathcal{A}$  be a  $C^*$  algebra over field  $\mathbb{C}$  or  $\mathbb{R}$ .  $\mathcal{S}_{\mathcal{A}}$  will stand for the set of all states on  $\mathcal{A}$ .

## Theorem (Gelfand-Naimark-Segal)

*Let  $a \in \mathcal{A}$ . Then there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$ .  
This can be rephrased as :  $\text{dist}(a, \{0\})^2 = \max\{\phi(a^*a) : \phi \in \mathcal{S}_{\mathcal{A}}\}$ .*

# Existence of states on a $C^*$ -algebra

Let  $\mathcal{A}$  be a  $C^*$  algebra over field  $\mathbb{C}$  or  $\mathbb{R}$ .  $\mathcal{S}_{\mathcal{A}}$  will stand for the set of all states on  $\mathcal{A}$ .

## Theorem (Gelfand-Naimark-Segal)

*Let  $a \in \mathcal{A}$ . Then there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$ .*

*This can be rephrased as :  $\text{dist}(a, \{0\})^2 = \max\{\phi(a^*a) : \phi \in \mathcal{S}_{\mathcal{A}}\}$ .*

A positive functional  $\phi$  gives a semi inner product on  $\mathcal{A}$  defined as  $\langle a|b \rangle_{\phi} = \phi(a^*b)$ .

# Existence of states on a $C^*$ -algebra

Let  $\mathcal{A}$  be a  $C^*$  algebra over field  $\mathbb{C}$  or  $\mathbb{R}$ .  $\mathcal{S}_{\mathcal{A}}$  will stand for the set of all states on  $\mathcal{A}$ .

## Theorem (Gelfand-Naimark-Segal)

*Let  $a \in \mathcal{A}$ . Then there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$ .*

*This can be rephrased as :  $\text{dist}(a, \{0\})^2 = \max\{\phi(a^*a) : \phi \in \mathcal{S}_{\mathcal{A}}\}$ .*

A positive functional  $\phi$  gives a semi inner product on  $\mathcal{A}$  defined as  $\langle a|b \rangle_{\phi} = \phi(a^*b)$ . The above theorem can be rephrased as -



# Existence of states on a $C^*$ -algebra

Let  $\mathcal{A}$  be a  $C^*$  algebra over field  $\mathbb{C}$  or  $\mathbb{R}$ .  $\mathcal{S}_{\mathcal{A}}$  will stand for the set of all states on  $\mathcal{A}$ .

## Theorem (Gelfand-Naimark-Segal)

*Let  $a \in \mathcal{A}$ . Then there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$ .*

*This can be rephrased as :  $\text{dist}(a, \{0\})^2 = \max\{\phi(a^*a) : \phi \in \mathcal{S}_{\mathcal{A}}\}$ .*

A positive functional  $\phi$  gives a semi inner product on  $\mathcal{A}$  defined as  $\langle a|b \rangle_{\phi} = \phi(a^*b)$ . The above theorem can be rephrased as -

There exists  $\phi \in \mathcal{S}(\mathcal{A})$  such that  $\langle a|a \rangle_{\phi} = \text{dist}(a, \{0\})^2$ .

# Existence of states on a $C^*$ -algebra

Let  $\mathcal{A}$  be a  $C^*$  algebra over field  $\mathbb{C}$  or  $\mathbb{R}$ .  $\mathcal{S}_{\mathcal{A}}$  will stand for the set of all states on  $\mathcal{A}$ .

## Theorem (Gelfand-Naimark-Segal)

*Let  $a \in \mathcal{A}$ . Then there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$ .*

*This can be rephrased as :  $\text{dist}(a, \{0\})^2 = \max\{\phi(a^*a) : \phi \in \mathcal{S}_{\mathcal{A}}\}$ .*

A positive functional  $\phi$  gives a semi inner product on  $\mathcal{A}$  defined as  $\langle a|b \rangle_{\phi} = \phi(a^*b)$ . The above theorem can be rephrased as -

There exists  $\phi \in \mathcal{S}(\mathcal{A})$  such that  $\langle a|a \rangle_{\phi} = \text{dist}(a, \{0\})^2$ . We generalize this for any subspace  $\mathcal{B}$ , when a best approximation to  $a$  in  $\mathcal{B}$  exists.

# Existence of states on a $C^*$ -algebra

Let  $\mathcal{A}$  be a  $C^*$  algebra over field  $\mathbb{C}$  or  $\mathbb{R}$ .  $\mathcal{S}_{\mathcal{A}}$  will stand for the set of all states on  $\mathcal{A}$ .

## Theorem (Gelfand-Naimark-Segal)

*Let  $a \in \mathcal{A}$ . Then there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$ .*

*This can be rephrased as :  $\text{dist}(a, \{0\})^2 = \max\{\phi(a^*a) : \phi \in \mathcal{S}_{\mathcal{A}}\}$ .*

A positive functional  $\phi$  gives a semi inner product on  $\mathcal{A}$  defined as  $\langle a|b \rangle_{\phi} = \phi(a^*b)$ . The above theorem can be rephrased as -

There exists  $\phi \in \mathcal{S}(\mathcal{A})$  such that  $\langle a|a \rangle_{\phi} = \text{dist}(a, \{0\})^2$ . We generalize this for any subspace  $\mathcal{B}$ , when a best approximation to  $a$  in  $\mathcal{B}$  exists.

# Birkhoff-James Orthogonality and best approximation

**Let  $W$  be a subspace of a normed space  $V$ .**

# Birkhoff-James Orthogonality and best approximation

**Let  $W$  be a subspace of a normed space  $V$ .**

## Definition

An element  $w_0 \in W$  is said to be a best approximation to  $v$  in  $W$  if and only if  $\text{dist}(v, W) = \|v - w_0\|$ .

# Birkhoff-James Orthogonality and best approximation

**Let  $W$  be a subspace of a normed space  $V$ .**

## Definition

An element  $w_0 \in W$  is said to be a best approximation to  $v$  in  $W$  if and only if  $\text{dist}(v, W) = \|v - w_0\|$ . In case  $w_0 = 0$ , we say  $v$  is Birkhoff-James orthogonal to  $W$ .

# Birkhoff-James Orthogonality and best approximation

**Let  $W$  be a subspace of a normed space  $V$ .**

## Definition

An element  $w_0 \in W$  is said to be a best approximation to  $v$  in  $W$  if and only if  $\text{dist}(v, W) = \|v - w_0\|$ . In case  $w_0 = 0$ , we say  $v$  is Birkhoff-James orthogonal to  $W$ .

Note that  $w_0$  is a best approximation to  $v$  in  $W$  if and only if  $v - w_0$  is Birkhoff-James orthogonal to  $W$ .

# Birkhoff-James Orthogonality and best approximation

**Let  $W$  be a subspace of a normed space  $V$ .**

## Definition

An element  $w_0 \in W$  is said to be a best approximation to  $v$  in  $W$  if and only if  $\text{dist}(v, W) = \|v - w_0\|$ . In case  $w_0 = 0$ , we say  $v$  is Birkhoff-James orthogonal to  $W$ .

Note that  $w_0$  is a best approximation to  $v$  in  $W$  if and only if  $v - w_0$  is Birkhoff-James orthogonal to  $W$ . Also we note that in case  $V$  is a Hilbert space, this notion of orthogonality matches with usual notion of orthogonality in a Hilbert space.

This viewpoint of best approximation as orthogonality enable us to guess results from geometric intuition and then try to prove it algebraically.



# Birkhoff-James Orthogonality and best approximation

**Let  $W$  be a subspace of a normed space  $V$ .**

## Definition

An element  $w_0 \in W$  is said to be a best approximation to  $v$  in  $W$  if and only if  $\text{dist}(v, W) = \|v - w_0\|$ . In case  $w_0 = 0$ , we say  $v$  is Birkhoff-James orthogonal to  $W$ .

Note that  $w_0$  is a best approximation to  $v$  in  $W$  if and only if  $v - w_0$  is Birkhoff-James orthogonal to  $W$ . Also we note that in case  $V$  is a Hilbert space, this notion of orthogonality matches with usual notion of orthogonality in a Hilbert space.

This viewpoint of best approximation as orthogonality enable us to guess results from geometric intuition and then try to prove it algebraically.

# Orthogonality characterization in $C^*$ -algebra

Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

# Orthogonality characterization in $C^*$ -algebra

Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

The above theorem says that  $b_0$  is a best approximation to  $a$  in  $\mathcal{B}$

# Orthogonality characterization in $C^*$ -algebra

## Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

The above theorem says that  $b_0$  is a best approximation to  $a$  in  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that

$$\|a - b_0\|_{\phi} = \|a - b_0\| \text{ and } \langle a - b_0 | b \rangle_{\phi} = 0 \text{ for all } b \in \mathcal{B}.$$

# Orthogonality characterization in $C^*$ -algebra

Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

The above theorem says that  $b_0$  is a best approximation to  $a$  in  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that

$$\|a - b_0\|_{\phi} = \|a - b_0\| \text{ and } \langle a - b_0 | b \rangle_{\phi} = 0 \text{ for all } b \in \mathcal{B}.$$

The above characterization of orthogonality has following geometric interpretation.

# Orthogonality characterization in $C^*$ -algebra

Theorem (Grover P.; Singla S., 2021)

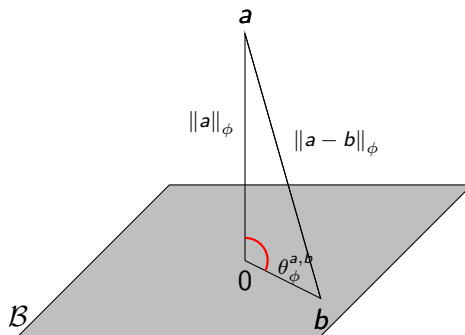
*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

The above theorem says that  $b_0$  is a best approximation to  $a$  in  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that

$$\|a - b_0\|_{\phi} = \|a - b_0\| \text{ and } \langle a - b_0 | b \rangle_{\phi} = 0 \text{ for all } b \in \mathcal{B}.$$

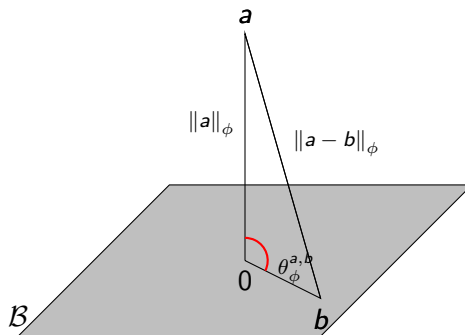
The above characterization of orthogonality has following geometric interpretation.

# Geometric interpretation



The above theorem is a generalization of very well known results, which follow as a corollary of the above result.

# Geometric interpretation



The above theorem is a generalization of very well known results, which follow as a corollary of the above result.



# Characterization of best approximation in $\mathcal{C}(X)$

**Notation:**  $\mathbb{F}$  will stand for  $\mathbb{C}$  or  $\mathbb{R}$ . Let  $(\mathcal{C}(X), \|\cdot\|_\infty)$  be the space of  $\mathbb{F}$ -valued continuous functions on a compact Hausdorff space  $X$ .

# Characterization of best approximation in $\mathcal{C}(X)$

**Notation:**  $\mathbb{F}$  will stand for  $\mathbb{C}$  or  $\mathbb{R}$ . Let  $(\mathcal{C}(X), \|\cdot\|_\infty)$  be the space of  $\mathbb{F}$ -valued continuous functions on a compact Hausdorff space  $X$ .

## Theorem (Singer I., 1970)

*Let  $f \in \mathcal{C}(X)$  and  $W$  is a subspace of  $\mathcal{C}(X)$ . Let  $g \in W$ , then the following are equivalent:*

# Characterization of best approximation in $\mathcal{C}(X)$

**Notation:**  $\mathbb{F}$  will stand for  $\mathbb{C}$  or  $\mathbb{R}$ . Let  $(\mathcal{C}(X), \|\cdot\|_\infty)$  be the space of  $\mathbb{F}$ -valued continuous functions on a compact Hausdorff space  $X$ .

## Theorem (Singer I., 1970)

Let  $f \in \mathcal{C}(X)$  and  $W$  is a subspace of  $\mathcal{C}(X)$ . Let  $g \in W$ , then the following are equivalent:

- ①  $g$  is a best approximation to  $f$  in  $W$ .
- ② There exists a regular Borel probability measure  $\mu$  on  $X$  such that
  - a) the support of  $\mu$  is contained in the set  $\{x \in X : |(f - g)(x)| = \|f - g\|_\infty\}$  and
  - b)  $\int_X (f - g)h \, d\mu = 0$  for all  $h \in W$ .

# Characterization of best approximation in $\mathcal{C}(X)$

**Notation:**  $\mathbb{F}$  will stand for  $\mathbb{C}$  or  $\mathbb{R}$ . Let  $(\mathcal{C}(X), \|\cdot\|_\infty)$  be the space of  $\mathbb{F}$ -valued continuous functions on a compact Hausdorff space  $X$ .

## Theorem (Singer I., 1970)

Let  $f \in \mathcal{C}(X)$  and  $W$  is a subspace of  $\mathcal{C}(X)$ . Let  $g \in W$ , then the following are equivalent:

- ①  $g$  is a best approximation to  $f$  in  $W$ .
- ② There exists a regular Borel probability measure  $\mu$  on  $X$  such that
  - a) the support of  $\mu$  is contained in the set  $\{x \in X : |(f - g)(x)| = \|f - g\|_\infty\}$  and
  - b)  $\int_X (f - g)h \, d\mu = 0$  for all  $h \in W$ .

(1) is equivalent to  $\int_X \overline{(f - g)}(f - g) \, d\mu = \|f - g\|_\infty^2$ .

# Characterization of best approximation in $\mathcal{C}(X)$

**Notation:**  $\mathbb{F}$  will stand for  $\mathbb{C}$  or  $\mathbb{R}$ . Let  $(\mathcal{C}(X), \|\cdot\|_\infty)$  be the space of  $\mathbb{F}$ -valued continuous functions on a compact Hausdorff space  $X$ .

## Theorem (Singer I., 1970)

Let  $f \in \mathcal{C}(X)$  and  $W$  is a subspace of  $\mathcal{C}(X)$ . Let  $g \in W$ , then the following are equivalent:

- ①  $g$  is a best approximation to  $f$  in  $W$ .
- ② There exists a regular Borel probability measure  $\mu$  on  $X$  such that
  - a) the support of  $\mu$  is contained in the set  $\{x \in X : |(f - g)(x)| = \|f - g\|_\infty\}$  and
  - b)  $\int_X (f - g)h \, d\mu = 0$  for all  $h \in W$ .

(1) is equivalent to  $\int_X \overline{(f - g)}(f - g) \, d\mu = \|f - g\|_\infty^2$ .

# Characterization of Birkhoff-James orthogonality in $\mathbb{M}_n(\mathbb{F})$

Let  $\mathbb{M}_n(\mathbb{F})$  be the space of  $n \times n$  matrices with entries in  $\mathbb{F}$ . A *density matrix*  $A \in \mathbb{M}_n(\mathbb{F})$  is a non-negative matrix with  $\text{trace}(A) = 1$ .

# Characterization of Birkhoff-James orthogonality in $\mathbb{M}_n(\mathbb{F})$

Let  $\mathbb{M}_n(\mathbb{F})$  be the space of  $n \times n$  matrices with entries in  $\mathbb{F}$ . A *density matrix*  $A \in \mathbb{M}_n(\mathbb{F})$  is a non-negative matrix with  $\text{trace}(A) = 1$ .

Theorem (Grover P., 2014)

Let  $A \in \mathbb{M}_n(\mathbb{F})$  and  $\mathcal{W}$  be a subspace of  $\mathbb{M}_n(\mathbb{F})$ .

# Characterization of Birkhoff-James orthogonality in $\mathbb{M}_n(\mathbb{F})$

Let  $\mathbb{M}_n(\mathbb{F})$  be the space of  $n \times n$  matrices with entries in  $\mathbb{F}$ . A *density matrix*  $A \in \mathbb{M}_n(\mathbb{F})$  is a non-negative matrix with  $\text{trace}(A) = 1$ .

**Theorem (Grover P., 2014)**

*Let  $A \in \mathbb{M}_n(\mathbb{F})$  and  $\mathcal{W}$  be a subspace of  $\mathbb{M}_n(\mathbb{F})$ . Then  $A$  is Birkhoff-James orthogonal to  $\mathcal{W}$*



# Characterization of Birkhoff-James orthogonality in $\mathbb{M}_n(\mathbb{F})$

Let  $\mathbb{M}_n(\mathbb{F})$  be the space of  $n \times n$  matrices with entries in  $\mathbb{F}$ . A *density matrix*  $A \in \mathbb{M}_n(\mathbb{F})$  is a non-negative matrix with  $\text{trace}(A) = 1$ .

## Theorem (Grover P., 2014)

*Let  $A \in \mathbb{M}_n(\mathbb{F})$  and  $\mathcal{W}$  be a subspace of  $\mathbb{M}_n(\mathbb{F})$ . Then  $A$  is Birkhoff-James orthogonal to  $\mathcal{W}$  if and only if there exists a density matrix  $T \in \mathbb{M}_n(\mathbb{F})$  such that  $A^*AT = \|A\|^2 T$  and  $\text{trace}(B^*AT) = 0$  for all  $B \in \mathcal{W}$ .*

# Characterization of Birkhoff-James orthogonality in $\mathbb{M}_n(\mathbb{F})$

Let  $\mathbb{M}_n(\mathbb{F})$  be the space of  $n \times n$  matrices with entries in  $\mathbb{F}$ . A *density matrix*  $A \in \mathbb{M}_n(\mathbb{F})$  is a non-negative matrix with  $\text{trace}(A) = 1$ .

## Theorem (Grover P., 2014)

*Let  $A \in \mathbb{M}_n(\mathbb{F})$  and  $\mathcal{W}$  be a subspace of  $\mathbb{M}_n(\mathbb{F})$ . Then  $A$  is Birkhoff-James orthogonal to  $\mathcal{W}$  if and only if there exists a density matrix  $T \in \mathbb{M}_n(\mathbb{F})$  such that  $A^*AT = \|A\|^2 T$  and  $\text{trace}(B^*AT) = 0$  for all  $B \in \mathcal{W}$ .*

Density matrices correspond to states on  $\mathbb{M}_n(\mathbb{F})$  and  $\text{trace}(A^*AT) = \|A\|^2$  is equivalent to  $A^*AT = \|A\|^2 T$ .

# Characterization of Birkhoff-James orthogonality in $\mathbb{M}_n(\mathbb{F})$

Let  $\mathbb{M}_n(\mathbb{F})$  be the space of  $n \times n$  matrices with entries in  $\mathbb{F}$ . A *density matrix*  $A \in \mathbb{M}_n(\mathbb{F})$  is a non-negative matrix with  $\text{trace}(A) = 1$ .

## Theorem (Grover P., 2014)

*Let  $A \in \mathbb{M}_n(\mathbb{F})$  and  $\mathcal{W}$  be a subspace of  $\mathbb{M}_n(\mathbb{F})$ . Then  $A$  is Birkhoff-James orthogonal to  $\mathcal{W}$  if and only if there exists a density matrix  $T \in \mathbb{M}_n(\mathbb{F})$  such that  $A^*AT = \|A\|^2 T$  and  $\text{trace}(B^*AT) = 0$  for all  $B \in \mathcal{W}$ .*

Density matrices correspond to states on  $\mathbb{M}_n(\mathbb{F})$  and  $\text{trace}(A^*AT) = \|A\|^2$  is equivalent to  $A^*AT = \|A\|^2 T$ .

# Corollaries

Theorem (Bhatia R.; Šemrl P., 1999)

*A matrix  $A$  is orthogonal to  $B$  if and only if there exist unit vector  $x$  such that  $\|Ax\| = \|A\|$  and  $\langle Ax|Bx\rangle = 0$ .*

# Corollaries

Theorem (Bhatia R.; Šemrl P., 1999)

*A matrix  $A$  is orthogonal to  $B$  if and only if there exist unit vector  $x$  such that  $\|Ax\| = \|A\|$  and  $\langle Ax|Bx \rangle = 0$ .*

# Corollaries

Theorem (Bhatia R.; Šemrl P., 1999)

*A matrix  $A$  is orthogonal to  $B$  if and only if there exist unit vector  $x$  such that  $\|Ax\| = \|A\|$  and  $\langle Ax|Bx\rangle = 0$ .*

A related to question will be given  $a, b \in \mathcal{A}$ , if  $a$  orthogonal to  $b$ , can we find a pur state  $\phi$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$ ?

# Corollaries

Theorem (Bhatia R.; Šemrl P., 1999)

*A matrix  $A$  is orthogonal to  $B$  if and only if there exist unit vector  $x$  such that  $\|Ax\| = \|A\|$  and  $\langle Ax|Bx\rangle = 0$ .*

A related to question will be given  $a, b \in \mathcal{A}$ , if  $a$  orthogonal to  $b$ , can we find a pur state  $\phi$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$ ? (answer is still unknown)

# Corollaries

## Theorem (Bhatia R.; Šemrl P., 1999)

*A matrix  $A$  is orthogonal to  $B$  if and only if there exist unit vector  $x$  such that  $\|Ax\| = \|A\|$  and  $\langle Ax | Bx \rangle = 0$ .*

A related to question will be given  $a, b \in \mathcal{A}$ , if  $a$  orthogonal to  $b$ , can we find a pur state  $\phi$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$ ? (answer is still unknown)

## Theorem (Rieffel M. A., 2011)

*Let  $a \in \mathcal{A}$  be a Hermitian element and  $\mathcal{B}$  be a  $C^*$ -subalgebra of  $\mathcal{A}$ . If  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$ , then there exists  $\phi \in S_{\mathcal{A}}$  such that  $\phi(a^2) = \|a\|^2$  and  $\phi(ab + b^*a) = 0$  for all  $b \in \mathcal{B}$ .*



# Corollaries

## Theorem (Bhatia R.; Šemrl P., 1999)

*A matrix  $A$  is orthogonal to  $B$  if and only if there exist unit vector  $x$  such that  $\|Ax\| = \|A\|$  and  $\langle Ax | Bx \rangle = 0$ .*

A related to question will be given  $a, b \in \mathcal{A}$ , if  $a$  orthogonal to  $b$ , can we find a pur state  $\phi$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$ ? (answer is still unknown)

## Theorem (Rieffel M. A., 2011)

*Let  $a \in \mathcal{A}$  be a Hermitian element and  $\mathcal{B}$  be a  $C^*$ -subalgebra of  $\mathcal{A}$ . If  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$ , then there exists  $\phi \in S_{\mathcal{A}}$  such that  $\phi(a^2) = \|a\|^2$  and  $\phi(ab + b^*a) = 0$  for all  $b \in \mathcal{B}$ .*

# Corollaries

## Theorem (Bhatia R.; Šemrl P., 1999)

*A matrix  $A$  is orthogonal to  $B$  if and only if there exist unit vector  $x$  such that  $\|Ax\| = \|A\|$  and  $\langle Ax | Bx \rangle = 0$ .*

A related to question will be given  $a, b \in \mathcal{A}$ , if  $a$  orthogonal to  $b$ , can we find a pur state  $\phi$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$ ? (answer is still unknown)

## Theorem (Rieffel M. A., 2011)

*Let  $a \in \mathcal{A}$  be a Hermitian element and  $\mathcal{B}$  be a  $C^*$ -subalgebra of  $\mathcal{A}$ . If  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$ , then there exists  $\phi \in S_{\mathcal{A}}$  such that  $\phi(a^2) = \|a\|^2$  and  $\phi(ab + b^*a) = 0$  for all  $b \in \mathcal{B}$ .*

# Application to distance formulas

## Theorem (Williams J. P., 1970)

For  $a \in \mathcal{A}$ , we have

$$\text{dist}(a, \mathbb{C}1_{\mathcal{A}})^2 = \max\{\phi(a^*a) - |\phi(a)|^2 : \phi \in \mathcal{S}_{\mathcal{A}}\}.$$

*Proof.* There exists  $\lambda_0 \in \mathbb{C}$  such that  $\text{dist}(a, \mathbb{C}1_{\mathcal{A}}) = \|a - \lambda_0 1_{\mathcal{A}}\|$ .

# Application to distance formulas

## Theorem (Williams J. P., 1970)

For  $a \in \mathcal{A}$ , we have

$$\text{dist}(a, \mathbb{C}1_{\mathcal{A}})^2 = \max\{\phi(a^*a) - |\phi(a)|^2 : \phi \in \mathcal{S}_{\mathcal{A}}\}.$$

*Proof.* There exists  $\lambda_0 \in \mathbb{C}$  such that  $\text{dist}(a, \mathbb{C}1_{\mathcal{A}}) = \|a - \lambda_0 1_{\mathcal{A}}\|$ .

Then there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that

$$\phi((a - \lambda_0 1_{\mathcal{A}})^*(a - \lambda_0 1_{\mathcal{A}})) = \text{dist}(a, \mathbb{C}1_{\mathcal{A}})^2$$

and  $\phi(a - \lambda_0 1_{\mathcal{A}}) = 0$ . □

# Application to distance formulas

## Theorem (Williams J. P., 1970)

For  $a \in \mathcal{A}$ , we have

$$\text{dist}(a, \mathbb{C}1_{\mathcal{A}})^2 = \max\{\phi(a^*a) - |\phi(a)|^2 : \phi \in \mathcal{S}_{\mathcal{A}}\}.$$

*Proof.* There exists  $\lambda_0 \in \mathbb{C}$  such that  $\text{dist}(a, \mathbb{C}1_{\mathcal{A}}) = \|a - \lambda_0 1_{\mathcal{A}}\|$ .

Then there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that

$$\phi((a - \lambda_0 1_{\mathcal{A}})^*(a - \lambda_0 1_{\mathcal{A}})) = \text{dist}(a, \mathbb{C}1_{\mathcal{A}})^2$$

and  $\phi(a - \lambda_0 1_{\mathcal{A}}) = 0$ . □

# Application to distance formulas

## Theorem (Williams J. P., 1970)

For  $a \in \mathcal{A}$ , we have

$$\text{dist}(a, \mathbb{C}1_{\mathcal{A}})^2 = \max\{\phi(a^*a) - |\phi(a)|^2 : \phi \in \mathcal{S}_{\mathcal{A}}\}.$$

*Proof.* There exists  $\lambda_0 \in \mathbb{C}$  such that  $\text{dist}(a, \mathbb{C}1_{\mathcal{A}}) = \|a - \lambda_0 1_{\mathcal{A}}\|$ .

Then there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that

$$\phi((a - \lambda_0 1_{\mathcal{A}})^*(a - \lambda_0 1_{\mathcal{A}})) = \text{dist}(a, \mathbb{C}1_{\mathcal{A}})^2$$

and  $\phi(a - \lambda_0 1_{\mathcal{A}}) = 0$ . □

A generalization of this will be :

## Theorem (Grover P.; Singla S., 2021)

Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Let  $b_0$  be a best approximation to  $a$  in  $\mathcal{B}$ . Then

$$\text{dist}(a, \mathcal{B})^2 = \max\{\phi(a^*a) - \phi(b_0^*b_0) : \phi \in \mathcal{S}_{\mathcal{A}} \text{ and } \phi(a^*b) = \phi(b_0^*b) \text{ for all } b \in \mathcal{B}\}.$$

# A distance formulas in terms of representation

## Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Suppose there is a best approximation to  $a$  in  $\mathcal{B}$ . Then*

$$\text{dist}(a, \mathcal{B}) = \max \left\{ |\langle \pi(a)\xi | \eta \rangle| : (\mathcal{H}, \pi, \xi) \text{ is cyclic representation of } \mathcal{A}, \right. \\ \left. \eta \in \mathcal{H}, \|\eta\| = 1 \text{ and } \langle \pi(b)\xi | \eta \rangle = 0 \text{ for all } b \in \mathcal{B} \right\}.$$

*Proof.* Clearly  $RHS \leq LHS$ .

# A distance formulas in terms of representation

## Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Suppose there is a best approximation to  $a$  in  $\mathcal{B}$ . Then*

$$\text{dist}(a, \mathcal{B}) = \max \left\{ |\langle \pi(a)\xi | \eta \rangle| : (\mathcal{H}, \pi, \xi) \text{ is cyclic representation of } \mathcal{A}, \right. \\ \left. \eta \in \mathcal{H}, \|\eta\| = 1 \text{ and } \langle \pi(b)\xi | \eta \rangle = 0 \text{ for all } b \in \mathcal{B} \right\}.$$

*Proof.* Clearly  $RHS \leq LHS$ . Let  $b_0$  be a best approximation to  $a$  in  $\mathcal{B}$ .



# A distance formulas in terms of representation

## Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Suppose there is a best approximation to  $a$  in  $\mathcal{B}$ . Then*

$$\text{dist}(a, \mathcal{B}) = \max \left\{ \left| \langle \pi(a)\xi | \eta \rangle \right| : (\mathcal{H}, \pi, \xi) \text{ is cyclic representation of } \mathcal{A}, \right. \\ \left. \eta \in \mathcal{H}, \|\eta\| = 1 \text{ and } \langle \pi(b)\xi | \eta \rangle = 0 \text{ for all } b \in \mathcal{B} \right\}.$$

*Proof.* Clearly  $RHS \leq LHS$ . Let  $b_0$  be a best approximation to  $a$  in  $\mathcal{B}$ . Then there exists  $\phi \in S_{\mathcal{A}}$  such that  $\|a - b_0\|_{\phi} = \|a - b_0\|$  and  $\langle a - b_0 | b \rangle_{\phi} = 0$  for all  $b \in \mathcal{B}$ .

# A distance formulas in terms of representation

## Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Suppose there is a best approximation to  $a$  in  $\mathcal{B}$ . Then*

$$\text{dist}(a, \mathcal{B}) = \max \left\{ |\langle \pi(a)\xi | \eta \rangle| : (\mathcal{H}, \pi, \xi) \text{ is cyclic representation of } \mathcal{A}, \right. \\ \left. \eta \in \mathcal{H}, \|\eta\| = 1 \text{ and } \langle \pi(b)\xi | \eta \rangle = 0 \text{ for all } b \in \mathcal{B} \right\}.$$

*Proof.* Clearly  $RHS \leq LHS$ . Let  $b_0$  be a best approximation to  $a$  in  $\mathcal{B}$ . Then there exists  $\phi \in S_{\mathcal{A}}$  such that  $\|a - b_0\|_{\phi} = \|a - b_0\|$  and  $\langle a - b_0 | b \rangle_{\phi} = 0$  for all  $b \in \mathcal{B}$ . Now there exists a cyclic representation  $(\mathcal{H}, \pi, \xi)$  such that  $\phi(c) = \langle \pi(c)\xi | \xi \rangle$  for all  $c \in \mathcal{A}$ .

# A distance formulas in terms of representation

## Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Suppose there is a best approximation to  $a$  in  $\mathcal{B}$ . Then*

$$\text{dist}(a, \mathcal{B}) = \max \left\{ \left| \langle \pi(a)\xi | \eta \rangle \right| : (\mathcal{H}, \pi, \xi) \text{ is cyclic representation of } \mathcal{A}, \right. \\ \left. \eta \in \mathcal{H}, \|\eta\| = 1 \text{ and } \langle \pi(b)\xi | \eta \rangle = 0 \text{ for all } b \in \mathcal{B} \right\}.$$

*Proof.* Clearly  $RHS \leq LHS$ . Let  $b_0$  be a best approximation to  $a$  in  $\mathcal{B}$ . Then there exists  $\phi \in S_{\mathcal{A}}$  such that  $\|a - b_0\|_{\phi} = \|a - b_0\|$  and  $\langle a - b_0 | b \rangle_{\phi} = 0$  for all  $b \in \mathcal{B}$ . Now there exists a cyclic representation  $(\mathcal{H}, \pi, \xi)$  such that  $\phi(c) = \langle \pi(c)\xi | \xi \rangle$  for all  $c \in \mathcal{A}$ . So  $\|\pi(a - b_0)\xi\| = \|a - b_0\|$  and  $\langle \pi(a - b_0)\xi | \pi(b)\xi \rangle = 0$  for all  $b \in \mathcal{B}$ .

# A distance formulas in terms of representation

## Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Suppose there is a best approximation to  $a$  in  $\mathcal{B}$ . Then*

$$\text{dist}(a, \mathcal{B}) = \max \left\{ |\langle \pi(a)\xi | \eta \rangle| : (\mathcal{H}, \pi, \xi) \text{ is cyclic representation of } \mathcal{A}, \right. \\ \left. \eta \in \mathcal{H}, \|\eta\| = 1 \text{ and } \langle \pi(b)\xi | \eta \rangle = 0 \text{ for all } b \in \mathcal{B} \right\}.$$

*Proof.* Clearly  $RHS \leq LHS$ . Let  $b_0$  be a best approximation to  $a$  in  $\mathcal{B}$ . Then there exists  $\phi \in S_{\mathcal{A}}$  such that  $\|a - b_0\|_{\phi} = \|a - b_0\|$  and  $\langle a - b_0 | b \rangle_{\phi} = 0$  for all  $b \in \mathcal{B}$ . Now there exists a cyclic representation  $(\mathcal{H}, \pi, \xi)$  such that  $\phi(c) = \langle \pi(c)\xi | \xi \rangle$  for all  $c \in \mathcal{A}$ . So  $\|\pi(a - b_0)\xi\| = \|a - b_0\|$  and  $\langle \pi(a - b_0)\xi | \pi(b)\xi \rangle = 0$  for all  $b \in \mathcal{B}$ . Taking  $\eta = \frac{1}{\|a - b_0\|} \pi(a - b_0)\xi$ , we get the required result.

# A distance formulas in terms of conditional expectation

Theorem (P. Grover, 2014)

*Let  $\mathcal{B}$  be  $C^*$ -subalgebra of  $(\mathbb{C})$  containing identity matrix. Let  $\mathcal{C}_{\mathcal{B}}$  be orthogonal projection of  $\mathbb{M}_n(\mathbb{C})$  onto  $\mathcal{B}$ .*

# A distance formulas in terms of conditional expectation

## Theorem (P. Grover, 2014)

*Let  $\mathcal{B}$  be  $C^*$ -subalgebra of  $(\mathbb{C})$  containing identity matrix. Let  $\mathcal{C}_{\mathcal{B}}$  be orthogonal projection of  $\mathbb{M}_n(\mathbb{C})$  onto  $\mathcal{B}$ . Then*

$$\text{dist}(a, \mathcal{B})^2 = \max\{\text{trace}(A^*AP - \mathcal{C}_{\mathcal{B}}(AP)^*\mathcal{C}_{\mathcal{B}}(AP)\mathcal{C}_{\mathcal{B}}(P)^{-1} : \\ P \geq 0, \text{trace}(P) = 1\}.$$

# A distance formulas in terms of conditional expectation

## Theorem (P. Grover, 2014)

*Let  $\mathcal{B}$  be  $C^*$ -subalgebra of  $(\mathbb{C})$  containing identity matrix. Let  $\mathcal{C}_{\mathcal{B}}$  be orthogonal projection of  $\mathbb{M}_n(\mathbb{C})$  onto  $\mathcal{B}$ . Then*

$$\text{dist}(a, \mathcal{B})^2 = \max\{\text{trace}(A^*AP - \mathcal{C}_{\mathcal{B}}(AP)^*\mathcal{C}_{\mathcal{B}}(AP)\mathcal{C}_{\mathcal{B}}(P)^{-1} : \\ P \geq 0, \text{trace}(P) = 1\}.$$

## Theorem

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be  $C^*$ -subalgebra of  $\mathcal{A}$  containing  $1_{\mathcal{A}}$ .*

# A distance formulas in terms of conditional expectation

## Theorem (P. Grover, 2014)

*Let  $\mathcal{B}$  be  $C^*$ -subalgebra of  $(\mathbb{C})$  containing identity matrix. Let  $\mathcal{C}_{\mathcal{B}}$  be orthogonal projection of  $\mathbb{M}_n(\mathbb{C})$  onto  $\mathcal{B}$ . Then*

$$\text{dist}(a, \mathcal{B})^2 = \max\{\text{trace}(A^*AP - \mathcal{C}_{\mathcal{B}}(AP)^*\mathcal{C}_{\mathcal{B}}(AP)\mathcal{C}_{\mathcal{B}}(P)^{-1} : \\ P \geq 0, \text{trace}(P) = 1\}.$$

## Theorem

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be  $C^*$ -subalgebra of  $\mathcal{A}$  containing  $1_{\mathcal{A}}$ . Then*

$$\text{dist}(a, \mathcal{B})^2 \geq \sup\{\phi(E(a^*a) - E(a)^*E(a)) : \phi \in \mathcal{S}_{\mathcal{A}}, \\ E \text{ is a conditional expectation from } \mathcal{A} \text{ to } \mathcal{B}\}.$$



# A distance formulas in terms of conditional expectation

## Theorem (P. Grover, 2014)

*Let  $\mathcal{B}$  be  $C^*$ -subalgebra of  $(\mathbb{C})$  containing identity matrix. Let  $\mathcal{C}_{\mathcal{B}}$  be orthogonal projection of  $\mathbb{M}_n(\mathbb{C})$  onto  $\mathcal{B}$ . Then*

$$\text{dist}(a, \mathcal{B})^2 = \max\{\text{trace}(A^*AP - \mathcal{C}_{\mathcal{B}}(AP)^*\mathcal{C}_{\mathcal{B}}(AP)\mathcal{C}_{\mathcal{B}}(P)^{-1} : \\ P \geq 0, \text{trace}(P) = 1\}.$$

## Theorem

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be  $C^*$ -subalgebra of  $\mathcal{A}$  containing  $1_{\mathcal{A}}$ . Then*

$$\text{dist}(a, \mathcal{B})^2 \geq \sup\{\phi(E(a^*a) - E(a)^*E(a)) : \phi \in \mathcal{S}_{\mathcal{A}}, \\ E \text{ is a conditional expectation from } \mathcal{A} \text{ to } \mathcal{B}\}.$$

We know equality occurs when  $\mathcal{B} = \mathbb{C}1_{\mathcal{A}}$

# A distance formulas in terms of conditional expectation

## Theorem (P. Grover, 2014)

*Let  $\mathcal{B}$  be  $C^*$ -subalgebra of  $(\mathbb{C})$  containing identity matrix. Let  $\mathcal{C}_{\mathcal{B}}$  be orthogonal projection of  $\mathbb{M}_n(\mathbb{C})$  onto  $\mathcal{B}$ . Then*

$$\text{dist}(a, \mathcal{B})^2 = \max\{\text{trace}(A^*AP - \mathcal{C}_{\mathcal{B}}(AP)^*\mathcal{C}_{\mathcal{B}}(AP)\mathcal{C}_{\mathcal{B}}(P)^{-1} : \\ P \geq 0, \text{trace}(P) = 1\}.$$

## Theorem

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be  $C^*$ -subalgebra of  $\mathcal{A}$  containing  $1_{\mathcal{A}}$ . Then*

$$\text{dist}(a, \mathcal{B})^2 \geq \sup\{\phi(E(a^*a) - E(a)^*E(a)) : \phi \in \mathcal{S}_{\mathcal{A}}, \\ E \text{ is a conditional expectation from } \mathcal{A} \text{ to } \mathcal{B}\}.$$

We know equality occurs when  $\mathcal{B} = \mathbb{C}1_{\mathcal{A}}$  and when  $\mathcal{B}$  is central, finite dimensional subspace but for general  $C^*$ -subalgebra, we still don't know.

# A distance formulas in terms of conditional expectation

## Theorem (P. Grover, 2014)

*Let  $\mathcal{B}$  be  $C^*$ -subalgebra of  $(\mathbb{C})$  containing identity matrix. Let  $\mathcal{C}_{\mathcal{B}}$  be orthogonal projection of  $\mathbb{M}_n(\mathbb{C})$  onto  $\mathcal{B}$ . Then*

$$\text{dist}(a, \mathcal{B})^2 = \max\{\text{trace}(A^*AP - \mathcal{C}_{\mathcal{B}}(AP)^*\mathcal{C}_{\mathcal{B}}(AP)\mathcal{C}_{\mathcal{B}}(P)^{-1} : \\ P \geq 0, \text{trace}(P) = 1\}.$$

## Theorem

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be  $C^*$ -subalgebra of  $\mathcal{A}$  containing  $1_{\mathcal{A}}$ . Then*

$$\text{dist}(a, \mathcal{B})^2 \geq \sup\{\phi(E(a^*a) - E(a)^*E(a)) : \phi \in \mathcal{S}_{\mathcal{A}}, \\ E \text{ is a conditional expectation from } \mathcal{A} \text{ to } \mathcal{B}\}.$$

We know equality occurs when  $\mathcal{B} = \mathbb{C}1_{\mathcal{A}}$  and when  $\mathcal{B}$  is central, finite dimensional subspace but for general  $C^*$ -subalgebra, we still don't know.

# Table of Contents

1 States and orthogonality in  $C^*$ -algebra

2 Proofs and applications

# Birkhoff-James orthogonality as a calculus problem

We consider the function  $f(\lambda) = \|a + \lambda b\|$  mapping  $\mathbb{C}$  into  $\mathbb{R}_+$ .

# Birkhoff-James orthogonality as a calculus problem

We consider the function  $f(\lambda) = \|a + \lambda b\|$  mapping  $\mathbb{C}$  into  $\mathbb{R}_+$ . To say that  $a$  is orthogonal to  $b$  is to say that  $f$  attains its minimum at the point 0.

# Birkhoff-James orthogonality as a calculus problem

We consider the function  $f(\lambda) = \|a + \lambda b\|$  mapping  $\mathbb{C}$  into  $\mathbb{R}_+$ . To say that  $a$  is orthogonal to  $b$  is to say that  $f$  attains its minimum at the point 0. This is clearly a calculus problem, except that the function  $\|\cdot\|$  is not differentiable.

# Birkhoff-James orthogonality as a calculus problem

We consider the function  $f(\lambda) = \|a + \lambda b\|$  mapping  $\mathbb{C}$  into  $\mathbb{R}_+$ . To say that  $a$  is orthogonal to  $b$  is to say that  $f$  attains its minimum at the point 0. This is clearly a calculus problem, except that the function  $\|\cdot\|$  is not differentiable.

So we can't use first derivative test. But  $\|\cdot\|$  is also convex, this gives motivation to define Gateaux derivative



# Birkhoff-James orthogonality as a calculus problem

We consider the function  $f(\lambda) = \|a + \lambda b\|$  mapping  $\mathbb{C}$  into  $\mathbb{R}_+$ . To say that  $a$  is orthogonal to  $b$  is to say that  $f$  attains its minimum at the point 0. This is clearly a calculus problem, except that the function  $\|\cdot\|$  is not differentiable.

So we can't use first derivative test. But  $\|\cdot\|$  is also convex, this gives motivation to define Gateaux derivative and we will see characterization of orthogonality in terms of Gateaux derivative.

# Birkhoff-James orthogonality as a calculus problem

We consider the function  $f(\lambda) = \|a + \lambda b\|$  mapping  $\mathbb{C}$  into  $\mathbb{R}_+$ . To say that  $a$  is orthogonal to  $b$  is to say that  $f$  attains its minimum at the point 0. This is clearly a calculus problem, except that the function  $\|\cdot\|$  is not differentiable.

So we can't use first derivative test. But  $\|\cdot\|$  is also convex, this gives motivation to define Gateaux derivative and we will see characterization of orthogonality in terms of Gateaux derivative.

# Gateaux derivative and orthogonality

## Theorem

Let  $X$  be a Banach space,  $x, y \in X$ , and  $\phi \in [0, 2\pi)$ .

- 1 The function  $\alpha : \mathbb{R} \rightarrow \mathbb{R}$ ,  $\alpha(t) = \|x + ty\|$  is convex.

# Gateaux derivative and orthogonality

## Theorem

Let  $X$  be a Banach space,  $x, y \in X$ , and  $\phi \in [0, 2\pi)$ .

- 1 The function  $\alpha : \mathbb{R} \rightarrow \mathbb{R}$ ,  $\alpha(t) = \|x + ty\|$  is convex. Hence the limit  $D_{0,x}(y) = \lim_{t \rightarrow 0^+} \frac{\|x + ty\| - \|x\|}{t}$  always exists.

# Gateaux derivative and orthogonality

## Theorem

Let  $X$  be a Banach space,  $x, y \in X$ , and  $\phi \in [0, 2\pi)$ .

- ① The function  $\alpha : \mathbb{R} \rightarrow \mathbb{R}$ ,  $\alpha(t) = \|x + ty\|$  is convex. Hence the limit  $D_{0,x}(y) = \lim_{t \rightarrow 0^+} \frac{\|x + ty\| - \|x\|}{t}$  always exists.
- ② We have  $\|x + ty\| \geq \|x\|$  for all  $t \in \mathbb{R}$  if and only if the inequality  $D_{0,x}(y) \geq 0$  holds.

# Gateaux derivative and orthogonality

## Theorem

Let  $X$  be a Banach space,  $x, y \in X$ , and  $\phi \in [0, 2\pi)$ .

- ① The function  $\alpha : \mathbb{R} \rightarrow \mathbb{R}$ ,  $\alpha(t) = \|x + ty\|$  is convex. Hence the limit  $D_{0,x}(y) = \lim_{t \rightarrow 0^+} \frac{\|x + ty\| - \|x\|}{t}$  always exists.
- ② We have  $\|x + ty\| \geq \|x\|$  for all  $t \in \mathbb{R}$  if and only if the inequality  $D_{0,x}(y) \geq 0$  holds.
- ③ And  $x$  is orthogonal to  $y$  if and only if  $\inf_{\phi} D_{\phi,x}(y) \geq 0$  where  $D_{\phi,x}(y) = \lim_{t \rightarrow 0^+} \frac{\|x + te^{i\phi}y\| - \|x\|}{t}$

# Gateaux derivative and orthogonality

## Theorem

Let  $X$  be a Banach space,  $x, y \in X$ , and  $\phi \in [0, 2\pi)$ .

- 1 The function  $\alpha : \mathbb{R} \rightarrow \mathbb{R}$ ,  $\alpha(t) = \|x + ty\|$  is convex. Hence the limit  $D_{0,x}(y) = \lim_{t \rightarrow 0^+} \frac{\|x + ty\| - \|x\|}{t}$  always exists.
- 2 We have  $\|x + ty\| \geq \|x\|$  for all  $t \in \mathbb{R}$  if and only if the inequality  $D_{0,x}(y) \geq 0$  holds.
- 3 And  $x$  is orthogonal to  $y$  if and only if  $\inf_{\phi} D_{\phi,x}(y) \geq 0$  where  $D_{\phi,x}(y) = \lim_{t \rightarrow 0^+} \frac{\|x + te^{i\phi}y\| - \|x\|}{t}$  is called the  $\phi$ -Gateaux derivative of the norm at the vector  $x$ , in the  $y$  and  $\phi$  directions.

# Gateaux derivative and orthogonality

## Theorem

Let  $X$  be a Banach space,  $x, y \in X$ , and  $\phi \in [0, 2\pi)$ .

- 1 The function  $\alpha : \mathbb{R} \rightarrow \mathbb{R}$ ,  $\alpha(t) = \|x + ty\|$  is convex. Hence the limit  $D_{0,x}(y) = \lim_{t \rightarrow 0^+} \frac{\|x + ty\| - \|x\|}{t}$  always exists.
- 2 We have  $\|x + ty\| \geq \|x\|$  for all  $t \in \mathbb{R}$  if and only if the inequality  $D_{0,x}(y) \geq 0$  holds.
- 3 And  $x$  is orthogonal to  $y$  if and only if  $\inf_{\phi} D_{\phi,x}(y) \geq 0$  where  $D_{\phi,x}(y) = \lim_{t \rightarrow 0^+} \frac{\|x + te^{i\phi}y\| - \|x\|}{t}$  is called the  $\phi$ -Gateaux derivative of the norm at the vector  $x$ , in the  $y$  and  $\phi$  directions.



# Proof using tools of convex analysis

Lemma (Singla S., 2021)

Let  $a, b \in \mathcal{A}$ . Then

$$\lim_{t \rightarrow 0^+} \frac{\|a + tb\| - \|a\|}{t} = \frac{1}{\|a\|} \lim_{t \rightarrow 0^+} \frac{\|a^*a + ta^*b\| - \|a^*a\|}{t}.$$

# Proof using tools of convex analysis

Lemma (Singla S., 2021)

Let  $a, b \in \mathcal{A}$ . Then

$$\lim_{t \rightarrow 0^+} \frac{\|a + tb\| - \|a\|}{t} = \frac{1}{\|a\|} \lim_{t \rightarrow 0^+} \frac{\|a^*a + ta^*b\| - \|a^*a\|}{t}.$$

Thus we get  $D_{\phi,a}(b) = \frac{1}{\|a\|} D_{\phi,a^*a}(a^*b)$ .

# Proof using tools of convex analysis

Lemma (Singla S., 2021)

Let  $a, b \in \mathcal{A}$ . Then

$$\lim_{t \rightarrow 0^+} \frac{\|a + tb\| - \|a\|}{t} = \frac{1}{\|a\|} \lim_{t \rightarrow 0^+} \frac{\|a^*a + ta^*b\| - \|a^*a\|}{t}.$$

Thus we get  $D_{\phi,a}(b) = \frac{1}{\|a\|} D_{\phi,a^*a}(a^*b)$ .

This gives  $\inf_{\phi} D_{\phi,a}(b) \geq 0$  if and only if  $\inf_{\phi} D_{\phi,a^*a}(a^*b) \geq 0$

# Proof using tools of convex analysis

Lemma (Singla S., 2021)

Let  $a, b \in \mathcal{A}$ . Then

$$\lim_{t \rightarrow 0^+} \frac{\|a + tb\| - \|a\|}{t} = \frac{1}{\|a\|} \lim_{t \rightarrow 0^+} \frac{\|a^*a + ta^*b\| - \|a^*a\|}{t}.$$

Thus we get  $D_{\phi,a}(b) = \frac{1}{\|a\|} D_{\phi,a^*a}(a^*b)$ .

This gives  $\inf_{\phi} D_{\phi,a}(b) \geq 0$  if and only if  $\inf_{\phi} D_{\phi,a^*a}(a^*b) \geq 0$  i.e.  $a$  is orthogonal to  $b$  if and only if  $a^*a$  is orthogonal to  $a^*b$ .

# Proof using tools of convex analysis

Lemma (Singla S., 2021)

Let  $a, b \in \mathcal{A}$ . Then

$$\lim_{t \rightarrow 0^+} \frac{\|a + tb\| - \|a\|}{t} = \frac{1}{\|a\|} \lim_{t \rightarrow 0^+} \frac{\|a^*a + ta^*b\| - \|a^*a\|}{t}.$$

Thus we get  $D_{\phi,a}(b) = \frac{1}{\|a\|} D_{\phi,a^*a}(a^*b)$ .

This gives  $\inf_{\phi} D_{\phi,a}(b) \geq 0$  if and only if  $\inf_{\phi} D_{\phi,a^*a}(a^*b) \geq 0$  i.e.  $a$  is orthogonal to  $b$  if and only if  $a^*a$  is orthogonal to  $a^*b$ .

Then by the Hahn-Banach Theorem, there exists  $\phi \in \mathcal{A}^*$  such that  $\|\phi\| = 1$ ,  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .

# Proof using tools of convex analysis

Lemma (Singla S., 2021)

Let  $a, b \in \mathcal{A}$ . Then

$$\lim_{t \rightarrow 0^+} \frac{\|a + tb\| - \|a\|}{t} = \frac{1}{\|a\|} \lim_{t \rightarrow 0^+} \frac{\|a^*a + ta^*b\| - \|a^*a\|}{t}.$$

Thus we get  $D_{\phi,a}(b) = \frac{1}{\|a\|} D_{\phi,a^*a}(a^*b)$ .

This gives  $\inf_{\phi} D_{\phi,a}(b) \geq 0$  if and only if  $\inf_{\phi} D_{\phi,a^*a}(a^*b) \geq 0$  i.e.  $a$  is orthogonal to  $b$  if and only if  $a^*a$  is orthogonal to  $a^*b$ .

Then by the Hahn-Banach Theorem, there exists  $\phi \in \mathcal{A}^*$  such that  $\|\phi\| = 1$ ,  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ . And  $\phi$  is required state using fact it attains its norm at a non-zero positive element.

# Proof using tools of convex analysis

Lemma (Singla S., 2021)

Let  $a, b \in \mathcal{A}$ . Then

$$\lim_{t \rightarrow 0^+} \frac{\|a + tb\| - \|a\|}{t} = \frac{1}{\|a\|} \lim_{t \rightarrow 0^+} \frac{\|a^*a + ta^*b\| - \|a^*a\|}{t}.$$

Thus we get  $D_{\phi,a}(b) = \frac{1}{\|a\|} D_{\phi,a^*a}(a^*b)$ .

This gives  $\inf_{\phi} D_{\phi,a}(b) \geq 0$  if and only if  $\inf_{\phi} D_{\phi,a^*a}(a^*b) \geq 0$  i.e.  $a$  is orthogonal to  $b$  if and only if  $a^*a$  is orthogonal to  $a^*b$ .

Then by the Hahn-Banach Theorem, there exists  $\phi \in \mathcal{A}^*$  such that  $\|\phi\| = 1$ ,  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ . And  $\phi$  is required state using fact it attains its norm at a non-zero positive element.

# Expression for Gateaux derivative

For a normed space  $V$  and  $v, u \in V$ , we have

$$\lim_{t \rightarrow 0^+} \frac{\|v + tu\| - \|v\|}{t} = \max\{\operatorname{Re} f(u) : f \in V^*, f(v) = \|v\|, \|f\| = 1\}.$$



# Expression for Gateuax derivative

For a normed space  $V$  and  $v, u \in V$ , we have

$$\lim_{t \rightarrow 0^+} \frac{\|v + tu\| - \|v\|}{t} = \max\{\operatorname{Re} f(u) : f \in V^*, f(v) = \|v\|, \|f\| = 1\}.$$

## Theorem (Singla S., 2021)

Let  $a, b \in \mathcal{A}$ . Then we have

$$\lim_{t \rightarrow 0^+} \frac{\|a + tb\| - \|a\|}{t} = \frac{1}{\|a\|} \max\{\operatorname{Re} \phi(a^* b) : \phi \in \mathcal{S}_{\mathcal{A}}, \phi(a^* a) = \|a\|^2\}.$$

# Expression for Gateaux derivative

For a normed space  $V$  and  $v, u \in V$ , we have

$$\lim_{t \rightarrow 0^+} \frac{\|v + tu\| - \|v\|}{t} = \max\{\operatorname{Re} f(u) : f \in V^*, f(v) = \|v\|, \|f\| = 1\}.$$

## Theorem (Singla S., 2021)

Let  $a, b \in \mathcal{A}$ . Then we have

$$\lim_{t \rightarrow 0^+} \frac{\|a + tb\| - \|a\|}{t} = \frac{1}{\|a\|} \max\{\operatorname{Re} \phi(a^* b) : \phi \in \mathcal{S}_{\mathcal{A}}, \phi(a^* a) = \|a\|^2\}.$$

*Corollary.* For  $A, B \in \mathcal{K}(\mathcal{H})$ , we have

$$\lim_{t \rightarrow 0^+} \frac{\|A + tB\| - \|A\|}{t} = \frac{1}{\|A\|} \max_{\|u\|=1, A^*Au=\|A\|^2u} \operatorname{Re} \langle Au | Bu \rangle.$$

# Smooth points

We say that a vector  $v$  of norm one is a smooth point of the unit ball of  $V$  if there exists a unique functional  $F_v$ , called the support functional, such that  $\|F_v\| = 1$  and  $F_v(v) = 1$ .

# Smooth points

We say that a vector  $v$  of norm one is a smooth point of the unit ball of  $V$  if there exists a unique functional  $F_v$ , called the support functional, such that  $\|F_v\| = 1$  and  $F_v(v) = 1$ .

It is a general fact that  $v$  is a smooth point of the unit ball of  $v$  if and only if  $\lim_{t \rightarrow 0} \frac{\|v + tu\| - \|v\|}{t}$  exists

# Smooth points

We say that a vector  $v$  of norm one is a smooth point of the unit ball of  $V$  if there exists a unique functional  $F_v$ , called the support functional, such that  $\|F_v\| = 1$  and  $F_v(v) = 1$ .

It is a general fact that  $v$  is a smooth point of the unit ball of  $V$  if and only if  $\lim_{t \rightarrow 0} \frac{\|v + tu\| - \|v\|}{t}$  exists and in this case, it is equal to  $\operatorname{Re} F_v(u)$ .

# Smooth points

We say that a vector  $v$  of norm one is a smooth point of the unit ball of  $V$  if there exists a unique functional  $F_v$ , called the support functional, such that  $\|F_v\| = 1$  and  $F_v(v) = 1$ .

It is a general fact that  $v$  is a smooth point of the unit ball of  $V$  if and only if  $\lim_{t \rightarrow 0} \frac{\|v + tu\| - \|v\|}{t}$  exists and in this case, it is equal to  $\operatorname{Re} F_v(u)$ .

Now using these facts and expression for Gateaux derivative of norm for  $\mathcal{K}(\mathcal{H})$ , we get a characterization of smooth points of  $\mathcal{K}(\mathcal{H})$ .

# Smooth points

We say that a vector  $v$  of norm one is a smooth point of the unit ball of  $V$  if there exists a unique functional  $F_v$ , called the support functional, such that  $\|F_v\| = 1$  and  $F_v(v) = 1$ .

It is a general fact that  $v$  is a smooth point of the unit ball of  $V$  if and only if  $\lim_{t \rightarrow 0} \frac{\|v + tu\| - \|v\|}{t}$  exists and in this case, it is equal to  $\operatorname{Re} F_v(u)$ .

Now using these facts and expression for Gateaux derivative of norm for  $\mathcal{K}(\mathcal{H})$ , we get a characterization of smooth points of  $\mathcal{K}(\mathcal{H})$ .

# Smooth points in $\mathcal{K}(\mathcal{H})$ and $\mathcal{B}(\mathcal{H})$

Using  $\lim_{t \rightarrow 0^+} \frac{\|A + tB\| - \|A\|}{t} = \frac{1}{\|A\|} \max_{\|u\|=1, A^*Au=\|A\|^2u} \operatorname{Re}\langle Au|Bu\rangle$ ,  
we get



# Smooth points in $\mathcal{K}(\mathcal{H})$ and $\mathcal{B}(\mathcal{H})$

Using  $\lim_{t \rightarrow 0^+} \frac{\|A + tB\| - \|A\|}{t} = \frac{1}{\|A\|} \max_{\|u\|=1, A^*Au=\|A\|^2u} \operatorname{Re}\langle Au|Bu\rangle$ ,  
we get

**Theorem (Holub J. R., 1973)**

*An operator  $A$  is a smooth point of the unit ball of  $\mathcal{B}(\mathcal{H})$  if and only if  $A$  attains its norm at a unit vector  $h$*

# Smooth points in $\mathcal{K}(\mathcal{H})$ and $\mathcal{B}(\mathcal{H})$

Using  $\lim_{t \rightarrow 0^+} \frac{\|A + tB\| - \|A\|}{t} = \frac{1}{\|A\|} \max_{\|u\|=1, A^*Au=\|A\|^2u} \operatorname{Re}\langle Au|Bu\rangle$ ,  
we get

**Theorem (Holub J. R., 1973)**

*An operator  $A$  is a smooth point of the unit ball of  $\mathcal{B}(\mathcal{H})$  if and only if  $A$  attains its norm at a unit vector  $h$  such that*

$$\sup_{x \perp h, \|x\|=1} \|Ax\| < \|A\|.$$

# Smooth points in $\mathcal{K}(\mathcal{H})$ and $\mathcal{B}(\mathcal{H})$

Using  $\lim_{t \rightarrow 0^+} \frac{\|A + tB\| - \|A\|}{t} = \frac{1}{\|A\|} \max_{\|u\|=1, A^*Au=\|A\|^2u} \operatorname{Re}\langle Au|Bu\rangle$ ,  
we get

**Theorem (Holub J. R., 1973)**

*An operator  $A$  is a smooth point of the unit ball of  $\mathcal{B}(\mathcal{H})$  if and only if  $A$  attains its norm at a unit vector  $h$  such that*

*$\sup_{x \perp h, \|x\|=1} \|Ax\| < \|A\|$ . In that case,*

$$\lim_{t \rightarrow 0} \frac{\|A + tB\| - \|A\|}{t} = \operatorname{Re}\langle Ah|Bh\rangle.$$

# Smooth points in $\mathcal{K}(\mathcal{H})$ and $\mathcal{B}(\mathcal{H})$

Using  $\lim_{t \rightarrow 0^+} \frac{\|A + tB\| - \|A\|}{t} = \frac{1}{\|A\|} \max_{\|u\|=1, A^*Au=\|A\|^2u} \operatorname{Re}\langle Au|Bu\rangle$ ,  
we get

**Theorem (Holub J. R., 1973)**

*An operator  $A$  is a smooth point of the unit ball of  $\mathcal{B}(\mathcal{H})$  if and only if  $A$  attains its norm at a unit vector  $h$  such that*

*$\sup_{x \perp h, \|x\|=1} \|Ax\| < \|A\|$ . In that case,*

$$\lim_{t \rightarrow 0} \frac{\|A + tB\| - \|A\|}{t} = \operatorname{Re}\langle Ah|Bh\rangle.$$

The same result holds true for smooth points of unit ball of  $\mathcal{B}(\mathcal{H})$ .

Smooth points in  $\mathcal{K}(\mathcal{H})$  and  $\mathcal{B}(\mathcal{H})$ 

Using  $\lim_{t \rightarrow 0^+} \frac{\|A + tB\| - \|A\|}{t} = \frac{1}{\|A\|} \max_{\|u\|=1, A^*Au=\|A\|^2u} \operatorname{Re}\langle Au|Bu\rangle$ ,  
we get

## Theorem (Holub J. R., 1973)

*An operator  $A$  is a smooth point of the unit ball of  $\mathcal{B}(\mathcal{H})$  if and only if  $A$  attains its norm at a unit vector  $h$  such that*

*$\sup_{x \perp h, \|x\|=1} \|Ax\| < \|A\|$ . In that case,*

$$\lim_{t \rightarrow 0} \frac{\|A + tB\| - \|A\|}{t} = \operatorname{Re}\langle Ah|Bh\rangle.$$

The same result holds true for smooth points of unit ball of  $\mathcal{B}(\mathcal{H})$ .  
One of the proof can be done by modifying proofs for finding Gateaux derivative in  $C^*$ -algebra when  $a \in \mathcal{I}$  for a two sided ideal  $I$ .

Smooth points in  $\mathcal{K}(\mathcal{H})$  and  $\mathcal{B}(\mathcal{H})$ 

Using  $\lim_{t \rightarrow 0^+} \frac{\|A + tB\| - \|A\|}{t} = \frac{1}{\|A\|} \max_{\|u\|=1, A^*Au=\|A\|^2u} \operatorname{Re}\langle Au|Bu\rangle$ ,  
we get

## Theorem (Holub J. R., 1973)

*An operator  $A$  is a smooth point of the unit ball of  $\mathcal{B}(\mathcal{H})$  if and only if  $A$  attains its norm at a unit vector  $h$  such that*

*$\sup_{x \perp h, \|x\|=1} \|Ax\| < \|A\|$ . In that case,*

$$\lim_{t \rightarrow 0} \frac{\|A + tB\| - \|A\|}{t} = \operatorname{Re}\langle Ah|Bh\rangle.$$

The same result holds true for smooth points of unit ball of  $\mathcal{B}(\mathcal{H})$ . One of the proof can be done by modifying proofs for finding Gateaux derivative in  $C^*$ -algebra when  $a \in \mathcal{I}$  for a two sided ideal  $\mathcal{I}$ . And we have also been able to find such a formula under the condition  $\operatorname{dist}(a, \mathcal{I}) < \|a\|$  and using tools of  $M$ -ideals theory.

Smooth points in  $\mathcal{K}(\mathcal{H})$  and  $\mathcal{B}(\mathcal{H})$ 

Using  $\lim_{t \rightarrow 0^+} \frac{\|A + tB\| - \|A\|}{t} = \frac{1}{\|A\|} \max_{\|u\|=1, A^*Au=\|A\|^2u} \operatorname{Re}\langle Au|Bu\rangle$ ,  
we get

## Theorem (Holub J. R., 1973)

*An operator  $A$  is a smooth point of the unit ball of  $\mathcal{B}(\mathcal{H})$  if and only if  $A$  attains its norm at a unit vector  $h$  such that*

*$\sup_{x \perp h, \|x\|=1} \|Ax\| < \|A\|$ . In that case,*

$$\lim_{t \rightarrow 0} \frac{\|A + tB\| - \|A\|}{t} = \operatorname{Re}\langle Ah|Bh\rangle.$$

The same result holds true for smooth points of unit ball of  $\mathcal{B}(\mathcal{H})$ .

One of the proof can be done by modifying proofs for finding Gateaux derivative in  $C^*$ -algebra when  $a \in \mathcal{I}$  for a two sided ideal  $\mathcal{I}$ . And we have also been able to find such a formula under the condition  $\operatorname{dist}(a, \mathcal{I}) < \|a\|$  and using tools of  $M$ -ideals theory.

# Proof using representations of $C^*$ -algebra

Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*



# Proof using representations of $C^*$ -algebra

Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

*Proof.*

- 1 Reverse direction is easy. For all  $b \in \mathcal{B}$ ,

# Proof using representations of $C^*$ -algebra

Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

*Proof.*

① Reverse direction is easy. For all  $b \in \mathcal{B}$ ,

$$\|a\|^2 = \phi(a^*a) \leq \phi(a^*a) + \phi(b^*b) = \phi((a-b)^*(a-b)) \leq \|a-b\|^2.$$

# Proof using representations of $C^*$ -algebra

Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

*Proof.*

- ① Reverse direction is easy. For all  $b \in \mathcal{B}$ ,

$$\|a\|^2 = \phi(a^*a) \leq \phi(a^*a) + \phi(b^*b) = \phi((a-b)^*(a-b)) \leq \|a-b\|^2.$$

- ② Let  $a$  be Birkhoff-James orthogonal to  $\mathcal{B}$  i.e.  $\text{dist}(a, \mathcal{B}) = \|a\|$ .

# Proof using representations of $C^*$ -algebra

Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

*Proof.*

- ① Reverse direction is easy. For all  $b \in \mathcal{B}$ ,

$$\|a\|^2 = \phi(a^*a) \leq \phi(a^*a) + \phi(b^*b) = \phi((a-b)^*(a-b)) \leq \|a-b\|^2.$$

- ② Let  $a$  be Birkhoff-James orthogonal to  $\mathcal{B}$  i.e.  $\text{dist}(a, \mathcal{B}) = \|a\|$ .  
 ③ By the Hahn-Banach theorem, there exists  $\psi \in \mathcal{A}^*$  such that  $\|\psi\| = 1$ ,  $\psi(a) = \|a\|$  and  $\psi(b) = 0$  for all  $b \in \mathcal{B}$ .

# Proof using representations of $C^*$ -algebra

Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

*Proof.*

- ① Reverse direction is easy. For all  $b \in \mathcal{B}$ ,

$$\|a\|^2 = \phi(a^*a) \leq \phi(a^*a) + \phi(b^*b) = \phi((a-b)^*(a-b)) \leq \|a-b\|^2.$$

- ② Let  $a$  be Birkhoff-James orthogonal to  $\mathcal{B}$  i.e.  $\text{dist}(a, \mathcal{B}) = \|a\|$ .  
③ By the Hahn-Banach theorem, there exists  $\psi \in \mathcal{A}^*$  such that  $\|\psi\| = 1$ ,  $\psi(a) = \|a\|$  and  $\psi(b) = 0$  for all  $b \in \mathcal{B}$ .  
④ Hence there exists a cyclic representation  $(\mathcal{H}, \pi, \xi)$  of  $\mathcal{A}$  and a unit vector  $\eta \in \mathcal{H}$  such that

$$\psi(c) = \langle \eta | \pi(c) \xi \rangle \text{ for all } c \in \mathcal{A}.$$

# Proof using representations of $C^*$ -algebra

Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

*Proof.*

- ① Reverse direction is easy. For all  $b \in \mathcal{B}$ ,

$$\|a\|^2 = \phi(a^*a) \leq \phi(a^*a) + \phi(b^*b) = \phi((a-b)^*(a-b)) \leq \|a-b\|^2.$$

- ② Let  $a$  be Birkhoff-James orthogonal to  $\mathcal{B}$  i.e.  $\text{dist}(a, \mathcal{B}) = \|a\|$ .  
③ By the Hahn-Banach theorem, there exists  $\psi \in \mathcal{A}^*$  such that  $\|\psi\| = 1$ ,  $\psi(a) = \|a\|$  and  $\psi(b) = 0$  for all  $b \in \mathcal{B}$ .  
④ Hence there exists a cyclic representation  $(\mathcal{H}, \pi, \xi)$  of  $\mathcal{A}$  and a unit vector  $\eta \in \mathcal{H}$  such that

$$\psi(c) = \langle \eta | \pi(c) \xi \rangle \text{ for all } c \in \mathcal{A}.$$

# Proof Continued

## Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

# Proof Continued

## Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

- 5 Now  $\psi(a) = \langle \eta | \pi(a)\xi \rangle = \|a\|$ . So by using the condition for equality in Cauchy-Schwarz inequality, we obtain  $\|a\|\eta = \pi(a)\xi$ .



# Proof Continued

## Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

- 5 Now  $\psi(a) = \langle \eta | \pi(a)\xi \rangle = \|a\|$ . So by using the condition for equality in Cauchy-Schwarz inequality, we obtain  $\|a\|\eta = \pi(a)\xi$ .
- 6 This gives  $\psi(c) = \frac{1}{\|a\|} \langle \pi(a)\xi | \pi(c)\xi \rangle$  for all  $c \in \mathcal{A}$ .

# Proof Continued

## Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

- 5 Now  $\psi(a) = \langle \eta | \pi(a)\xi \rangle = \|a\|$ . So by using the condition for equality in Cauchy-Schwarz inequality, we obtain  $\|a\|\eta = \pi(a)\xi$ .
- 6 This gives  $\psi(c) = \frac{1}{\|a\|} \langle \pi(a)\xi | \pi(c)\xi \rangle$  for all  $c \in \mathcal{A}$ .

# Proof Continued

## Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

- 5 Now  $\psi(a) = \langle \eta | \pi(a)\xi \rangle = \|a\|$ . So by using the condition for equality in Cauchy-Schwarz inequality, we obtain  $\|a\|\eta = \pi(a)\xi$ .
- 6 This gives  $\psi(c) = \frac{1}{\|a\|} \langle \pi(a)\xi | \pi(c)\xi \rangle$  for all  $c \in \mathcal{A}$ .
- 7 Therefore,  $\langle \pi(a)\xi | \pi(a)\xi \rangle = \|a\|^2$  and  $\langle \pi(a)\xi | \pi(b)\xi \rangle = 0$  for all  $b \in \mathcal{B}$ .

# Proof Continued

## Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

- 5 Now  $\psi(a) = \langle \eta | \pi(a)\xi \rangle = \|a\|$ . So by using the condition for equality in Cauchy-Schwarz inequality, we obtain  $\|a\|\eta = \pi(a)\xi$ .
- 6 This gives  $\psi(c) = \frac{1}{\|a\|} \langle \pi(a)\xi | \pi(c)\xi \rangle$  for all  $c \in \mathcal{A}$ .
- 7 Therefore,  $\langle \pi(a)\xi | \pi(a)\xi \rangle = \|a\|^2$  and  $\langle \pi(a)\xi | \pi(b)\xi \rangle = 0$  for all  $b \in \mathcal{B}$ .
- 8 Define  $\phi \in \mathcal{A}^*$  as  $\phi(c) = \langle \xi | \pi(c)\xi \rangle$ .

# Proof Continued

## Theorem (Grover P.; Singla S., 2021)

*Let  $a \in \mathcal{A}$ . Let  $\mathcal{B}$  be a subspace of  $\mathcal{A}$ . Then  $a$  is Birkhoff-James orthogonal to  $\mathcal{B}$  if and only if there exists  $\phi \in \mathcal{S}_{\mathcal{A}}$  such that  $\phi(a^*a) = \|a\|^2$  and  $\phi(a^*b) = 0$  for all  $b \in \mathcal{B}$ .*

- 5 Now  $\psi(a) = \langle \eta | \pi(a)\xi \rangle = \|a\|$ . So by using the condition for equality in Cauchy-Schwarz inequality, we obtain  $\|a\|\eta = \pi(a)\xi$ .
- 6 This gives  $\psi(c) = \frac{1}{\|a\|} \langle \pi(a)\xi | \pi(c)\xi \rangle$  for all  $c \in \mathcal{A}$ .
- 7 Therefore,  $\langle \pi(a)\xi | \pi(a)\xi \rangle = \|a\|^2$  and  $\langle \pi(a)\xi | \pi(b)\xi \rangle = 0$  for all  $b \in \mathcal{B}$ .
- 8 Define  $\phi \in \mathcal{A}^*$  as  $\phi(c) = \langle \xi | \pi(c)\xi \rangle$ .

# References

- ⑤ Bhatia R.; Šemrl P. : Orthogonality of matrices and some distance problems. *Linear Algebra Appl.* 287 (1999), 77–85.
- ⑥ Holub J. R. : On the metric geometry of ideals of operators on Hilbert space. *Math. Ann.* 201 (1973), 157–163.
- ⑦ Rieffel M. A. : Leibniz seminorms and best approximation from  $C^*$ -subalgebras. *Sci. China Math.* 54 (2011), 2259–2274.
- ⑧ Singer I. : Best Approximation in Normed Linear Spaces by Elements of Linear Subspaces. *Springer-Verlag, Berlin*, 1970.
- ⑨ Williams J. P. : Finite operators. *Proc. Amer. Math. Soc.* 26 (1970), 129–136.

## References

- ① James R. C. : Orthogonality and linear functionals in normed linear spaces. *Trans. Amer. Math. Soc.* 61 (1947), 265–292.
- ② Grover P. : Orthogonality to matrix subspaces, and a distance formula. *Linear Algebra Appl.* 445 (2014), 280–288.
- ③ Grover P. ; Singla S. : Best Approximations, distance formulas and orthogonality in  $C^*$ -algebras. *J. Ramanujan Math. Soc.* 36 (2021), 85–91.
- ④ Grover P. ; Singla S. : Birkhoff-James orthogonality and applications : A survey. *Operator Theory, Functional Analysis and Applications*, Birkhäuser, Springer, vol. 282, 2021.
- ⑤ Singla S. : Gateaux derivative of  $C^*$  norm. *communicated*.